

# Ultraviolet completion and predictivity from minimal parameterizations of Beyond-Standard-Model physics

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Cosmology in Colombia (CoCo) 2020

## 1 Introduction to Asymptotic Safety

## 2 AS extensions of the SM

## 3 AS Gravity

# Asymptotic Safety - The concept

Definition:

$$\mathcal{L} = \sum_i g_i(k) \mathcal{O}_i(\varphi) \implies \beta_i(g_j^*) = k \frac{dg_i}{dk} = 0.$$

Linearized analysis for  $y_i = g_i - g_i^*$

$$\frac{dy_i}{dt} = M_{ij}y_j, \quad M_{ij} = \frac{\partial \beta_i}{\partial g_j} \quad (1)$$

$$(S^{-1})_{ij} M_{jl} S_{ln} = \delta_{in} \lambda_n, \quad z_i = S_{ij}^{-1} y_j \quad (2)$$

$$\frac{dz_i}{dt} = \lambda_i z_i \quad \text{and} \quad z_i(t) = c_i e^{\lambda_i t} = c_i \left( \frac{k}{k_0} \right)^{\lambda_i}. \quad (3)$$

- If  $\Re(\lambda_i) > 0$ , *irrelevant* direction.
- If  $\Re(\lambda_i) < 0$ , *relevant* direction.
- If  $\Re(\lambda_i) = 0$ , *marginal* direction.

# Theory space

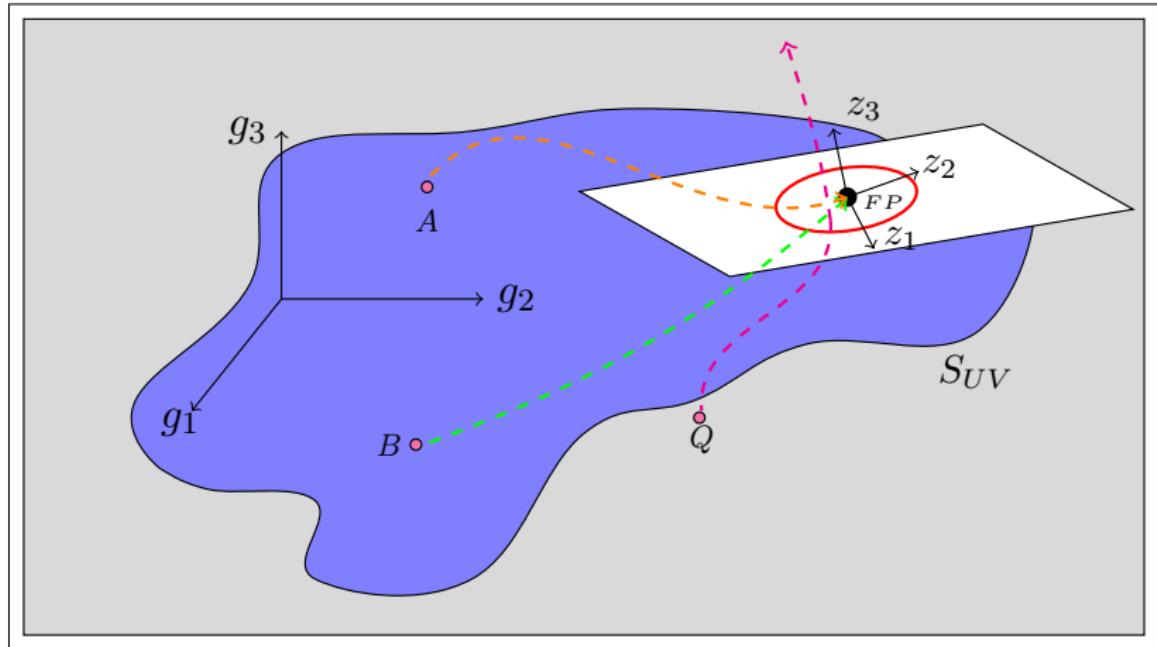


Figure : Theory space and fixed-point properties.

# Running of the SM gauge couplings

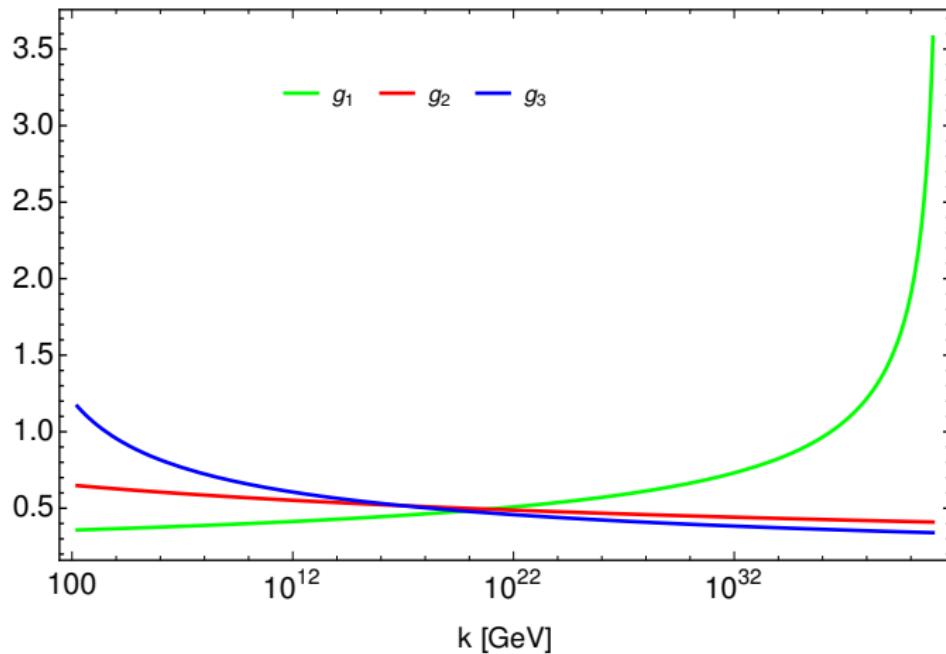


Figure : Running of the gauge couplings  $g_1$ ,  $g_2$  and  $g_3$ . At large values of  $k$ ,  $g_1$  begins its ascent towards the Landau pole.

# Gauge theories in $d = 4$ : one loop

- $SU(N_c)$  theory with  $N_f$  fermions in the fundamental representation

$$\mathcal{L} = -\frac{1}{4}\text{tr}F_{\mu\nu}F^{\mu\nu} + \bar{\psi}iD\!\!\!/ \psi \quad (4)$$

The beta function of  $\alpha_g = \frac{g^2 N_c}{(4\pi)^2}$  is

$$\beta_g = -B\alpha_g^2 \quad (5)$$

$$B = -\frac{4}{3}\epsilon ; \quad \epsilon = \frac{N_F}{N_c} - \frac{11}{2} \quad (6)$$

$$N_F < \frac{11}{2}N_c \implies \epsilon < 0 \implies B > 0 \implies \text{AF}$$

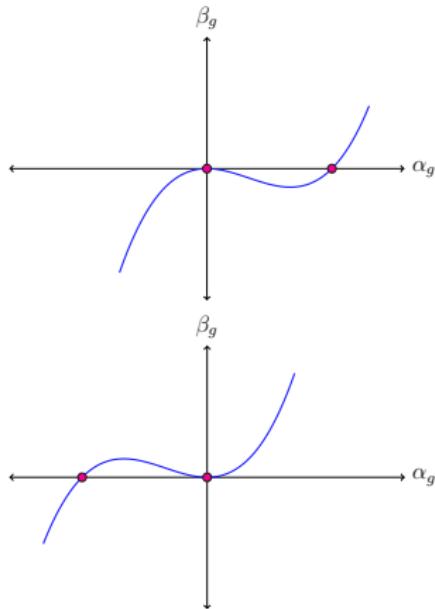
# Gauge theories in $d = 4$ : two loops

$$\beta_g = -B\alpha_g^2 + C\alpha_g^3$$

$$C > 0$$

$$C < 0$$

$$B > 0$$



$$B < 0$$

# Yukawa couplings

- Adding scalar fields  $H$

$$\Delta\mathcal{L} = \text{tr}(\partial^\mu H)^\dagger(\partial_\mu H) + y \text{tr}(\bar{\psi}_L H \psi_R + \bar{\psi}_R H \psi_L) \quad (7)$$

$$\beta_g = \frac{d\alpha_g}{dt} = (-\textcolor{blue}{B} + \textcolor{blue}{C}\alpha_g - \textcolor{red}{D}\alpha_y)\alpha_g^2$$

$$\beta_y = \frac{d\alpha_y}{dt} = (\textcolor{red}{E}\alpha_y - \textcolor{red}{F}\alpha_g)\alpha_y$$

Beta functions for  $\alpha_g$  and  $\alpha_y = \frac{y^2 N_c}{(4\pi)^2}$

$$\begin{aligned}\beta_g &= \alpha_g^2 \left[ \frac{4}{3}\epsilon + \left( 25 + \frac{26}{3}\epsilon \right) \alpha_g - 2 \left( \frac{11}{3} + \epsilon \right) \alpha_y \right] \\ \beta_y &= \alpha_y [(13 + 2\epsilon)\alpha_y - 6\alpha_g]\end{aligned} \quad (8)$$

# Fixed-point solutions

- For  $\epsilon < 0$ , Banks-Zaks

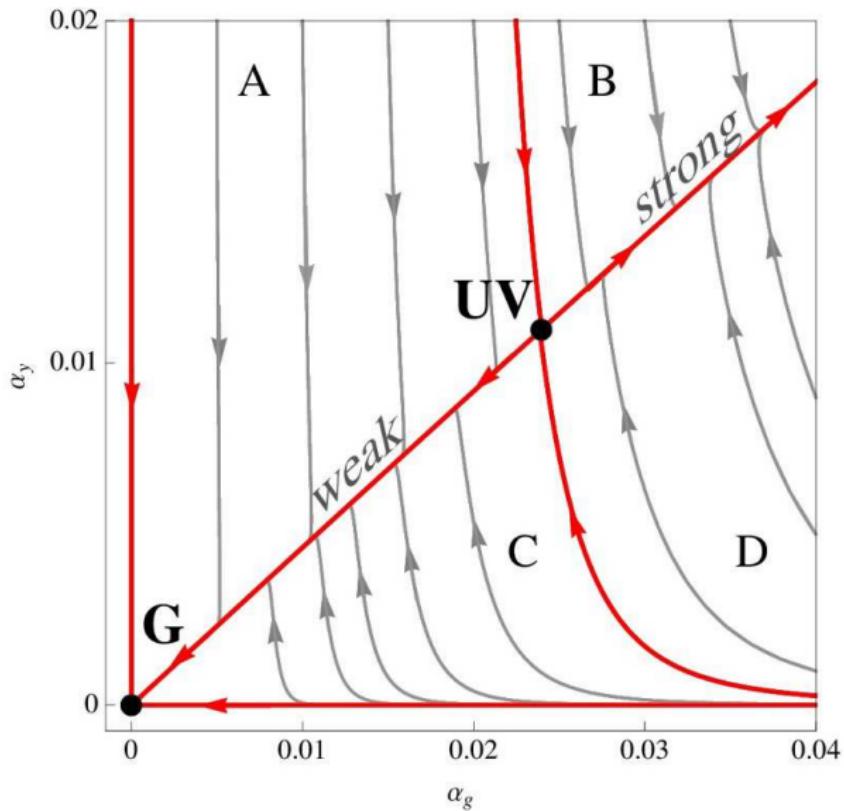
$$(\alpha_{g*}, \alpha_{y*}) = \left( -\frac{4\epsilon}{75 + 26\epsilon}, 0 \right) \quad (9)$$

- For  $\epsilon > 0$ , Litim-Sannino

$$\begin{aligned} (\alpha_{g*}, \alpha_{y*}) &= \left( \frac{2(13\epsilon + 2\epsilon^2)}{57 - 46\epsilon - 8\epsilon^2}, \frac{12\epsilon}{57 - 46\epsilon - 8\epsilon^2} \right) \quad (10) \\ &\approx (0.456\epsilon + O(\epsilon^2), 0.211\epsilon + O(\epsilon^2)) \end{aligned}$$

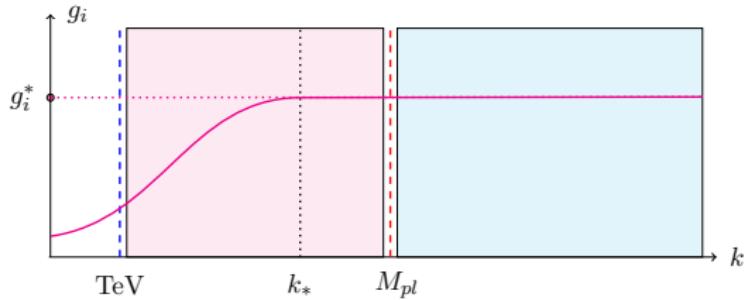
[D.F. Litim and F. Sannino, JHEP 1412 (2014) 178 ]

# Phase diagram

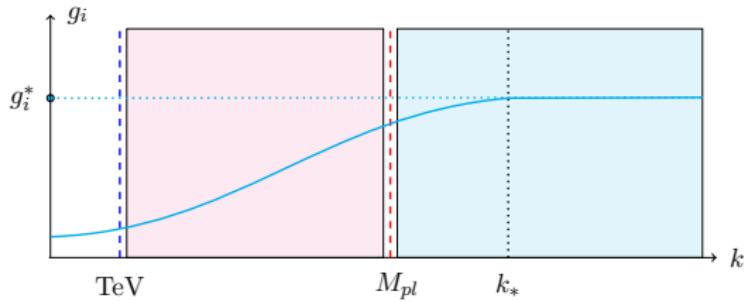


# Fixed-point regimes

- $k_* < M_{pl}$



- $k_* > M_{pl}$



# A class of BSM models

- Are there phenomenologically viable AS gauge-Yukawa theories?

Finite  $N_f$  and  $N_c$

[A. Bond, D. Litim, Eur.Phys.J. C77 (2017) no.6, 429, arXiv:1608.00519 [hep-th]]

[A. Bond, G. Hiller, K. Kowalska, D. Litim, JHEP 1708 (2017) 004, arXiv:1702.01727 [hep-ph]]

[G.M. Pelaggi, A.D. Plascencia, A. Salvio, F. Sannino, Y. Smirnov, A. Strumia, Phys.Rev. D97 (2018) no.9, 095013 arXiv:1708.00437 [hep-th]]

[R.B. Mann, J.R. Meffe, F. Sannino, T.G. Steele, Z.W. Wang and C. Zhang, Phys. Rev. Lett. 119, 261802 (2017), arXiv:1707.02942 [hep-th]]

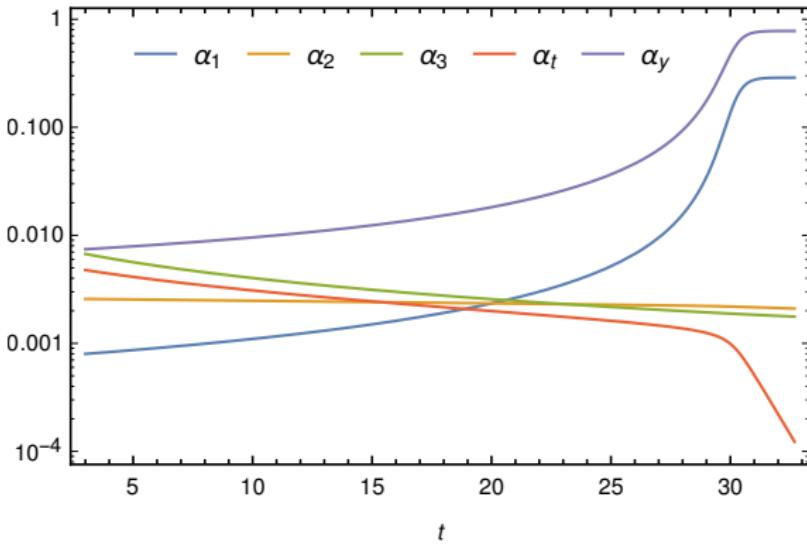
Simplest models use additional vector-like fermions.

# A class of BSM models

- Group:  $SU_c(3) \times SU_L(2) \times U_Y(1)$ .
- Add  $N_f$  families of vector-like fermions  $\psi_i$  minimally coupled to SM and Yukawa interactions new scalars  $S$ .
- $\mathcal{L} = \mathcal{L}_{SM} + \text{Tr}(\bar{\psi} i \not{D} \psi) + \text{Tr}(\partial_\mu S^\dagger \partial_\mu S) - y \text{Tr}(\bar{\psi}_L S \psi_R + \bar{\psi}_R S^\dagger \psi_L)$ .
- Representation labels  $(p, q)$ ,  $\ell$ ,  $Y$  and  $N_f$ .
- Couplings:  $(\alpha_1, \alpha_2, \alpha_3, \alpha_t, \alpha_y, \alpha_\lambda)$ , where  $\alpha_i \equiv \left(\frac{g_i}{4\pi}\right)^2$  and  $\alpha_\lambda \equiv \frac{\lambda}{(4\pi)^2}$ .

# A promising model

$$N_f = 3, \ell = 1/2, Y = 3/2, p = q = 0$$
$$\alpha_1^* = 0.188, \alpha_2^* = 0, \alpha_3^* = 0, \alpha_t^* = 0, \alpha_y^* = 0.778$$
$$\lambda_1 = 33.2, \lambda_2 = -3.36, \lambda_3 = -0.817, \lambda_4 = 0, \lambda_5 = 0.$$



# Requirements

- Stability under loop expansions
- SM matching at Fermi scale

# Criteria for stability

- Small couplings

$$\alpha_i^* \equiv \left( \frac{g_i^*}{4\pi} \right)^2 \lesssim O(1).$$

- Small critical exponents

$$\beta_i = -d_i g_i + \beta_i^q(g_j), M_{ij} = -d_i \delta_{ij} + \frac{\partial \beta_i^q}{\partial g_j}, \text{ demand } |\lambda_i| \lesssim O(1).$$

- Hierarchy in the loop contributions

At the FP  $0 = \beta_i = A_*^{(i)} + B_*^{(i)} + C_*^{(i)}$ ,  
demand  $\rho_i < \sigma_i < 1$  where  $\rho_i = |C_*^{(i)}|/|A_*^{(i)}|$  and  $\sigma_i = |B_*^{(i)}|/|A_*^{(i)}|$ .

# The search

## Parameter space

- $N_f = 1, 2, \dots, 300$
- $\ell = 1/2, 1, \dots, 10$
- $Y = 0, 1/2, 1, \dots, 10$

Singlet  $SU(3) \Rightarrow (N, \ell) : (1, 1), (2, 1/2), (3, 1/2), (4, 1/2)$

Fundamental  $SU(3) \Rightarrow (N, \ell) : (1, 1/2), (1, 5/2), (1, 3), (1, 7/2), (1, 4), (1, 9/2), (2, 1), (2, 3/2), (2, 2), (3, 1/2), (3, 1), (4, 1/2), (5, 1/2).$

Adjoint  $SU(3) \Rightarrow (N, \ell) : \text{None}$

Stable models have the  $U(1)$  triviality problem.  
 $\Rightarrow$  no satisfactory UV fixed points.

# Results

- Instability of fixed points with large scaling exponents.
- Low-dimensional representations are preferable
- Stable solutions show that there are no UV perturbative FPs that can be connected to the  $TeV$  physics.

- Stability condition rules out other models appearing in the literature.

[A. Bond, G. Hiller, K. Kowalska, D. Litim, Directions for model building from asymptotic safety, JHEP 1708 (2017) 004]

- Explore non-abelian embeddings.

[B. Bajc, F. Sannino, Asymptotically safe grand unification, JHEP 1612 (2016) 141]

[A. Eichhorn, A. Held, C. Wetterich, Quantum-gravity predictions for the fine-structure constant, Phys.Rev. D99 (2019) no.3, 035030]

- Consider gravity+matter systems.

# Gravitational running

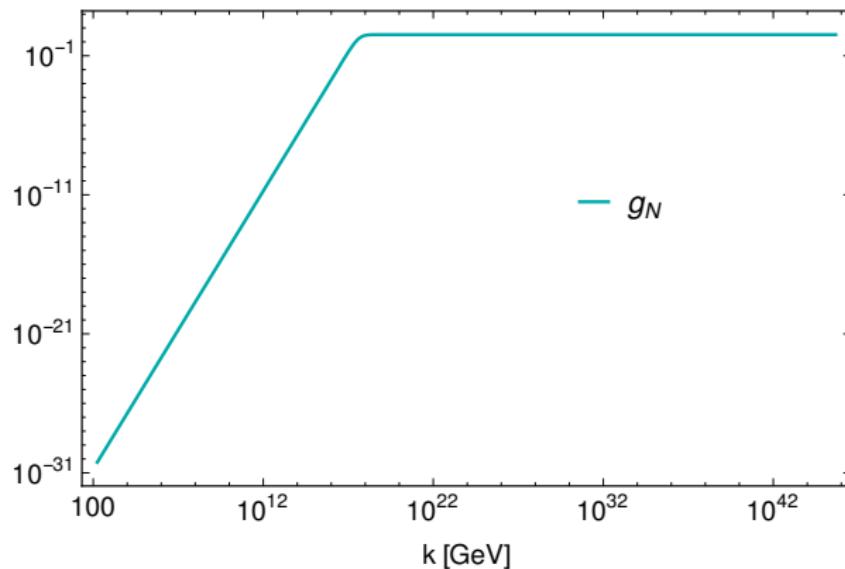


Figure : RG flow of the dimensionless Newton coupling  $g_N$  in the EH truncation.

# Gravity plus matter

Gravity modifies the beta functions of matter couplings by universal (flavor-independent) terms.

$$\beta_{g_i} = \beta_{g_i}^{Matter} + f_g g_i \quad (11)$$

$$\beta_{Y_i} = \beta_{Y_i}^{Matter} + f_y Y_i \quad (12)$$

$$\beta_{\lambda_i} = \beta_{\lambda_i}^{Matter} + f_\lambda \lambda_i \quad (13)$$

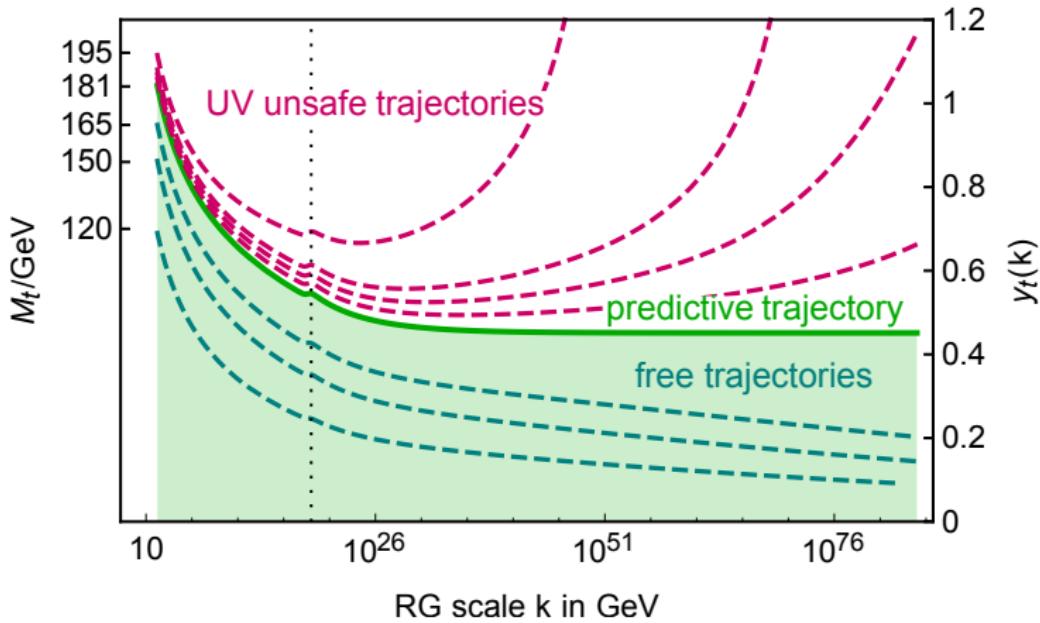
These can generate nontrivial fixed points for matter couplings

[S. P. Robinson, F. Wilczek, Complete asymptotically safe embedding of the standard model, Phys. Rev. Lett. 96 (2006) 231601]

[A. Salvio, A. Strumia, Agravity, JHEP 1406 (2014) 080]

[O. Zanusso, L. Zambelli, G. P. Vacca, R. Percacci, Gravitational corrections to Yukawa systems, Phys. Lett. B689 (2010) 90]

# Calculation of top mass



$$f_g = G_N \frac{5(1 - 4\Lambda)}{18\pi(1 - 2\Lambda)^2}, \quad f_y = G_N \frac{\Lambda(235 - \Lambda(103 + 56\Lambda)) - 96}{12\pi(3 + 2\Lambda(-5 + 4\Lambda))^2}$$

[A. Eichhorn and A. Held, Phys. Lett. B777, (2018) 217]

# Gauge-Quark-Yukawa system

Gauge sector

$$\frac{dg_i}{dt} = \frac{1}{16\pi^2} b_i g_i^3 - \textcolor{blue}{f_g g_i}.$$

Up-type Yukawas

$$\begin{aligned} \beta_{Y_U} = \frac{1}{16\pi^2} & \left[ \frac{3}{2} Y_U Y_U^\dagger Y_U - \frac{3}{2} Y_D Y_D^\dagger Y_U + 3 \operatorname{Tr} \left( Y_U Y_U^\dagger + Y_D Y_D^\dagger \right) Y_U \right. \\ & \left. - \left( \frac{17}{12} g_1^2 + \frac{9}{4} g_2^2 + 8g_3^2 \right) Y_U \right] - \textcolor{blue}{f_y Y_U}. \end{aligned}$$

Down-type Yukawas

$$\begin{aligned} \beta_{Y_D} = \frac{1}{16\pi^2} & \left[ \frac{3}{2} Y_D Y_D^\dagger Y_D - \frac{3}{2} Y_U Y_U^\dagger Y_D + 3 \operatorname{Tr} \left( Y_U Y_U^\dagger + Y_D Y_D^\dagger \right) Y_D \right. \\ & \left. - \left( \frac{5}{12} g_1^2 + \frac{9}{4} g_2^2 + 8g_3^2 \right) Y_D \right] - \textcolor{blue}{f_y Y_D}. \end{aligned}$$

## Mass basis

- We introduce the unitary matrices  $V_L^U$  and  $V_L^D$  such that

$$V_L^U M_U V_L^{U\dagger} = D_U^2 = \text{diag}[y_u^2, y_c^2, y_t^2],$$

$$V_L^D M_D V_L^{D\dagger} = D_D^2 = \text{diag}[y_d^2, y_s^2, y_b^2].$$

- Thus, we get the CKM-matrix

$$V = V_L^U V_L^{D\dagger} = \begin{bmatrix} V_{ud} & V_{us} & V_{ub} \\ V_{cd} & V_{cs} & V_{cb} \\ V_{td} & V_{ts} & V_{tb} \end{bmatrix}.$$

- Set of variables:  $y_i = (y_u, y_c, y_t)$ ,  $y_\rho = (y_d, y_s, y_b)$  and 4 CKM elements  $|V_{i\rho}|^2$

# Diagonalized basis

Up-type Yukawas

$$\frac{dy_i}{dt} = \frac{y_i}{16\pi^2} \left( 3 \sum_j y_j^2 + 3 \sum_\rho y_\rho^2 - \left( \frac{17}{12} g_1^2 + \frac{9}{4} g_2^2 + 8g_3^2 \right) + \frac{3}{2} y_i^2 - \frac{3}{2} \sum_\rho y_\rho^2 |V_{i\rho}|^2 \right) - f_y y_i.$$

Down-type Yukawas

$$\frac{dy_\rho}{dt} = \frac{y_\rho}{16\pi^2} \left( 3 \sum_j y_j^2 + 3 \sum_\alpha y_\alpha^2 - \left( \frac{5}{12} g_Y^2 + \frac{9}{4} g_2^2 + 8g_3^2 \right) + \frac{3}{2} y_\rho^2 - \frac{3}{2} \sum_i y_i^2 |V_{i\rho}|^2 \right) - f_y y_\rho.$$

CKM elements

$$\begin{aligned} \beta_{|V_{i\rho}|^2} = & -\frac{3}{2} \left( \sum_{\sigma, j \neq i} \frac{y_i^2 + y_j^2}{y_i^2 - y_j^2} y_\sigma^2 (V_{i\sigma} V_{j\sigma}^* V_{j\rho} V_{i\rho}^* + V_{i\sigma}^* V_{j\sigma} V_{j\rho}^* V_{i\rho}) \right. \\ & \left. + \sum_{j, \sigma \neq \rho} \frac{y_\rho^2 + y_j^2}{y_\rho^2 - y_j^2} y_j^2 (V_{j\sigma}^* V_{j\rho} V_{i\sigma} V_{i\rho}^* + V_{j\sigma} V_{j\rho}^* V_{i\sigma}^* V_{i\rho}) \right). \end{aligned}$$

# Two generations

- CKM matrix

$$V = \begin{bmatrix} V_{tb} & V_{ts} \\ V_{cb} & V_{cs} \end{bmatrix}.$$

- We choose  $|V_{tb}|^2 = W$ , such that  $|V_{ts}|^2 = 1 - W$ ,  
 $|V_{cb}|^2 = 1 - W$  and  $|V_{cs}|^2 = W$ .

$$V_2 = \begin{bmatrix} W & 1 - W \\ 1 - W & W \end{bmatrix},$$

$$\frac{dW}{dt} = -\frac{3}{16\pi^2}(1-W)W \left[ \frac{y_t^2 + y_c^2}{y_t^2 - y_c^2}(y_b^2 - y_s^2) + \frac{y_b^2 + y_s^2}{y_b^2 - y_s^2}(y_t^2 - y_c^2) \right].$$

- Two important points:  $W = 0$  and  $W = 1$ .

# Two generations

- Yukawa beta-functions

$$\begin{aligned}\beta_{y_t} = \frac{y_t}{16\pi^2} & \left( 3(y_t^2 + y_c^2 + y_b^2 + y_s^2) + 3y_t^2 - \frac{3}{2}y_b^2W - \frac{3}{2}y_s^2(1-W) \right. \\ & \left. - \frac{9}{4}g_2^2 - 8g_3^2 - \frac{17}{12}g_1^2 \right) - f_y y_t.\end{aligned}\quad (14)$$

$$\begin{aligned}\beta_{y_b} = \frac{y_b}{16\pi^2} & \left( 3(y_t^2 + y_c^2 + y_b^2 + y_s^2) + 3y_b^2 - \frac{3}{2}y_t^2W - \frac{3}{2}y_c^2(1-W) \right. \\ & \left. - \frac{9}{4}g_2^2 - 8g_3^2 - \frac{5}{12}g_1^2 \right) - f_y y_b.\end{aligned}\quad (15)$$

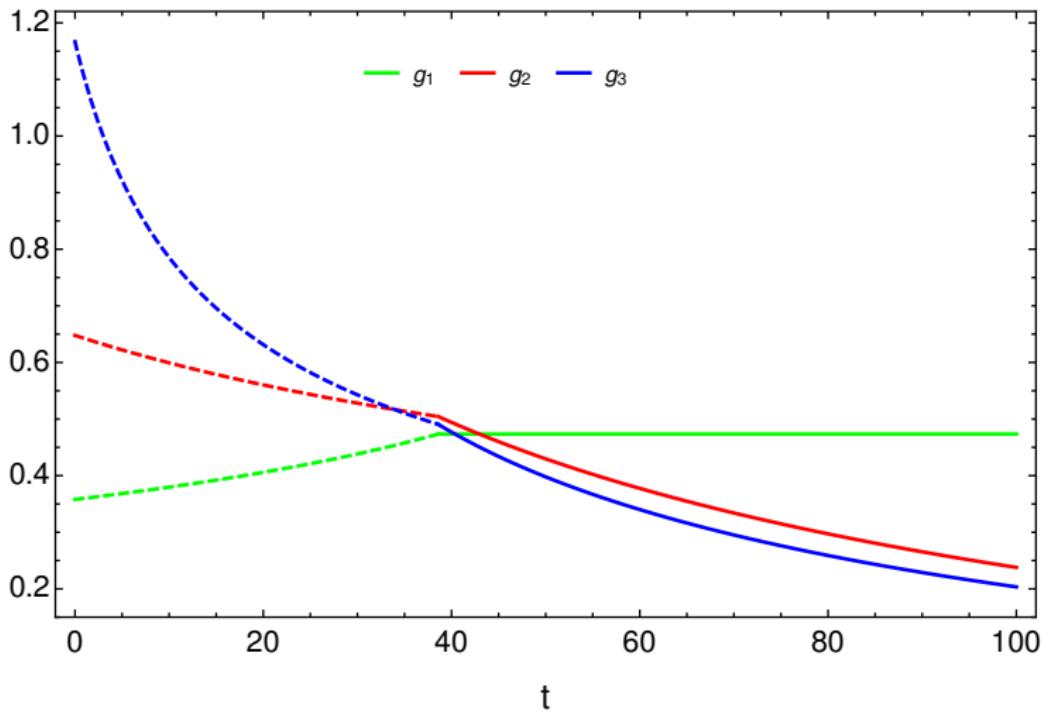
For  $y_c$  and  $y_b$ , we have  $(t, b) \leftrightarrow (c, s)$ .

- Using  $g_{1*} = 4\pi\sqrt{6f_g/41}$ , demanding  $y_{t*} > y_{c*}$  and  $y_{b*} > y_{s*}$

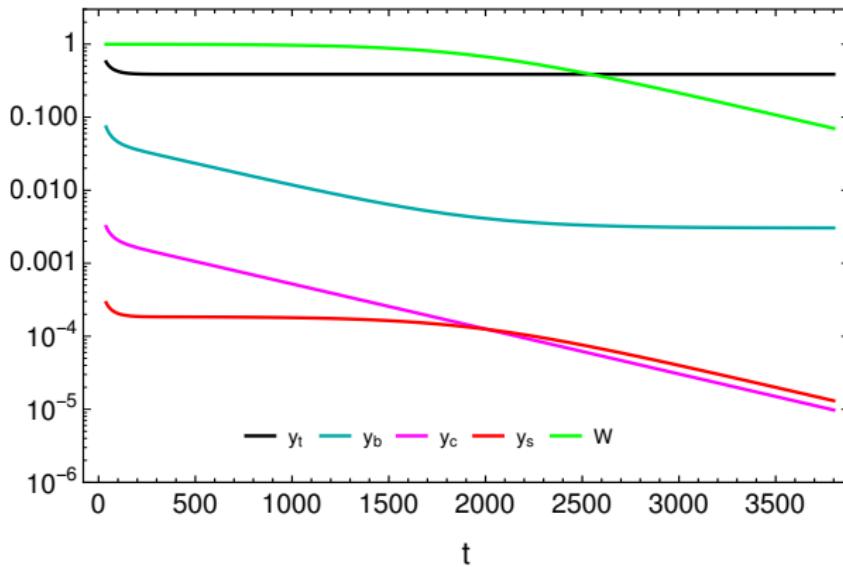
$$W_* = 0, \quad y_{t*} = \frac{4\pi}{\sqrt{15}}\sqrt{f_g + 2f_y}, \quad y_{b*} = \frac{4\pi}{\sqrt{615}}\sqrt{-19f_g + 82f_y}. \quad (16)$$

$$y_{t*}^2 - y_{b*}^2 = \frac{2}{3}g_{1*}^2. \quad (17)$$

# Two generations - Gauge running



# Two generations - Yukawa running



**Figure :** Trajectory emanating from the asymptotically safe fixed point. IR predictions:  $M_t = 185$  GeV (173.21),  $M_c = 1.27$  GeV,  $M_b = 4.18$  GeV,  $M_s = 0.096$  GeV,  $W = 0.9984$ (0.9980).

# Three generations

- Yukawa couplings  $y_i = (y_u, y_c, y_t)$ ,  $y_\rho = (y_d, y_s, y_b)$ .
- CKM matrix

$$V = V_L^U V_L^{D\dagger} = \begin{bmatrix} V_{ud} & V_{us} & V_{ub} \\ V_{cd} & V_{cs} & V_{cb} \\ V_{td} & V_{ts} & V_{tb} \end{bmatrix}.$$

- We choose  $|V_{ud}|^2 = X$ ,  $|V_{us}|^2 = Y$ ,  $|V_{cd}|^2 = Z$ ,  $|V_{cs}|^2 = W$

$$V_2 = \begin{bmatrix} X & Y & 1 - X - Y \\ Z & W & 1 - Z - W \\ 1 - X - Z & 1 - Y - W & X + Y + Z + W - 1 \end{bmatrix}.$$

# CKM beta-functions

$$\begin{aligned} \frac{dX}{dt} = & -\frac{3}{(4\pi)^2} \left[ \frac{y_u^2 + y_c^2}{y_u^2 - y_c^2} \left\{ (y_d^2 - y_b^2) X Z + \frac{(y_b^2 - y_s^2)}{2} (W(1-X) + X - (1-Y)(1-Z)) \right\} \right. \\ & + \frac{y_u^2 + y_t^2}{y_u^2 - y_t^2} \left\{ (y_d^2 - y_b^2) X (1-X-Z) + \frac{(y_b^2 - y_s^2)}{2} ((1-Y)(1-Z) - X(1-2Y) - W(1-X)) \right\} \\ & + \frac{y_d^2 + y_s^2}{y_d^2 - y_s^2} \left\{ (y_u^2 - y_t^2) X Y + \frac{y_t^2 - y_c^2}{2} (W(1-X) + X - (1-Y)(1-Z)) \right\} \\ & \left. + \frac{y_d^2 + y_b^2}{y_d^2 - y_b^2} \left\{ (y_u^2 - y_t^2) X (1-X-Y) + \frac{y_t^2 - y_c^2}{2} ((1-Y)(1-Z) - X(1-2Z) - W(1-X)) \right\} \right] \end{aligned}$$

$$\begin{aligned} \frac{dY}{dt} = & -\frac{3}{(4\pi)^2} \left[ \frac{y_u^2 + y_c^2}{y_u^2 - y_c^2} \left\{ \frac{(y_b^2 - y_d^2)}{2} (W(1-X) + X - (1-Y)(1-Z)) + (y_s^2 - y_b^2) Y W \right\} \right. \\ & + \frac{y_u^2 + y_t^2}{y_u^2 - y_t^2} \left\{ \frac{(y_b^2 - y_d^2)}{2} ((1-Y)(1-Z) - W(1-X) - X(1-2Y)) + (y_s^2 - y_b^2) Y (1-Y-W) \right\} \\ & + \frac{y_s^2 + y_d^2}{y_s^2 - y_d^2} \left\{ (y_u^2 - y_t^2) X Y + \frac{y_t^2 - y_c^2}{2} (W(1-X) + X - (1-Y)(1-Z)) \right\} \\ & \left. + \frac{y_s^2 + y_b^2}{y_s^2 - y_b^2} \left\{ (y_u^2 - y_t^2) Y (1-X-Y) + \frac{(y_c^2 - y_t^2)}{2} (W(1-X-2Y) + X - (1-Z)(1-Y)) \right\} \right] \end{aligned}$$

# CKM beta-functions

$$\frac{dZ}{dt} = -\frac{3}{(4\pi)^2} \left[ \frac{y_c^2 + y_u^2}{y_c^2 - y_u^2} \left\{ (y_d^2 - y_b^2) X Z + \frac{(y_b^2 - y_s^2)}{2} (W(1-X) + X - (1-Z)(1-Y)) \right\} \right. \\ \left. + \frac{y_c^2 + y_t^2}{y_c^2 - y_t^2} \left\{ (y_d^2 - y_b^2) Z(1-X-Z) + \frac{(y_s^2 - y_b^2)}{2} (W(1-X-2Z) + X - (1-Y)(1-Z)) \right\} \right. \\ \left. + \frac{y_d^2 + y_s^2}{y_d^2 - y_s^2} \left\{ \frac{(y_u^2 - y_t^2)}{2} ((1-Y)(1-Z) - X - W(1-X)) + (y_c^2 - y_t^2) Z W \right\} \right. \\ \left. + \frac{y_d^2 + y_b^2}{y_d^2 - y_b^2} \left\{ \frac{(y_t^2 - y_u^2)}{2} ((1-Z)(1-Y) - W(1-X) - X(1-2Z)) + (y_c^2 - y_t^2) Z(1-Z-W) \right\} \right]$$

$$\frac{dW}{dt} = -\frac{3}{(4\pi)^2} \left[ \frac{y_c^2 + y_u^2}{y_c^2 - y_u^2} \left\{ (y_s^2 - y_b^2) W Y + \frac{(y_b^2 - y_d^2)}{2} ((1-X)W + X - (1-Y)(1-Z)) \right\} \right. \\ \left. + \frac{y_c^2 + y_t^2}{y_c^2 - y_t^2} \left\{ (y_s^2 - y_b^2) W(1-Y-W) + \frac{(y_b^2 - y_d^2)}{2} ((1-Y)(1-Z) - X - W(1-X-2Z)) \right\} \right. \\ \left. + \frac{y_s^2 + y_d^2}{y_s^2 - y_d^2} \left\{ (y_c^2 - y_t^2) W Z + \frac{(y_t^2 - y_u^2)}{2} Z((1-X)W + X - (1-Y)(1-Z)) \right\} \right. \\ \left. + \frac{y_s^2 + y_b^2}{y_s^2 - y_b^2} \left\{ (y_c^2 - y_t^2) W(1-Z-W) + \frac{(y_t^2 - y_u^2)}{2} ((1-Y)(1-Z) - X - W(1-X-2Y)) \right\} \right]$$

# Three generations

- CKM fixed points

$$M_{123} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad M_{132} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \quad M_{321} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix},$$
$$M_{213} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad M_{312} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, \quad M_{231} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}.$$

- We seek for solutions of  $\beta_{y_i} = 0 = \beta_{y_\rho}$  in each of the cases  $|V|^2 = M_{abc}$ .
- Solutions for  $|V|^2$  are obtained from  $M_{123}$  by applying the corresponding  $M_{abc}^{-1}$  to  $y_\rho = (y_d, y_s, y_b)$
- We select the positive solutions having at most two zero couplings.

## Three generations

- 392 solutions for each  $V_2$
- We find 1 plane of fixed-points and 6 lines. We impose the conditions  $y_{t*} > y_{c*} > y_{u*}$  and  $y_{b*} > y_{s*} > y_{d*}$ .
- Only the case remains

$$V_2^* = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- Three solutions remain

$$y_{u*}^2 = \frac{4\pi^2}{123}(47f_g + 82f_y) - y_{c*}^2 - y_{t*}^2, \quad y_{s*}^2 = -\frac{32f_g\pi^2}{41} + y_{c*}^2,$$
$$y_{d*}^2 = \frac{4\pi^2}{123}(23f_g + 82f_y) - y_{c*}^2 - y_{t*}^2, \quad y_{b*}^2 = -\frac{32f_g\pi^2}{41} + y_{t*}^2.$$

# Three generations

$$y_{c*}^2 = \frac{4\pi^2}{123}(35f_g + 82f_y) - y_{t*}^2 , \quad y_{b*}^2 = -\frac{32f_g\pi^2}{41} + y_{t*}^2 ,$$

$$y_{s*}^2 = \frac{4\pi^2}{123}(11f_g + 82f_y) - y_{t*}^2 , \quad y_{d*}^2 = 0 , \quad y_u^2 = 0 .$$

$$y_{c*}^2 = \frac{4\pi^2}{123}(23f_g + 82f_y) - y_{t*}^2 , \quad y_{b*}^2 = -\frac{32f_g\pi^2}{41} + y_{t*}^2 ,$$

$$y_{s*}^2 = \frac{4\pi^2}{123}(-f_g + 82f_y) - y_{t*}^2 , \quad y_u^2 = \frac{32f_g\pi^2}{41} , \quad y_d^2 = 0 .$$

- These fixed-points are UV repulsive.
- Other non-trivial CKM fixed-points generate negative Yukawa couplings.

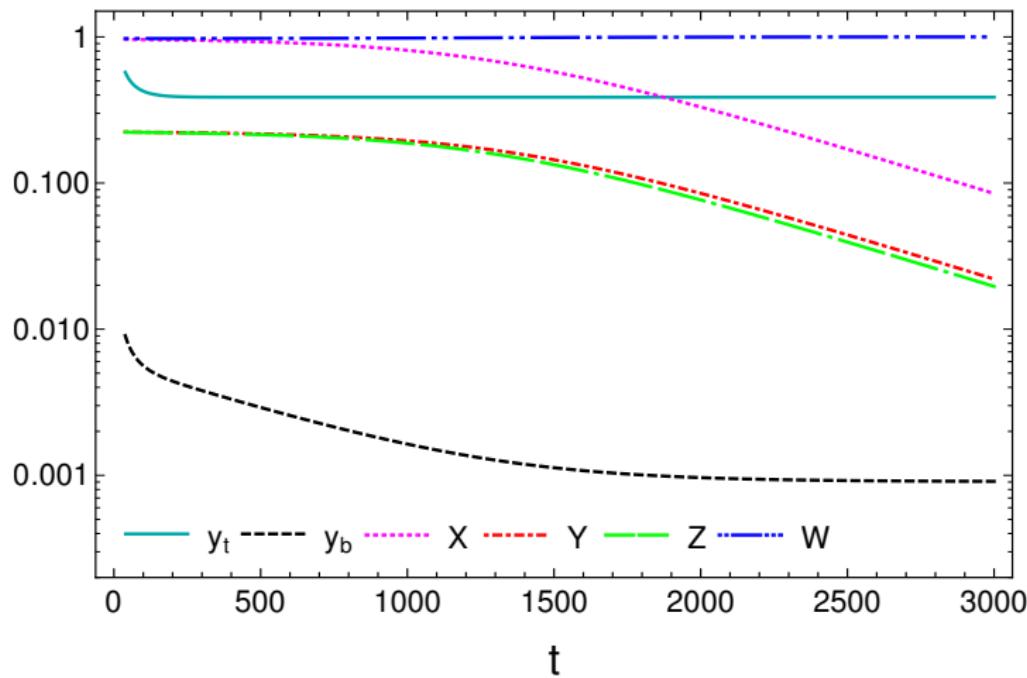
# Limit

We approach  $y_u \rightarrow 0, y_d \rightarrow 0, y_s \rightarrow 0, y_c \rightarrow 0,$   
 $\implies$  solvable system

$$y_{t*} = \frac{4\pi}{\sqrt{15}} \sqrt{f_g + 2f_y}, \quad y_{b*} = \frac{4\pi}{\sqrt{615}} \sqrt{-19f_g + 82f_y}.$$

$$V_2^* = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

# Running couplings



	Flow	Exp.
$M_t$	185 GeV	173 GeV
$M_b$	4.2 GeV	4.18 GeV
$M_c$	1.27 GeV	1.275 GeV
$M_s$	96 MeV	95 MeV
$M_d$	4.7 MeV	4.7 MeV
$M_u$	2.2 MeV	2.2 MeV
$X$	0.9326	0.9495
$Y$	0.05053	0.05040
$Z$	0.05035	0.05034
$W$	0.94961	0.94788

# Conclusions

- It seems it is not possible to render the SM AS with a finite number of extra fields.
- A GUT extension can provide a solution to the triviality problem.
- The solution of the Landau pole in the  $U(1)$  sector opens the possibility of exploring interesting UV properties of the SM.
- Using gravity effects, we can (partially) have an understanding of the mass hierarchy in the quark sector.
- A full understanding of the complete flavor structure of the SM remains an open question.