

Machine learning for data taking, monitoring, and processing

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What we do with ML today

- Classification:

- identify a particle & reject fakes

- identify signal events & reject background

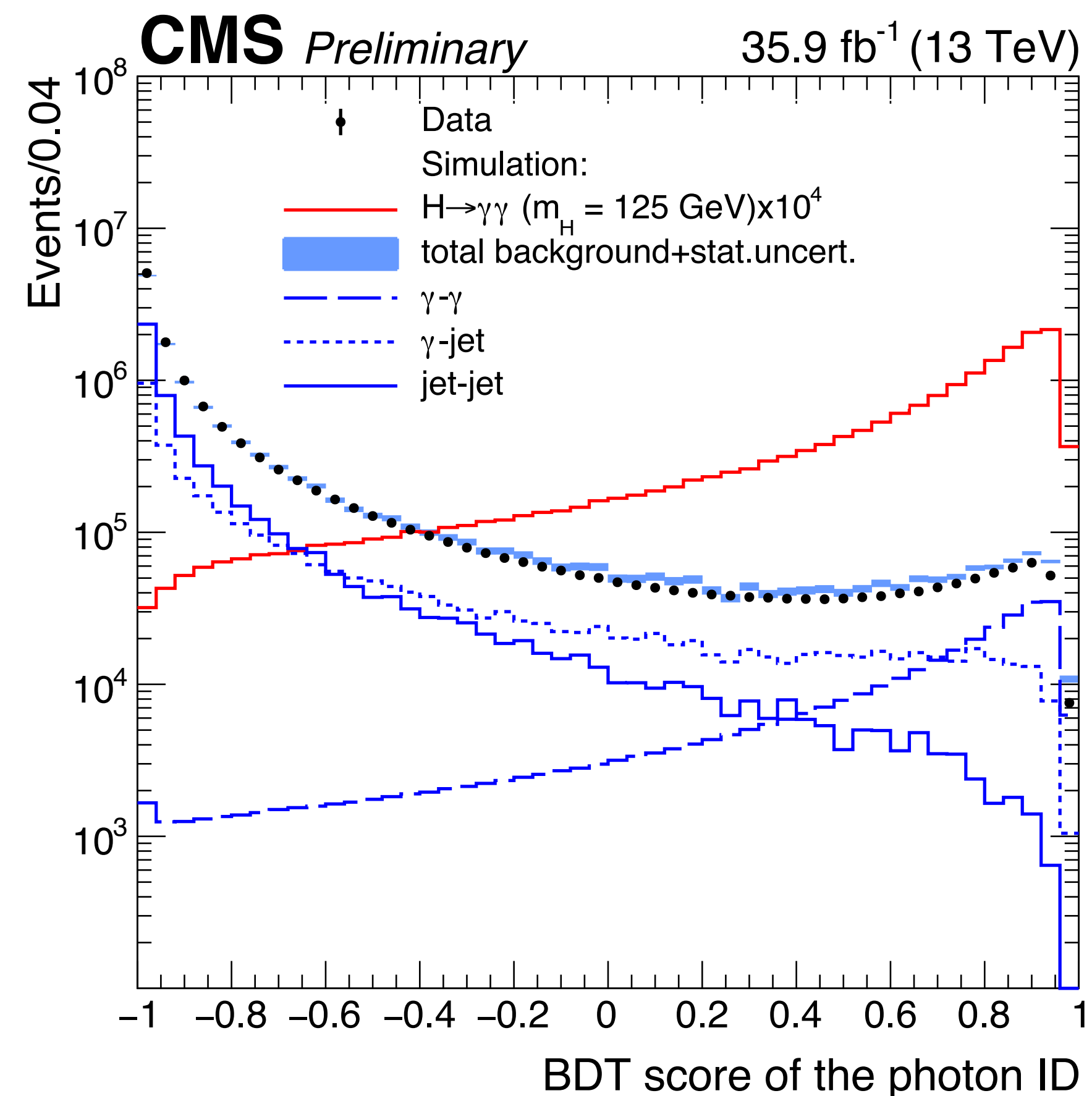
- Regression:

- Measure energy of a particle

- We typically use BDTs for these task

- moved to Deep Learning for analysis-specific tasks

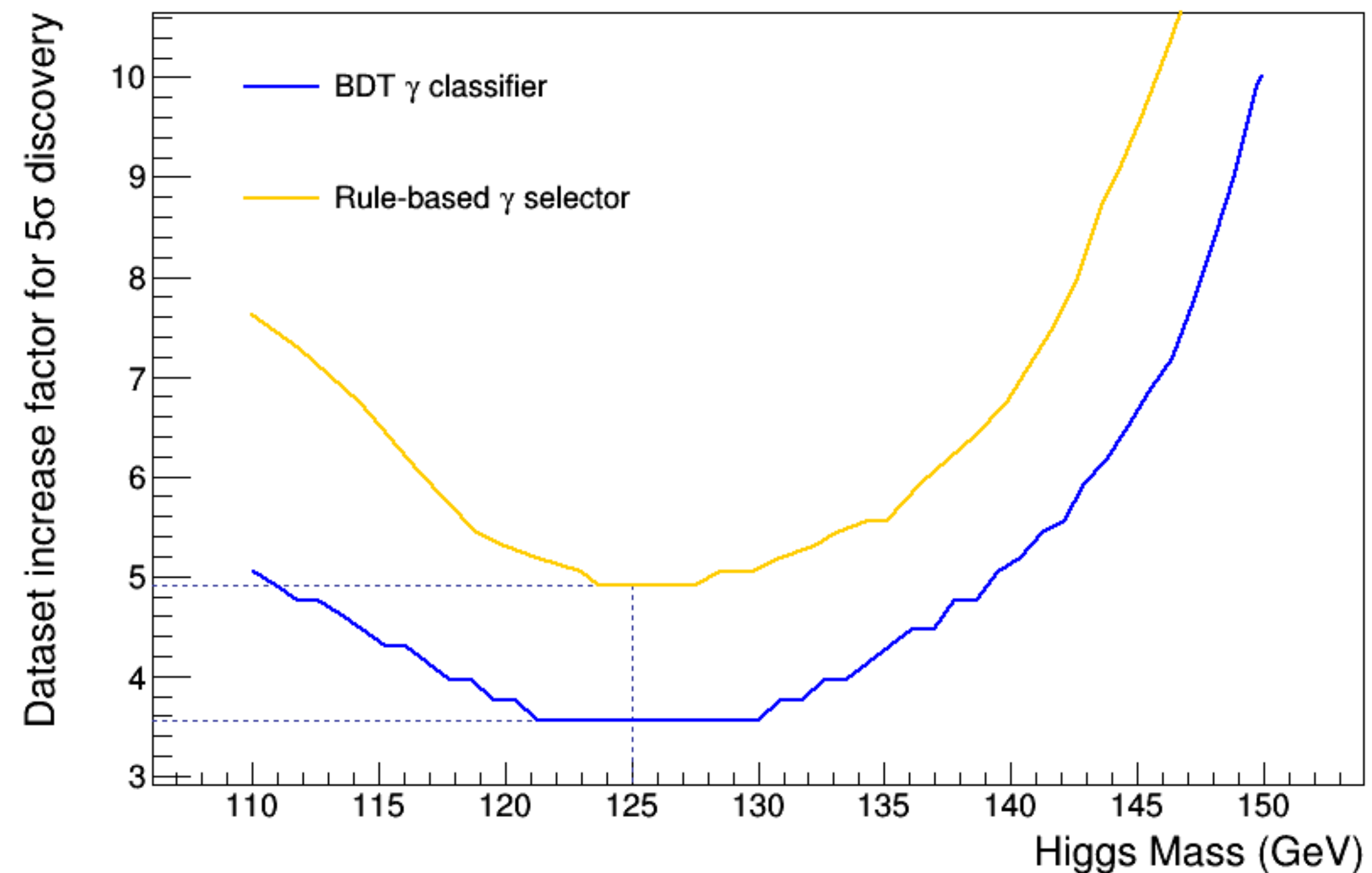
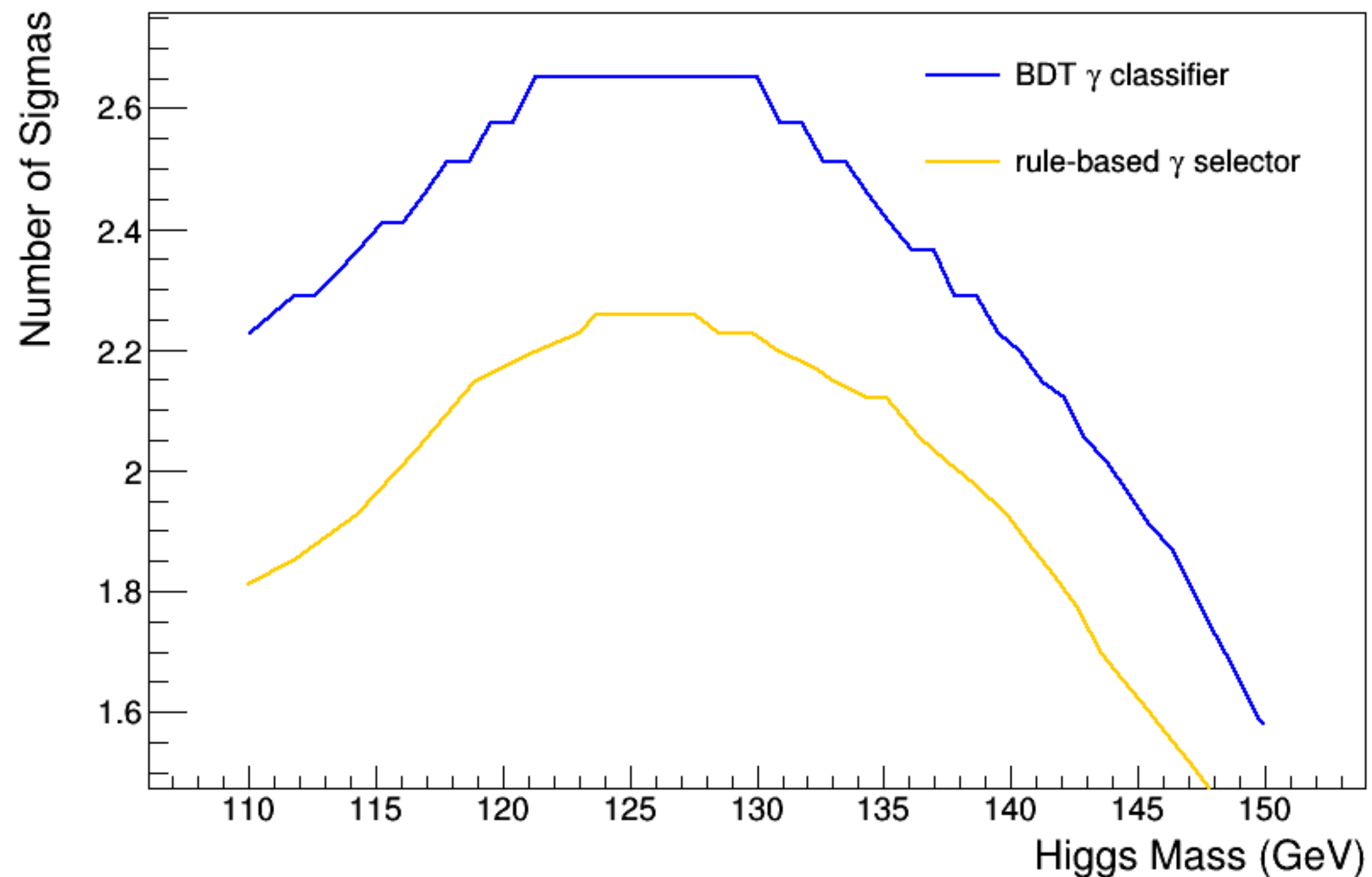
- same will happen for centralised tasks (eventually)



Centralised task (in online or offline reconstruction)
 Analysis-specific task (by users on local computing infrastructures)

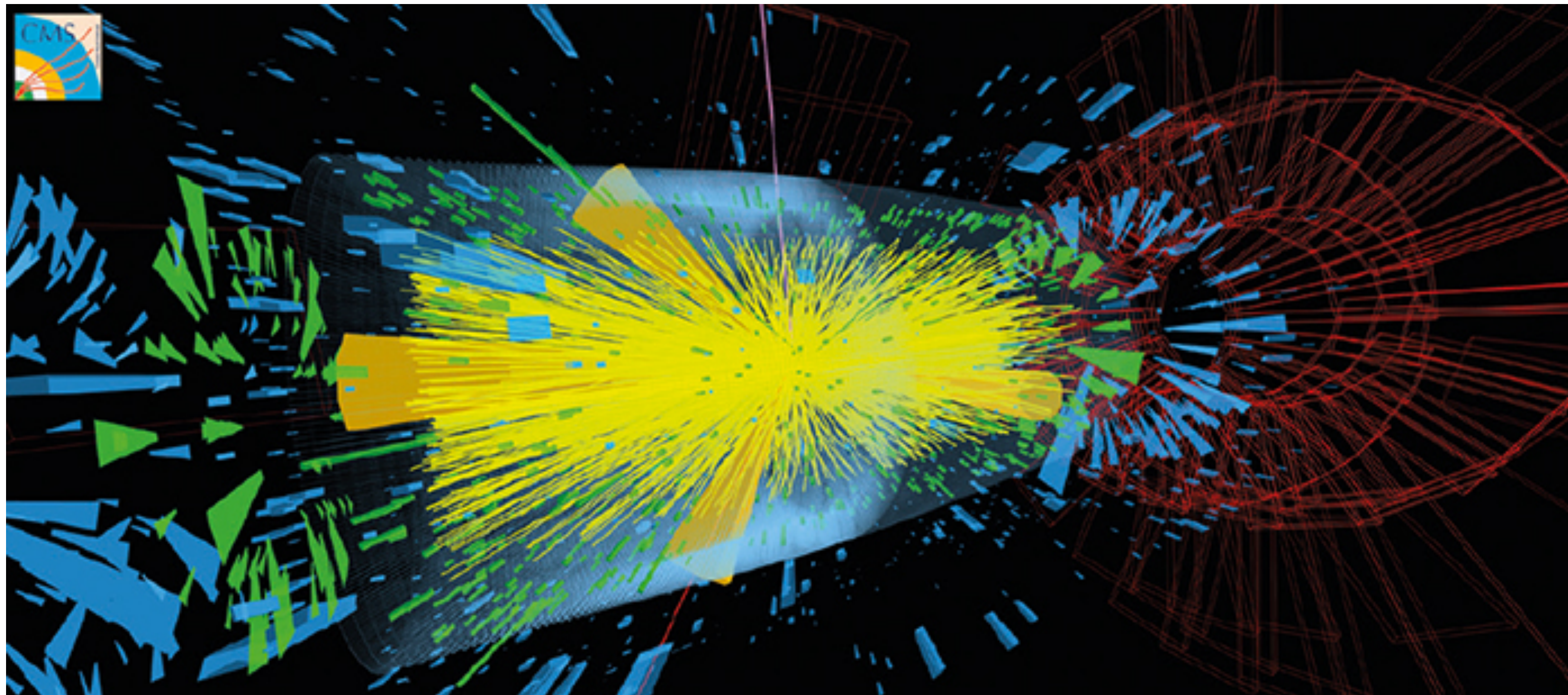
Example: ML for Higgs discovery

- ◉ *We were not supposed to discover the Higgs boson as early as 2012*
- ◉ *Given how the machine progressed, we expected discovery by end 2015 /mid 2016*
- ◉ *We made it earlier thanks (also) to Machine Learning*

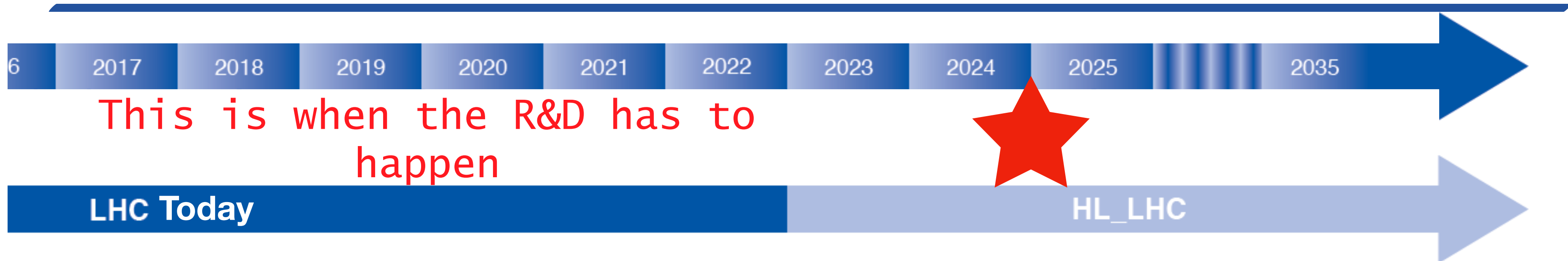


What is ahead of us

- ◎ *Deep Learning will be more and more central*
 - ◎ *Analysis-specific applications poses no problem in terms of latency/memory/etc*
- ◎ *Challenges ahead will force us (willing or not) to use DL in many centralised tasks*
 - ◎ *but we are still far from being ready to a systematic usage of DL in production*



HL-LHC: elephant in the room



This is when the R&D has to happen

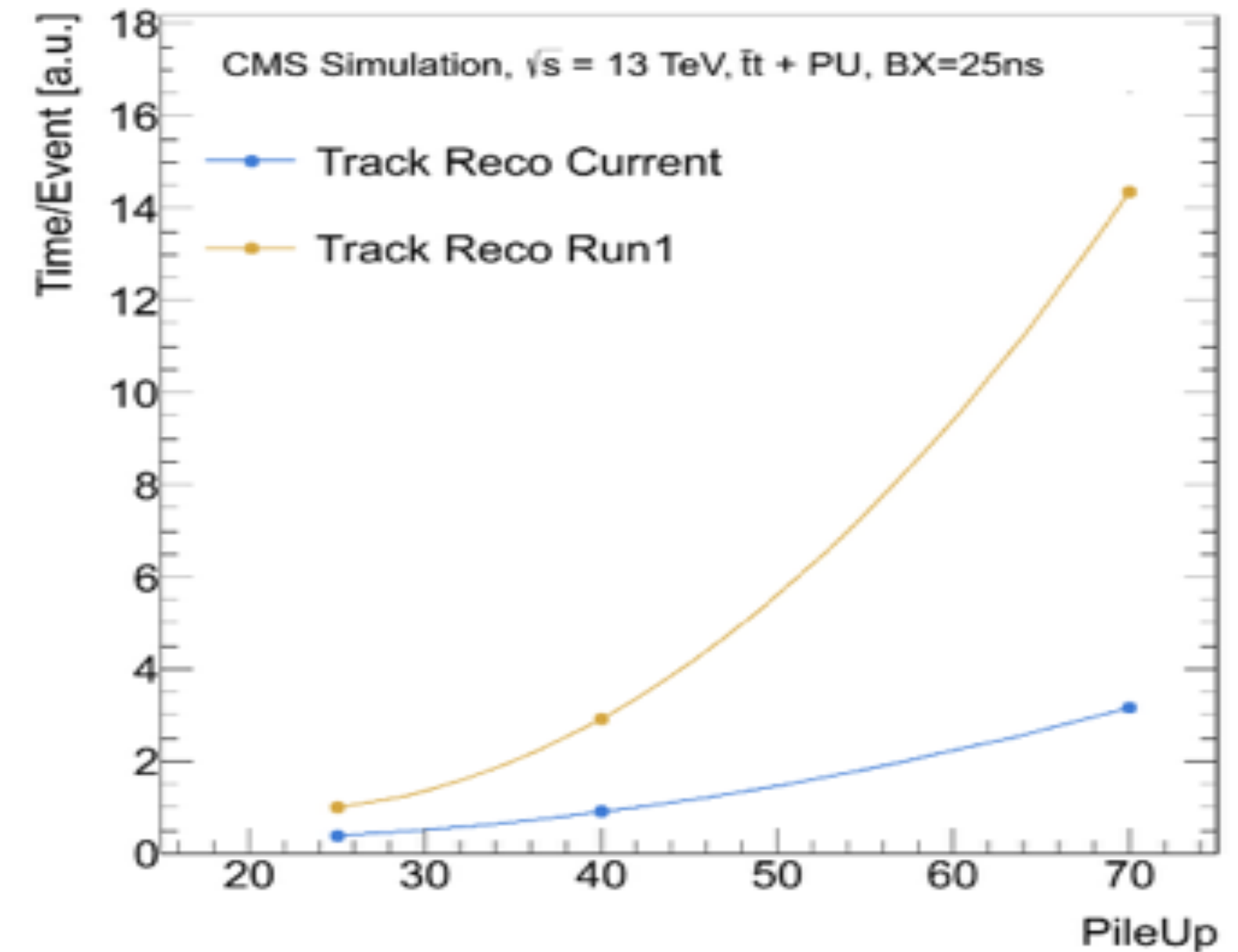
- ▶ ~40 collisions/event
- ▶ ~10 sec/event processing time
- ▶ (at best) Same computing resources as today

- ▶ ~200 collisions/event
- ▶ ~minute/event processing time(*)
- ▶ (at best) Same computing resources as today

◎ Flat budget vs. more needs = current rule-based reconstruction algorithms will not be sustainable

◎ Adopted solution: more granular and complex detectors → more computing resources needed → more problems

◎ **Modern Machine Learning might be the way out**

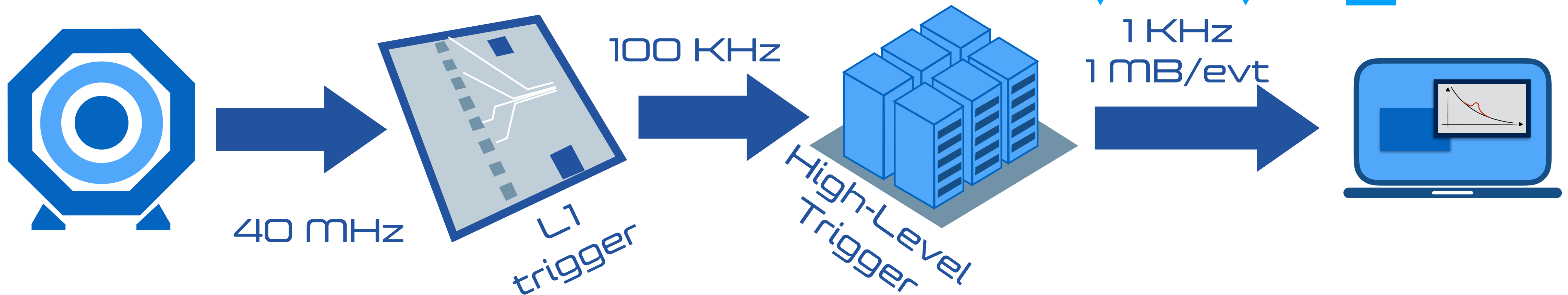
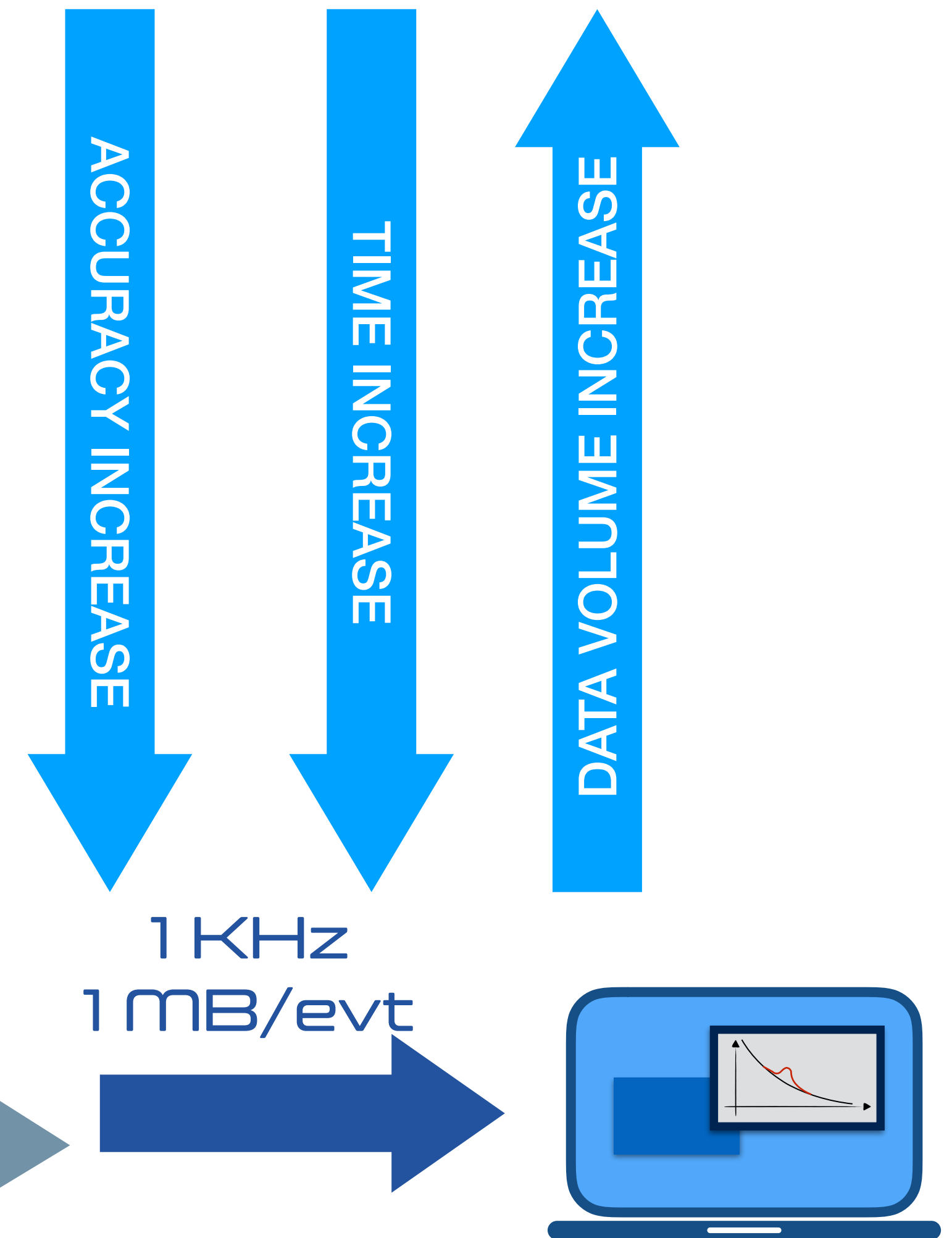


(*)With nowadays software development

Three layers of reconstruction

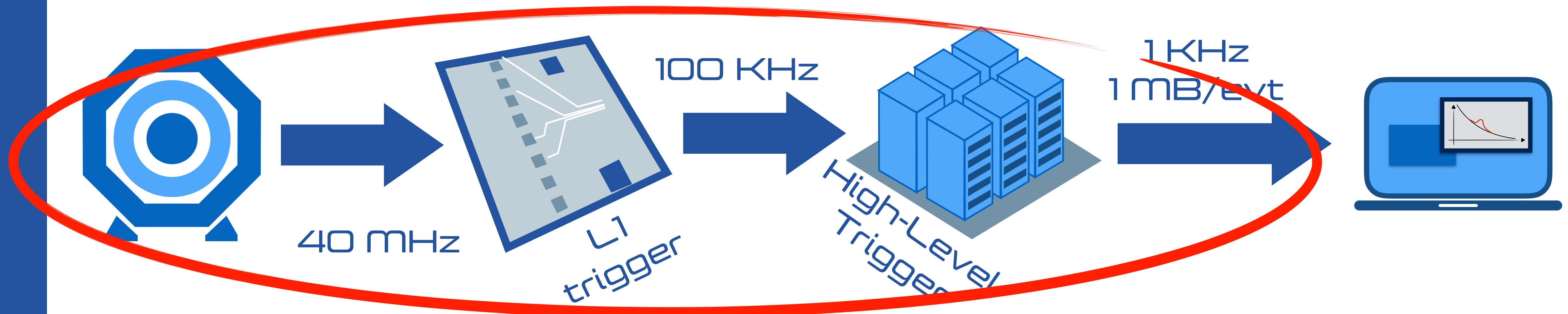
◎ A typical reconstruction chain has 4 steps (*)

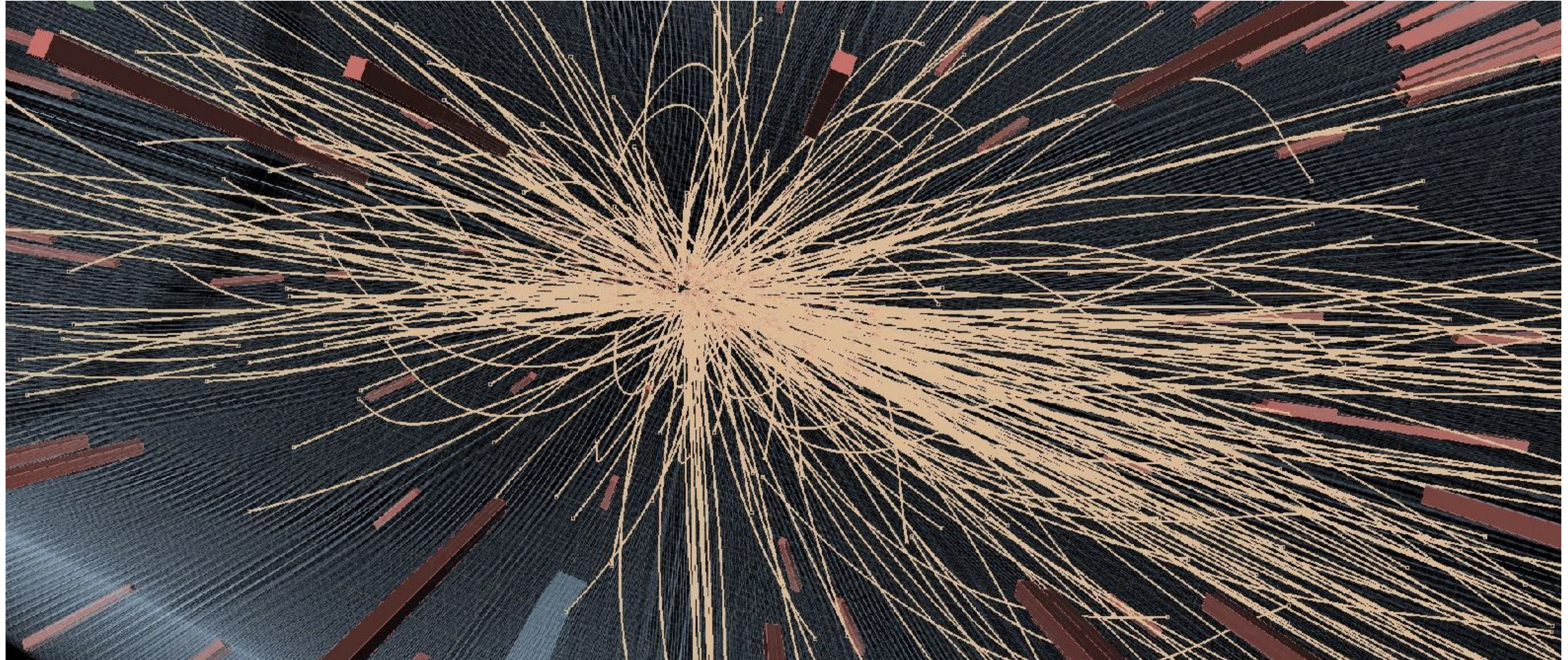
- ▶ L1 trigger: local, hardware based, on FPGA, @experiment site
- ▶ HLT: local/global, software based, on CPU, @experiment site
- ▶ Offline: global, software based, on CPU, @CERN T0
- ▶ Analysis: user-specific applications running on the grid



What DL could do for us

- ◎ *The solution to the HL-LHC problem: modern Machine Learning ...*
 - ▶ ... to be faster
 - ▶ ... to do better
 - ▶ ... to do more
- ◎ *And this is a NEED for what happens **in between data taking and data analysis** (trigger, reconstruction, simulation, ...)*

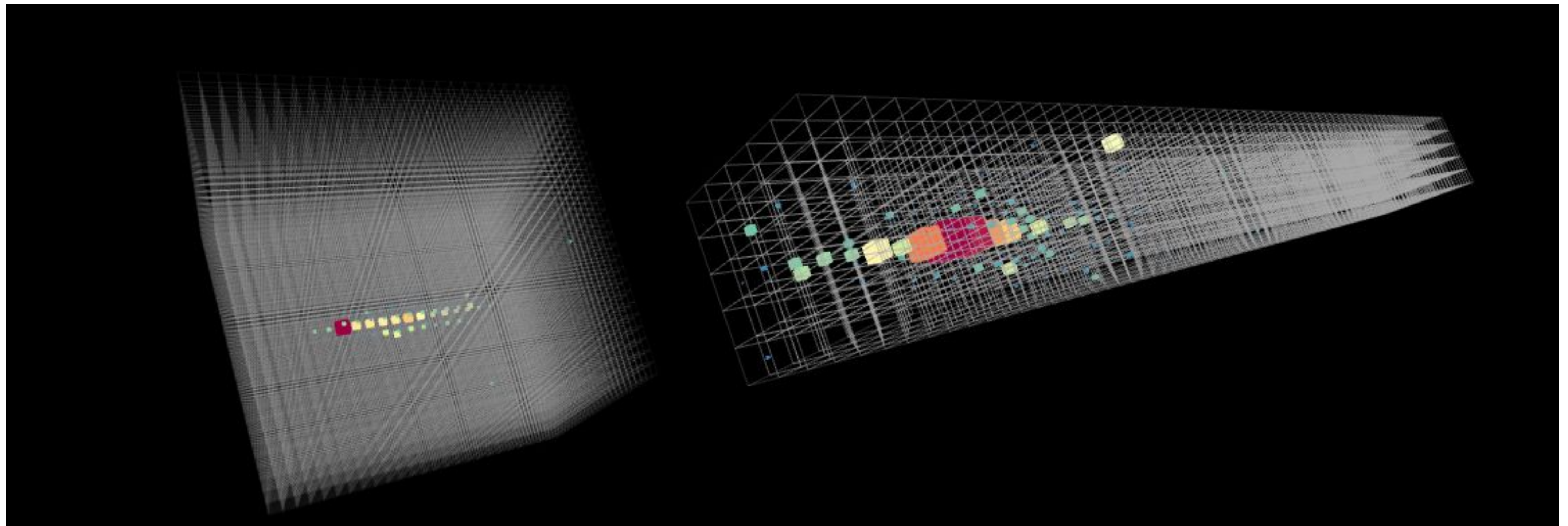




~~Deep~~ Machine Learning for event processing

Particle reconstruction as image detection

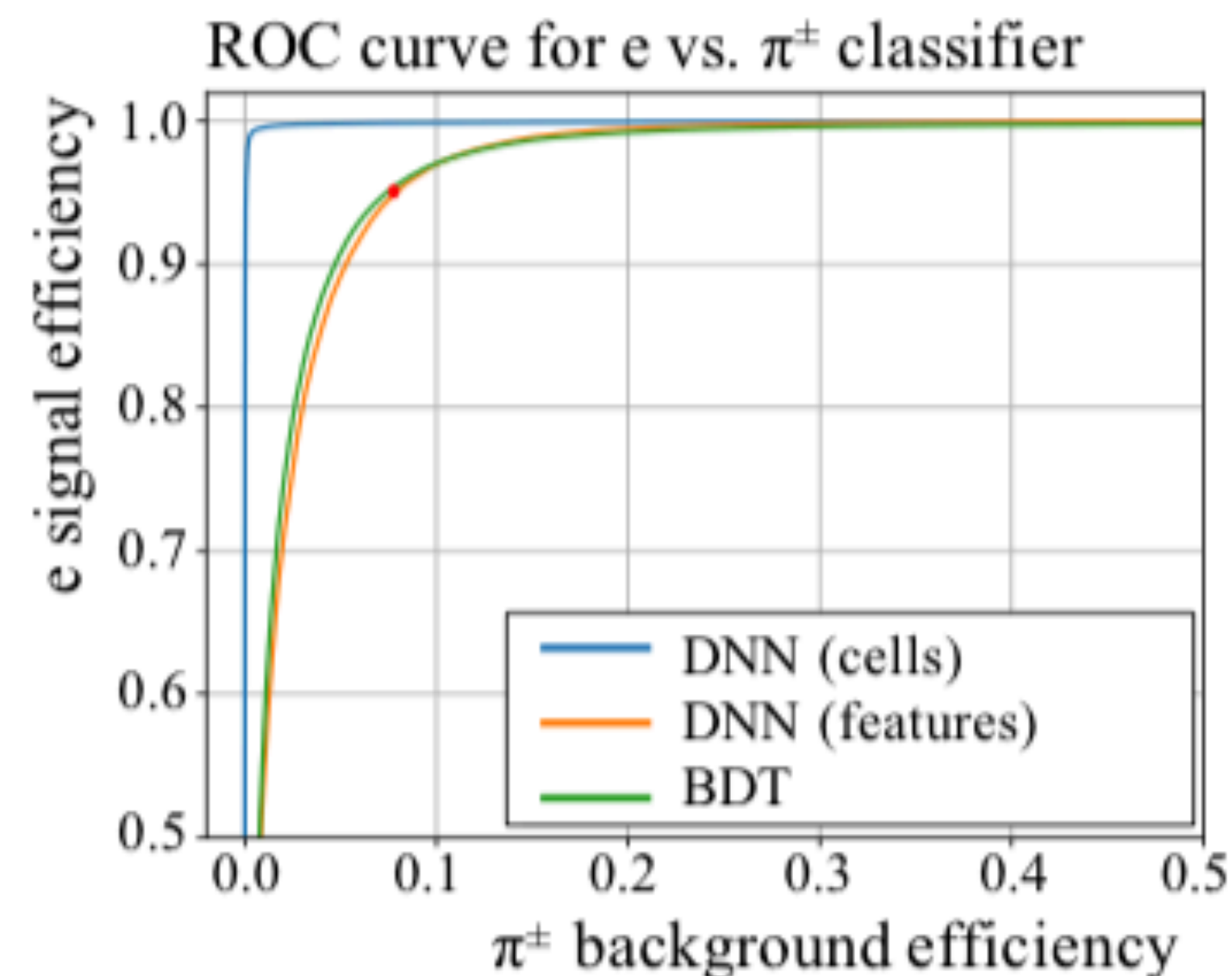
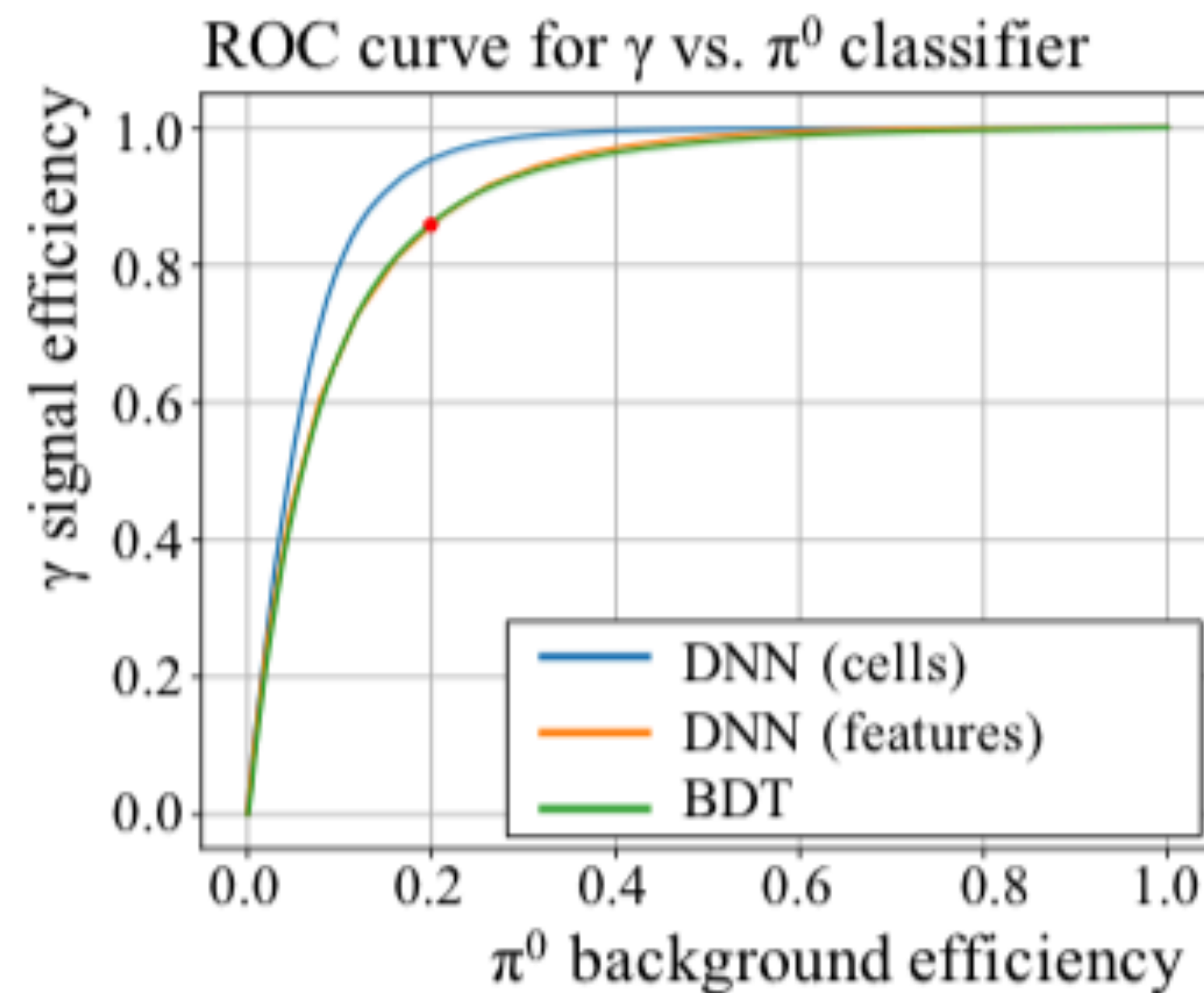
- ◎ *Future detectors will be 3D arrays of sensors with regular geometry*
- ◎ *It would be ideal to quickly reconstruct particles directly from the image (which is what Deep Learning became famous for)*



[See contribution to NIPS workshop](#)

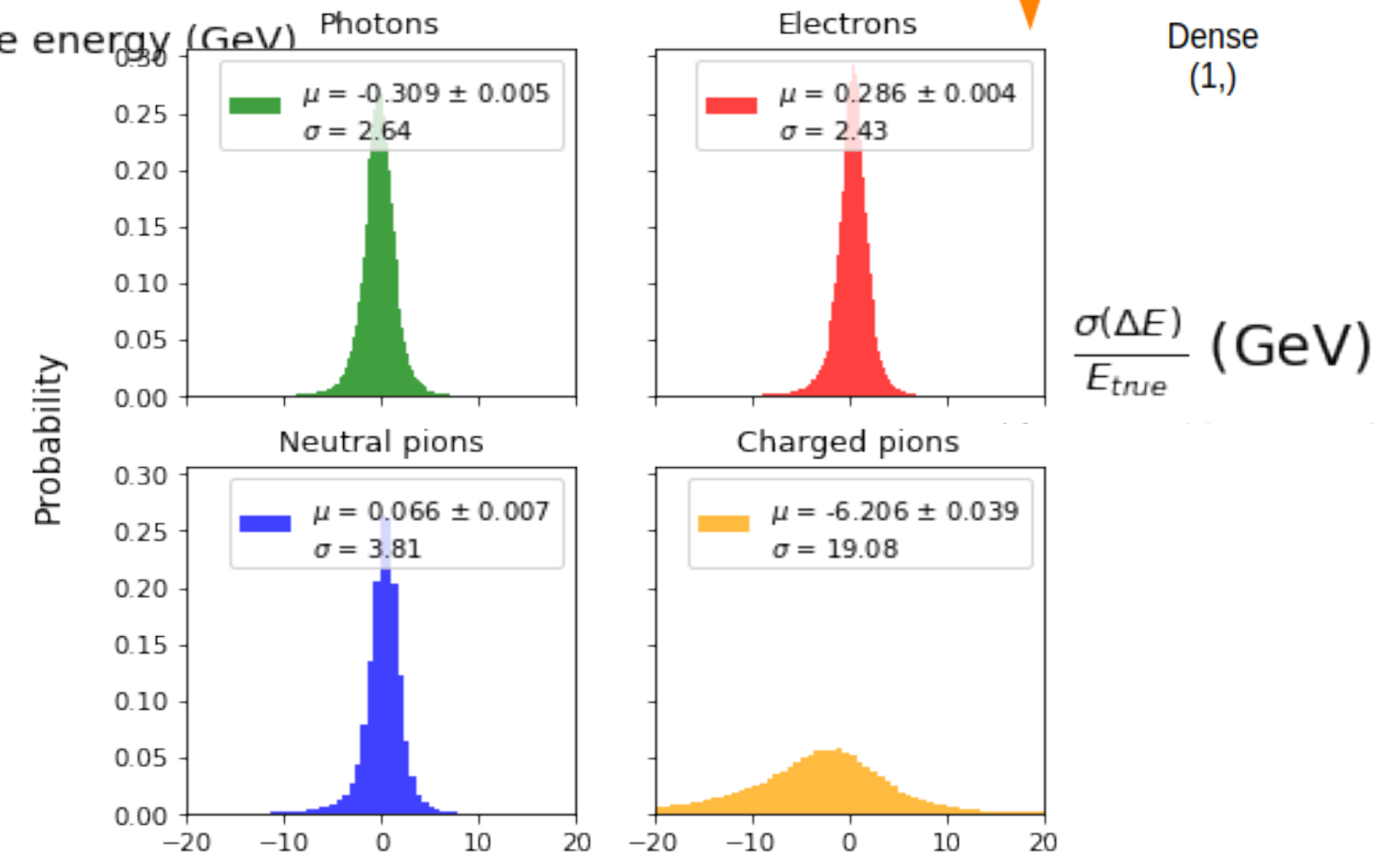
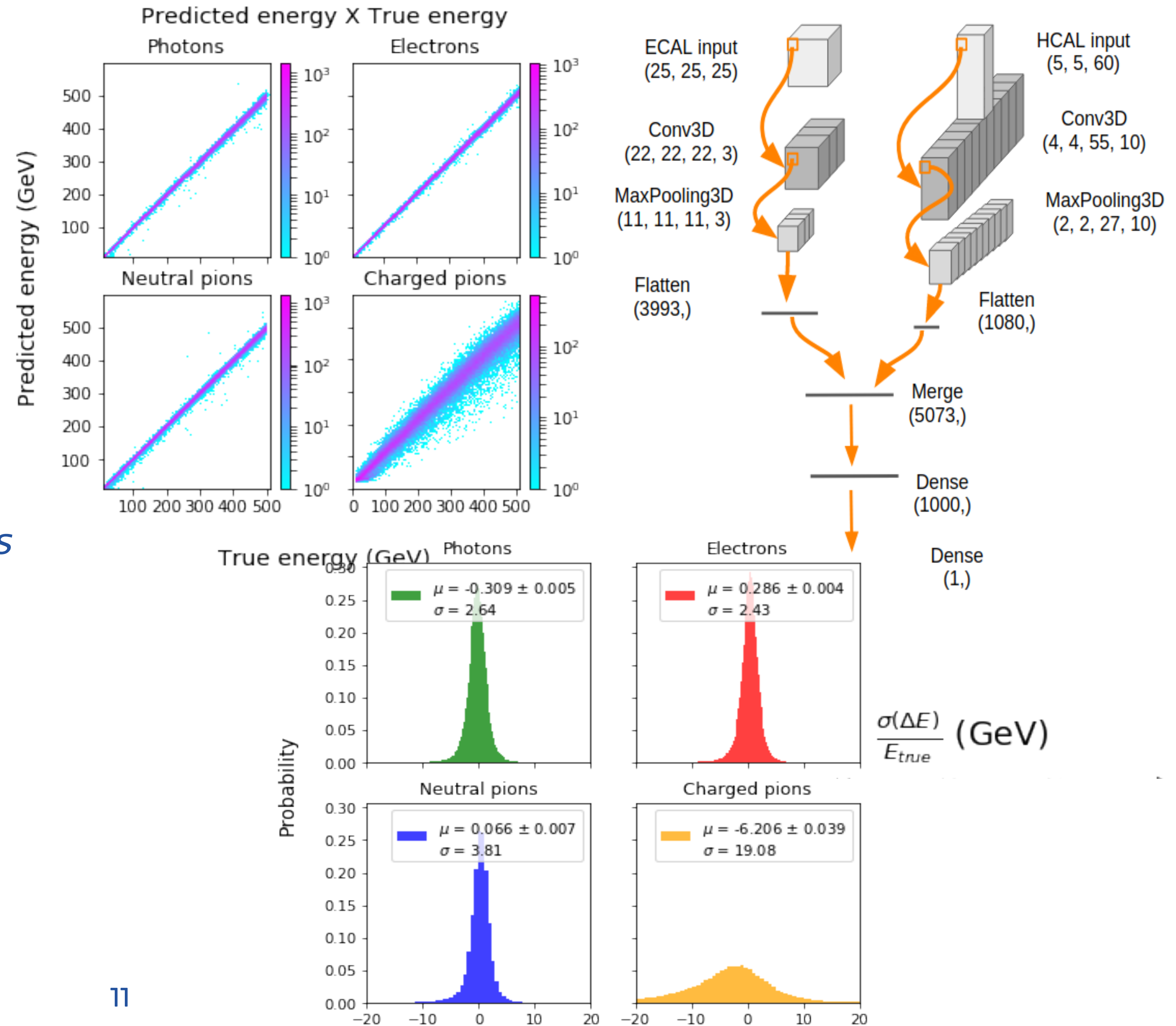
Proof of Principle: Particle ID

- ⊙ *We tried particle ID on a sample of simulated events*
 - ⊙ *one particle/event (e, γ , π^0 , π)*
- ⊙ *Different event representations*
 - ⊙ *high-level features related to event shape (moments of X, Y, and Z projections, etc)*
 - ⊙ *raw data (energy recorded in each cell)*
- ⊙ *Pre-filtered pion events to select the nasty ones and make the problem harder*



Proof of Principle: Energy Regression

- 3D Convolution NN can learn true energy of an incoming particle from the recorded hit pattern
 - Correctly reconstruct energy
 - ECAL performances better than HCAL (as expected)
 - π^0 resolution $\sim \sqrt{2}$ γ resolution (as expected)
- No high-level knowledge of physics and/or detector features
 - used only RAW data as inputs
- In real life, this could be used offline, at HLT, and (maybe) even at L1

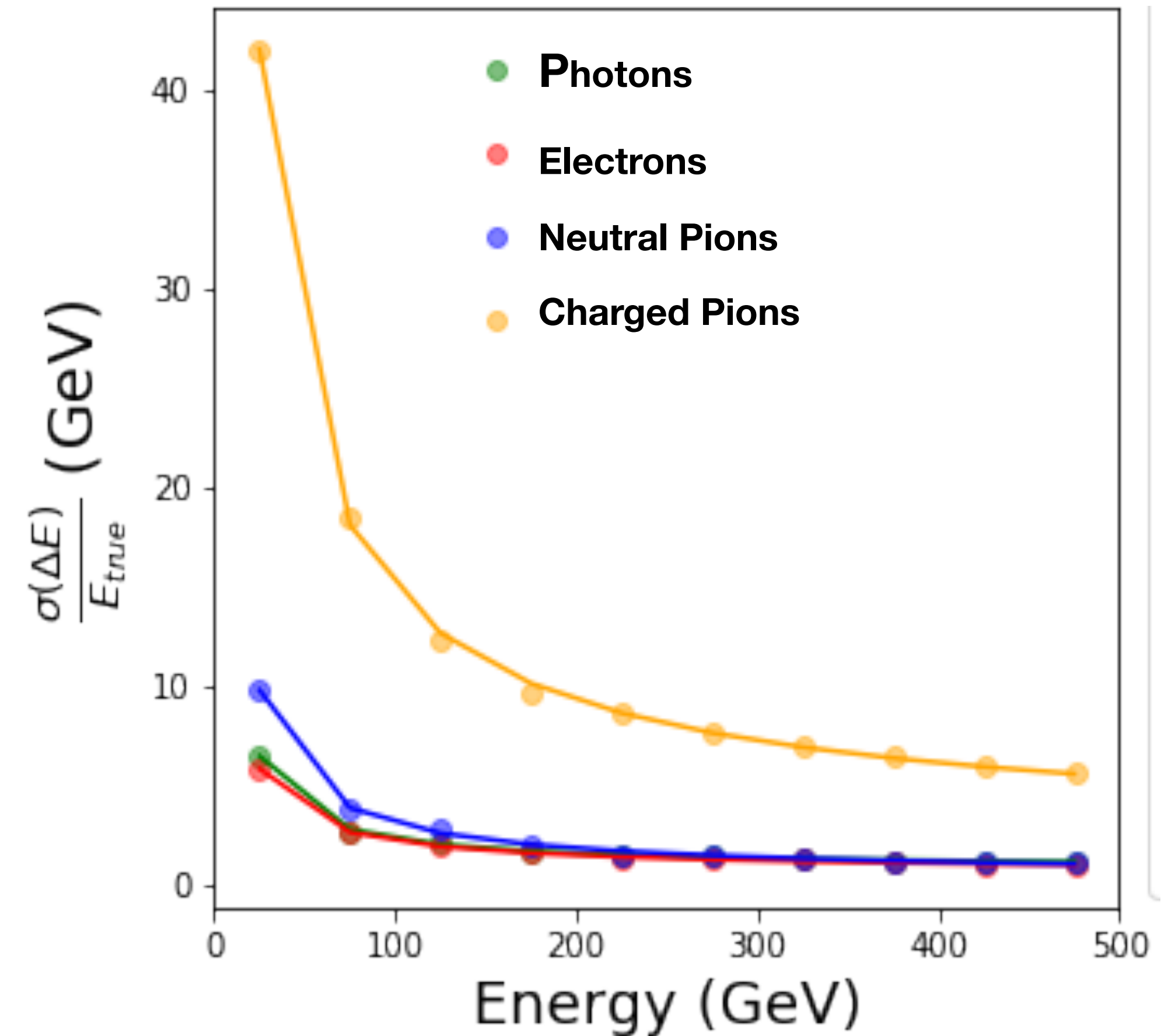


Proof of Principle: Energy Regression

▶ *Competitive and meaningful results*

▶ *Processing time reduced by 10^3 wrt traditional approaches*

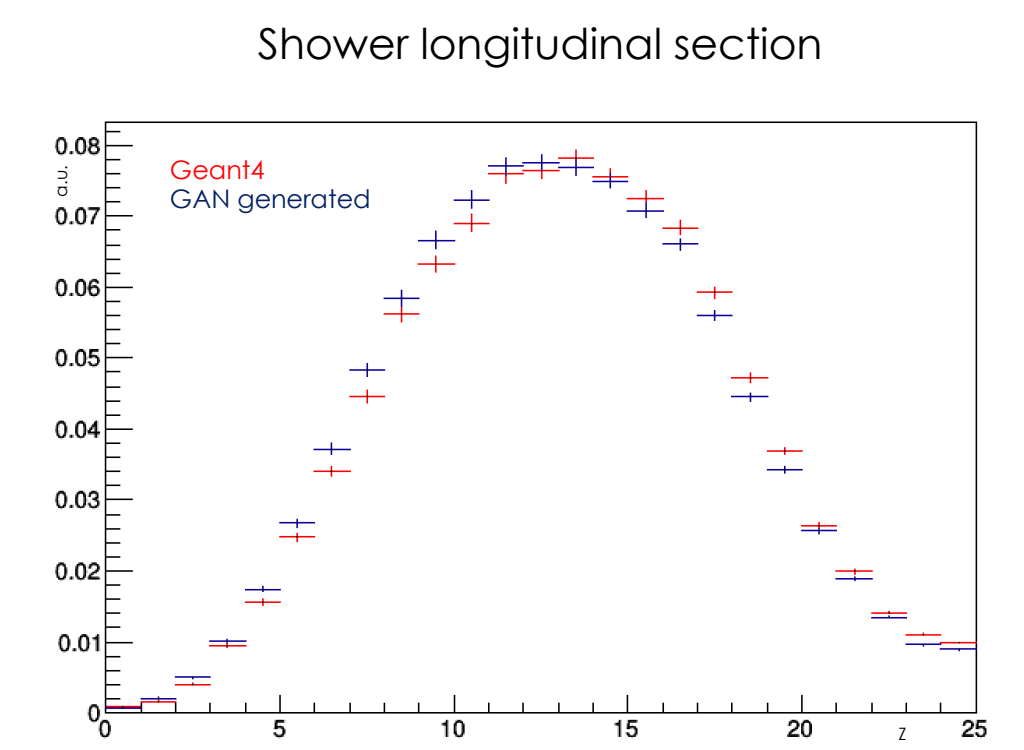
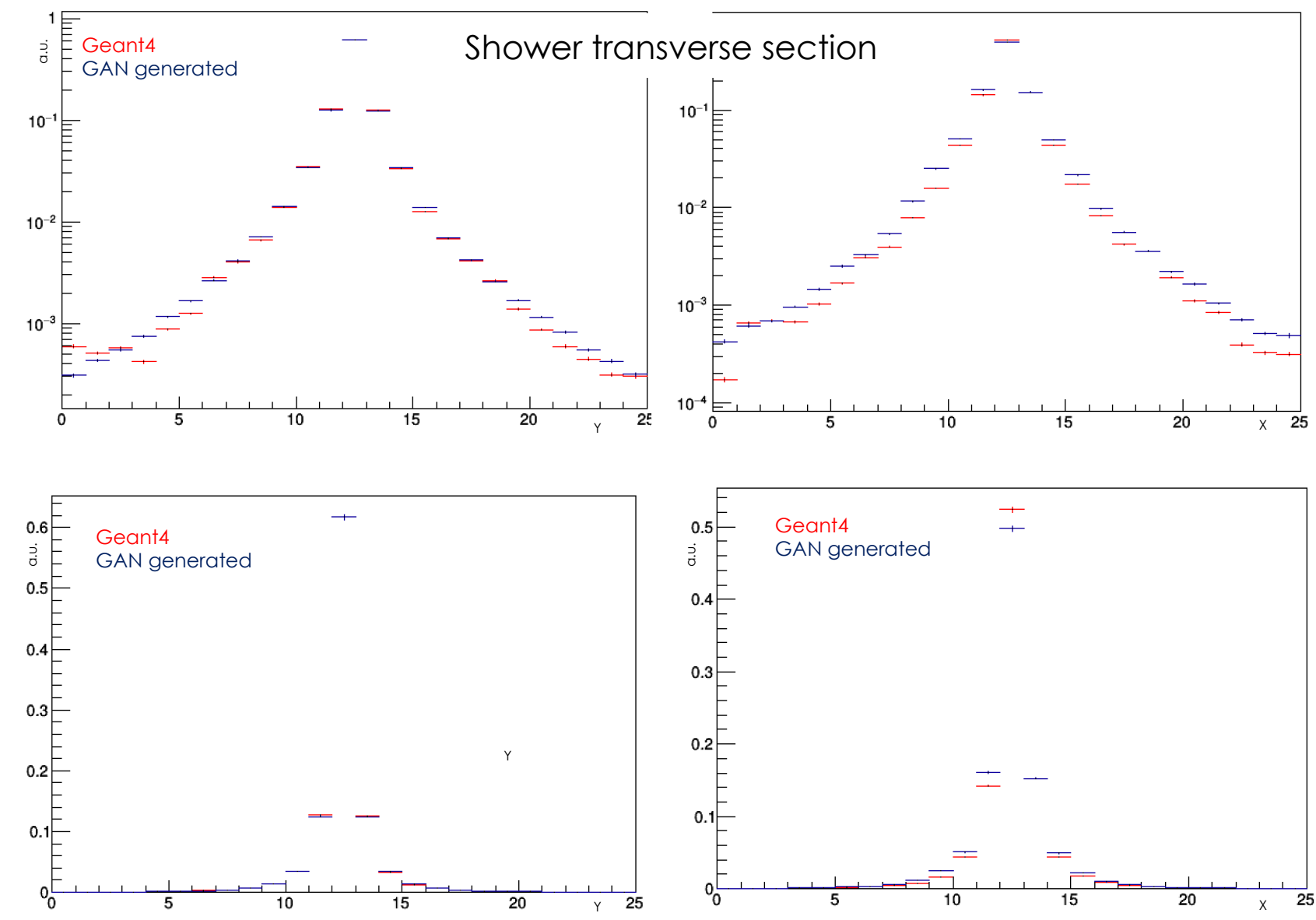
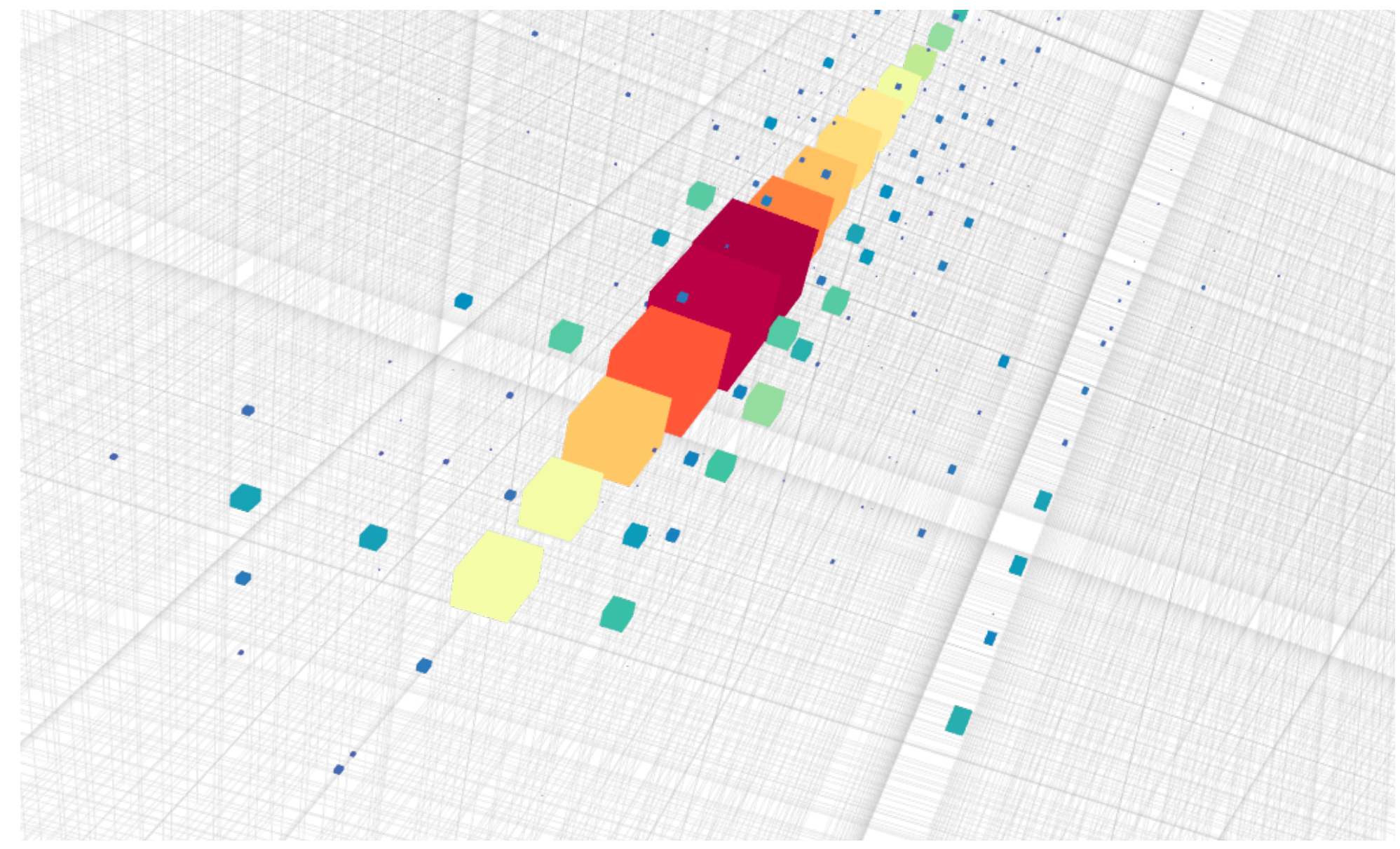
◎ *In real life, this could be used while selecting events in real time (“trigger”)*

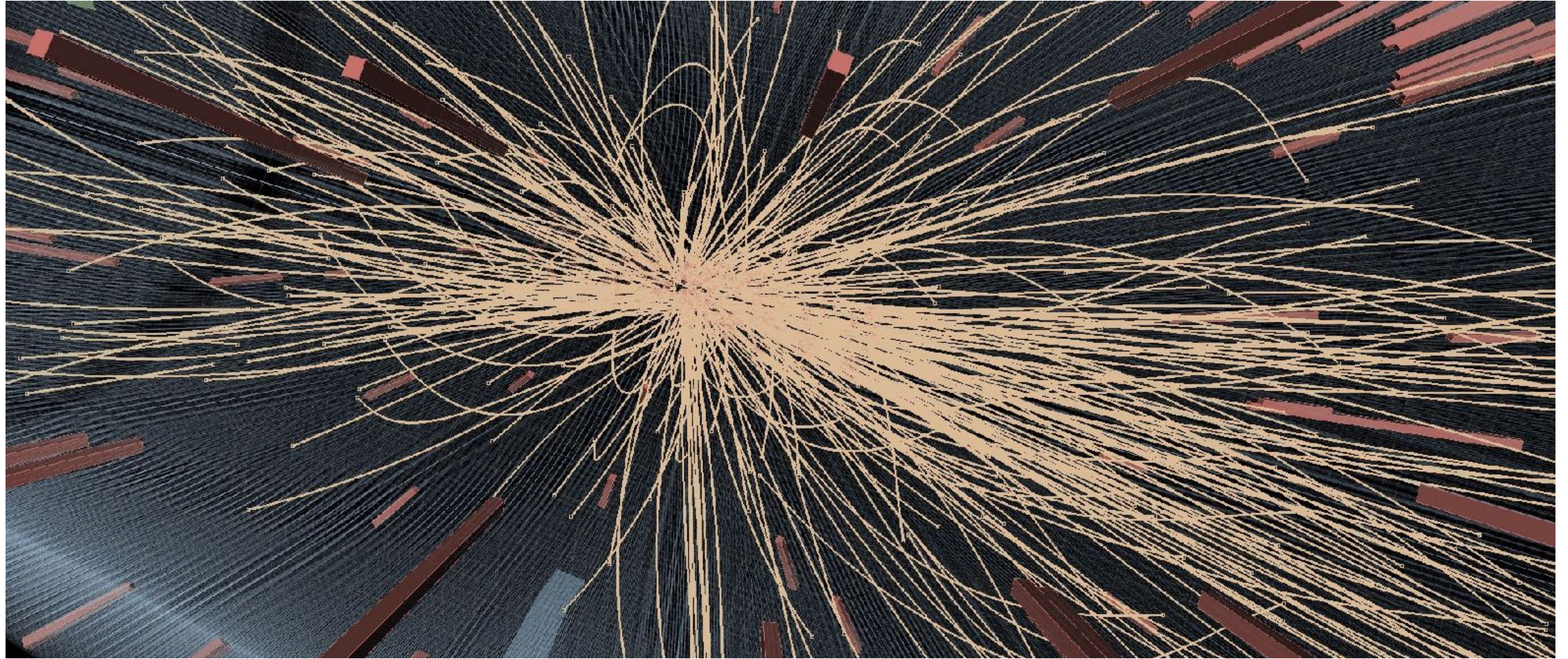




Generative Adversarial Networks

- With x10 more data being stored during HL-LHC, we will need > x10 more Monte Carlo to do precision physics
- This will not be possible with current generation techniques
- Generative models might provide a way out of this dead end





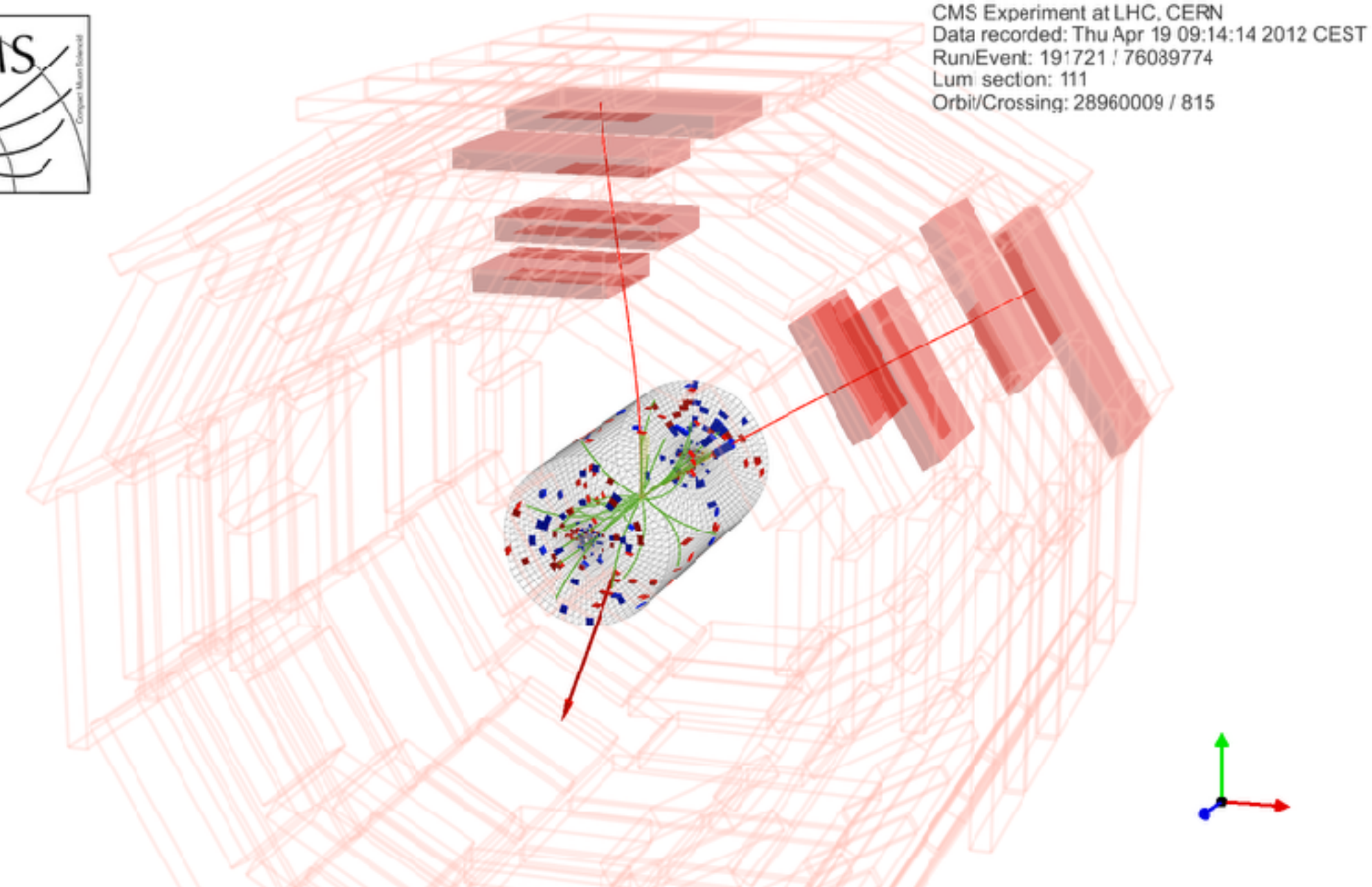
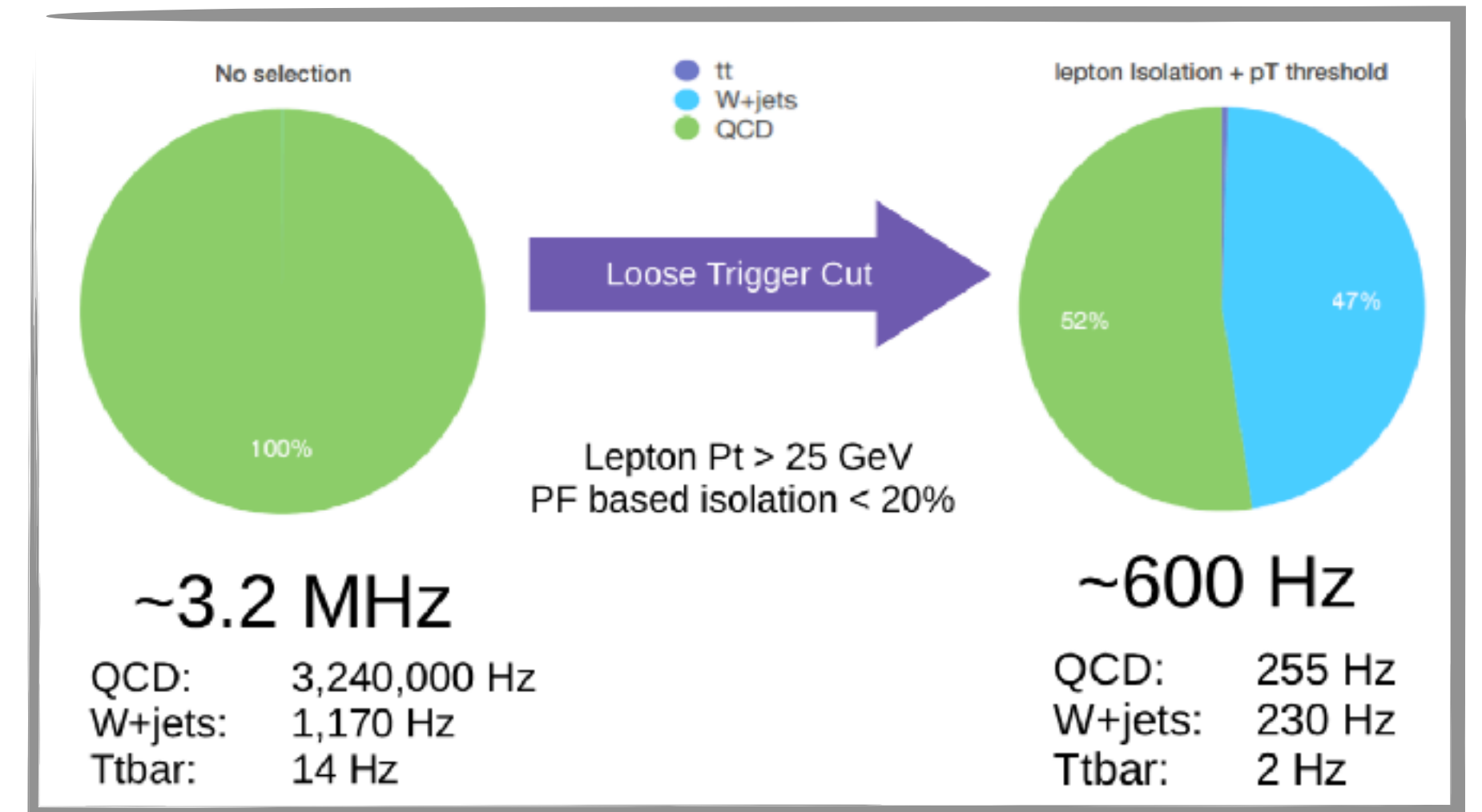
Deep
~~Machine Learning~~ for data taking

Cleaning up selected sample

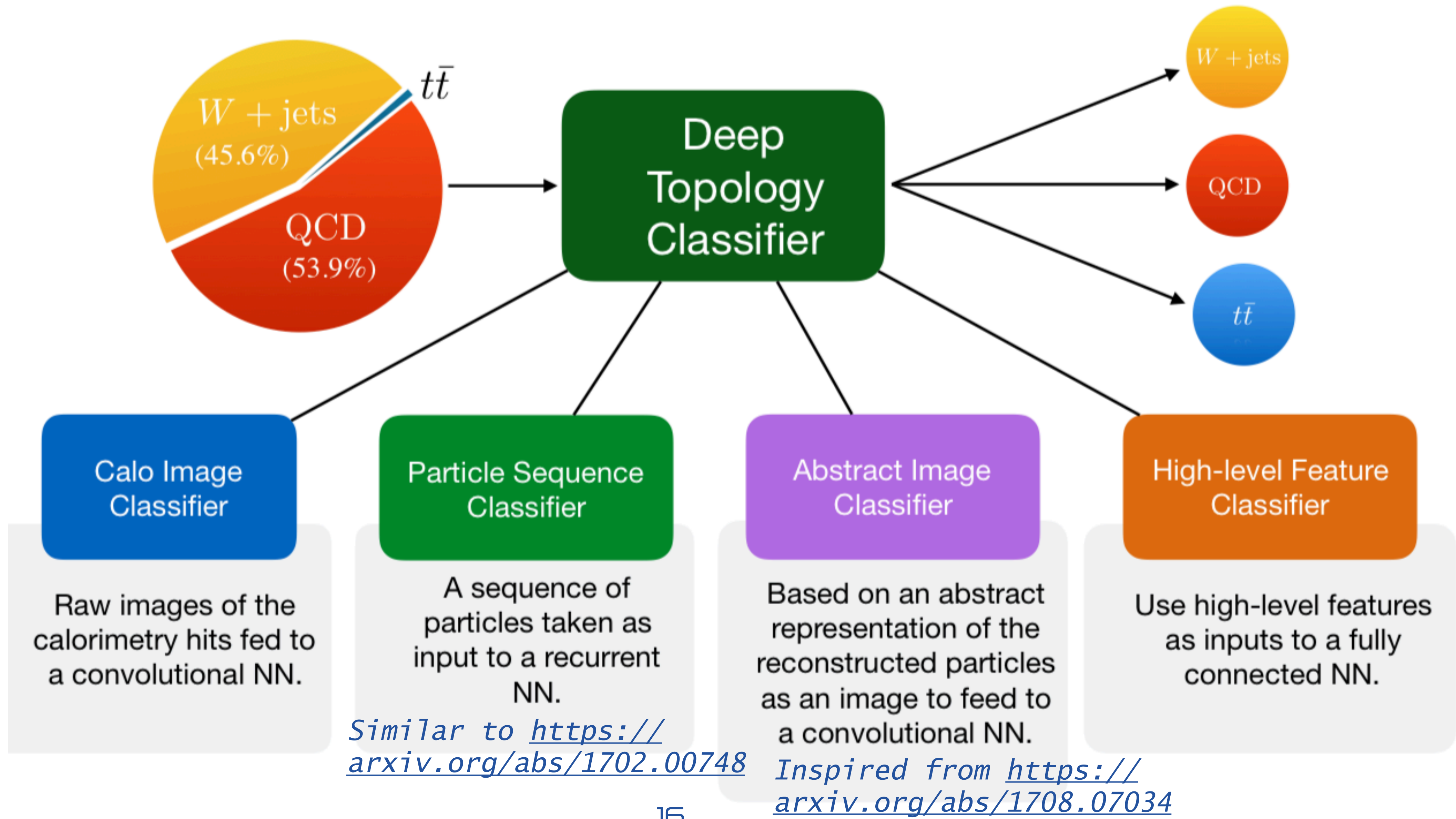
A typical example: leptonic triggers

- at the LHC, producing an isolated electron or muon is very rare. Typical smoking gun that something interesting happened (Z, W, top, H production)
- Triggers like those are very central to ATLAS/CMS physics
- The sample selected is enriched in interesting events, but still contaminated by non-interesting ones
- Contamination can be reduced with a DL classifier that rejects obvious false positives looking at the full event, not just at the lepton

See contribution to NIPS workshop

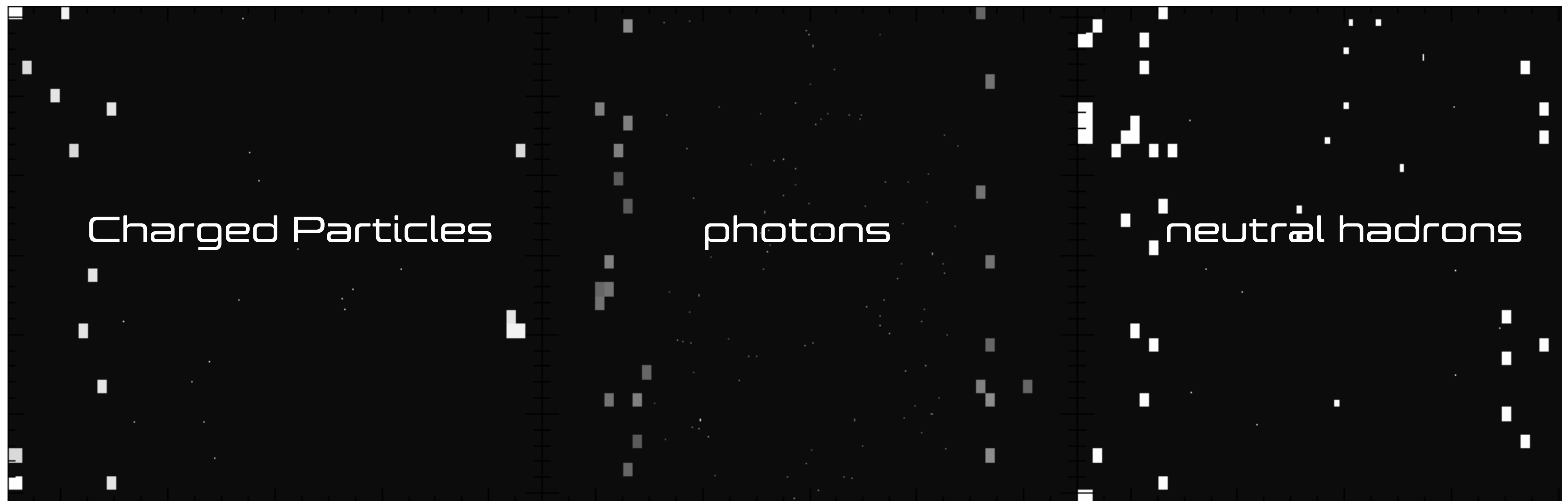


Event Representations



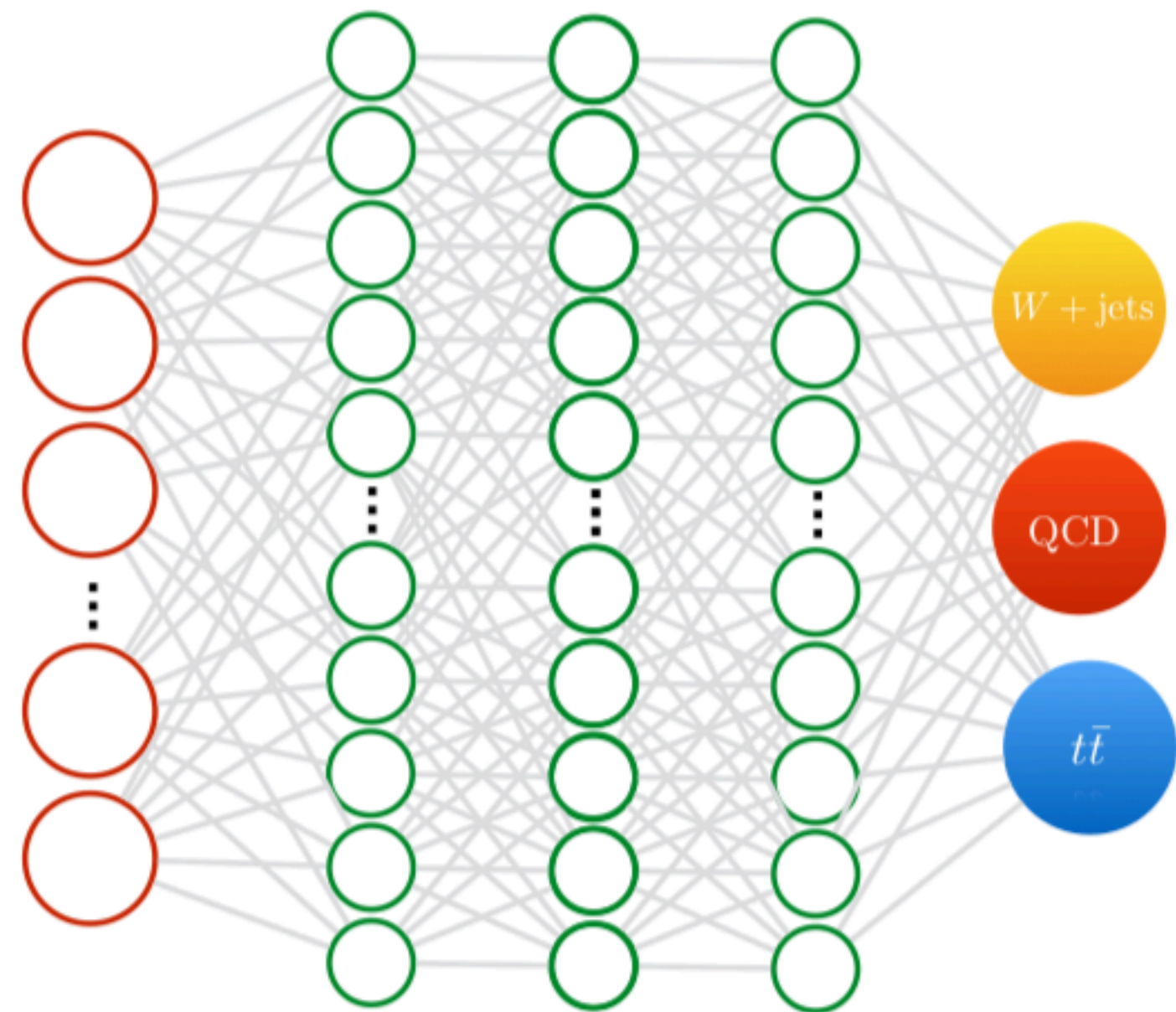
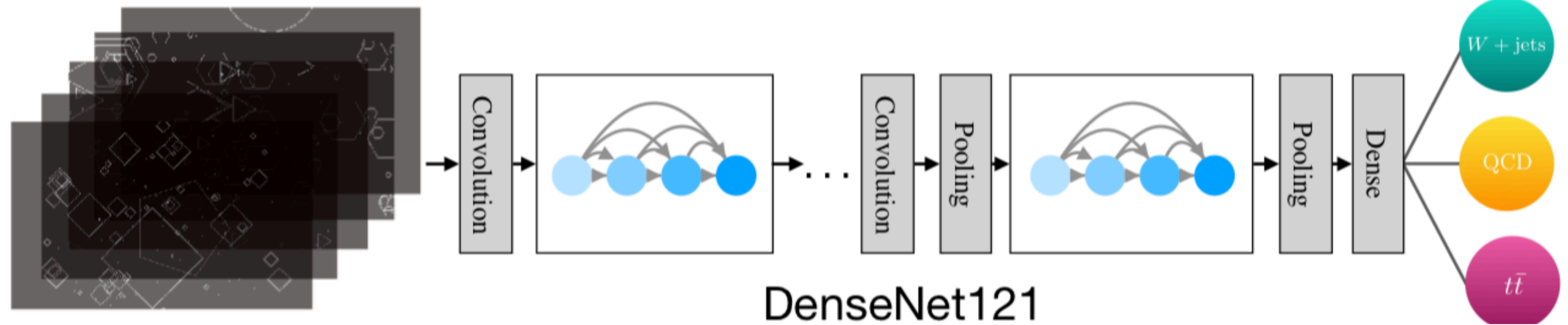
What the event looks like

- ◎ *sparse image with many pixels*
- ◎ *not the kind of image that CNNs usually deal with*
- ◎ *still, reasonable performances (AUC~90%) can be obtained*



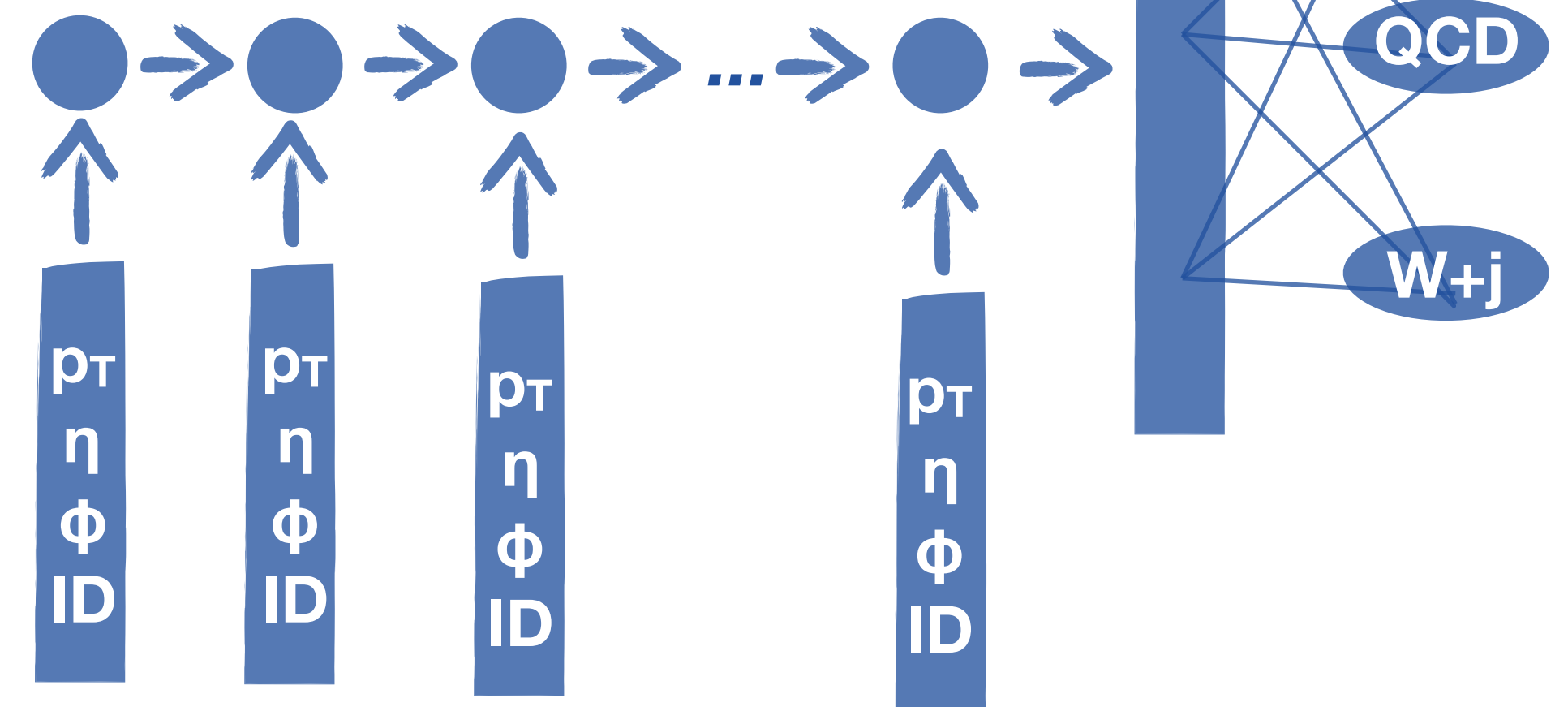
Event Representations

DenseNet on the abstract image



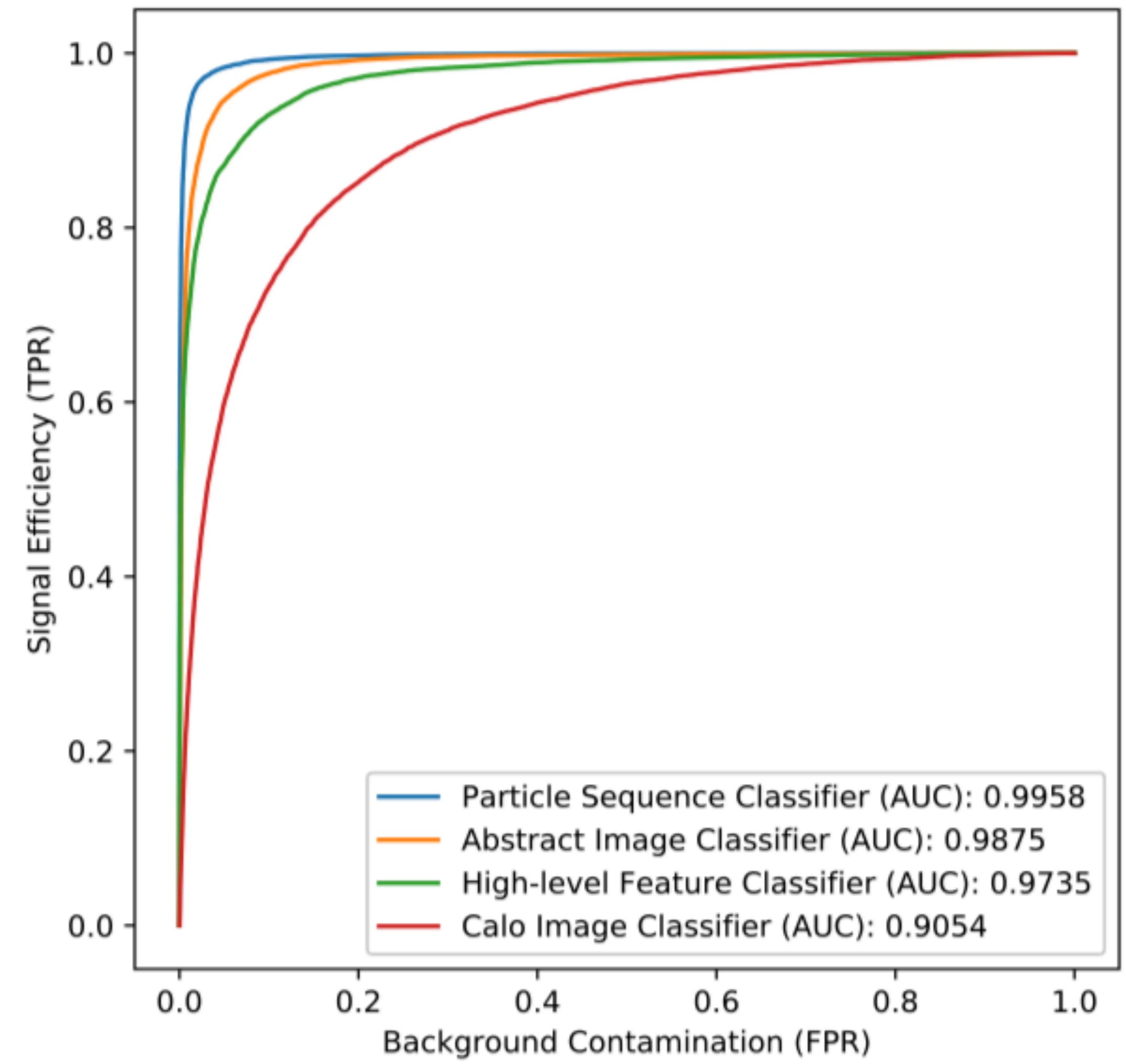
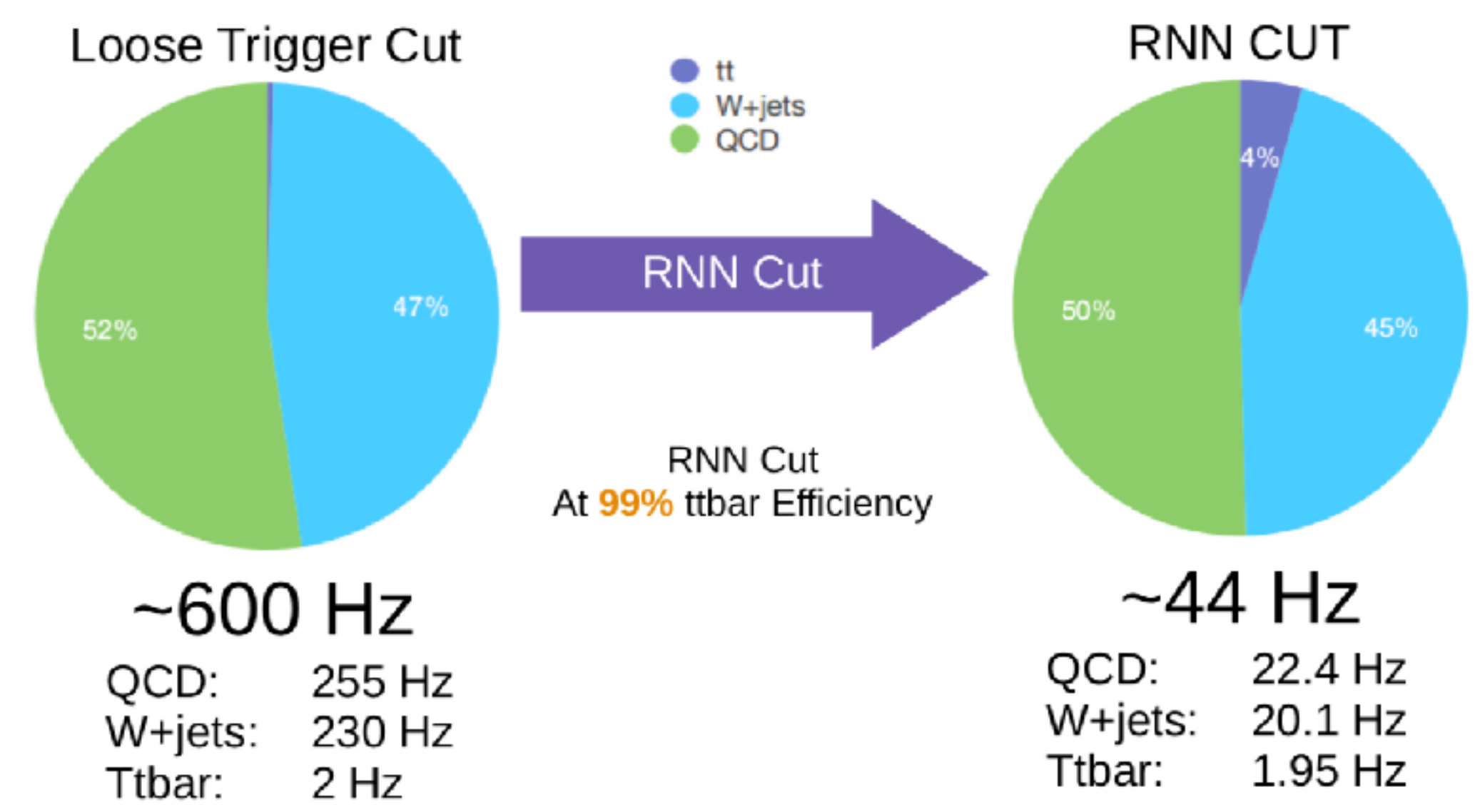
Fully-Connected classifier on physics-motivated features

Recurrent nets on the list of particles (LSTM, GRUs, etc)



Proof of principle: trigger cleanup

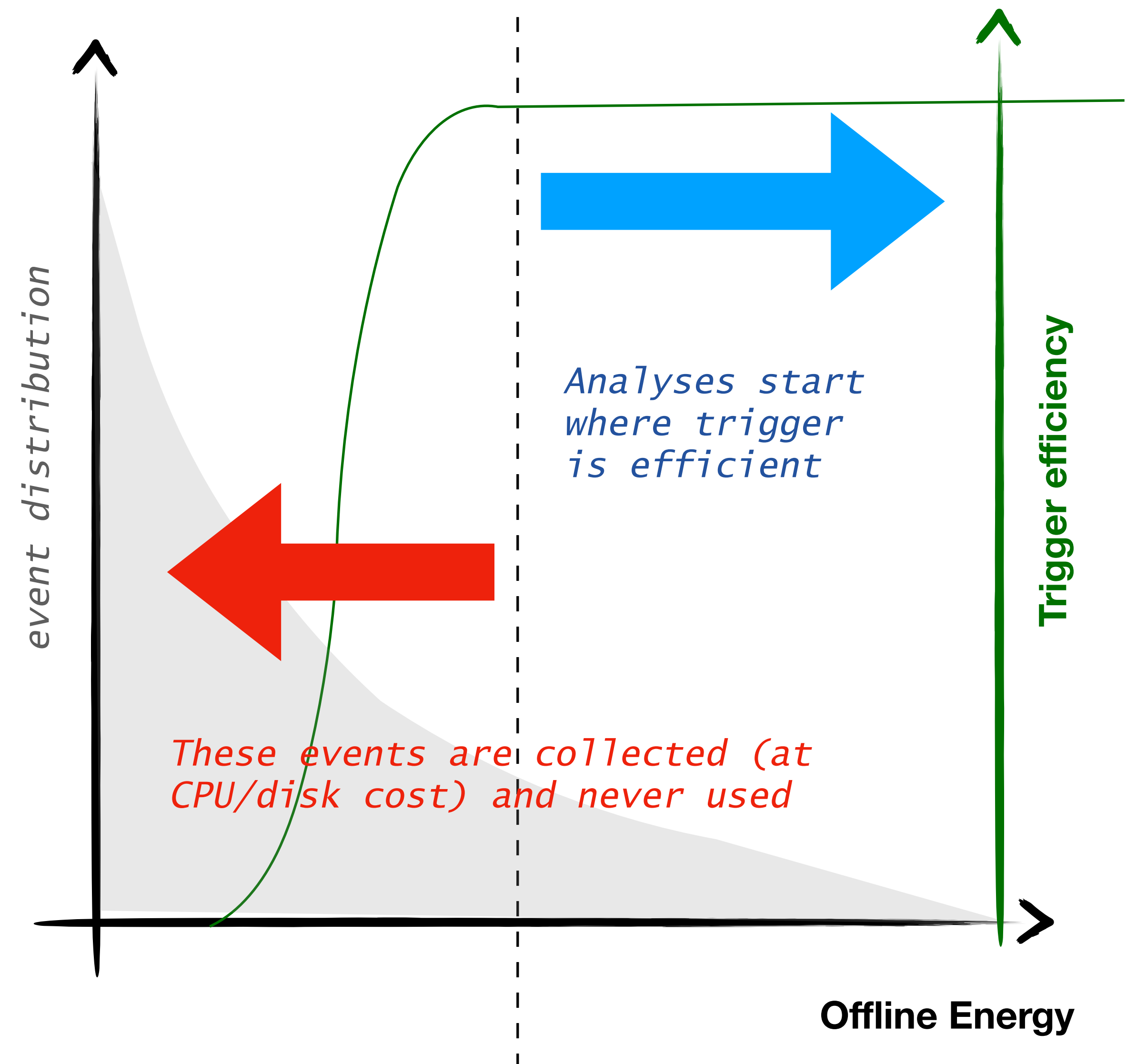
- With non-trivial event representation, can drop false positives by factor 10 with 99% true-positive rate



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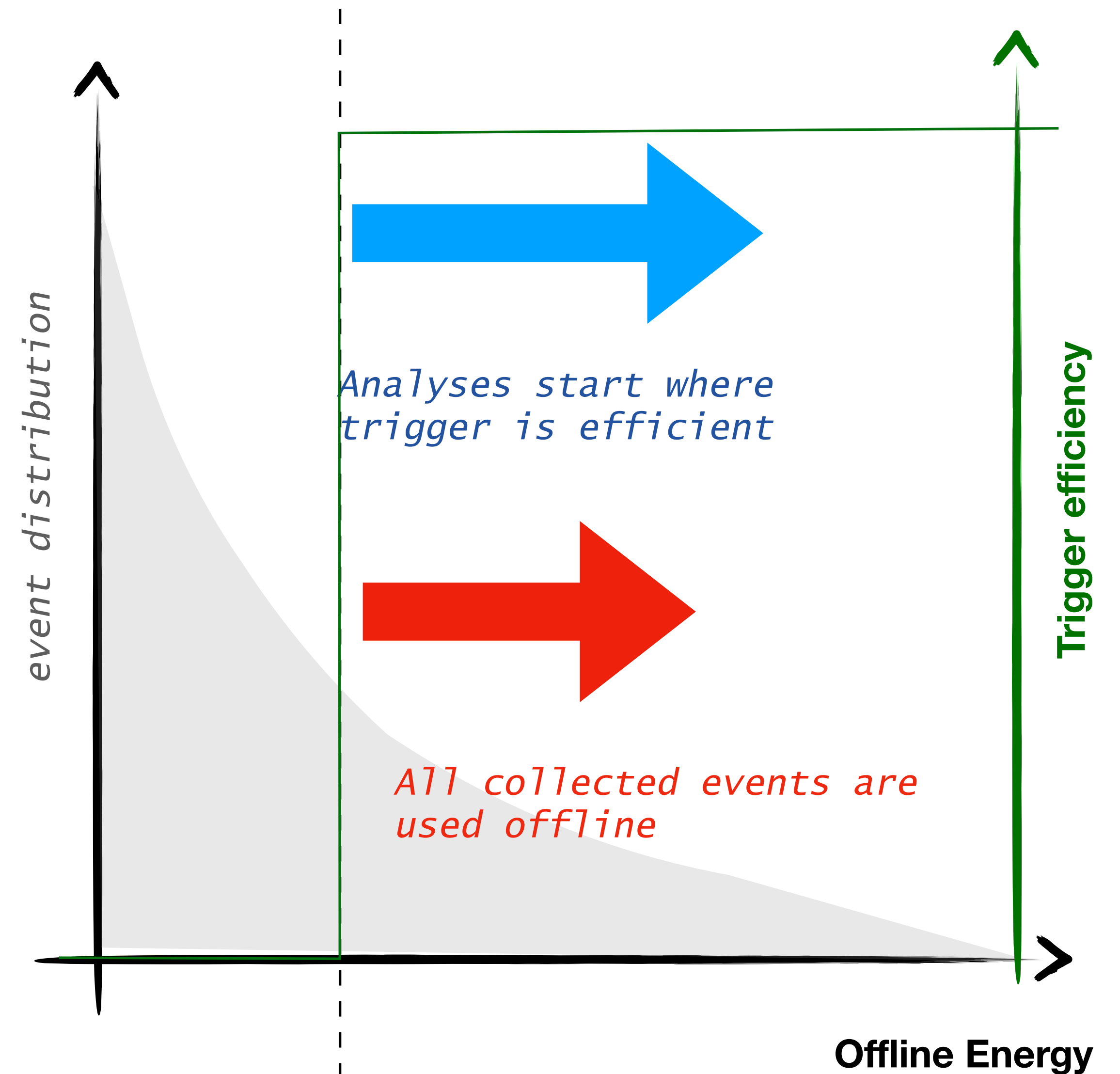
The importance of being fast

- *Online vs offline reconstruction differences are limiting our discovery reach*
- *Seen offline, the online selection is a not-flat response function*
- *Forces us to work on tails of event distribution, reducing sensitivity to new physics*
- *Not optimal use of resources*



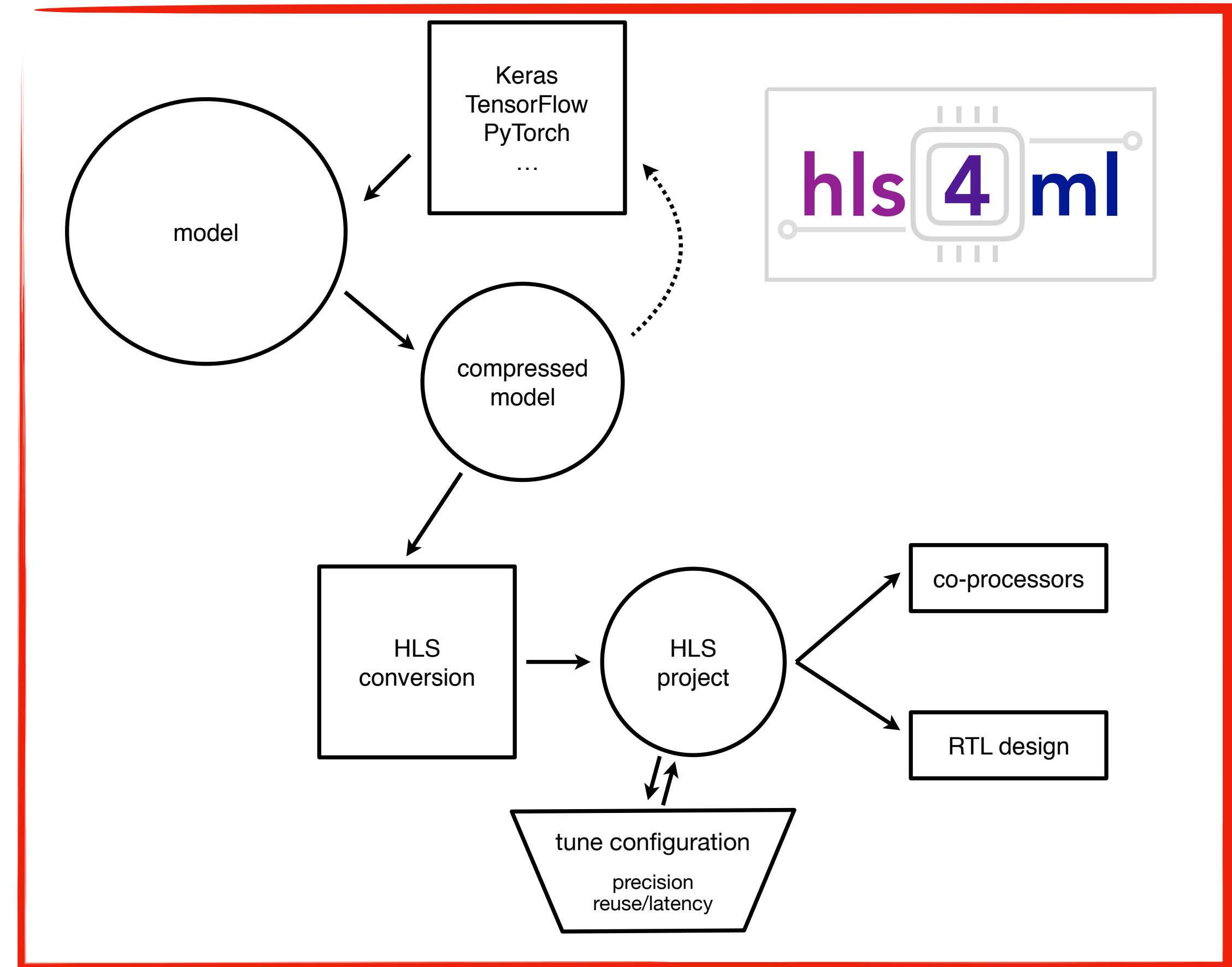
The importance of being fast

- ◎ Having the same reconstruction at L1/HLT/Offline would help us to recover this lost sensitivity ...
- ◎ ... and to free resources that could be spent otherwise (e.g., looking for tricky new physics scenarios)
- ◎ This cannot be done exactly (offline code too slow)
- ◎ But it could be done “in average” (offline response modelled by ML algorithm)



The frontier: bring DL to L1

- *The L1 trigger is a complicated environment*
 - *decision to be taken in $\sim 10 \mu\text{sec}$*
 - *only access to local portions of the detector*
 - *processing on Xilinx FPGA, with limited memory resources*
- *Some ML already running @L1*
 - *CMS has BDT-based regressions coded as look-up tables*
- *Working to facilitate DL solutions @L1 with dedicated library*

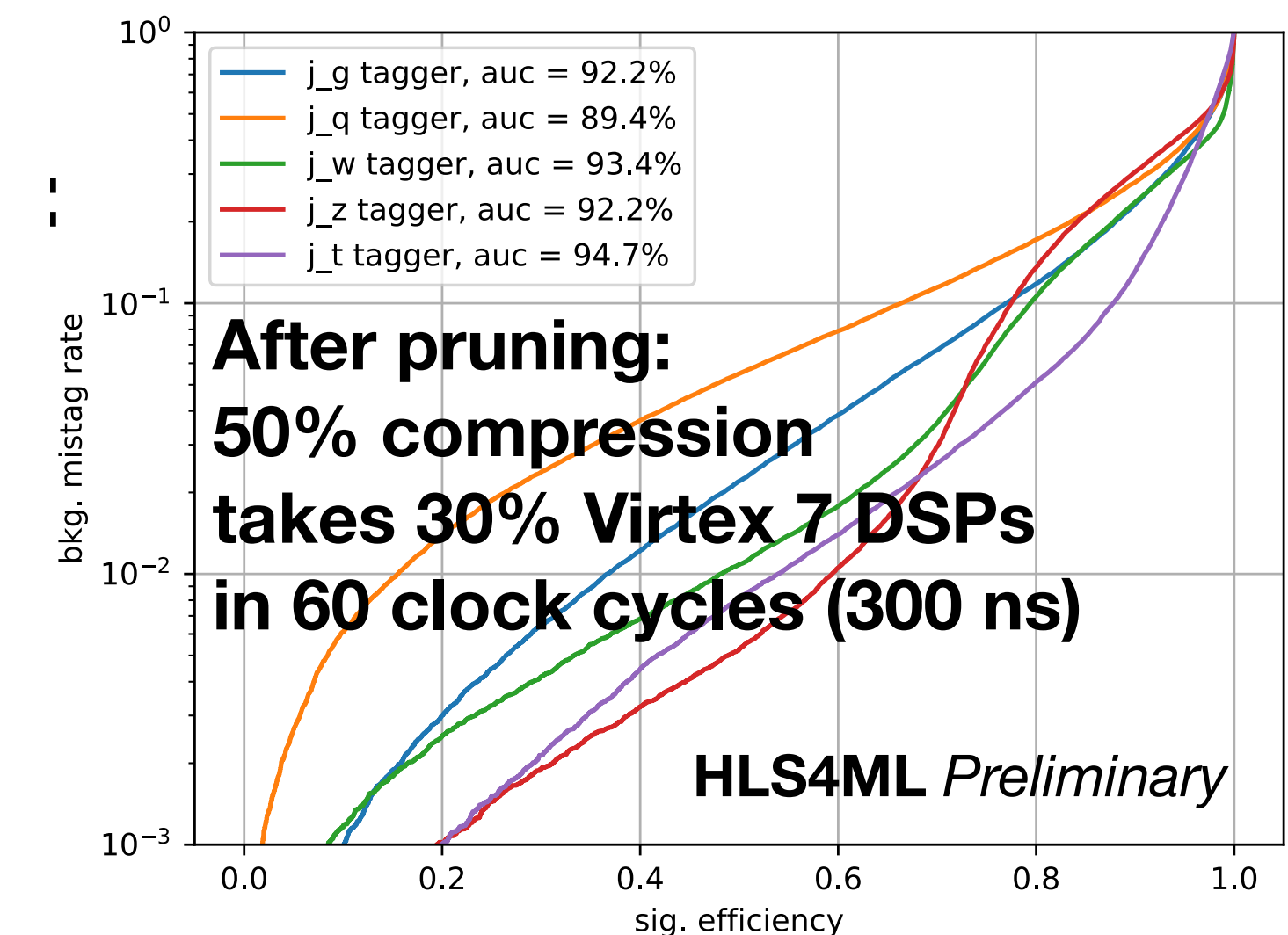
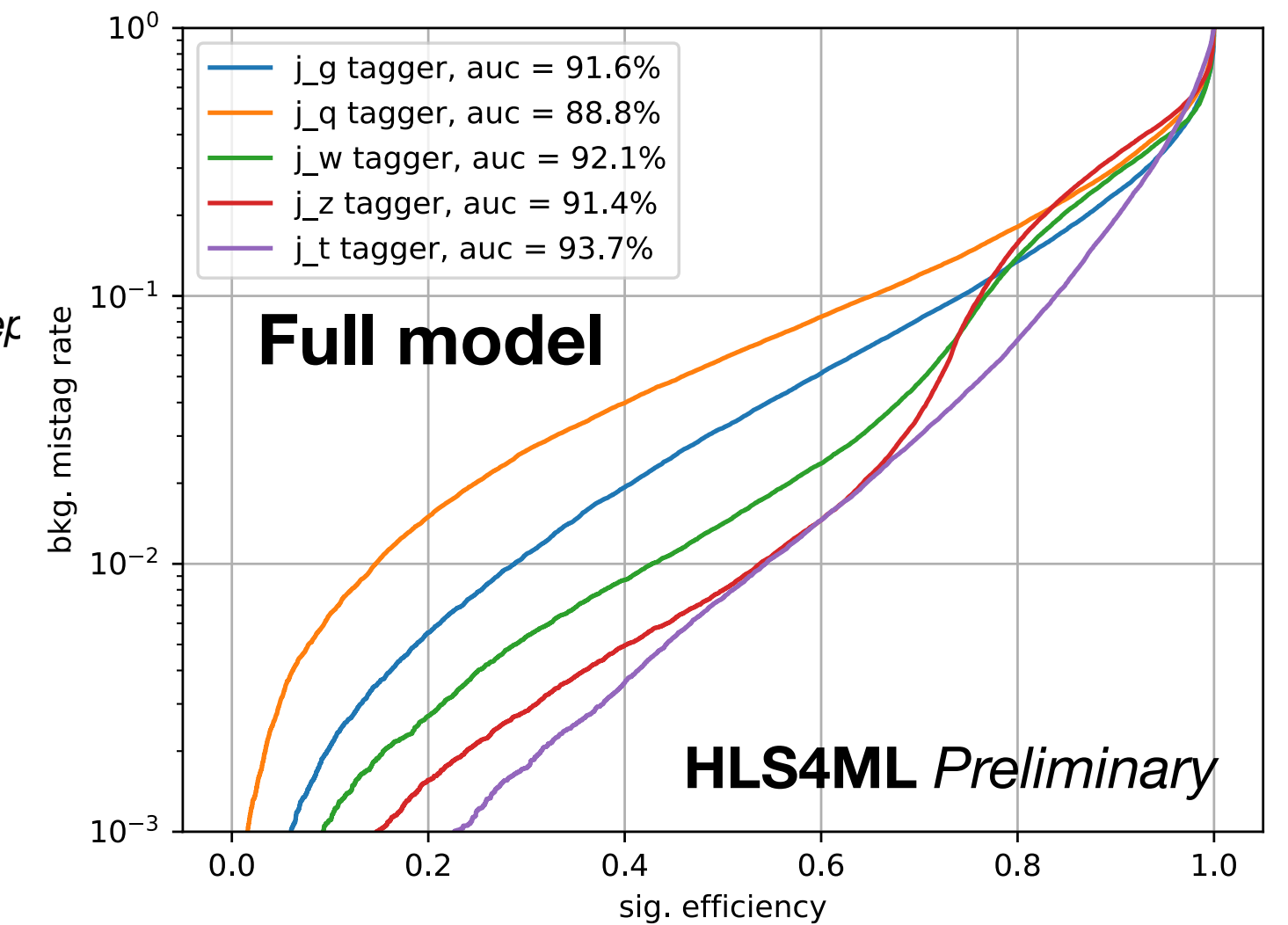
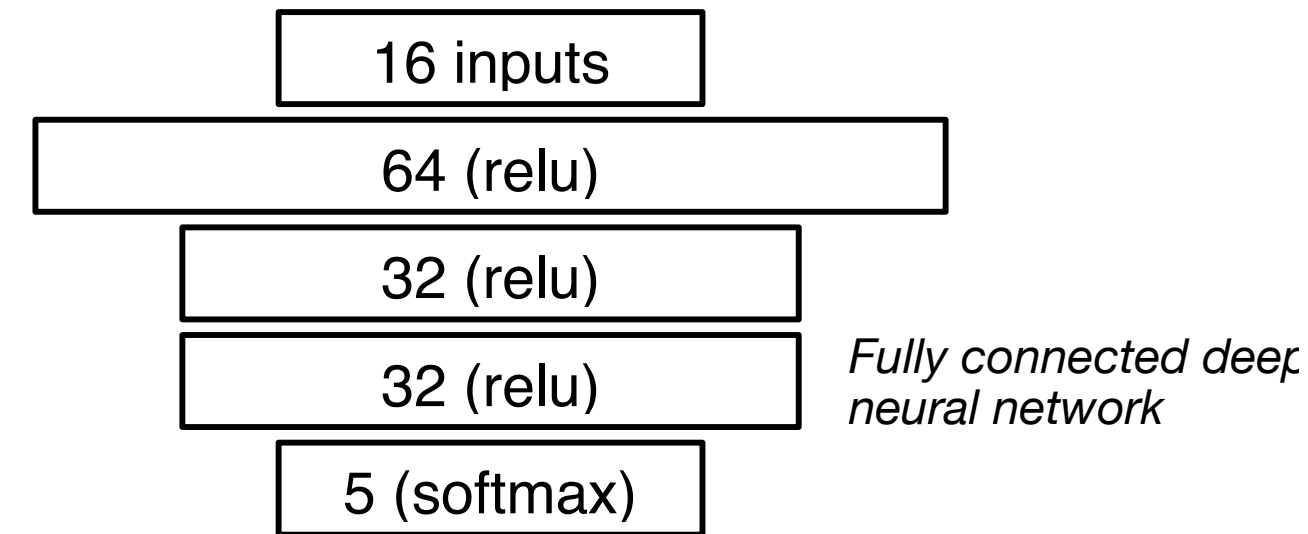


HLS4ML: CERN/FNAL/MIT joint effort

To debut at Connecting The Dots 2018 in Seattle (March 2018)

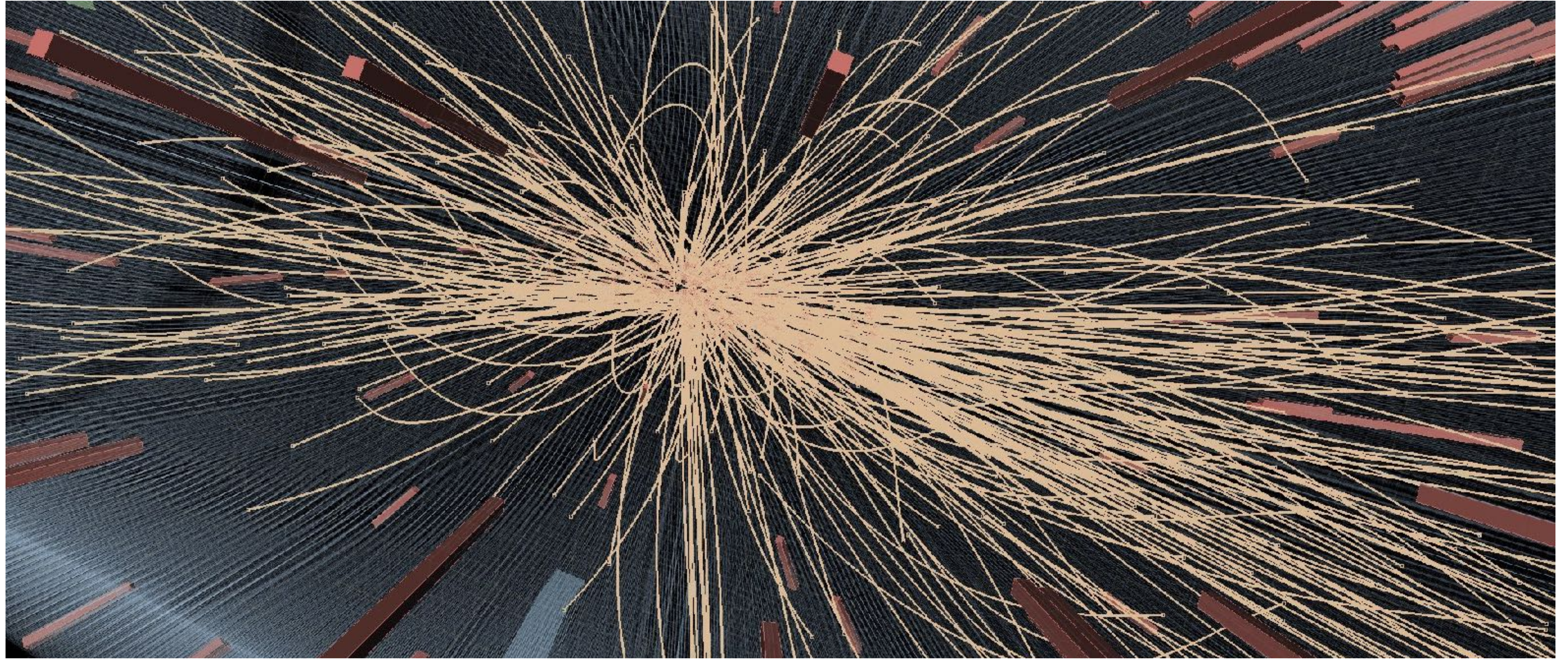
The frontier: bring DL to L1

- Work is still preliminary
- Take as use case jet tagging
 - get a jet @L1
 - from its shape (jet substructure) tell which jet it is
- Problem solved with large network (cannot fit FPGA)
- Implementing pruning solutions to keep only relevant neurons
- Further decrease resources with practical tricks & thumb rules (e.g., divisions are expensive)



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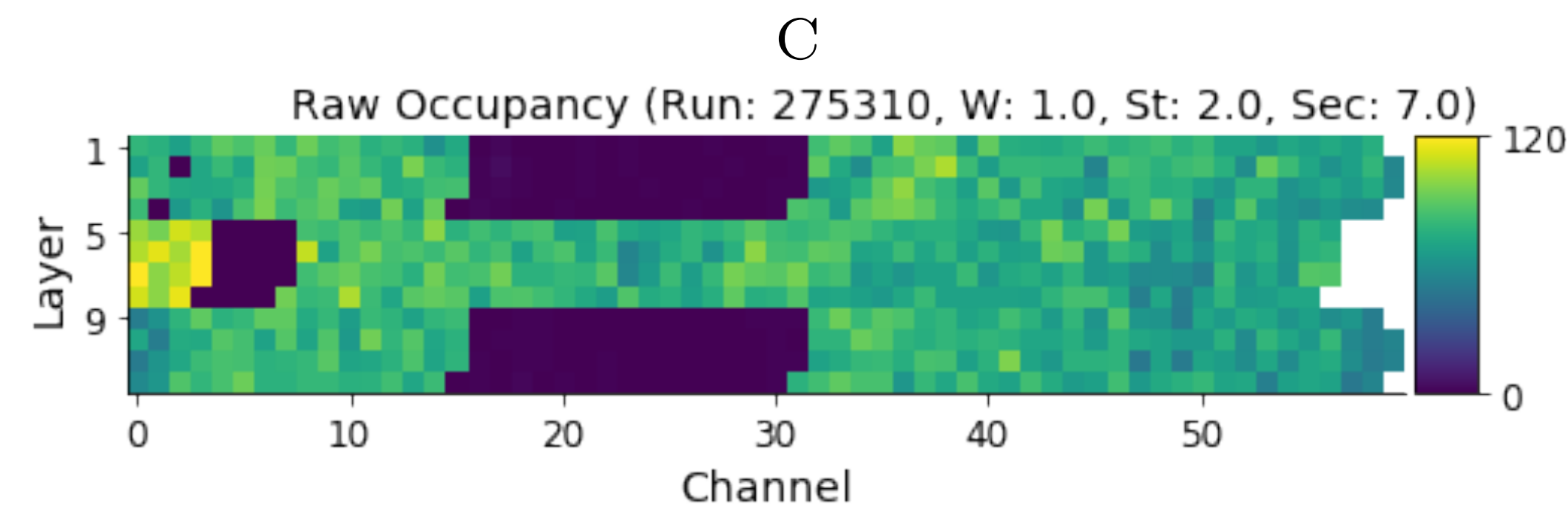
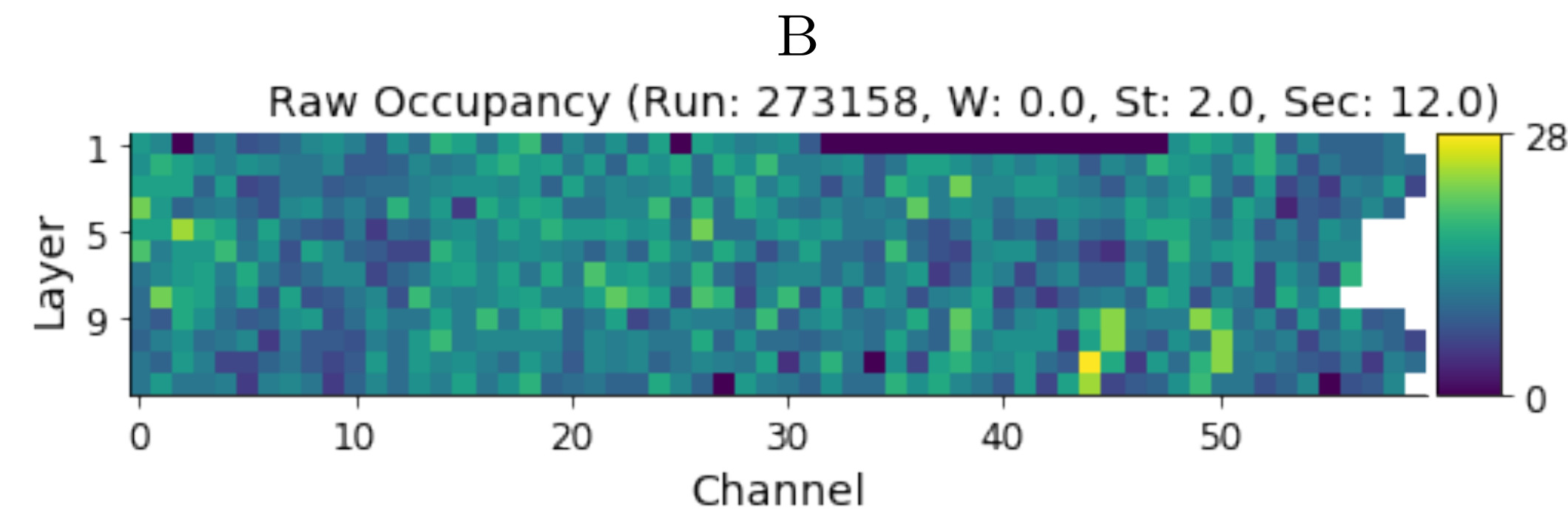
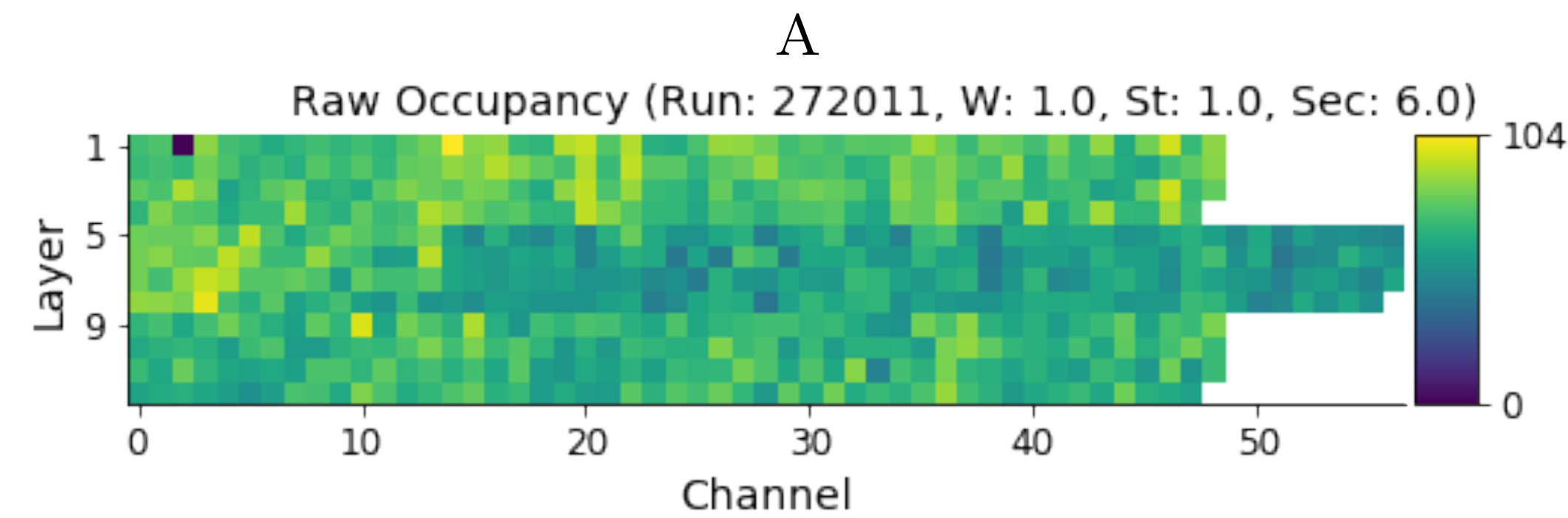
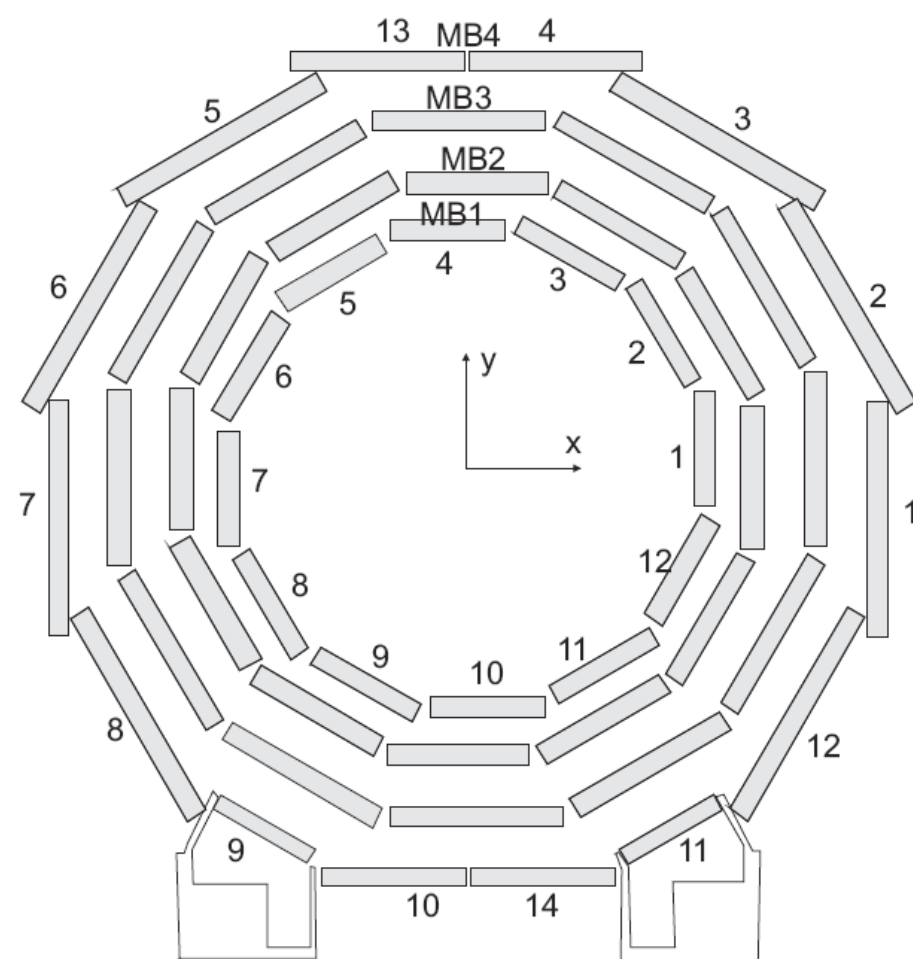
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Deep
~~Machine Learning~~ for monitoring

Data Quality Monitoring

- When taking data, >1 person watches for anomalies in the detector 24/7
- At this stage no global processing of the event
- Instead, local information from detector components available (e.g., detector occupancy in a certain time window)

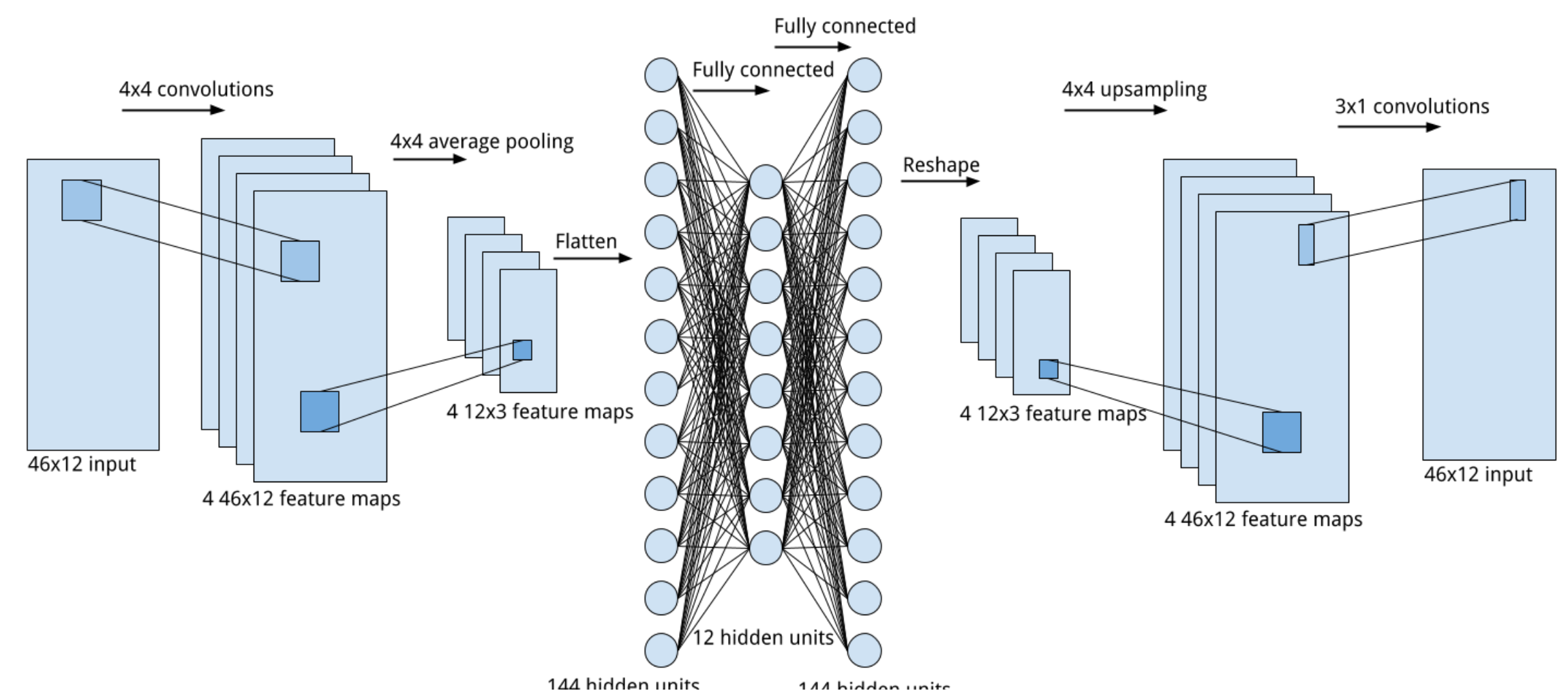
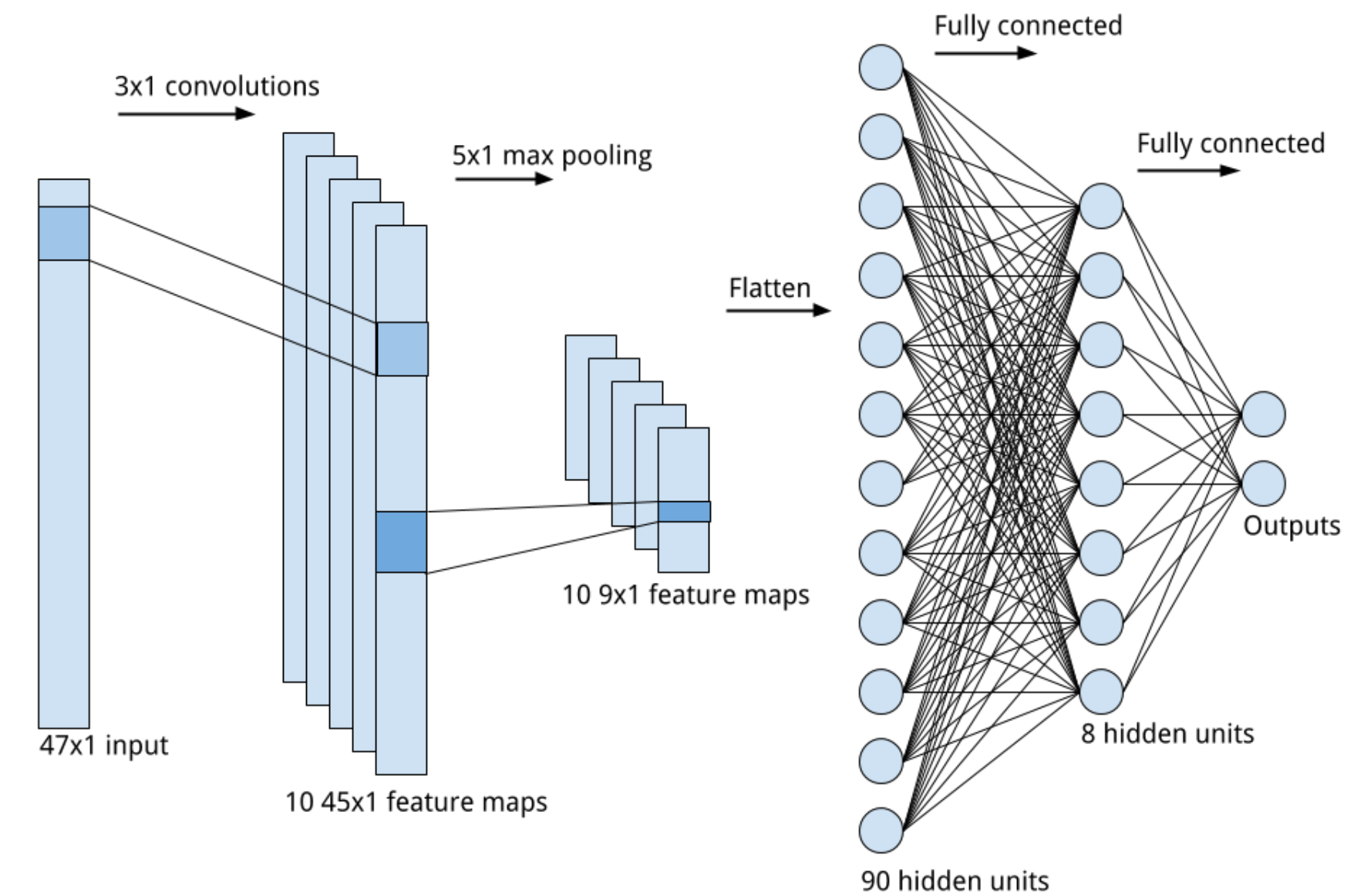


Two approaches

Given the nature of these data, ConvNN are a natural analysis tool. Two approaches pursued

Classify good vs bad data. Works if failure mode is known

Use autoencoders to assess data “typicality”. Generalises to unknown failure modes

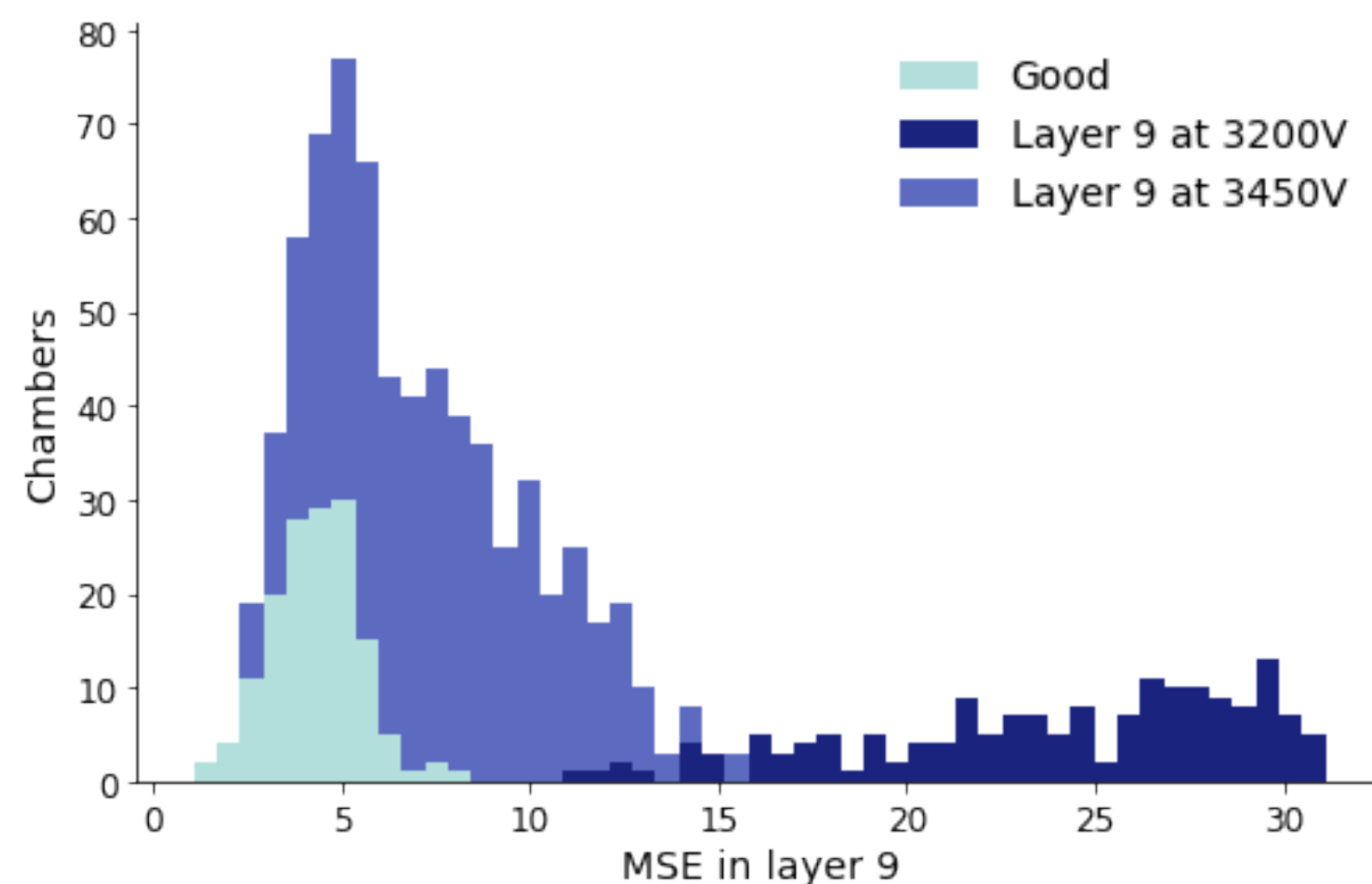
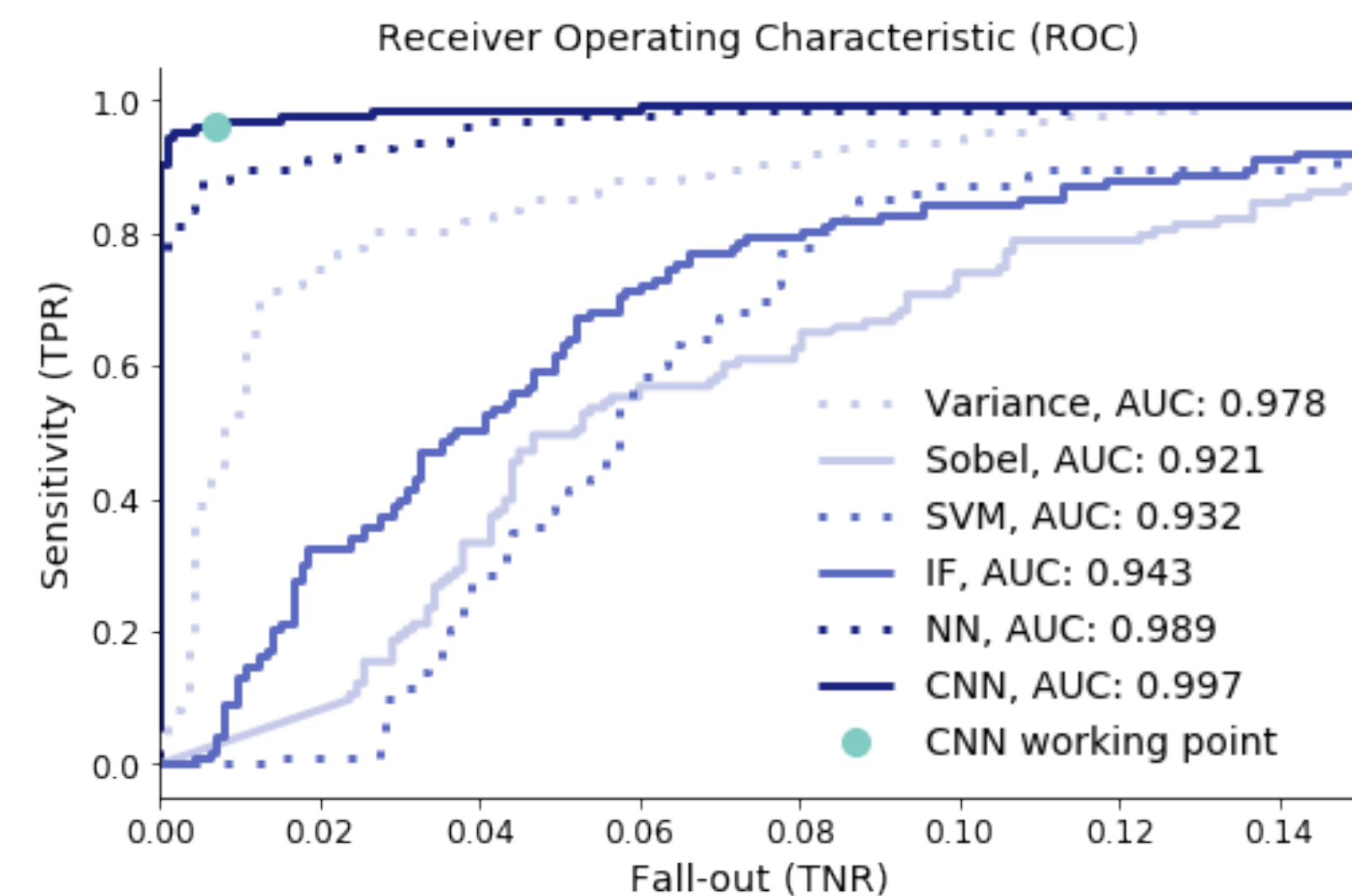


A. Pol et al., to appear soon

Two approaches

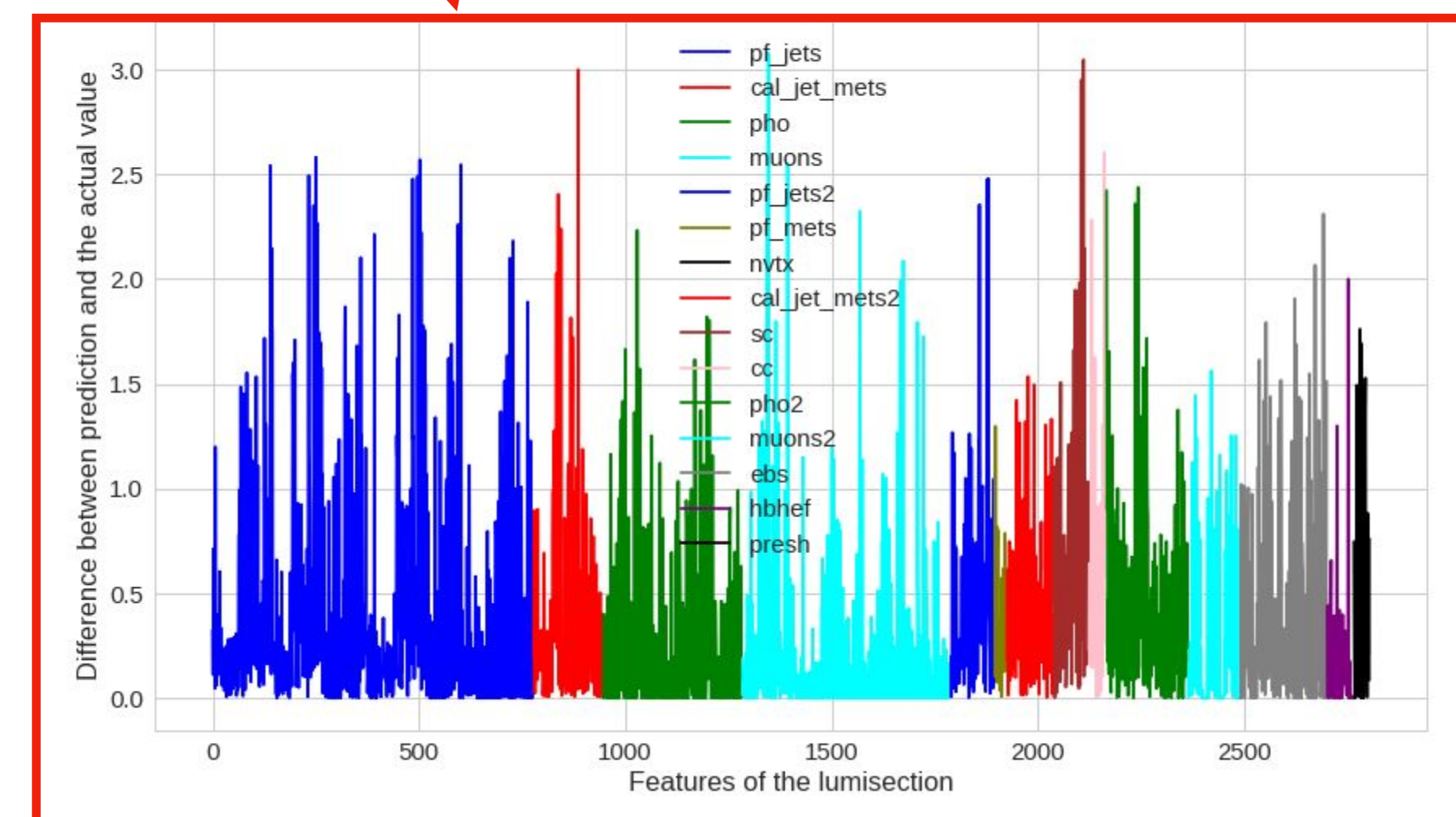
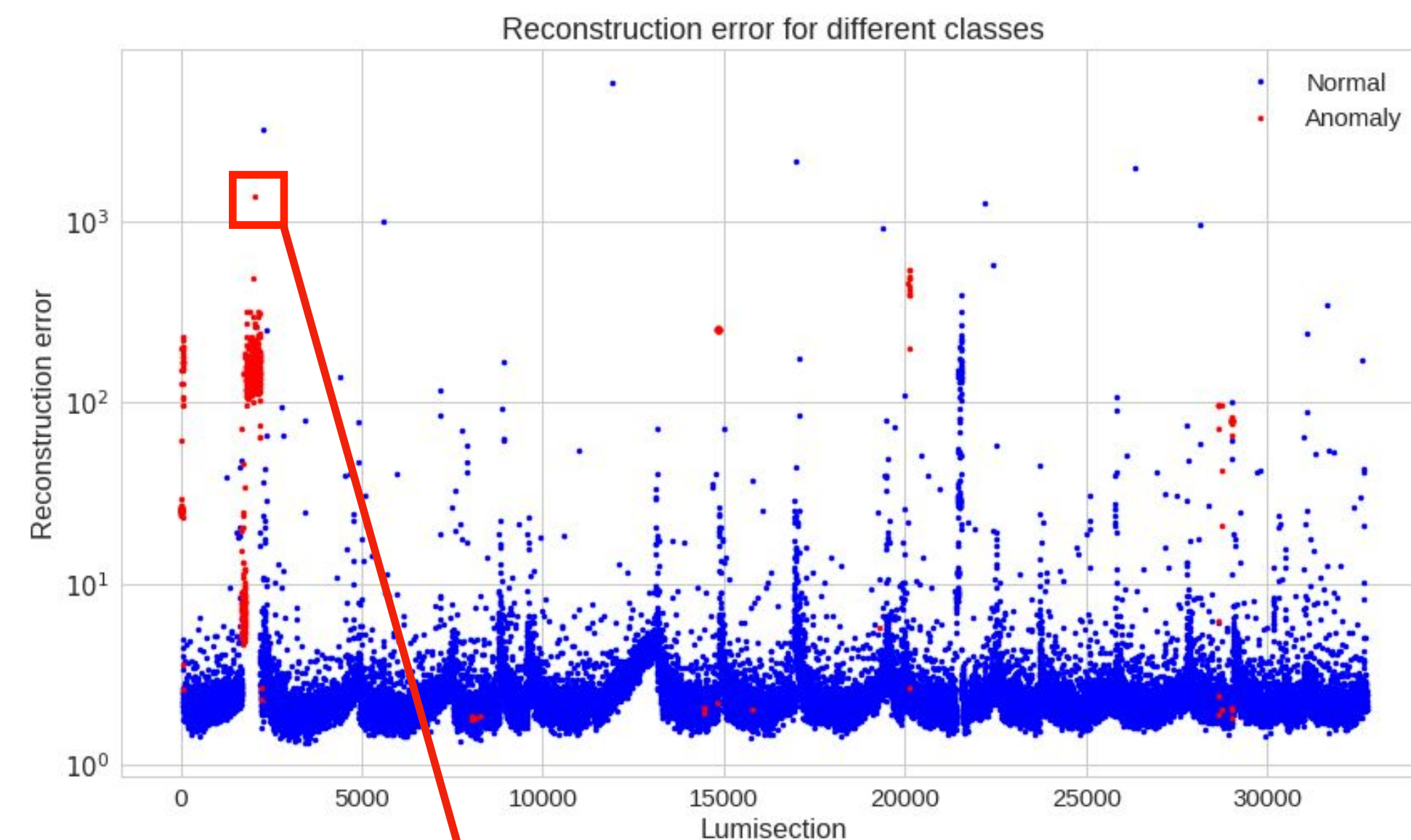
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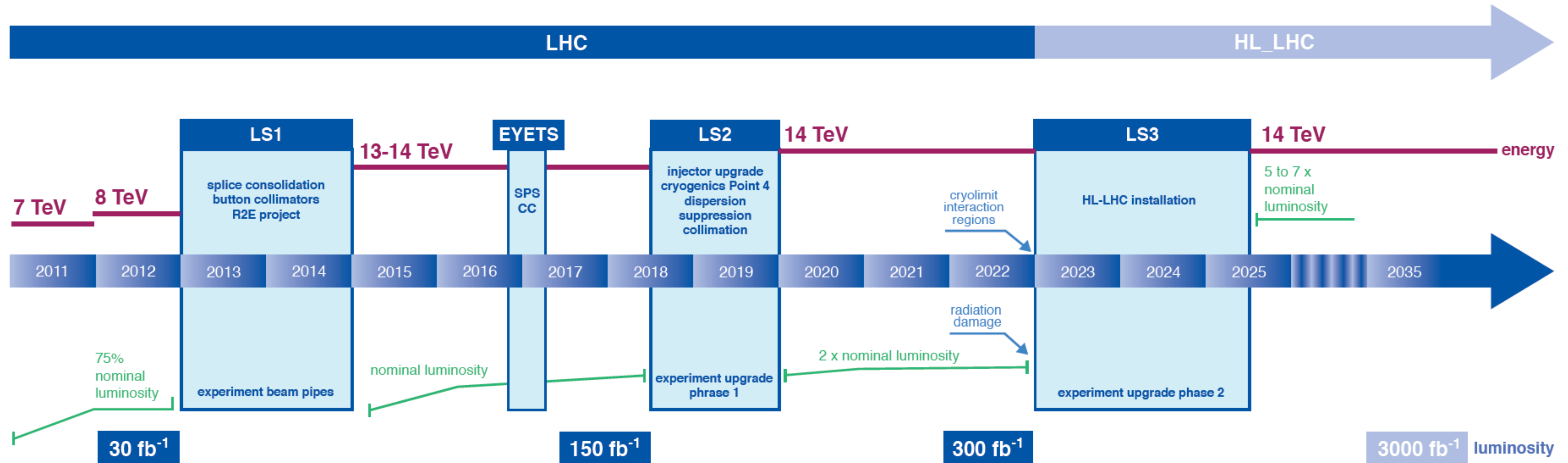


Data Quality Certification

- ◎ *Autoencoder-based 1-class approach generalises to later stages of quality assessment*
 - ◎ *after reconstruction of the events, event reconstruction allows a global assessment (w.g., looking at electrons, muons, etc rather than hits in the detector)*
 - ◎ *A global autoencoder can spot all these features*
 - ◎ *Monitoring individual contributions to loss function (e.g., MSE) one can track the problem back to a specific physics object/detector component*



A roadmap towards HL-LHC



- ◉ We need to be ready by **2025** (High-Luminosity LHC)
- ◉ LHC Run 3 (2020-2022) is the ultimate demonstration opportunity
 - ◉ produce proof-of-principle studies on simulations and open datasets
 - ◉ bring ML expertise at CERN and in the experiments
 - ◉ within experiments, develop/test/deploy ML solutions to solve technical tasks

Backup

Practical infos

- ◎ *CERN Data Science Seminars*

- ◎ *LHC iML working group*

- ◎ *Data Science @HEP workshop series*
 - ◎ *CERN 2015*
 - ◎ *Simons Foundation (New York) 2016*
 - ◎ *Fermilab 2017*