

Software developments and analysis in the ATLAS group

- Starting October 2021 G. Stavropoulos is appointed ATLAS muon software coordinator.
- **Goal:** Design, develop and maintain the ATLAS muon offline software all the way from DAQ byte-stream reading to muon reconstruction and identification.
- Muon software domain:
 - Data Access: Byte-stream Conversion - Cabling
 - Detector Description
 - **Task :** Development of an XML-based description of the ATLAS Muon Detector. Develop the necessary C++/OO and Python software to prepare the data for track reconstruction and muon identification.
 - Modelling of the Detector Response (Simulation, Digitization, "Local" Reconstruction)
 - **Task :** Muon detector digitization development in the new ATLAS Run-4 software framework.
 - Track Reconstruction and Muon Identification
 - **Task : Develop track reconstruction algorithms in the new ATLAS Run-4 software framework.**
 - Conditions Database and Detector Control system
 - Detector Specific calibration procedures
 - Trigger
 - Offline Data Quality
 - Validation

- The precise reconstruction of the **trajectories of muons** created in proton-proton (pp) collisions is a key ingredient in many of the physics processes.
- In order to reconstruct muon trajectories, ATLAS uses **energy deposits** from charged particles (hits) recorded in individual detector elements of the New Small Wheel (NSW) and applies **clustering algorithms** to them.
- The purpose of the clustering algorithms is to **group together** these energy deposits. Based on those groups of hits called **clusters** in a number of the layers of NSW, the associated track parameters can be estimated.
- Therefore, the performance in the reconstruction of these clusters heavily affects with the associated tracks.
- In the context of this task, we work with Micromegas clusters, which are a collection of strips (sensitive element of the Micromegas detector).

- Muons with high transverse momentum undergo radiative energy losses.
- These may produce hits near the muon track and 'spoil' the shape of the cluster in the NSW.
- **Goal:** In order to accurately find the hit positions of the muon track along the detector layers, we would like to **identify** these problematic clusters.
- We refer to:
 - **Signal:** Clusters with simulated hits from muons.
 - **Background:** Clusters with simulated hits from electrons, photons apart from muons.
- This is a classification task with a binary (two level) qualitative response ($Y=1$ for signal, $Y=0$ for background).
- Someone can explore a number of methods like **Boosted decision trees, Random Forests, Support Vector Machines** etc.

- Our group is taking part in the precision measurement of the Z boson mass and specifically in the muon momentum calibration part.
- Last measurement from Large Electron–Positron Collider (LEP):
 $91.187,6 \pm 2,1(\text{MeV})$.
Given this precisely measured value of the Z boson mass and the clean leptonic final state of Z decaying into 2 leptons, these $Z \rightarrow \ell\ell$ processes provide the primary constraints for detector calibration, physics modeling as well as validation of an analysis strategy.
- Why? Prerequisite for a very precise measurement of the:
 - Higgs mass and width. Certain studies shows that the mass of the Higgs boson can be measured with a precision of 10-20 MeV.
 - W mass
 - and a self consistency check of the Standard Model.
- LHC can move from the 17 million Z bosons produced at LEP to 100 million Z leptonic decays at the end of Run3.