

Detector Simulation — Geant4

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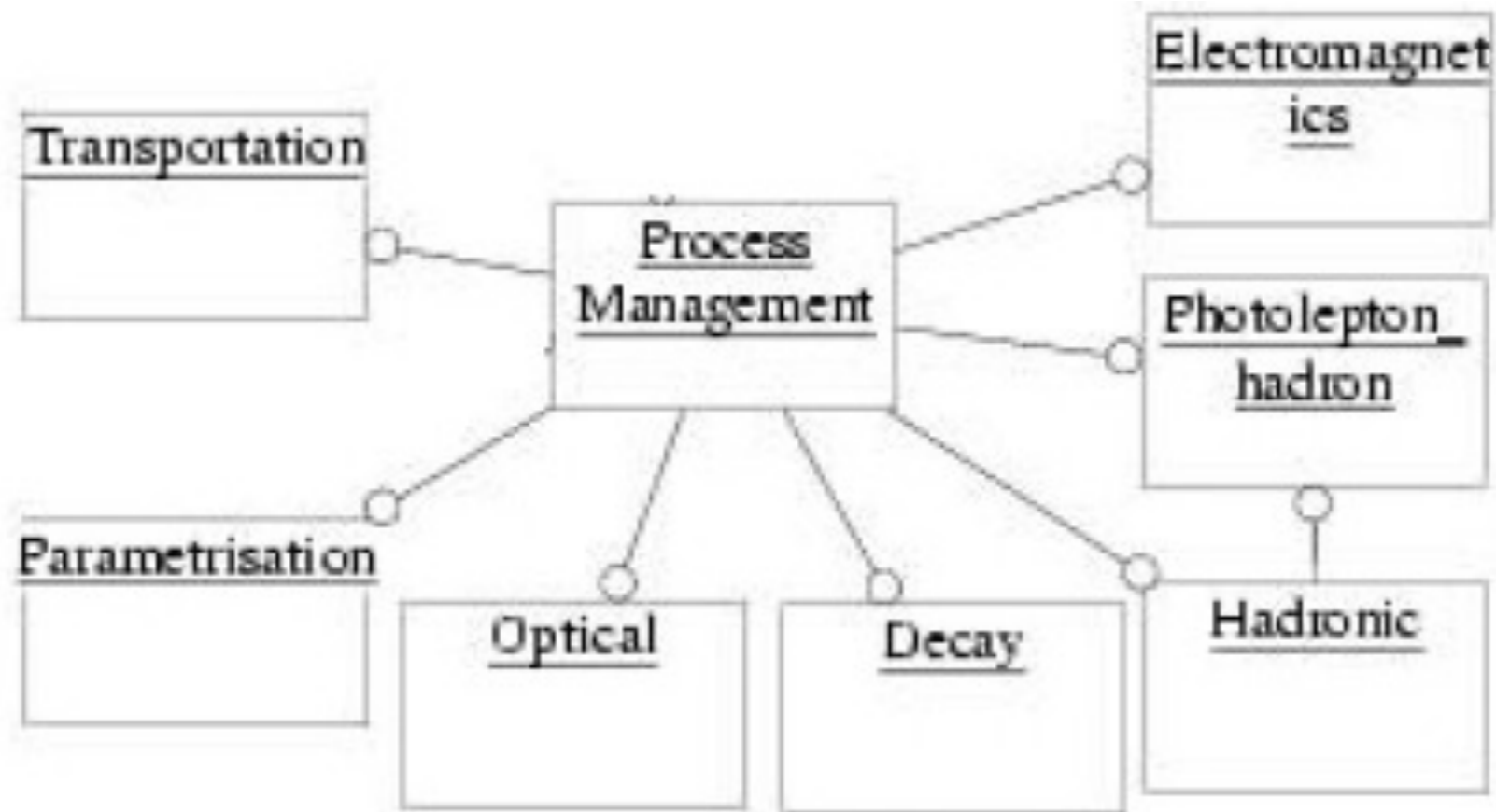
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GEANT4: Physics Process & List

Physics Lists

- Geant4 provides the possibility of simulating the physics processes of a variety of particles
- each such particle can have interactions of different types: strong, electromagnetic or weak and each such interaction can be described by different models
- unlike many other simulation tools, Geant4 leaves it to the user to decide on which particles, which interactions and which models are to be used during the simulation step
- declaration of the list of particles and the choice of models is done using the physics list
- the toolkit provides handles for a few well-defined physics lists which are suitable for certain specific types of application

Processes in Geant4



- Processes describe how particles interact with material or with a volume
- Three basic types:
 - At rest process (e.g. decay at rest)
 - Continuous process (e.g. ionisation)
 - Discrete process (e.g. Compton scattering)
- Transportation is also a process
 - Interacting with the volume boundary
- A process which requires the shortest interaction length limits the step

Types of Processes

- There are several types of modules which can be combined to define the physics list
 - electromagnetic physics
 - extra physics processes for photons and leptons
 - decays
 - hadronic elastic
 - hadronic inelastic
 - stopping particles and capture processes
 - ion nuclear interactions
 - step limits
 - others
- The others category includes optical photons, exotic physics processes, thermal neutron transport models,
- The user needs to define the physics list through the 3 handles:
 - RegisterPhysics
 - ReplacePhysics
 - RemovePhysics

An Example of Making a Physics List

```
// EM Physics
RegisterPhysics(new G4EmStandardPhysics(verbosity));

// Synchrotron Radiation & GN Physics
G4EmExtraPhysics* gn = new G4EmExtraPhysics(verbosity);
RegisterPhysics(gn);

// Decays
this->RegisterPhysics(new G4DecayPhysics(verbosity));

// Hadron Elastic scattering
RegisterPhysics(new G4HadronElasticPhysics(verbosity));

// Hadron Physics
RegisterPhysics(new G4HadronPhysicsFTF_BIC(verbosity));

// Stopping Physics
RegisterPhysics(new G4StoppingPhysics(verbosity));

// Ion Physics
RegisterPhysics(new G4IonPhysics(verbosity));

// Neutron tracking cut
RegisterPhysics(new G4NeutronTrackingCut(verbosity));
```

Electromagnetic Physics

- Applicable to
 - electrons and positrons
 - γ , X-ray and optical photons
 - muons
 - charged hadrons
 - ions
- Several physics models are available. Standard EM physics is extended to low energies using many data-driven techniques to improve the quality of simulation at low energies
- *All obey the same abstract Process interface:* transparent to tracking

Models available for

- Multiple scattering
- Bremsstrahlung
- Ionization
- Annihilation
- Photoelectric effect
- Compton scattering
- Pair production
- Rayleigh scattering
- γ conversion
- Synchrotron radiation
- Transition radiation
- Reflection, refraction
- Cherenkov radiation
- Scintillation
-

Geant4 Options for EM Physics

- There are 10+ options for EM physics
 - opt1 (EMV): a fast but less precise version used in HE physics lists
 - opt2 (EMX): also a fast and less precise version for HE physics lists
 - opt3 (EMY): provides a more accurate simulation of photons and charged hadrons
 - opt4 (EMZ): most precise but slow description of EM physics for HE applications
 - LIV: similar to opt3 but models for photons and electrons make use of Livermore set of models
 - PEN: similar to opt3 with models for photons and electrons making use of Penelope set of models
 - _GS: substitute Urban multiple scattering models with the Goudschmidt-Sanderson model
 - _LE: low energy WentzelVI model is used for multiple scattering
 - WVI: WentzelVI model and ATIMA ion ionisation models are used for a better description of multiple scattering
 - _SS: single scattering models used on top of standard EM configuration
- Please note that the same model describes EM physics over the entire energy region

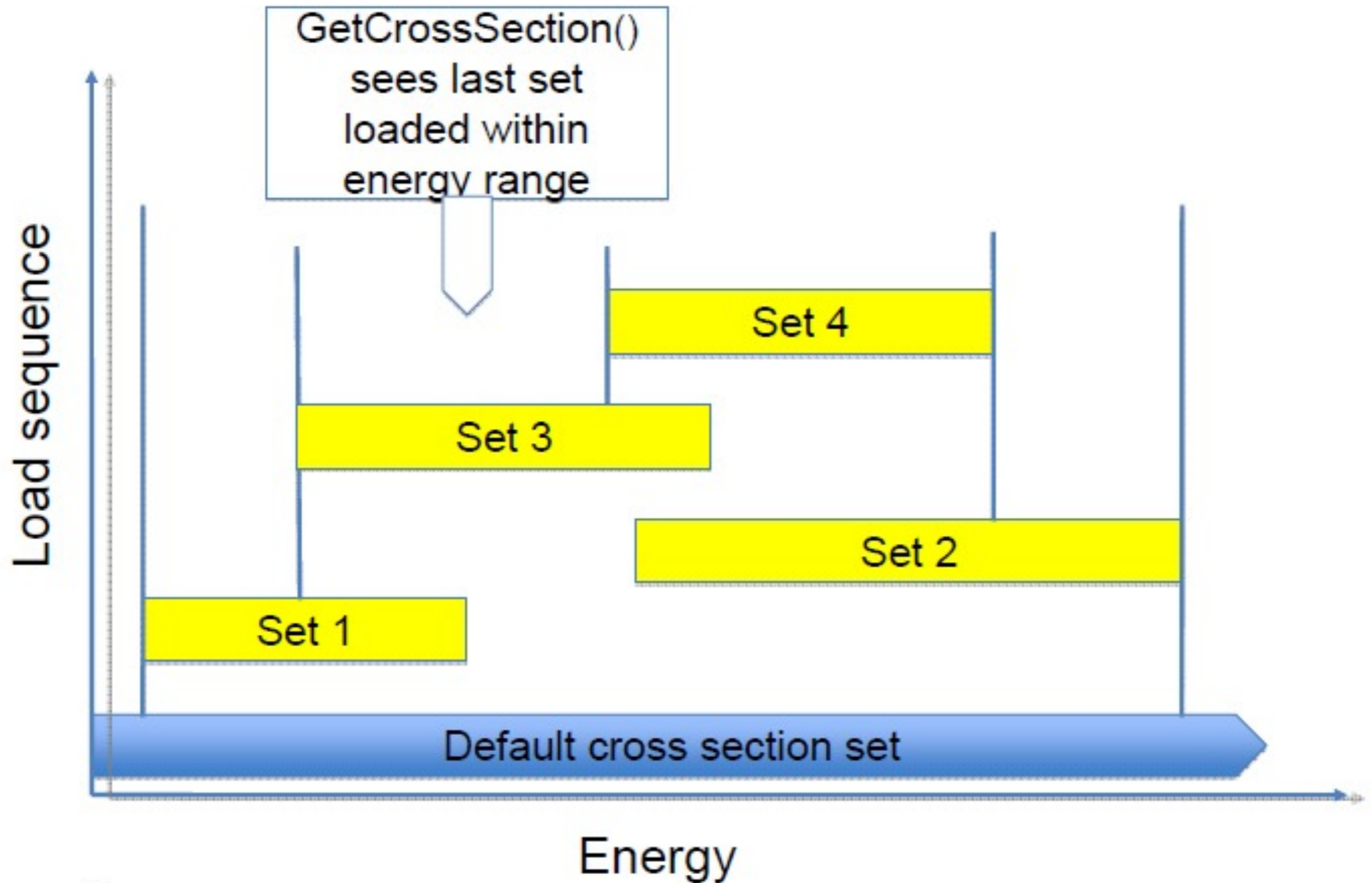
Hadronic Processes

- Hadronic processes are often implemented in terms of a **model** class
- There are usually several models for a given process
 - user must choose
 - can, and sometimes must, have more than one per process
- A process must also have **cross sections** assigned
 - here too, there are options
- Default cross-section sets are provided for each type of hadronic process
 - fission, capture, elastic, inelastic
 - can be overridden or completely replaced
- Different types of cross-section sets exist
 - some contain a few numbers to parametric the cross-section as a function of energy
 - some represent large databases
 - some are purely theoretical (equation driven)

Alternative Cross Sections

- Cross-section databases are available for low-energy neutrons
 - G4NDL available among the Geant4 distribution files
 - Livermore database (LEND) is also available
 - these are available with or without thermal cross-sections
- Cross section table is available for medium energy neutrons and protons
 - $14 \text{ MeV} < E < 20 \text{ MeV}$
- Several alternatives exist for ion-nucleus cross-section
 - these are empirical and parametrised cross-section formulae with some theoretical insight
 - these are good for $E/A < 10 \text{ GeV}$
- Alternative cross-sections also exist for pion cross-section

Cross Section Management



Models in Hadronic Interactions

- **Data-driven models:** When sufficient data are available with sufficient coverage over the phase space, a data-driven approach is the optimal way
 - neutron transport, photon evaporation, absorption at rest, isotope production, inclusive cross section,
- **Parametrised models:** Extrapolation of cross sections and parametrisation of multiplicity distributions and final state kinematics
 - adaptation of GHEISHA in some earlier versions of Geant4
- **Theory-based models:** These include a set of theoretical models describing hadronic interactions depending on the addressed energy range
 - diffractive string excitation, dual parton model or quark-gluon string model at medium to high energies
 - intra-nuclear cascade models air medium to low energies
 - nuclear evaporation, fission models,

Data Driven Hadronic Models

- These are characterised by lots of data on
 - cross sections
 - angular distributions
 - multiplicities, etc.
- To get interaction length and final state, these models depend on interpolation of data
 - cross sections, Legendre coefficients, ..
- Examples:
 - neutrons with $E < 20$ MeV
 - coherent elastic scattering (pp, np, nn)
 - radioactive decays

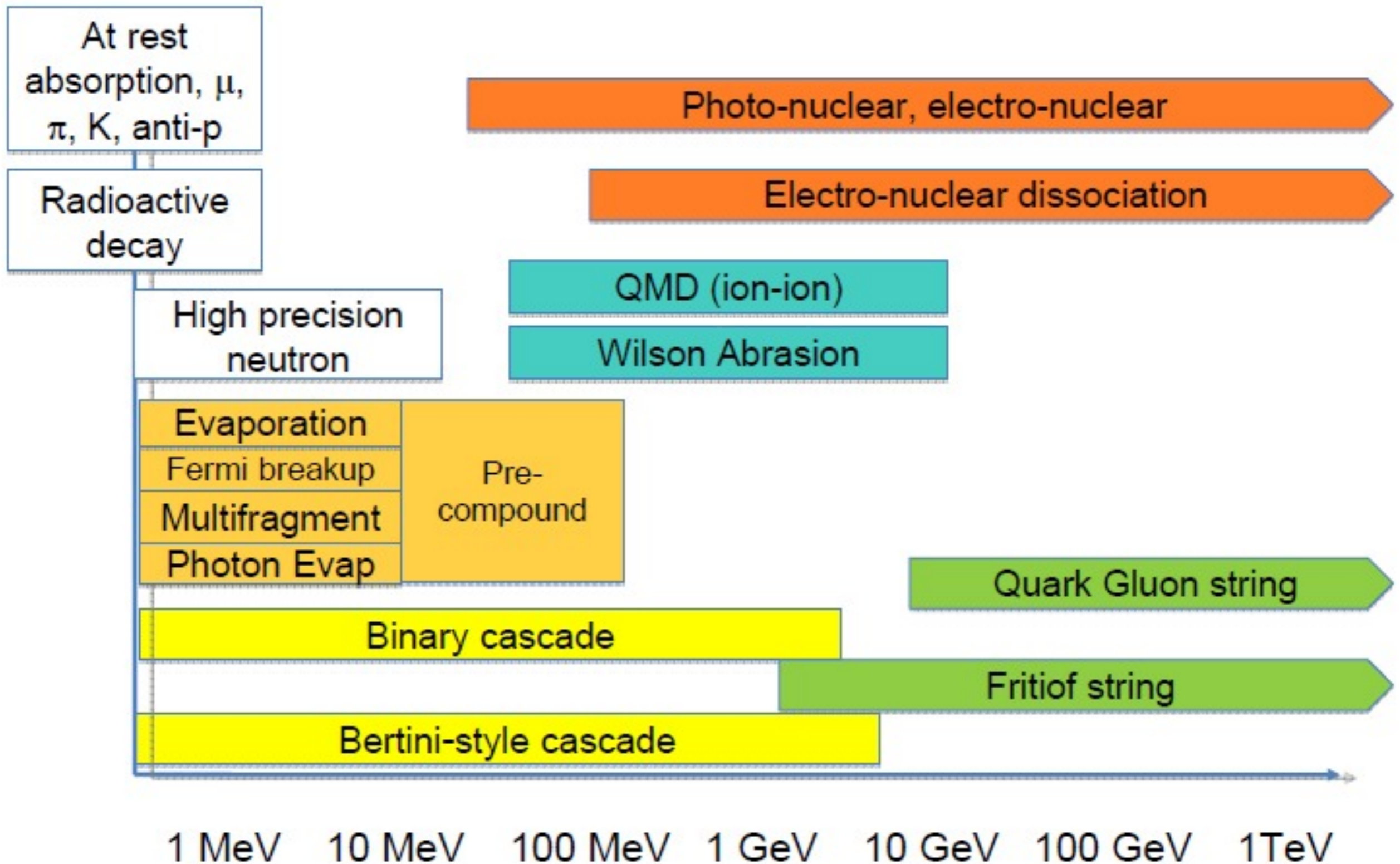
Theory Driven Hadronic Models

- These are dominated by theoretical arguments (QCD, Glauber theory, exciton model, ...)
- Final states (number and type of particles in the final state with their energy and angular distributions) are determined by sampling theoretically calculated distributions
- This type of models is preferred as they are the most predictive
- Examples:
 - quark-gluon string models (projectiles with $E > 20$ GeV)
 - intra-nuclear cascade models (intermediate energies)
 - nuclear de-excitation and break-up

Parametrised Hadronic Models

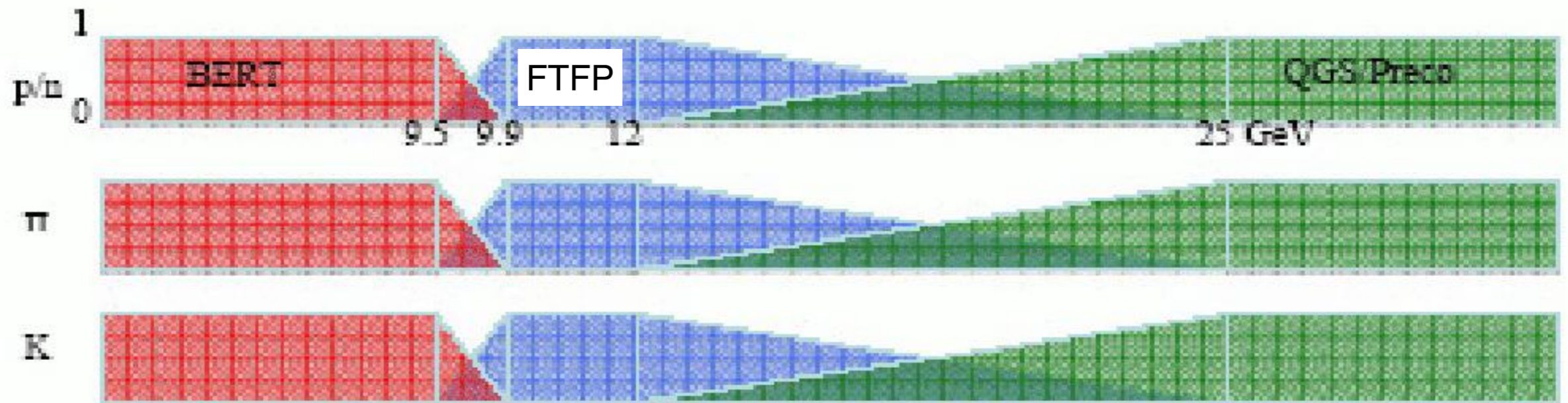
- Current versions do not contain any parametrised version. In versions preceding **Geant4** 10.0, two models existed. They were re-engineered versions of the **Fortran Gheisha** code used in **Geant3**
- These models depended mostly on fits to data with some theoretical guidance
- Two such models existed:
 - Low Energy Parametrised (**LEP**) for $E < 20$ GeV
 - High Energy Parametrised (**HEP**) for $E > 20$ GeV
 - each type referred to a collection of models (one for each type of hadron)
- These codes were fast and existed for all types of particles. But they were not detailed enough and there was no-one to maintain these codes

Partial Hadronic Model Inventory



Inelastic Hadronic Interactions

- No single model for hadron inelastic process can cover the entire energy region required in a high-energy physics experiment
 - Quark-gluon string models are good at high energies
 - Nuclear cascade models are good at medium and low energies
 - At very low energies, models for fission and pre-combination are required
- So all physics lists for inelastic hadronic interaction combine a number of models



Physics List Library

- There are a number of Physics Lists available in the Geant4 library which can be directly incorporated into the user code

- **FTFP_BERT**

High Energy Experiments

- FTFP_BERT_ATL
- FTFP_BERT_HP
- FTFP_BERT_TRV
- FTFP_INCLXX
- FTFQGSP_BERT
- FTF_BIC

- **QBBC**

Medical and Space Physics Applications

- **QGSP_BERT**

Former default for High Energy Experiments

- **QGSP_BERT_HP**

- **QGSP_BIC**

Cosmic Ray applications

- **QGSP_BIC_AIHHP**

- **QGSP_BIC_HIP**

- **QGSP_FTFP_BERT**

- **QGSP_INCLXX**

- **QGS_BIC**

- **Shielding**

Recommended for shielding studies

- **ShieldingLEND**

- **LBE**

- **NuBeam**

Main Program

- Simple example of the main program:

```
#include "G4RunManager.hh"
#include "G4UImanager.hh"
#include "Randomize.hh"
#include "time.h"
#include "MyDetectorConstruction.hh"
#include "MyEventAction.hh"
#include "MyPrimaryGeneratorAction.hh"
#include "G4PhysListFactory.hh"
#include "QGSP_BERT.hh"

int main(int argc, char** argv) {
    // Choose the Random engine
    CLHEP::HepRandom::setTheEngine(new CLHEP::RanecuEngine);
    // Set random seed with system time
    G4long seed = time(NULL);
    CLHEP::HepRandom::setTheSeed(seed);

    // Construct the default run manager, which manages start and stop simulation
    G4RunManager * runManager = new G4RunManager;

    // Set mandatory initialization classes:
    // =====
    // Initilization detector construction class
    MyDetectorConstruction* detector = new MyDetectorConstruction;
    runManager->SetUserInitialization(detector);

    G4PhysListFactory factory;
    runManager->SetUserInitialization(factory.GetReferencePhysList("QGSP_BERT"));
}
```

Main Program (cont)

```
// Set user generator action class
MyPrimaryGeneratorAction* genAction = new MyPrimaryGeneratorAction();
runManager->SetUserAction(genAction);

// Set user event-action class
MyEventAction* eventAction = new MyEventAction(detector);
runManager->SetUserAction(eventAction);

// Initialize G4 kernel
runManager->Initialize();

// Get the pointer to the User Interface manager
G4UImanager* UI = G4UImanager::GetUIpointer();

G4String command = "/control/execute ";
G4String fileName = argv[1];
UI->ApplyCommand(command+fileName);

// Job termination
// Free the store: user actions, physics_list and detector_description are
// owned and deleted by the run manager, so they should not
// be deleted in the main() program !
delete runManager;

return 0;
```

Hit Class

```
#include "G4VHit.hh"
#include "G4THitsCollection.hh"
#include "G4Allocator.hh"

class G4AttDef;

class MyHit : public G4VHit {

public:
    MyHit();
    MyHit(G4int id, G4double e, G4double t);
    ~MyHit() = default;
    MyHit(const MyHit &right);
    const MyHit& operator=(const MyHit &right);
    G4int operator=(const MyHit &right) const;

    inline void *operator new(size_t);
    inline void operator delete(void *aHit);
    void Draw() {}
    void Print() {}

private:
    G4int          cellID_;
    G4double       edep_, time_;
    ...
};
```

```
public:
    inline void setCellID(G4int id) { cellID_ = id; }
    inline G4int cellID() const { return cellID_; }
    inline void setEdep(G4double de) { edep_ = de; }
    inline void addEdep(G4double de) { edep_ += de; }
    inline G4double getEdep() const { return edep_; }
    inline void setTime(G4double t) { time_ = t; }
    inline G4double time() const { return time_; }

};

typedef G4THitsCollection<MyHit> MyHitsCollection;
extern G4Allocator<MyHit> MyHitAllocator;

inline void* MyHit::operator new(size_t) {
    void *aHit;
    aHit = (void *) MyHitAllocator.MallocSingle();
    return aHit;
}

inline void MyHit::operator delete(void *aHit) {
    MyHitAllocator.FreeSingle((MyHit*) aHit);
}
```

Detector Construction

```
#include "G4VUserDetectorConstruction.hh"

#include "G4RunManager.hh"
#include "G4LogicalVolume.hh"
#include "G4PVPlacement.hh"
#include "G4SystemOfUnits.hh"
#include "G4VPhysicalVolume.hh"
#include "G4LogicalVolume.hh"

class MyDetectorConstruction : public G4VUserDetectorConstruction {
public:
    MyDetectorConstruction() {}
    ~MyDetectorConstruction() override = default;
    G4VPhysicalVolume* Construct();

    void setSensitive();

private:
    G4LogicalVolume *logSens;
};
```

Sensitive Detector

```
#include "G4VSensitiveDetector.hh"
#include "MyHit.hh"

class MyDetectorConstruction;
class G4Step;
class G4HCofThisEvent;
class G4TouchableHistory;

class MySensitiveDetector : public G4VSensitiveDetector {
public:
    MySensitiveDetector(MyDetectorConstruction*, G4String);
    ~MySensitiveDetector();

    void      Initialize(G4HCofThisEvent*HCE);
    G4bool    ProcessHits(G4Step*aStep, G4TouchableHistory*R0hist);
    void      EndOfEvent(G4HCofThisEvent*HCE);
    void      clear();
    void      DrawAll();
    void      PrintAll();

private:
    const MyDetectorConstruction *detector_;
    MyHitsCollection *calCollection_;
    G4int hcID_;

};
```

Primary Generator Action

```
#include "G4VUserPrimaryGeneratorAction.hh"
#include "globals.hh"
#include "G4ParticleGun.hh"
#include "G4ThreeVector.hh"

class G4Event;

class PrimaryGeneratorAction : public G4VUserPrimaryGeneratorAction {

public:
    PrimaryGeneratorAction();
    virtual ~PrimaryGeneratorAction();

    void GeneratePrimaries(G4Event*);
    G4ParticleGun* GetParticleGun() {return particleGun;};
private:
    G4ParticleGun*          particleGun;          //pointer a to G4 class
    G4double                xVertex, yVertex, zVertex;
};
```


EventAction

```
#include <iostream>
#include <vector>
#include "TFile.h"
#include "TTree.h"
#include "G4UserEventAction.hh"
#include "globals.hh"

#include "MyDetectorConstruction.hh"

class MyEventAction : public G4UserEventAction {

public:

    MyEventAction(MyDetectorConstruction *det);
    virtual ~MyEventAction();

    void BeginOfEventAction(const G4Event*);
    void EndOfEventAction(const G4Event*);

private:
    const MyDetectorConstruction *detCon;

    ///tree variables
    std::vector<int> *cellX, *cellY, *layer;

    G4double gunPx, gunPy, gunPz, gunP, gunPt, gunE;
    G4double distX, distY, gunX, gunY, gunZ;

    TFile *file;
    TTree *tree;
};
```

Additional Slides