

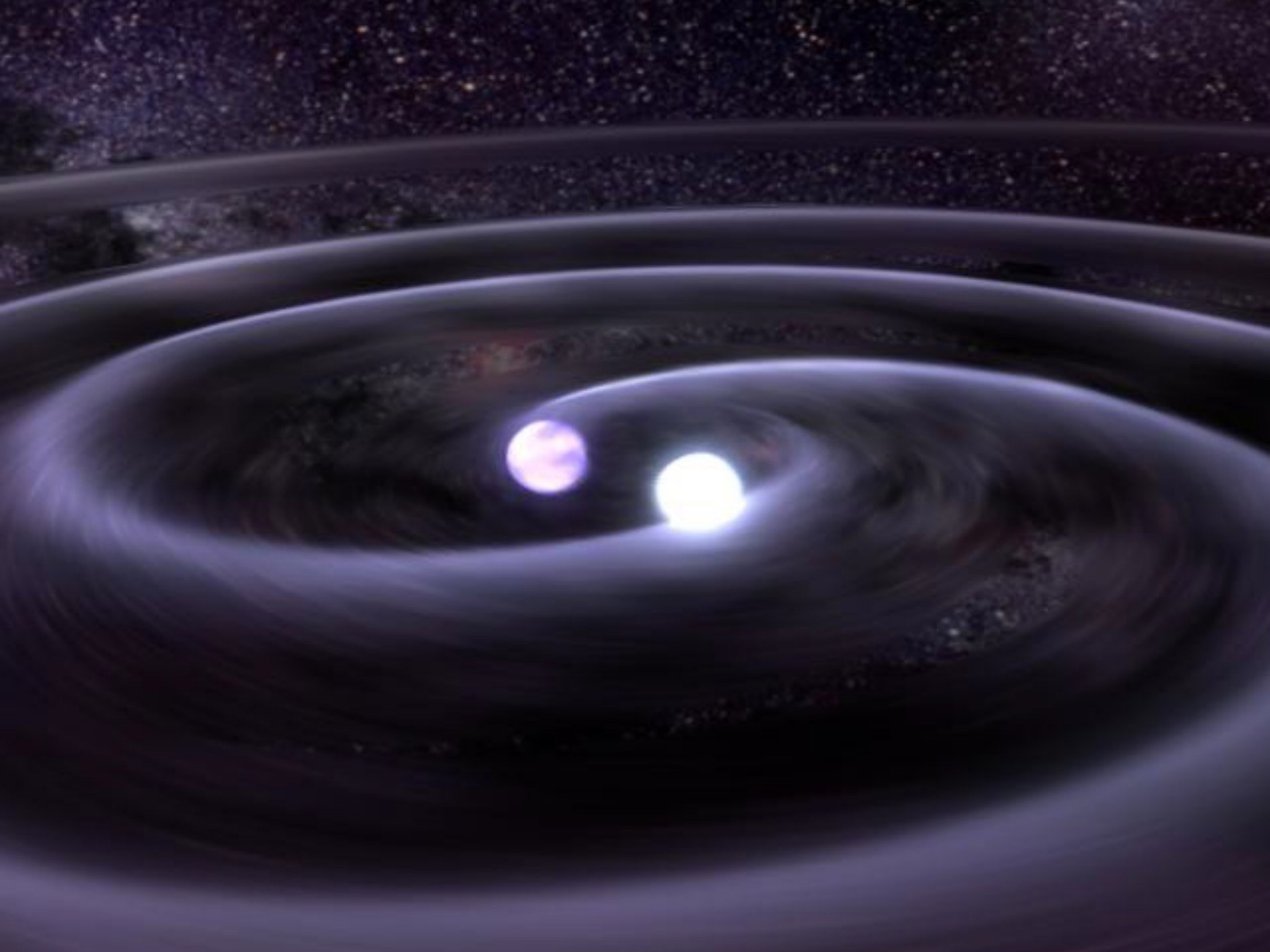
The underlying simplicity of precessing black-hole binaries

Mark Hannam
Cardiff University

Texas Symposium
December 16, 2015
Geneva







Masses: m_1, m_2

Spins: $\mathbf{S}_1, \mathbf{S}_2$

(8 parameters)

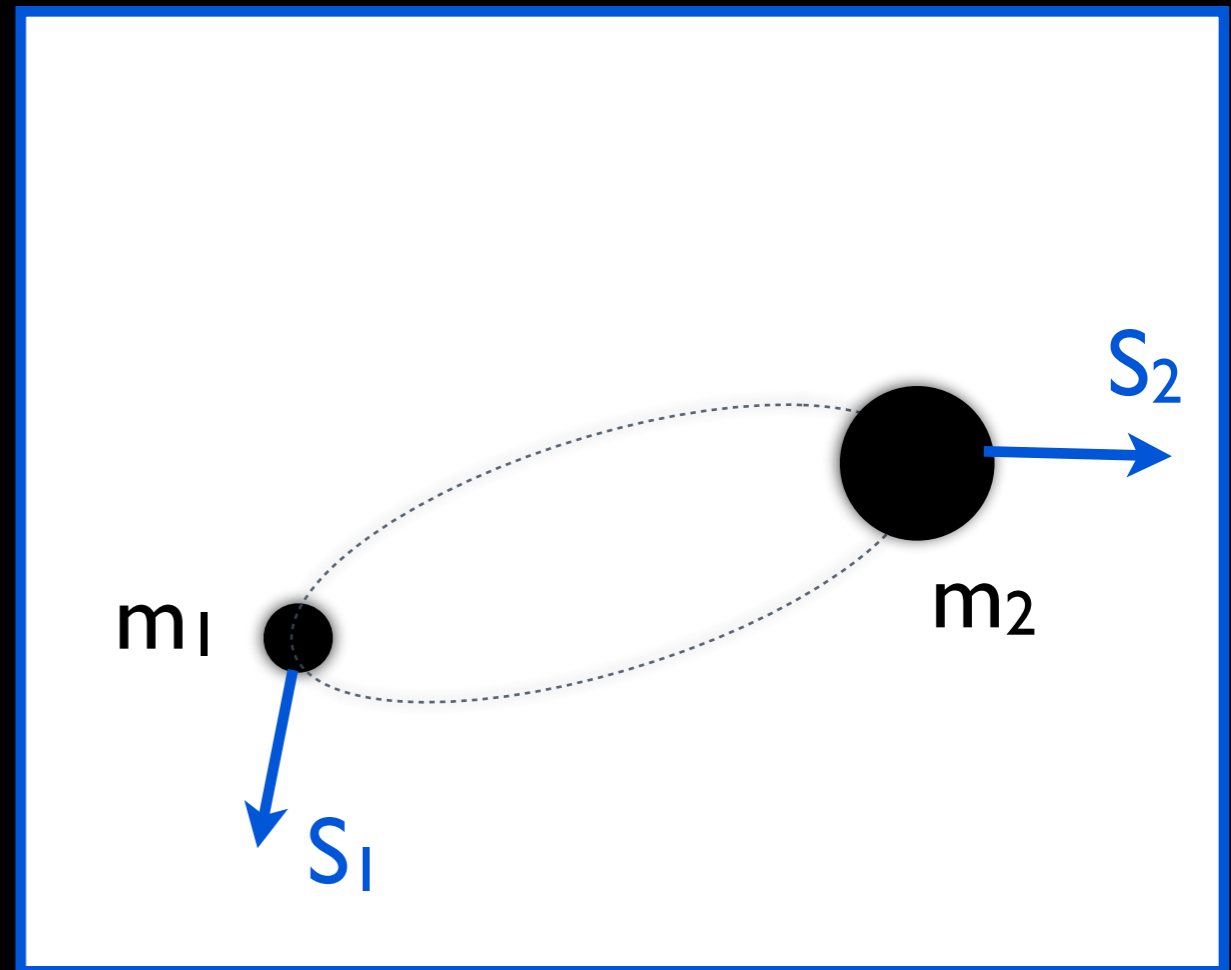
useful combinations:

$$M = m_1 + m_2$$

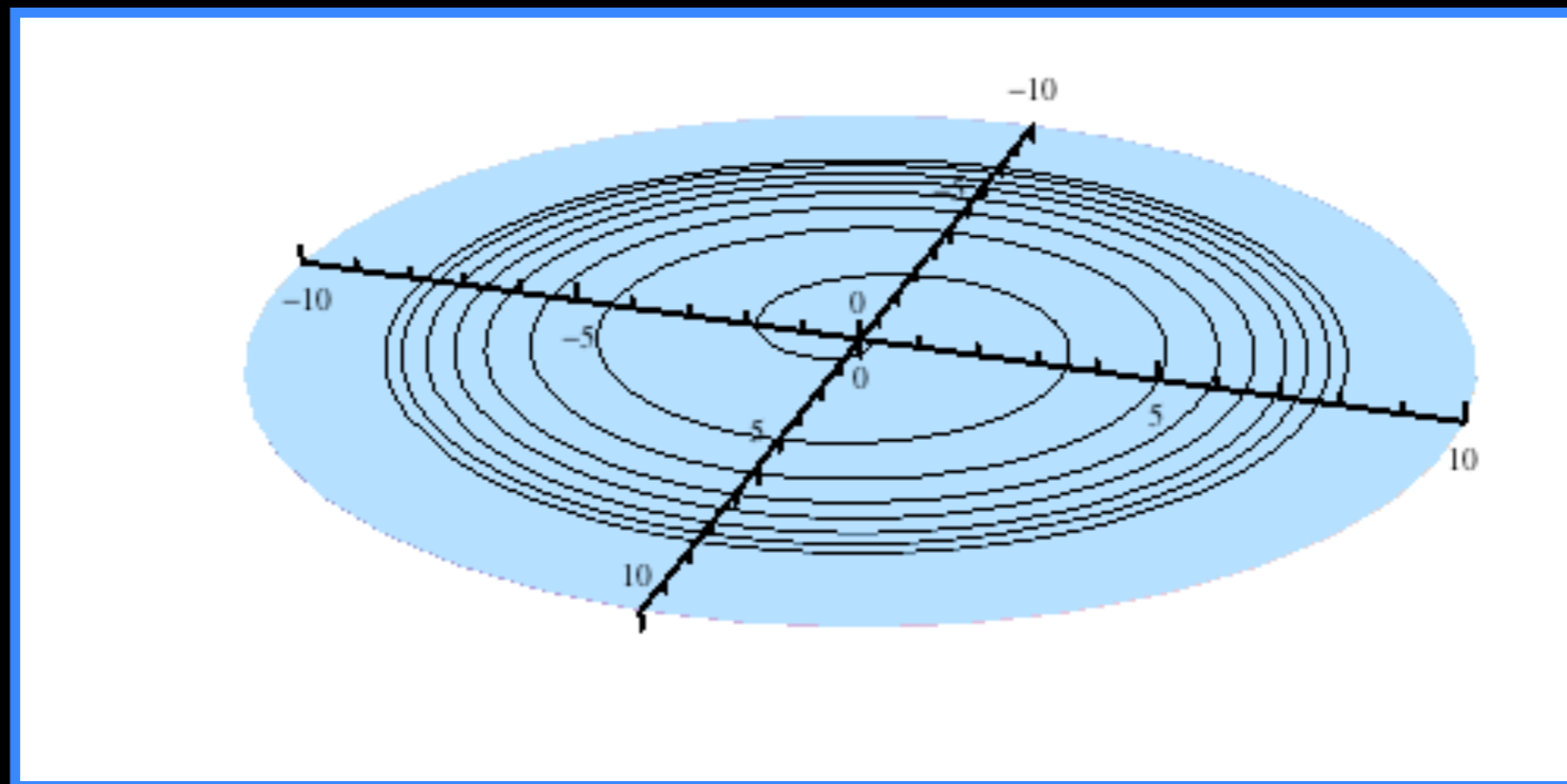
$$q = m_2 / m_1$$

$$\eta = m_1 m_2 / M^2$$

$$\chi = S/m^2$$

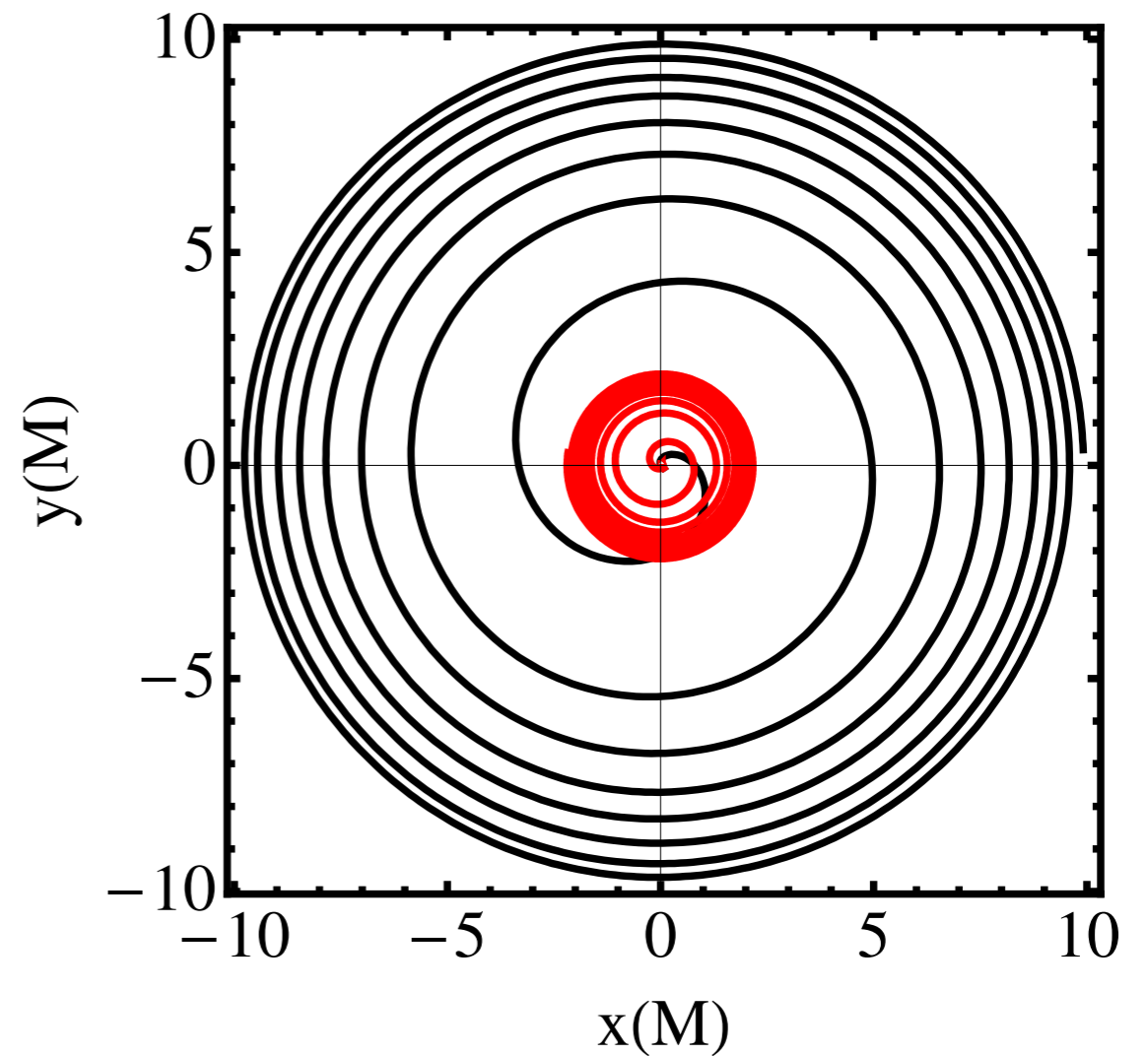
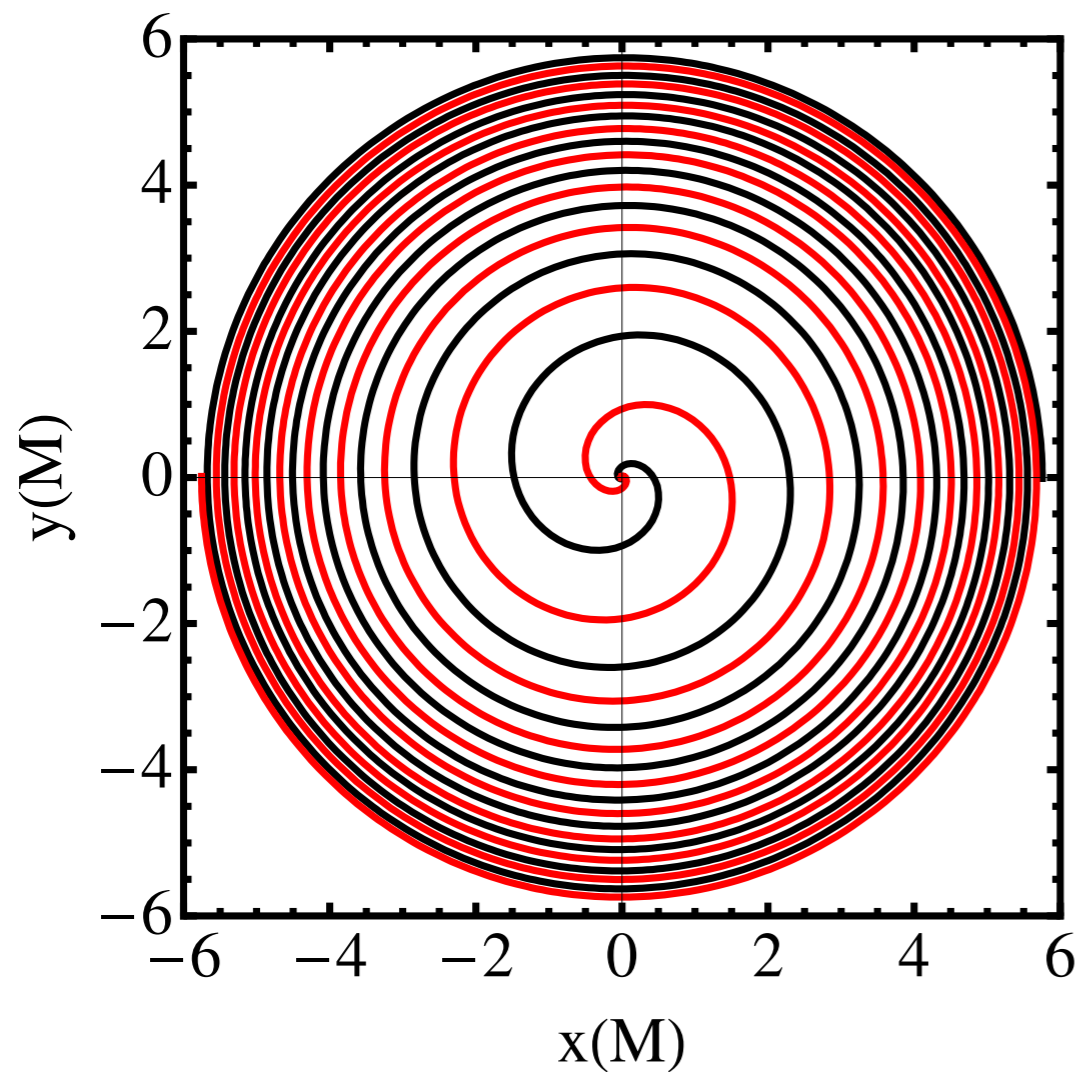


Nonspinning black holes



(Mass ratio 1:4, $\eta = 0.16$)

Nonspinning black holes



Amplitude:



Optimally oriented
(face on)

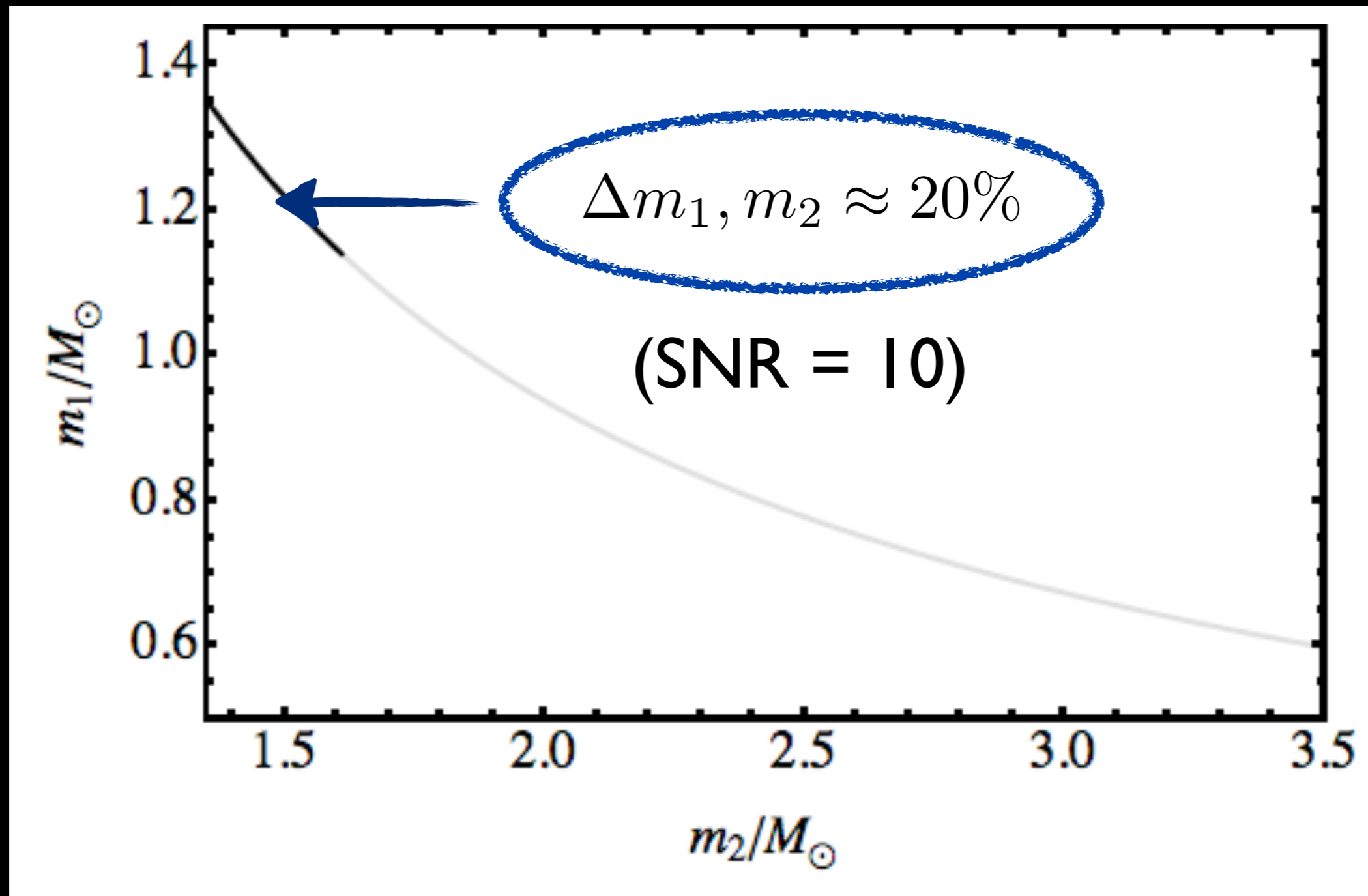


Edge on

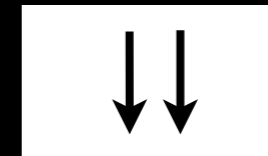
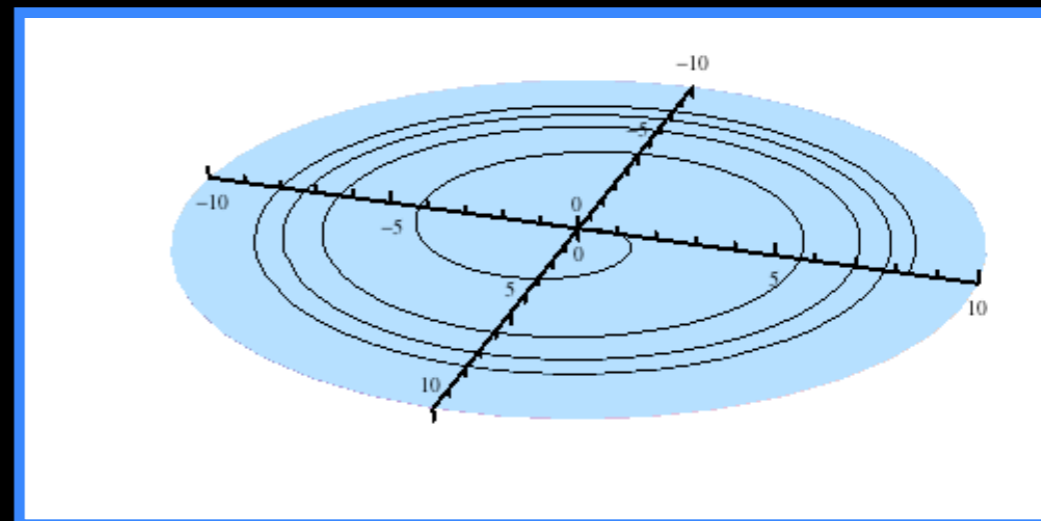
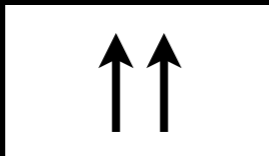
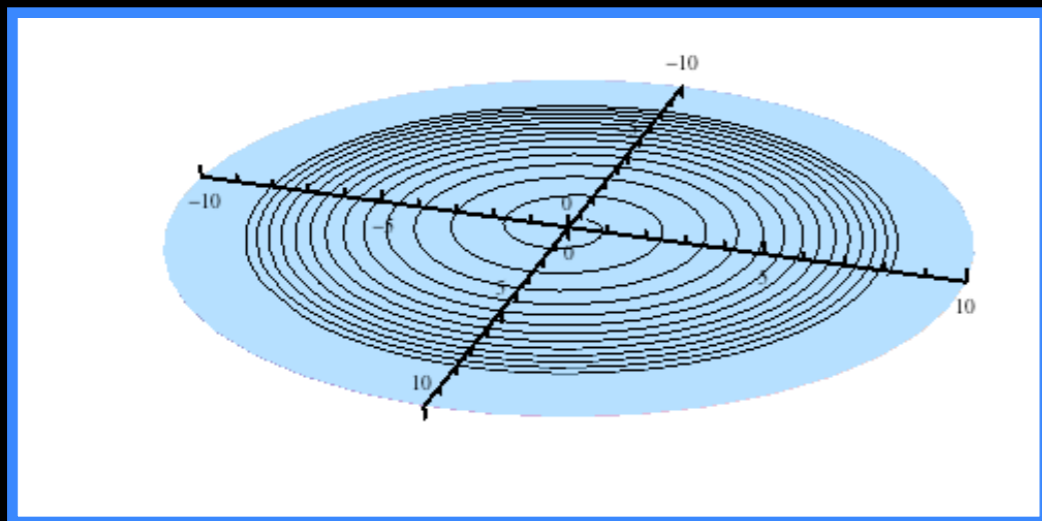
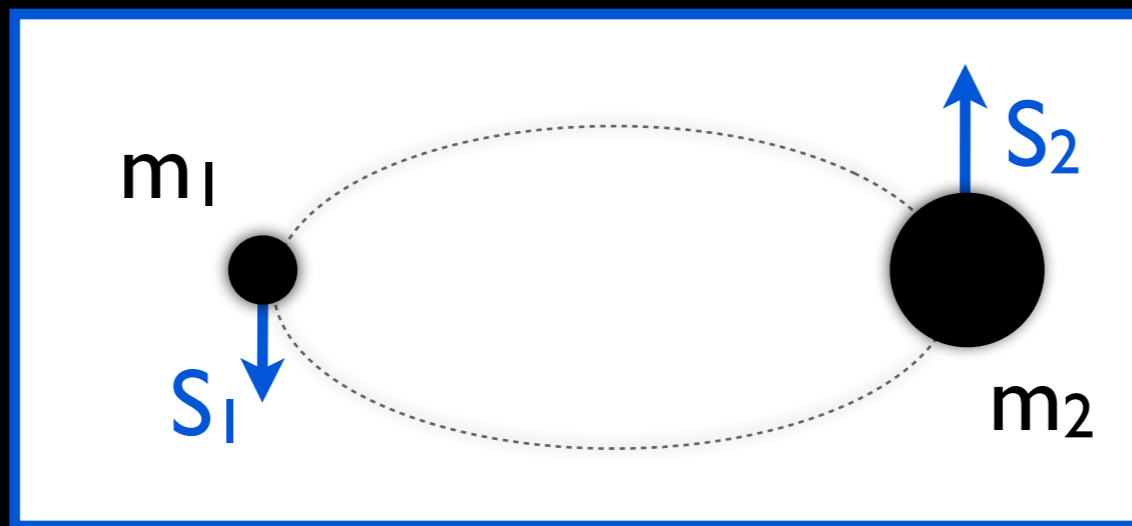
Signal shape is independent of orientation

Key information is in the phasing

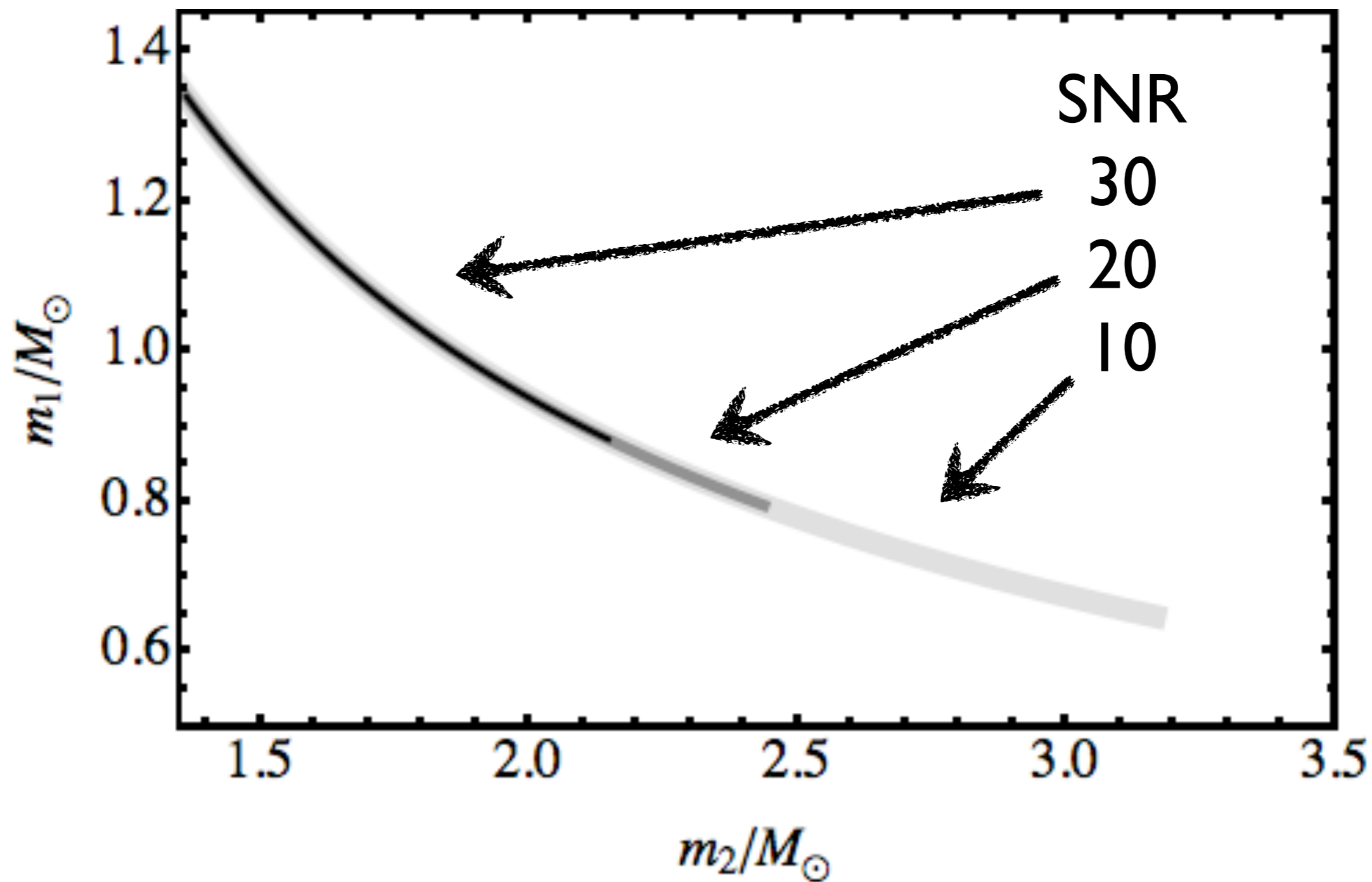
Mass measurements

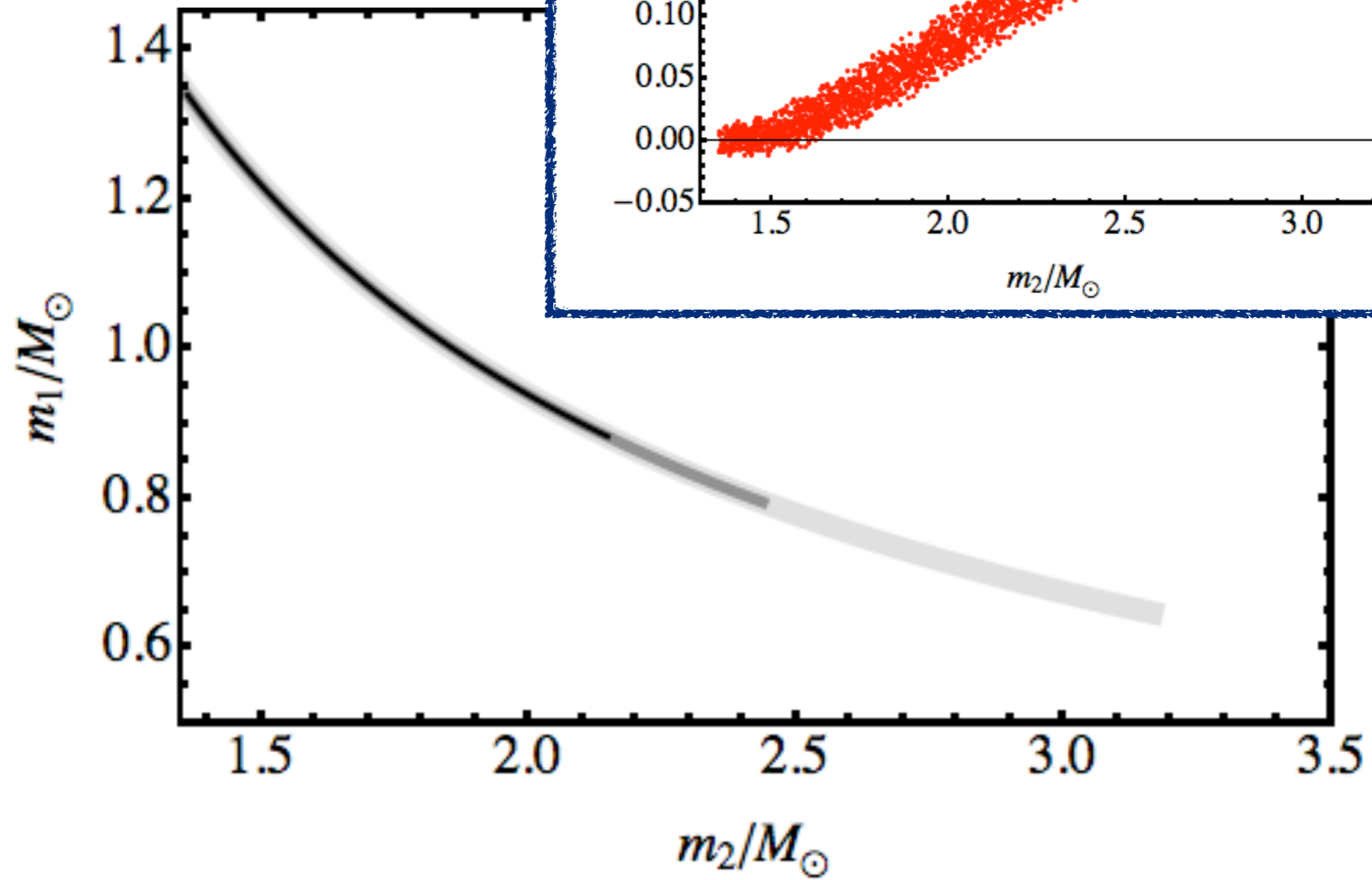


Aligned spins



Aligned spins





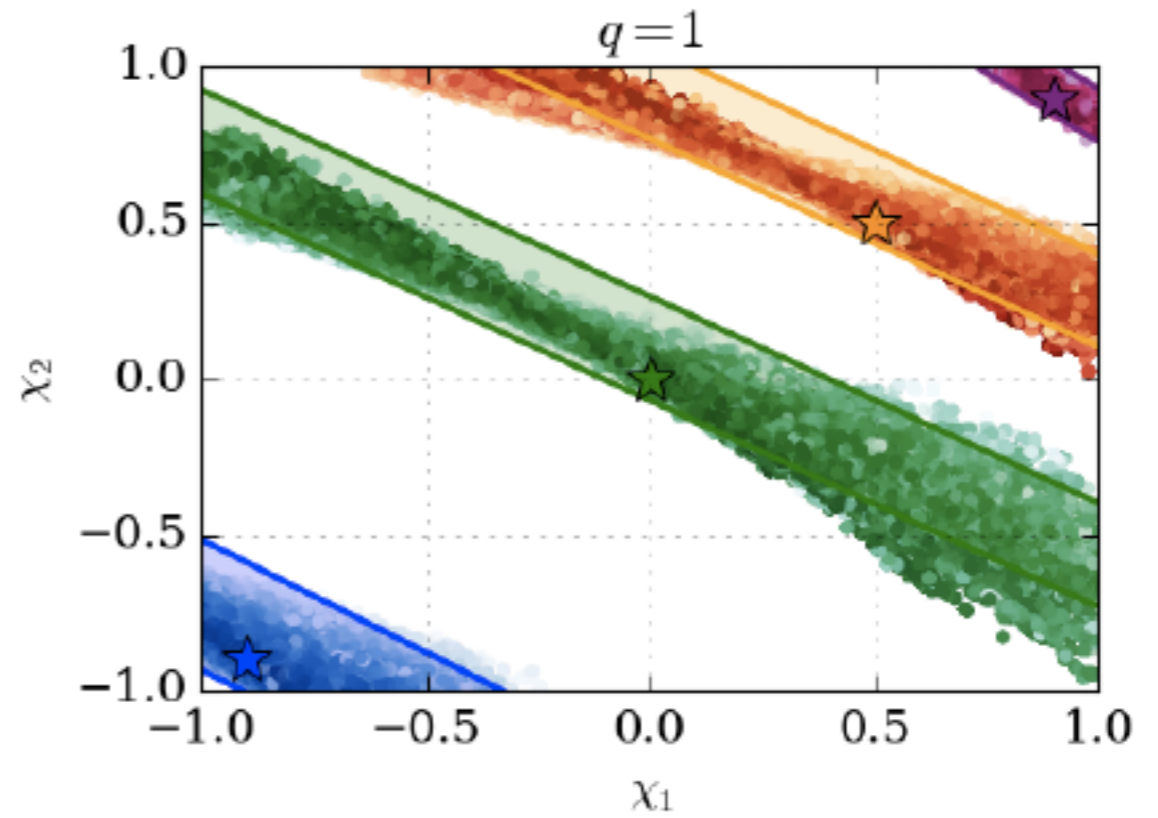
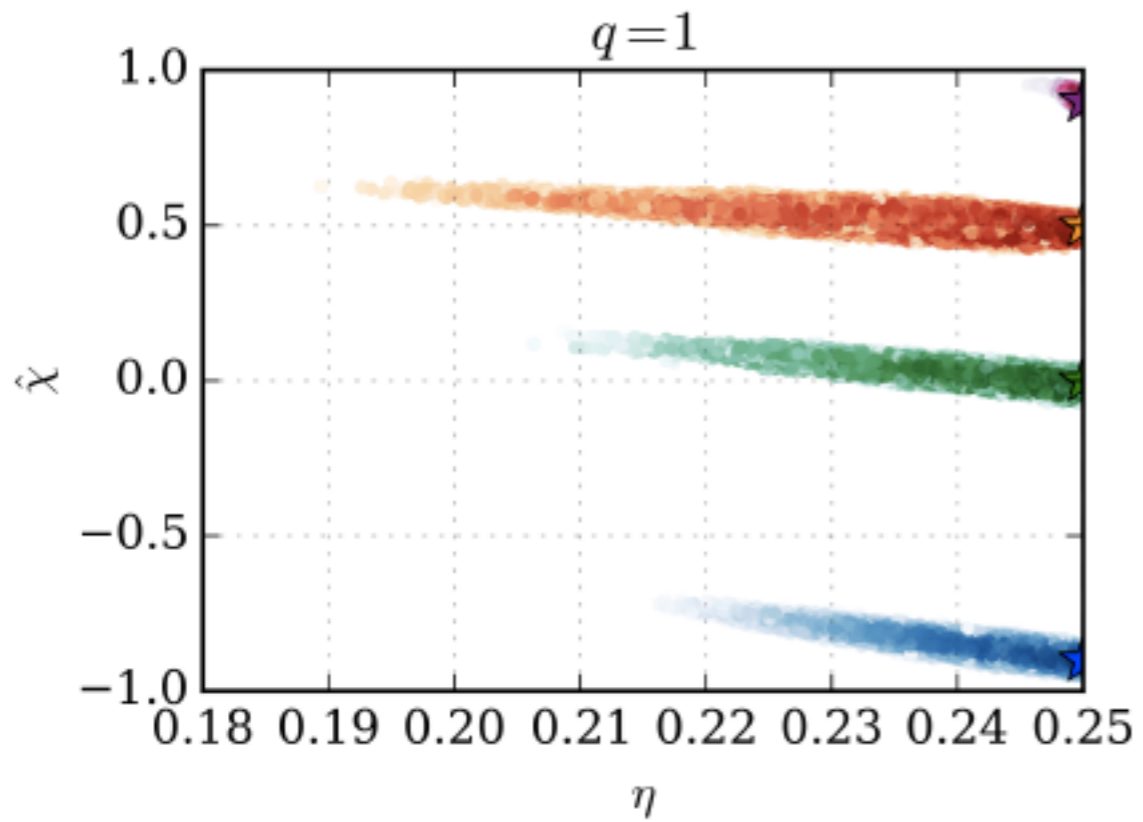
What is “ χ ”?

χ is a weighted sum of the two spins

χ is the dominant spin effect on the phasing

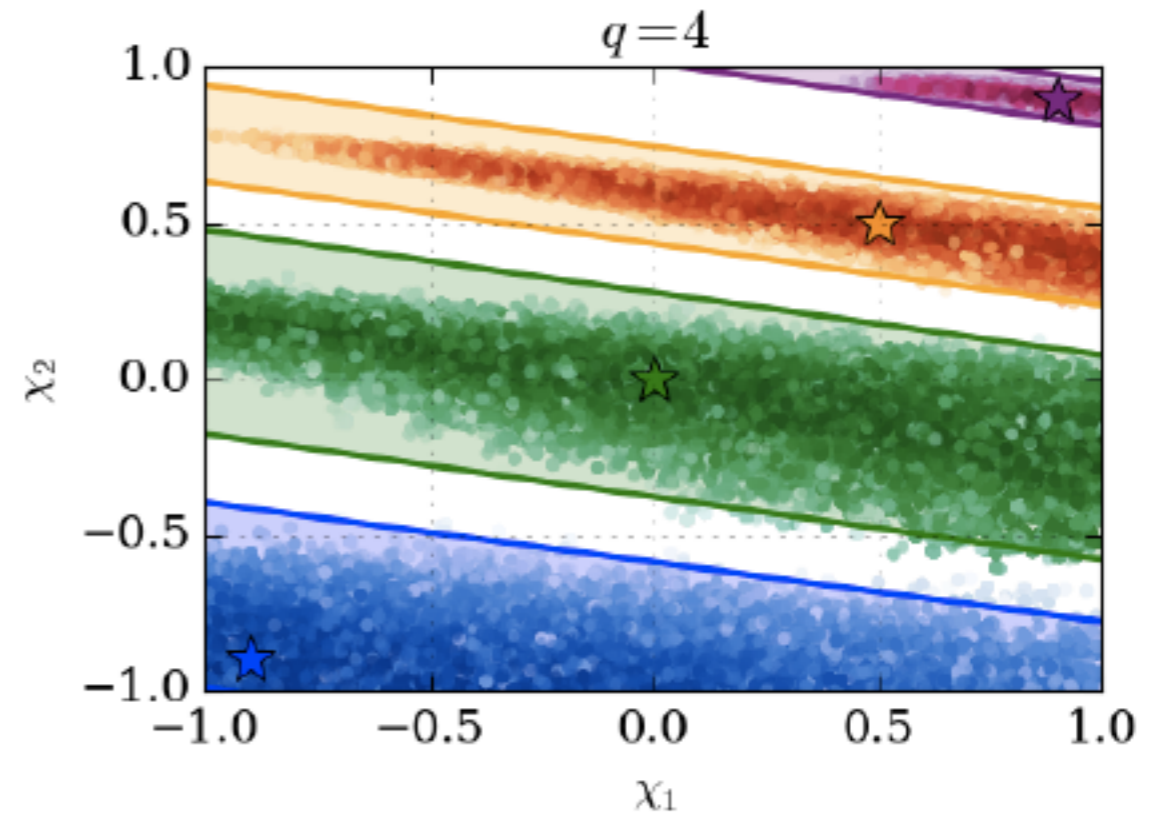
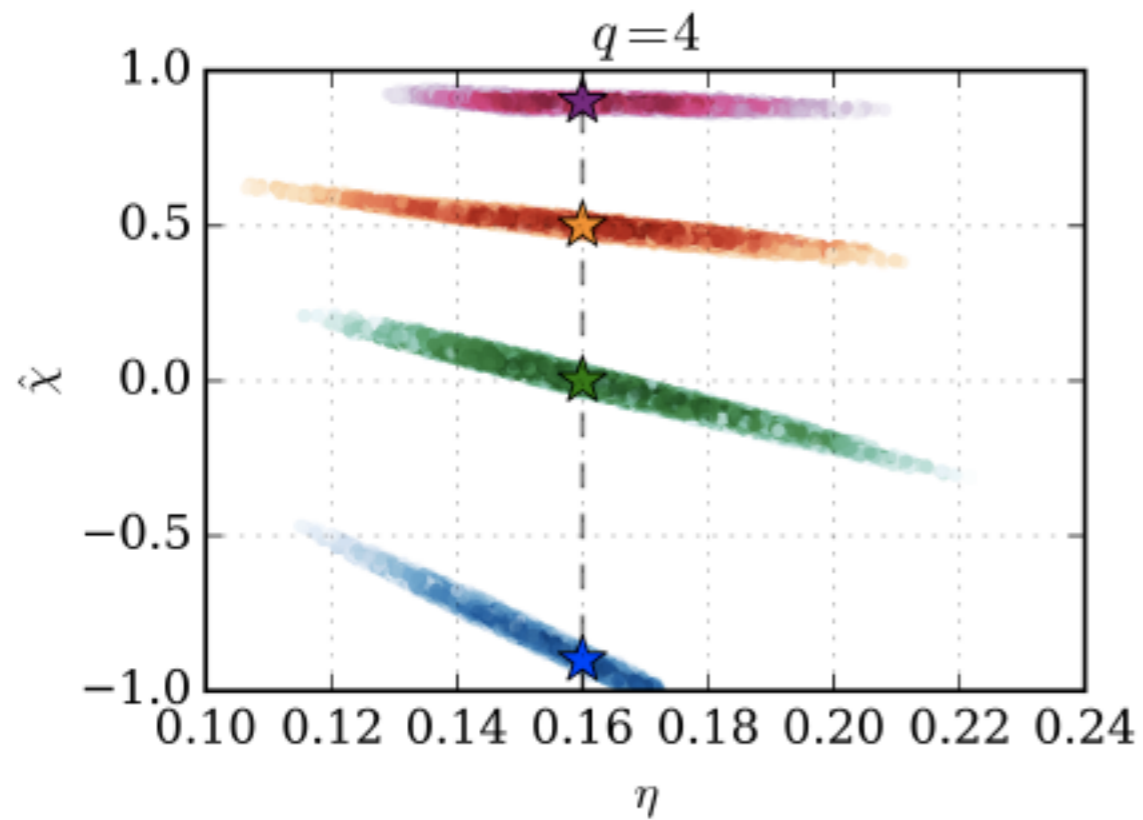
The individual spins have only a weak effect

(50-solar-mass, equal spins)



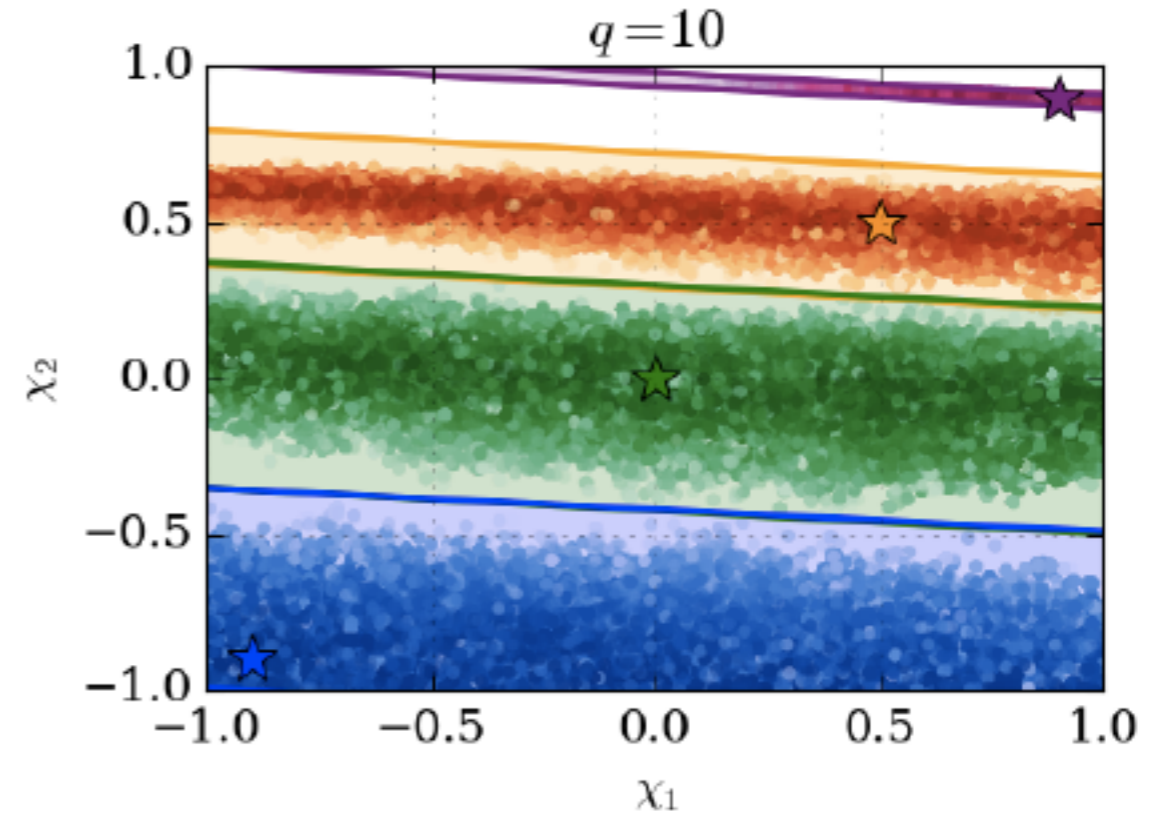
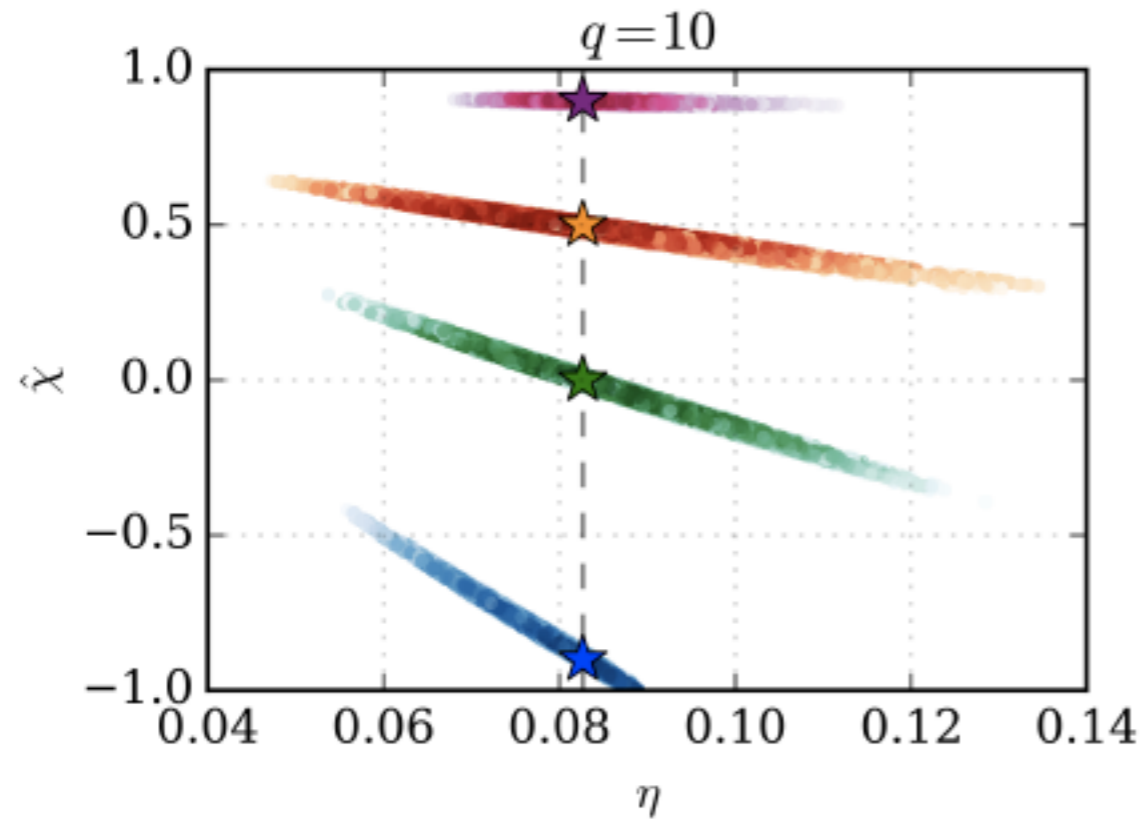
[Puerrer, Hannam, Ohme (2015, to appear)]

(50-solar-mass, equal spins)



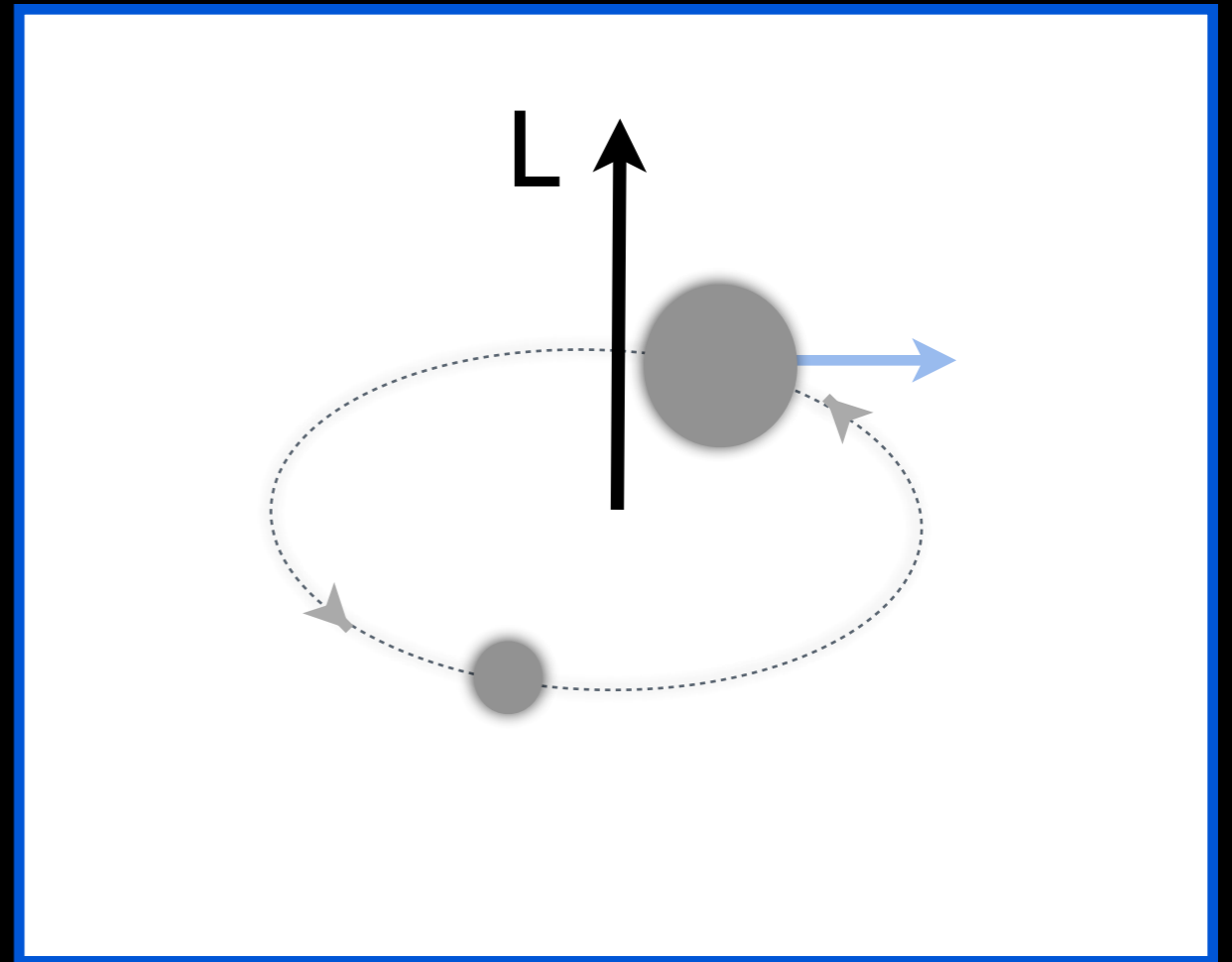
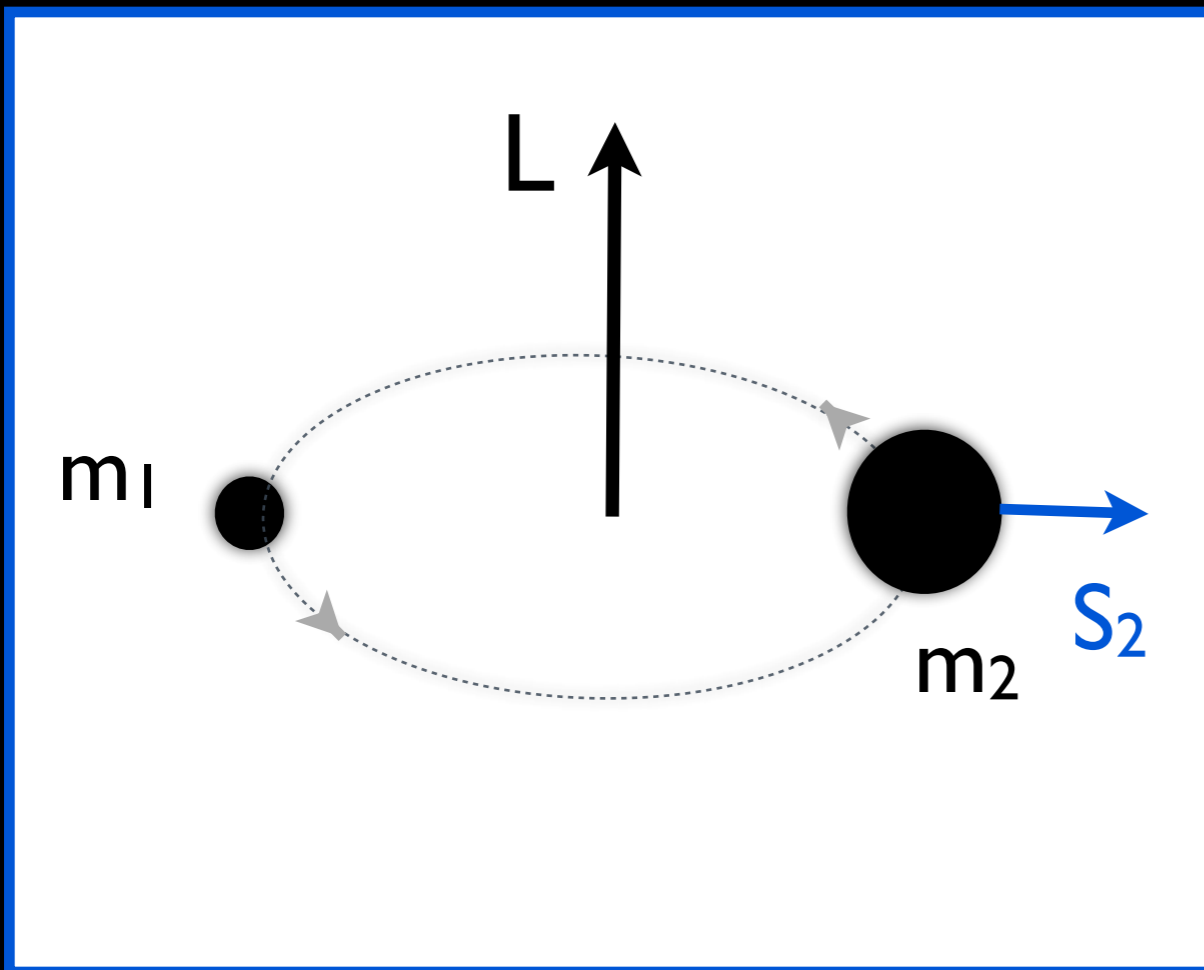
[Puerrer, Hannam, Ohme, 2015 (to appear)]

(50-solar-mass, equal spins)



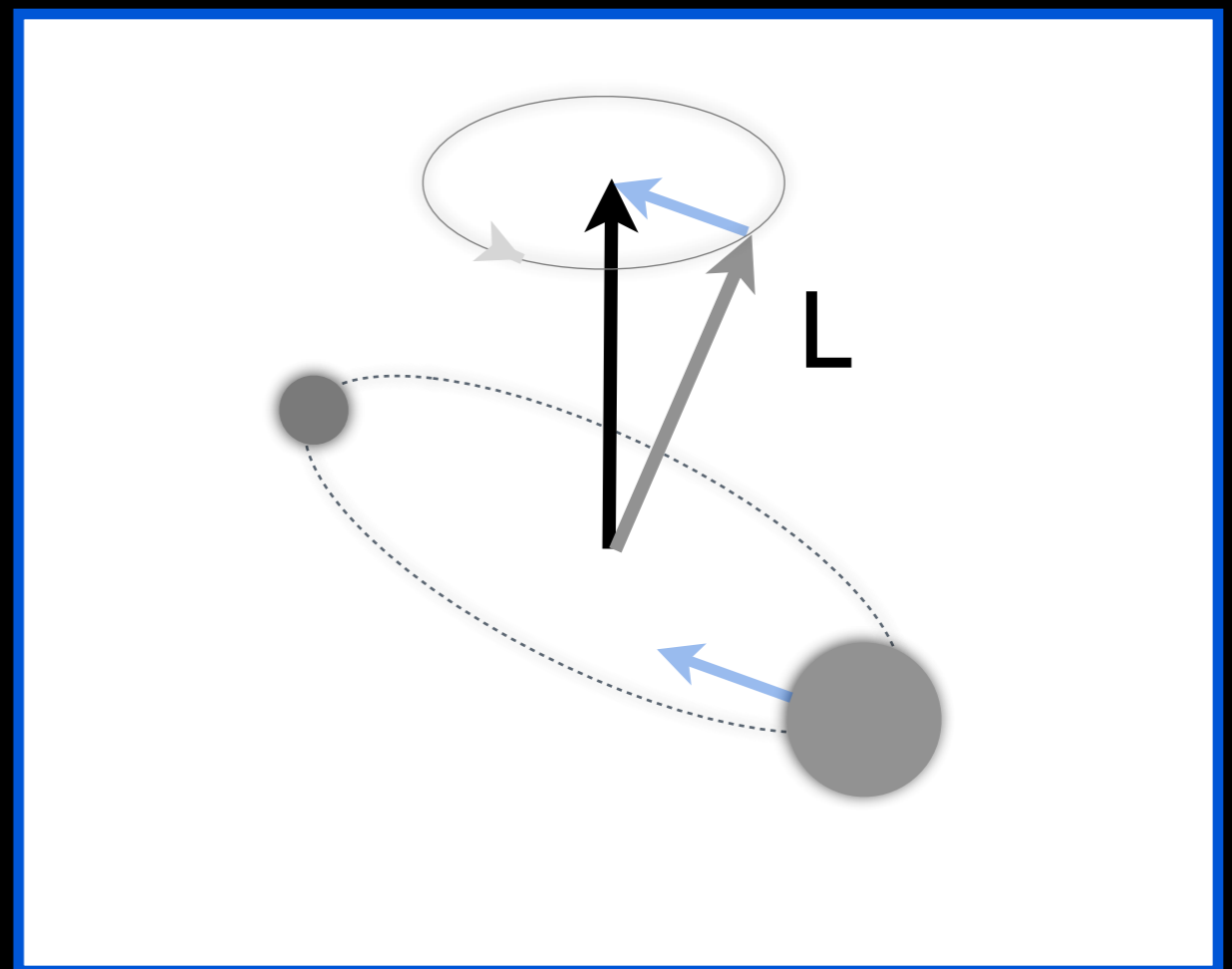
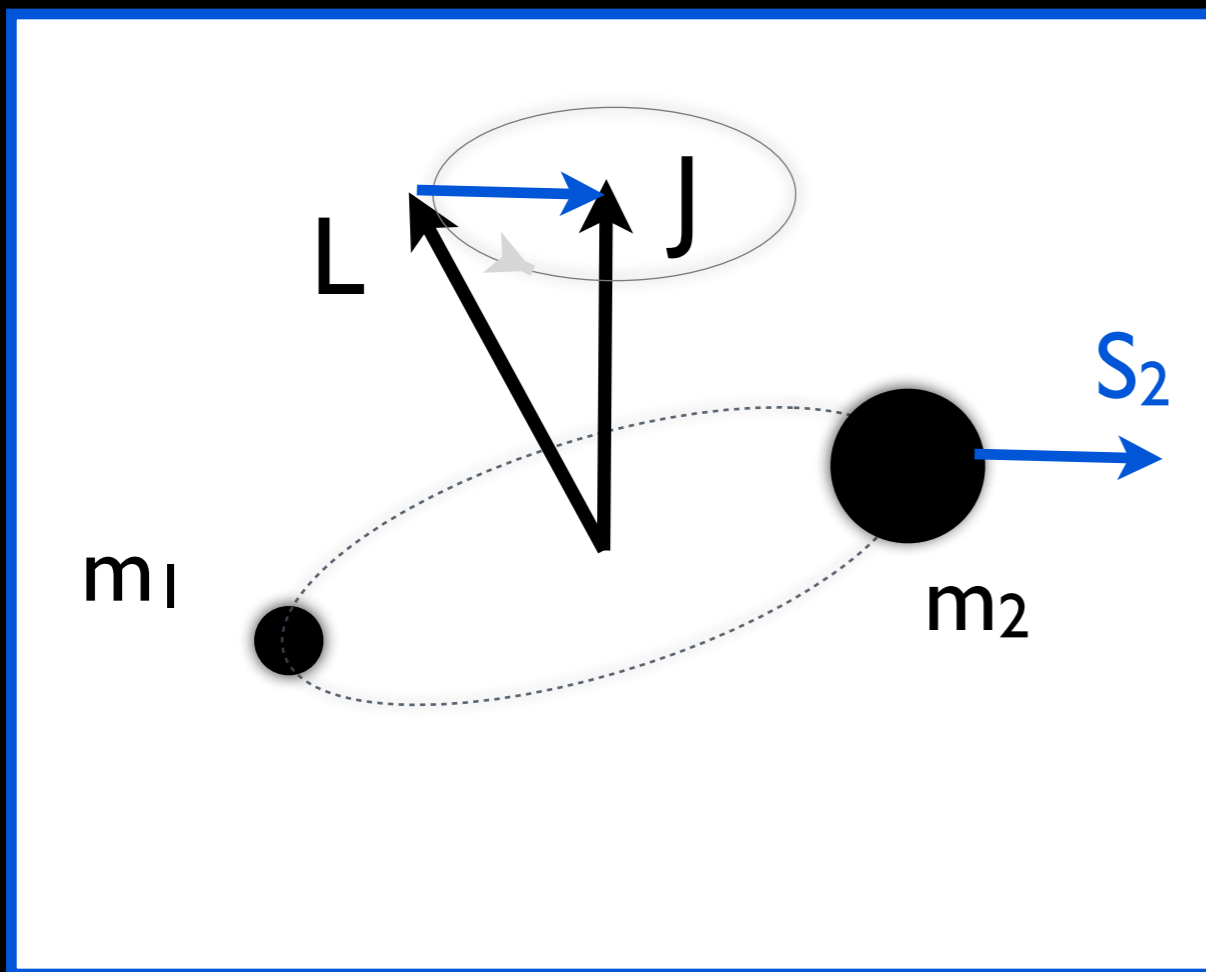
[Puerrer, Hannam, Ohme, 2015 (to appear)]

Orbital precession



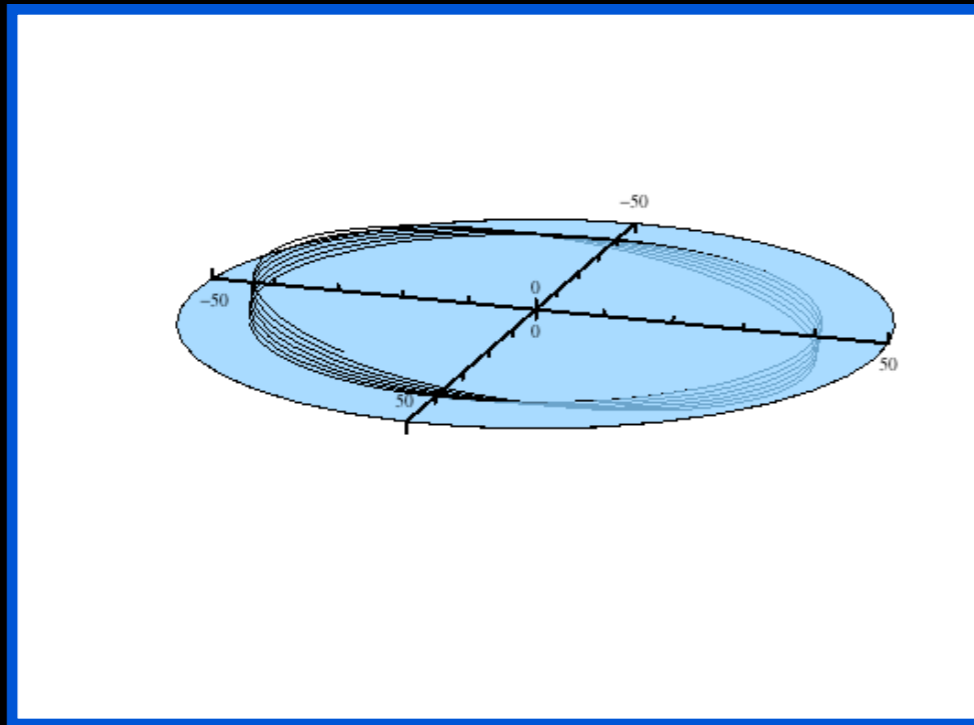
Newtonian gravity:
 L, S_1, S_2 remain fixed

Orbital precession

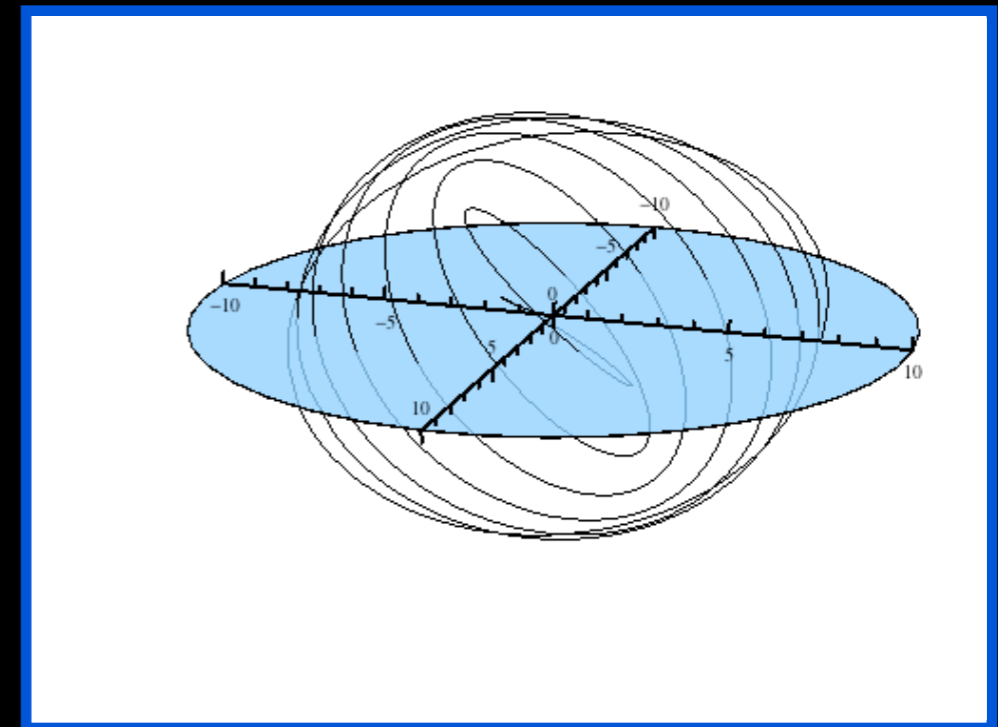


General relativity
(L, S_1, S_2) precess around J

Precessional dynamics

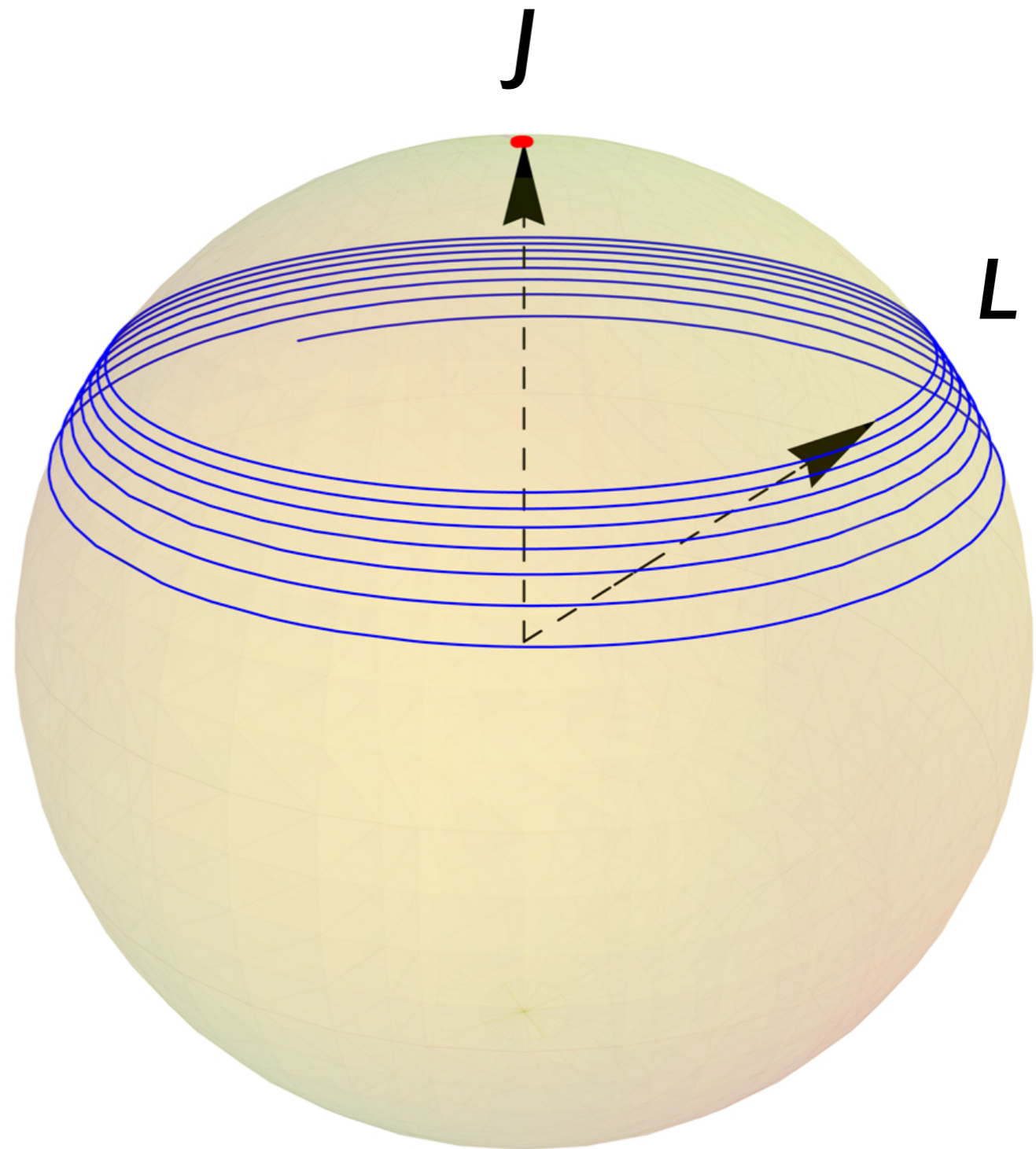


Large separation



Merger

Example:
 $q=3$, $|\mathbf{S}_2| = 0.75$
(in plane)



Orientation dependence

$q=3$, $|S_2| = 0.75$ (in plane)



Observer aligned
with J

Orientation dependence

$q=3, |S_2| = 0.75$ (in plane)



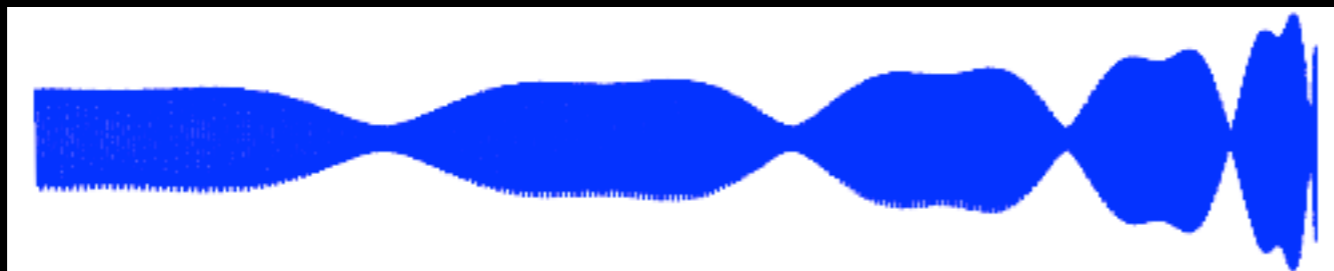
Observer aligned
with J



Observer inclined
 $\pi/6$ to J



Observer inclined
 $\pi/3$ to J

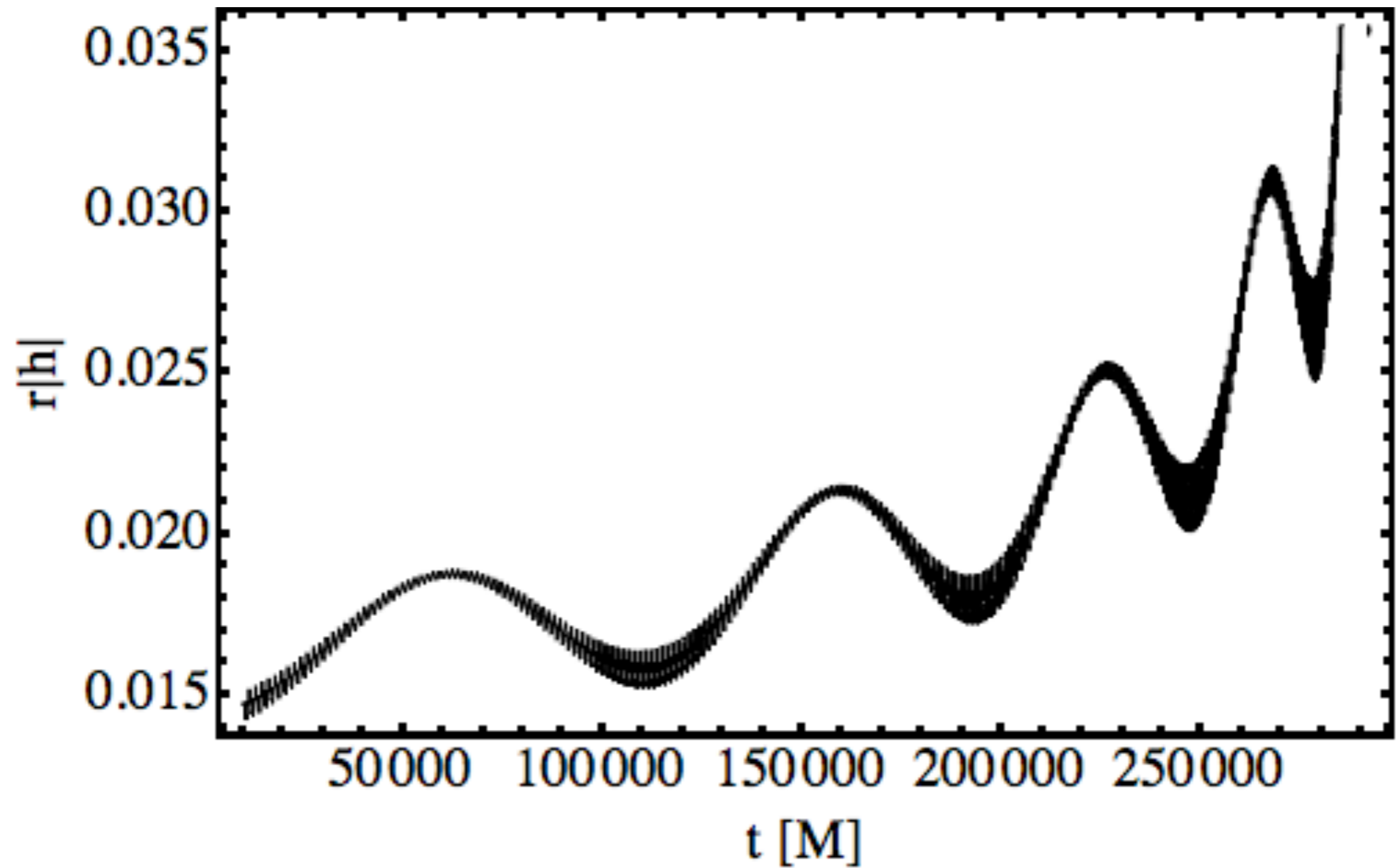


Observer inclined
 $\pi/2$ to J

Aside: modelling precession

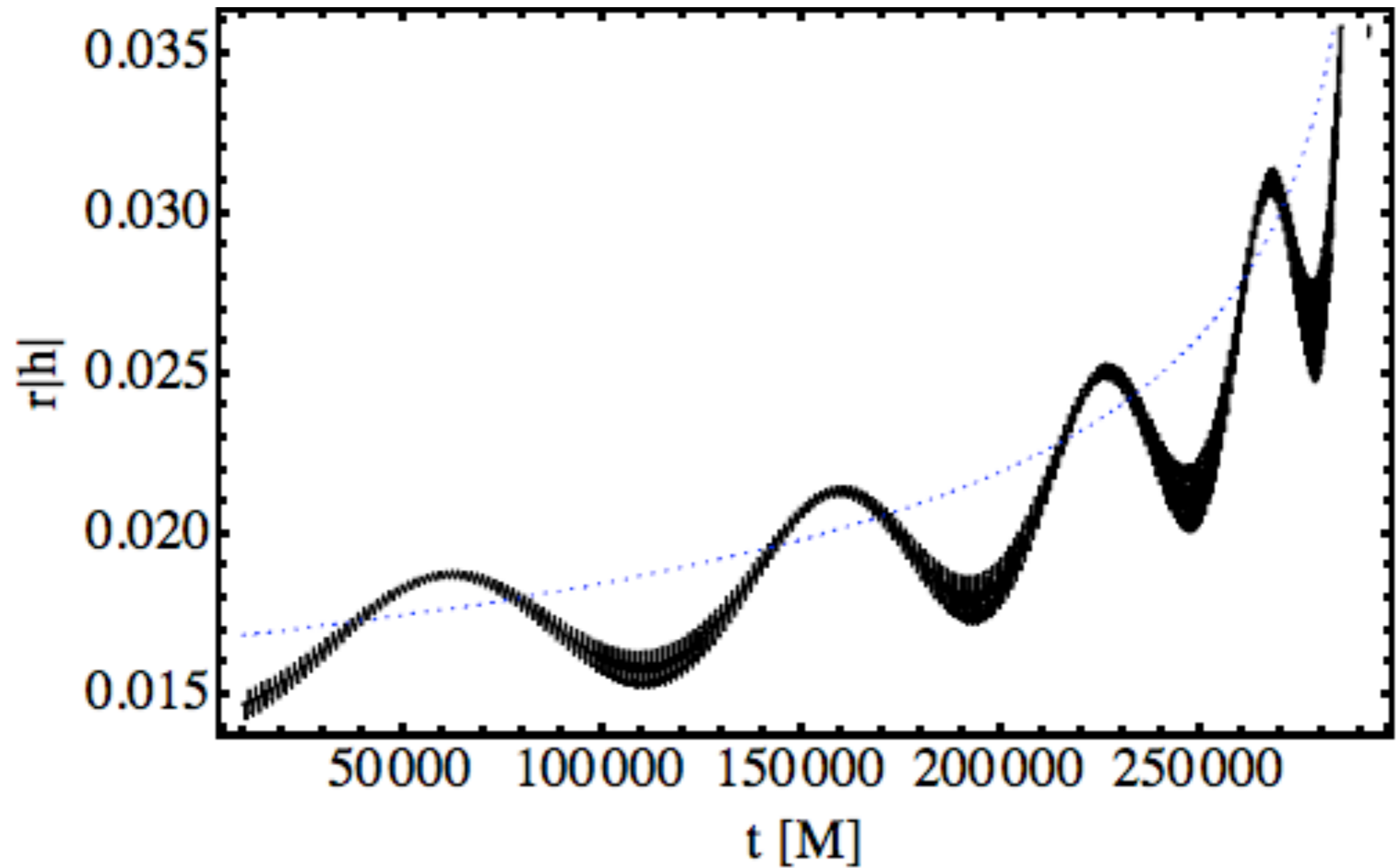
Precessing waveform =
(non-precessing waveform)
x (time dependent rotation)

(Inclination 2.8 rad)



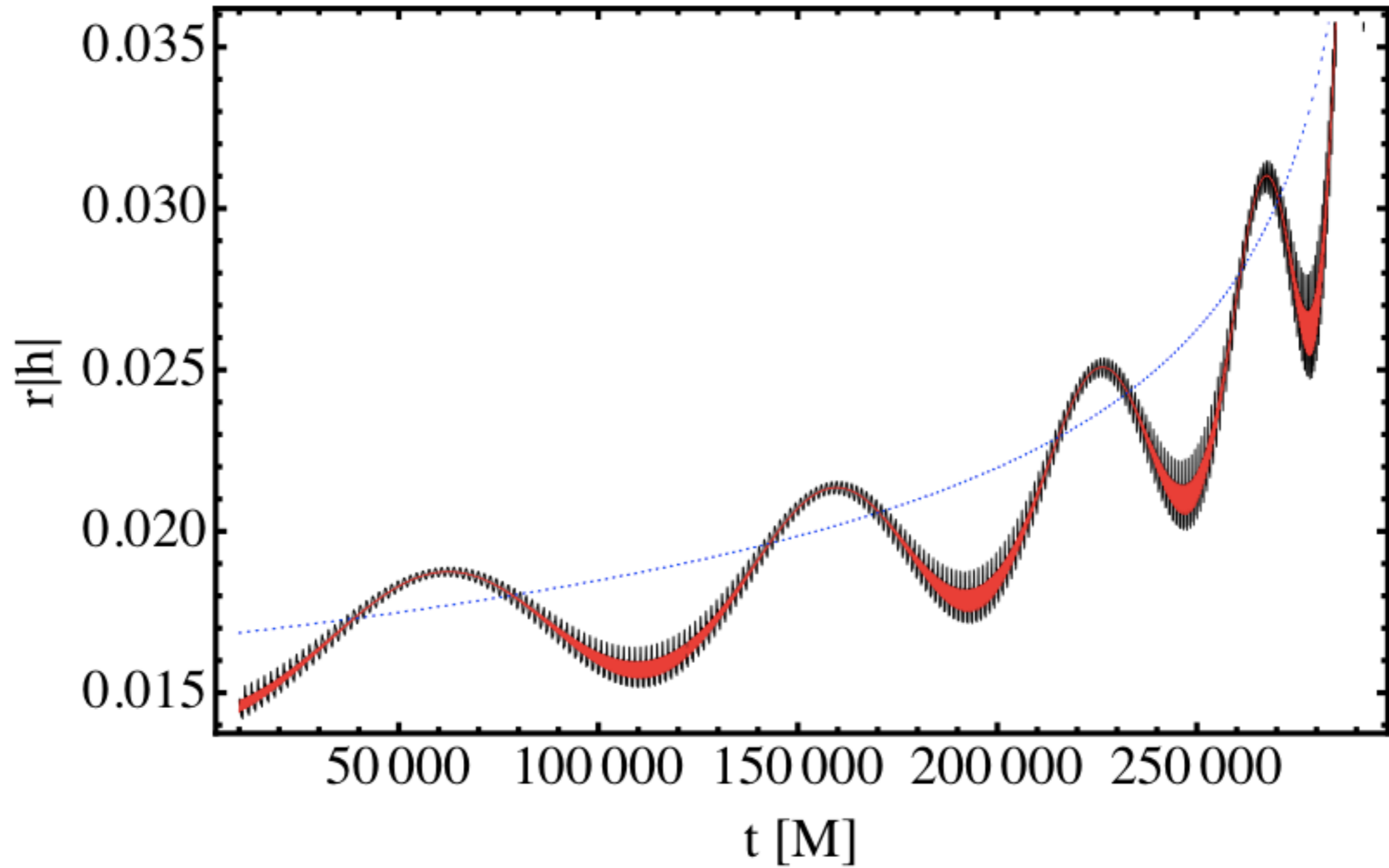
[Schmidt, Hannam, Husa (2012)]

(Inclination 2.8 rad)



[Schmidt, Hannam, Husa (2012)]

(Inclination 2.8 rad)



[Schmidt, Hannam, Husa (2012)]

Aside: modelling precession

Precessing waveform =
(non-precessing waveform)
x (time dependent rotation)

Accurate non-precessing models are crucial

(See next talk by Sascha Husa)

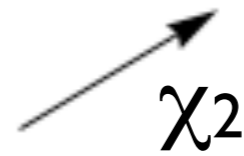
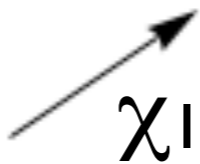
For non-precessing binaries we
used only *one* spin parameter

Can we use the same trick for precession?
i.e., replace
the four in-plane spin components
with *one* “precession spin”?

A precession parameter

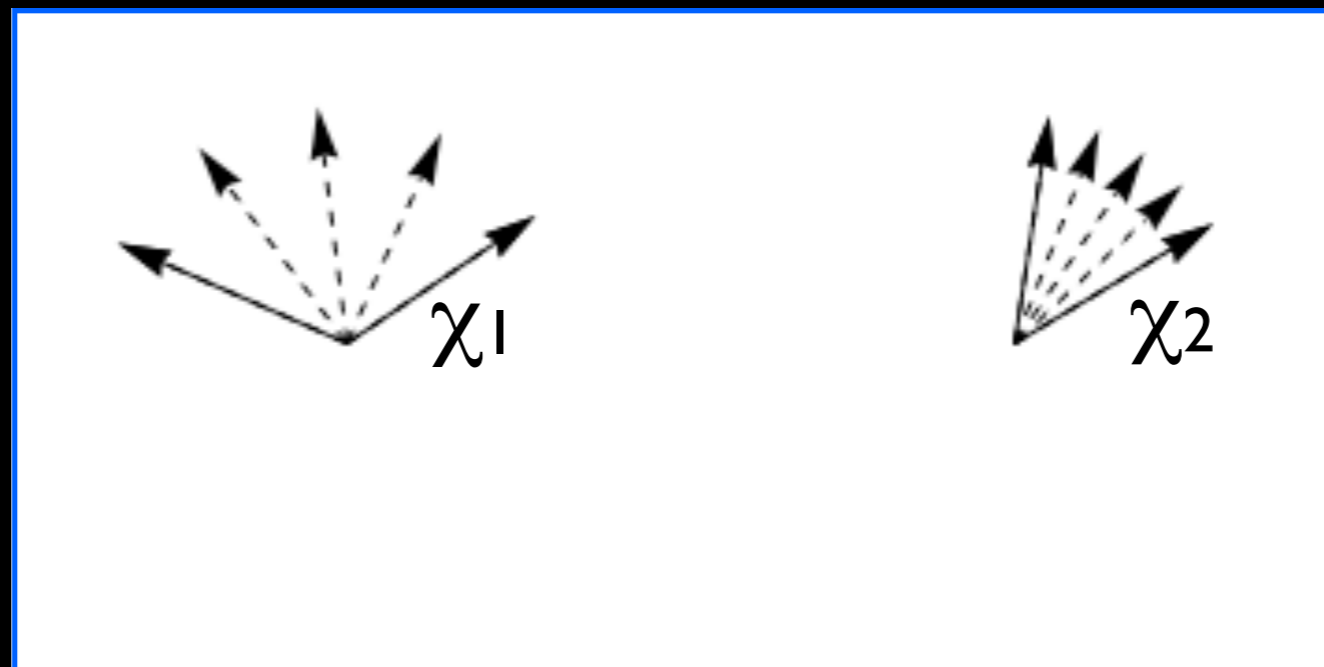
- Consider one spinning BH
- spin rotates in the plane during evolution
- Precession effects dominated by in-plane spin *magnitude*!

Double spins?



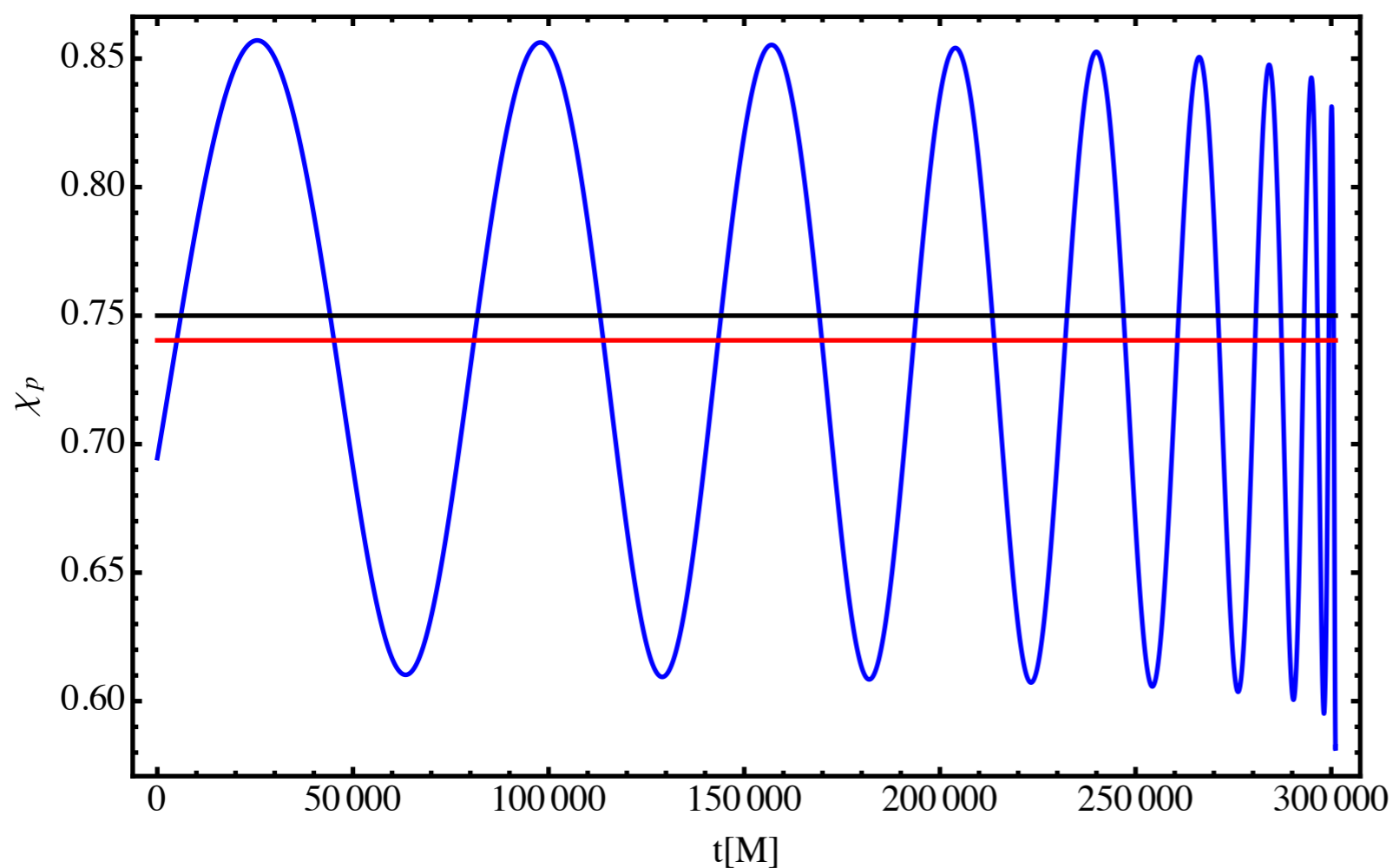
Double spins?

- Spins rotate at different rates
- Consider only the average spin in the plane, “ χ_p ”!



Double spins?

- Spins rotate at different rates
- Consider only the average spin in the plane, “ χ_p ”!



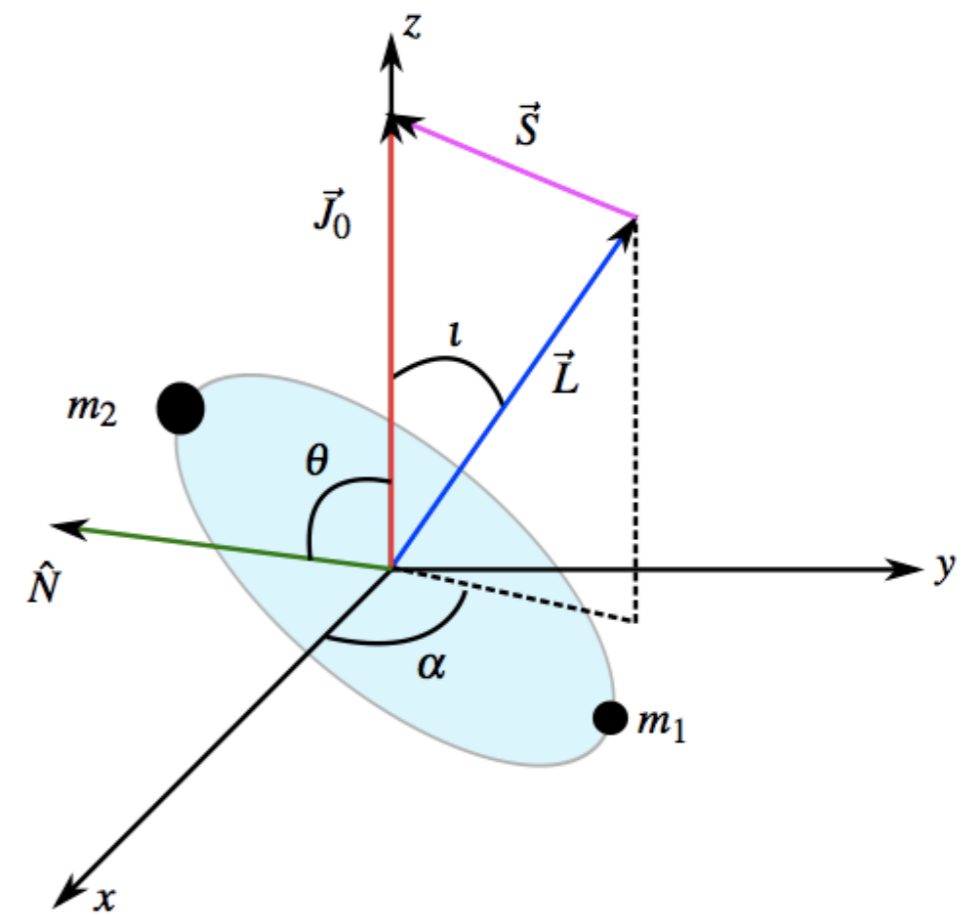
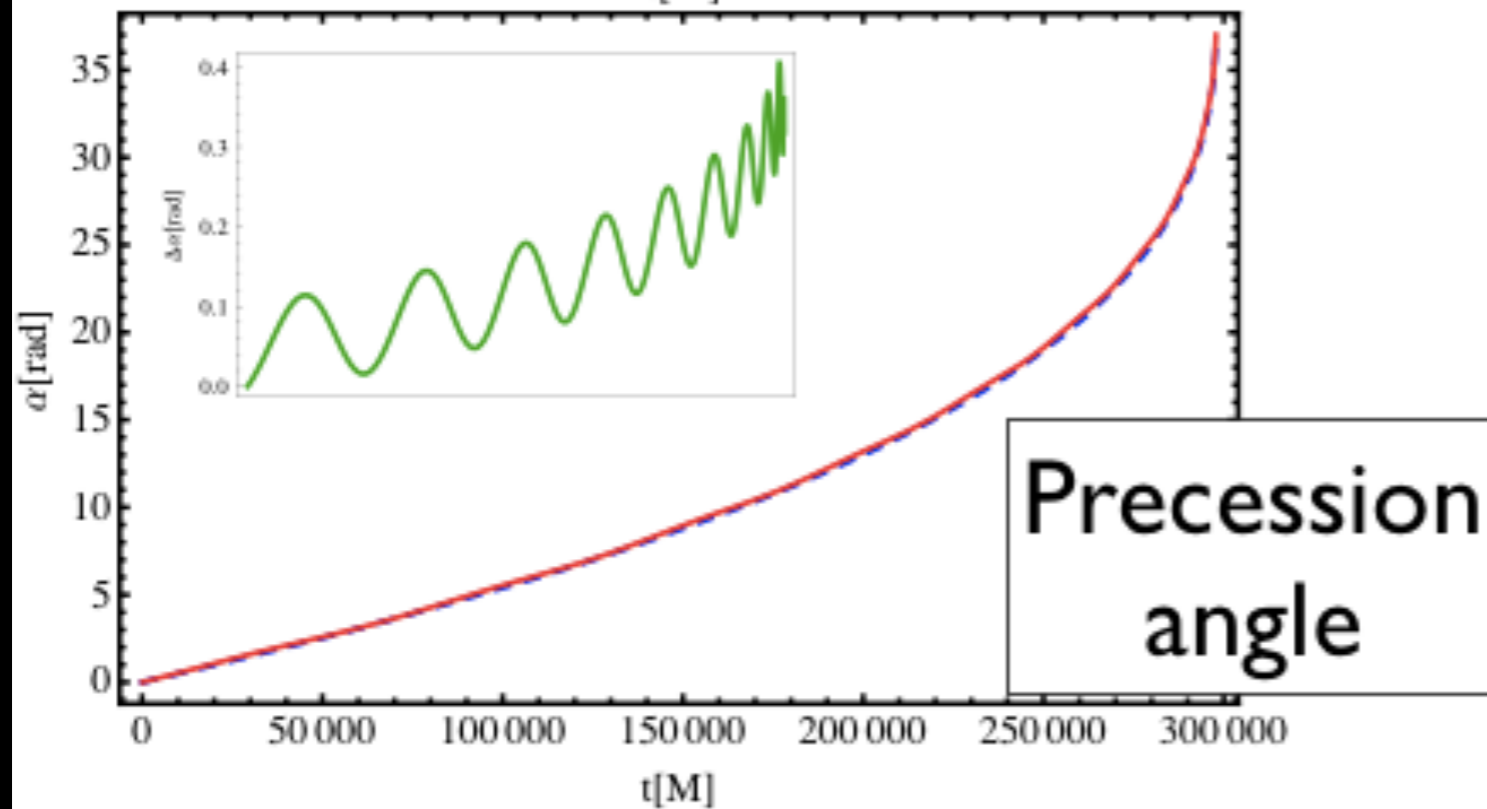
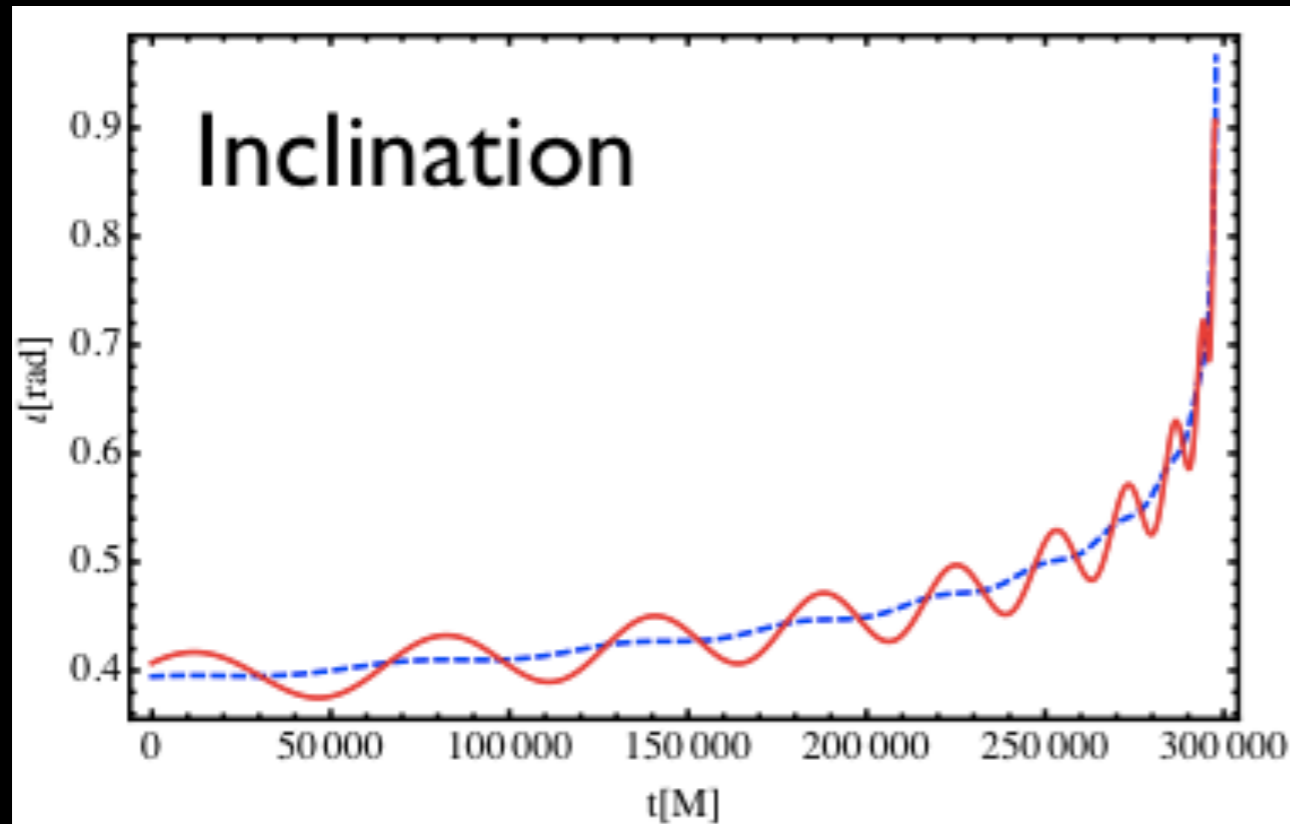
$$q=3,$$

$$\chi_1 = (-0.2, -0.4, 0.3)$$

$$\chi_2 = (0.747, 0.045, 0.1)$$

$$\chi_p = 0.75$$

Compare precession angles



[Schmidt, Ohme, Hannam (2015)]

Summary

- Non-precessing-binary inspiral dominated by mass ratio and “effective spin”, χ .
- Precession (approximately) decouples from non-precessing effects.
- Precession effects parametrized also by “effective precession spin”, χ_p .
- Current inspiral-merger-ringdown waveforms exploit these degeneracies and simplifications.
- How well do these work through merger? Stay tuned...