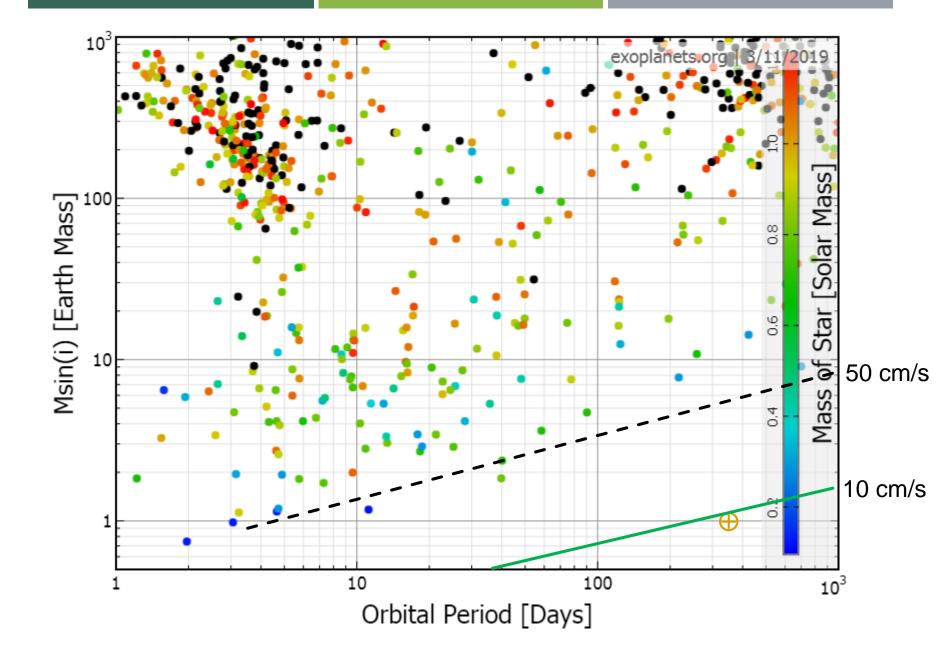
# HARPS3

#### SAMANTHA THOMPSON – CAVENDISH LABORATORY, CAMBRIDGE



#### www.terrahunting.org

# WHY ARE WE BUILDING HARPS3?



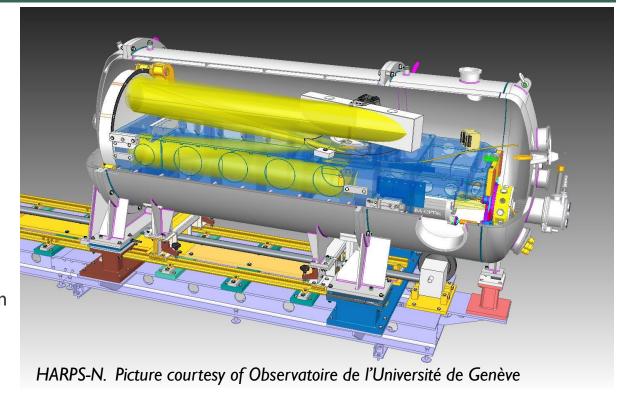
### TERRA HUNTING EXPERIMENT

- I 0 year programme to find the RV signal of an "Earth-twin"
  - > (and also be filling in the long-period planets discovery space as a byproduct)
- Sample of bright solar-like stars (Vmag < 8.5)
- Optimised, intensive observing strategy <u>robotic scheduling and</u> <u>operations</u>
  - > Targets observed <u>every night</u>
  - + Spectro-polarimetric measurements (cadence TBD)
  - > Allows better tracking of stellar activity signals
  - $\succ$  Repeated over many years  $\rightarrow$  capture many repeats of planetary Doppler signal
  - … 1000+ measurements per star

### BRIEF OVERVIEW OF HARPS3

- Close-copy of HARPS/HARPS-N
  - Demonstrated RV accuracy ~ 50 cm/s
- Stable, fibre-fed, high resolution spectrograph
  - ▶ R = 115,000





HARPS3 for a Roboticized Isaac Newton Telescope, Samantha J. Thompson, Didier Queloz, Isabelle Baraffe, Martyn Brake, Andrey Dolgopolov, Martin Fisher, Michel Fleury, Joost Geelhoed and 20 co-authors, Proc. SPIE vol. 9908 (2016).

### WHERE WILL IT BE INSTALLED?

- The 2.5m Isaac Newton Telescope (INT) in La Palma, Canary Islands
  - Equatorial mounting
  - Fibre at Cassegrain focus (1.4" on-sky)
  - Photon noise of 40cm/s for 8th mag G-dwarf, av. seeing, 20min exp.
  - Dedicated Coudé rooms
    - Shorter fibre, improved blue efficiency
  - Refurb to enable robotic operations
  - Nightly access for 10 years (~50% time per night on average)

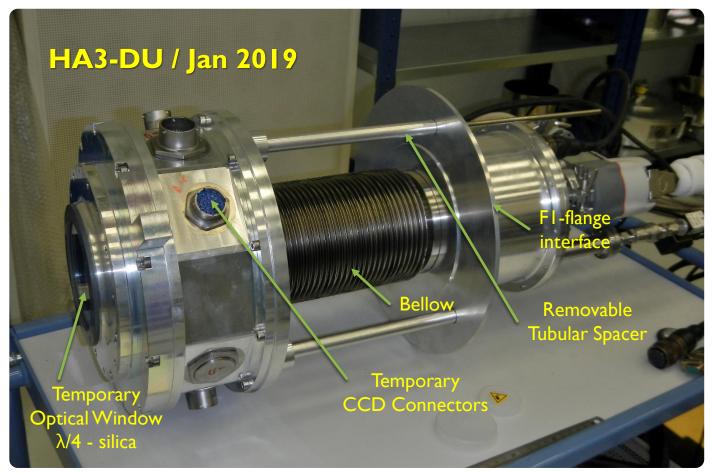


INT current info: http://www.ing.iac.es/Astronomy/telescopes/int/

- Full-Stokes, dual-beam polarimeter (integrated in the design of the Cass fibre adapter)
- Octagonal fibres + double scrambler + guiding accuracy of 0.05" RMS (goal) over an exposure
- Echelle grating substrate: Zerodur Class 0 SPECIAL, CTE = 0 ± 0.010 10<sup>-6</sup>/K
- Calibration Unit 8 switchable light sources
- Detector Unit:
  - e2V chip: CCD231-84-0-G57
  - A new design continuous-flow cryostat
  - Enhanced CCD calibration
- Nightly access for THE  $\rightarrow$  improved time sampled RV data series
- Robotic operation

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#### MICHEL FLEURY / GENEVA OBSERVATORY / CAM - 31.01.2019



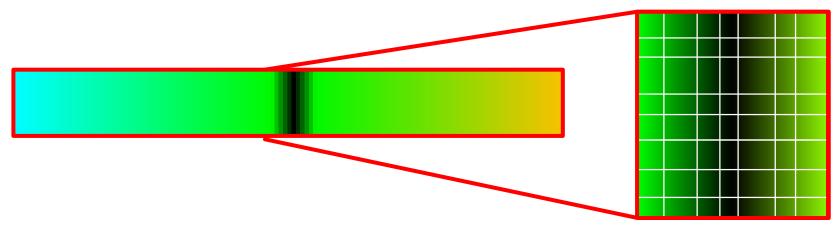
- > ~1 mK rms stability ... verification tests this summer
- > Vacuum pressure inside detector unit  $\sim 2 \times 10^{-6}$  mbar

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### CCD CHARACTERISATION

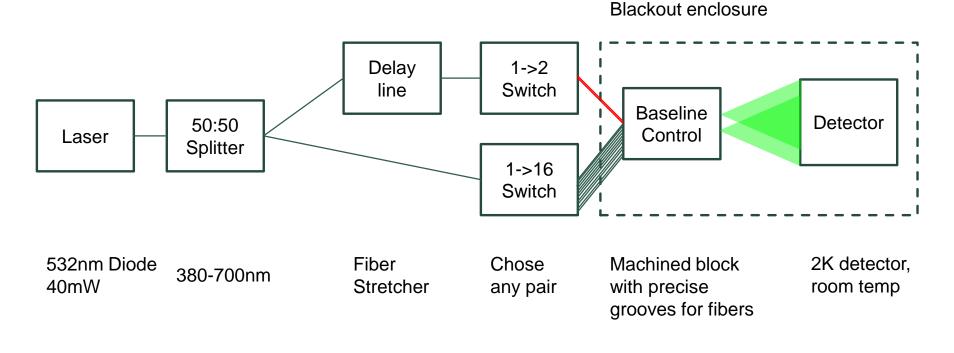
#### **Motivation:**

- Assuming a perfect CCD geometry introduces error to wavelength solution
- FWHM of spectral line ~ 3 px, 0.1 m/s  $\approx$  1/1000 px
- > Map the effective pixel positions to this accuracy or better (goal 1e-4 px)



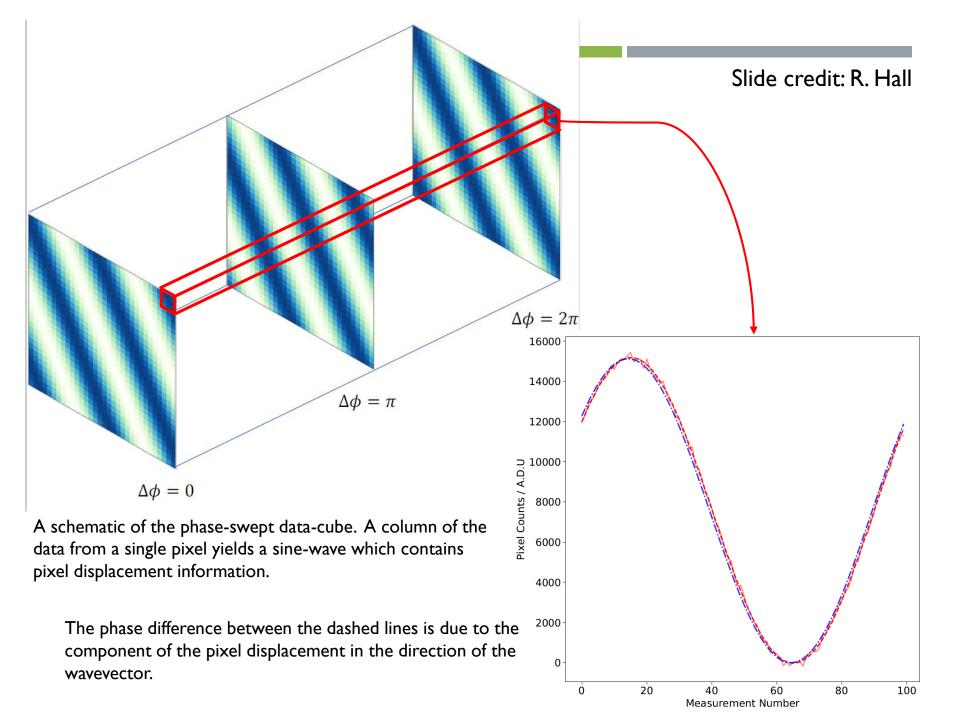
Picture credit: R. Hall

## Schematic of CCD measurement



Measuring the effective pixel positions for the HARPS3 CCD, *Richard Hall et al.*, SPIE 2016, new paper in prep – 2019

Method based on previous works by Shaklan+ 1995, Crouzier+ 2012



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### SAMPLING STRATEGIES

On the Feasibility of Intense Radial Velocity Surveys for Earth-twin Discoveries, *RD Hall, SJ Thompson, W Handley, D Queloz,* Monthly Notices of the Royal Astronomical Society 479 (3), 2968-2987 (2018).

#### Simulated data series:

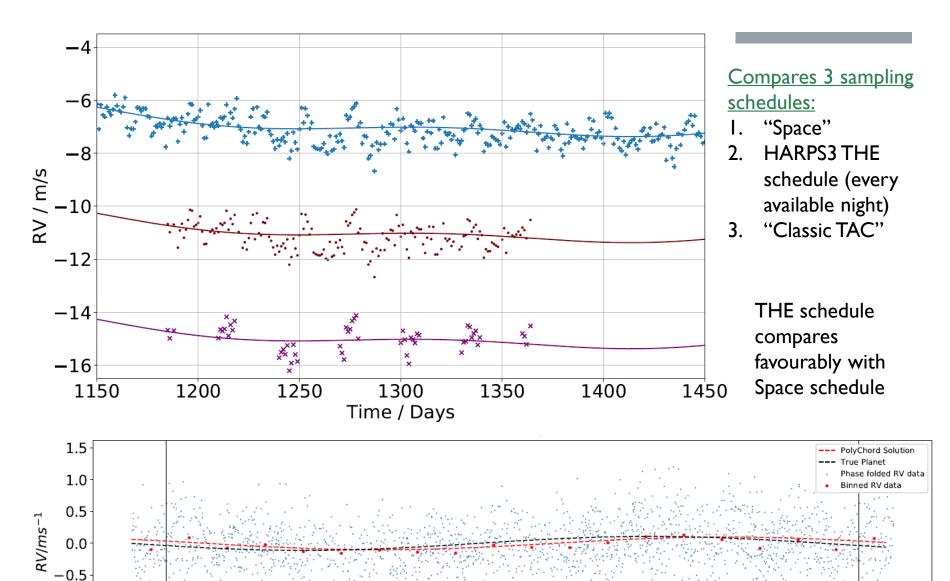
- Used SOAP 2.0 for stellar "noise" signal (Dumusque et al.ApJ, Vol. 796, 2 (2014))
- Assumed a low activity G8 star (0.8  $M_{\odot}$ )
- Included photon noise at the  $1\sigma$  = 30 cm/s level

#### Simulated observing schedules for THE:

- 180 day obs window in 1 year
- 20% bad weather outages (summer weather pattern)
- Total duration: 5 years and 10 years

#### Analysis:

- Assumed a stellar noise "correction factor" of 4 (original stellar noise ~ 1.5 m/s)
- Used a Bayesian nested sampling approach: PolyChord Handley et al. MNRAS, Vol. 453, 4 (2015)





-1.0

-1.5

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### **ROBOTIC OPERATION**

- Design in all functionality needed for a fully robotic operation
- Dispatch scheduler (automated, optimised observations)
  - Science and calibration data collection

Quality control tools:

- Extensive engineering database (recording time series data from all the environment sensors, system faults/alerts etc...)
- Alerts can be generated from:
  - DRS-processed data and Engineering data
  - Any monitored variables (and combinations)
  - Event triggered
- FITS files will be assembled from a raw detector frame and ancillary data/metadata provided by the robotic control system:
  - Usual science metadata
  - Engineering metadata to include exp meter time series and acquisition and integrated guide images



### CURRENT STATUS

#### 2019

- > HARPS3 is now fully funded full steam ahead!
- > Final design reviews for Cass fibre adapter unit, telescope upgrade plans, software systems
- Delivery of Grade0 CCD
- Assembly and testing of new continuous flow cryostat
- Delivery of Echelle grating

#### 2020

- Refurbishment of INT's large Coudé room
- > INT roboticization works begin

#### 202 I

Assembly, integration and testing in labs (all sub-systems)

HARPS3 I<sup>st</sup> light on INT

#### SUMMARY

- HARPS3 will be commissioned on the Isaac Newton Telescope during 2021
- HARPS3 + POL on the INT will offer a unique capability
  - Robotic mode of operation + automated scheduler -> <u>facilitates optimum</u> <u>sampling strategies</u>
  - Every night has time dedicated to THE and open-time programmes
- I Terra Hunting Experiment
  - Sampling regular and long time-series RV data (up to 1500 points over 10 years) to help disambiguate stellar activity and planetary Doppler signals
  - Geared to find Earth-mass planets in the unexplored low-mass/long-period region of 100-300 days