

Analysis of Bayesian estimates for missing higher orders in perturbative calculations

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C. Duhr, A. Huss, AM, R. Szafron, to appear soon



Standard Model predictions for hadron colliders

Theory predictions for collider experiments rely on the QCD factorization theorem:

$$\Sigma_n(\mu_R, \mu_F) = \sum_{i,j} \int_{x_1, x_2} f_i(x_1, \mu_F) f_j(x_2, \mu_F) \hat{\Sigma}_{n,ij}(x_1, x_2, \mu_F, \mu_R) + \mathcal{O}\left(\frac{\Lambda_{\text{QCD}}}{Q}\right)$$

Factorization μ_F and renormalization μ_R scales \sim characteristic hard scale Q .

(Next-to) n -leading order calculations Σ_n with $n = 1, 2$ and even $n = 3$ are available.

However, truncated perturbative series has:

- unphysical scale dependence $\Sigma_n(\mu_F, \mu_R)$
- unknown missing higher order terms (MHO) $\Sigma - \Sigma_n(\mu_F, \mu_R) = \mathcal{O}(N^{n+1}\text{LO})$

The only reliable way of estimating MHO is to compute them, but in the absence of calculations one can guesstimate – this is the topic of this talk.

Scale variation prescription

The conventional method uses scale dependence, which is higher order effect:

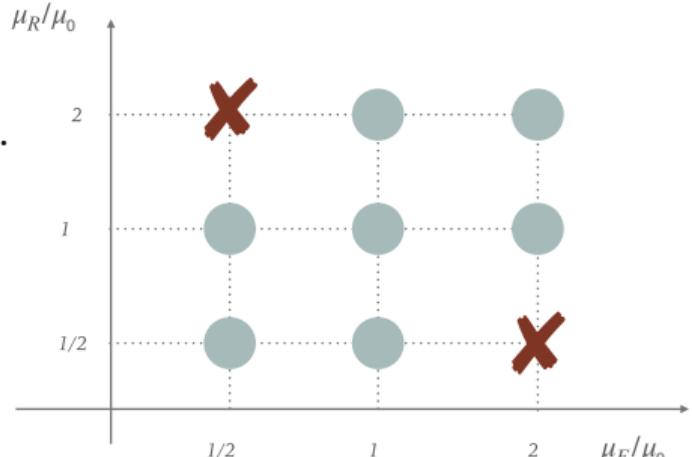
$$|\Sigma_n(k_F\mu_0, k_R\mu_0) - \Sigma_n(\mu_0, \mu_0)| = \mathcal{O}(N^{n+1}LO), \quad \mu_0 - \text{central scale (not unique)}.$$

7 point (9 point) scale “uncertainty”

$$\left[\min_{k_F, k_R} \Sigma_n(k_F\mu_0, k_R\mu_0), \max_{k_F, k_R} \Sigma_n(k_F\mu_0, k_R\mu_0) \right].$$

- ✗ no genuine MHO information
- ✗ must be verified for each process
- ✗ *no statistical interpretation, e.g. 5σ*

Are there alternative methods?



Bayesian inference from series progression

Pioneered by Cacciari, Houdeau (2011) [1] and recently extended by Bonvini (2020) [2]

Consider the sequence of perturbative corrections δ_k normalized to LO

$$\Sigma_n = \Sigma_0 \times \left(1 + \underbrace{\delta_1}_{\mathcal{O}(\alpha_s^1)} + \underbrace{\delta_2}_{\mathcal{O}(\alpha_s^2)} + \dots + \underbrace{\delta_n}_{\mathcal{O}(\alpha_s^n)} \right).$$

Assume **geometric model** for δ_k with hidden parameters $\mathbf{p} = (a, c)$

Bonvini (2020) [2]

$$|\delta_k| \leq ca^k, \quad 0 < a < 1, \quad c > 0.$$

Can do Bayesian inference for δ_{n+1} given $\boldsymbol{\delta}_n = (\delta_0, \delta_1, \dots, \delta_n)$,

$$P(\delta_{n+1} | \boldsymbol{\delta}_n) = \frac{P(\boldsymbol{\delta}_{n+1})}{P(\boldsymbol{\delta}_n)} = \frac{\int d^m \mathbf{p} P(\boldsymbol{\delta}_{n+1} | \mathbf{p}) P_0(\mathbf{p})}{\int d^m \mathbf{p} P(\boldsymbol{\delta}_n | \mathbf{p}) P_0(\mathbf{p})}.$$

- $P(\boldsymbol{\delta}_n | \mathbf{p})$ – model for the distribution of $\boldsymbol{\delta}_n$ given hidden parameter \mathbf{p}
- $P_0(\mathbf{p})$ – prior distribution of the model parameters \mathbf{p}

Posterior distribution for $\delta_{n+1} \implies$ MHO uncertainty at order n .

Asymmetric geometric (abc) model

Geometric model ignores sign of $\delta_k \implies$ posterior is symmetric and $\langle \delta_{n+1} \rangle_{geo} = 0$

- 1 Assume that δ_n is bracketed by two geometric series

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$$b - c \leq \frac{\delta_n}{a^n} \leq b + c, \quad -1 < a < 1, \quad c > 0.$$

- 2 Choose flat, but asymmetric distribution for δ_k

$$P_{abc}(\delta_k|a, c) = \frac{1}{2c|a|^k} \theta\left(c - \left|\frac{\delta_k}{a^k} - b\right|\right), \quad P_{abc}(\delta_n|a, c) = \prod_{k=0}^n P_{abc}(\delta_k|a, c).$$

- 3 Choose priors for model parameters $p = (a, b, c)$

$$P_0(a) = \frac{1}{2}(1 + \omega)(1 - |a|)^\omega \theta(1 - |a|) \quad P_0(b, c) = \frac{\epsilon \eta^\epsilon}{2\xi c^{2+\epsilon}} \theta(c - \eta) \theta(\xi c - |b|).$$

$\omega = 1, \eta = 0.1, \xi = 2, \epsilon = 0.1$ – constants, not hidden parameters.

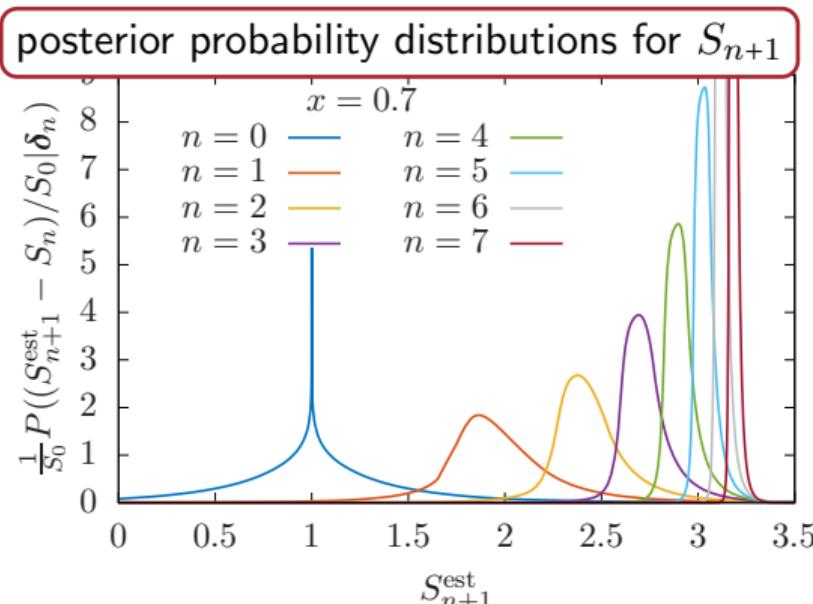
$\langle \delta_{n+1} \rangle_{abc} \neq 0$ and both monotonic and alternating series are treated correctly.

Simple toy example: geometric series

Consider geometric series $S_n = \sum_{k=0}^n x^k$ with $x = 0.7$. Posterior distribution

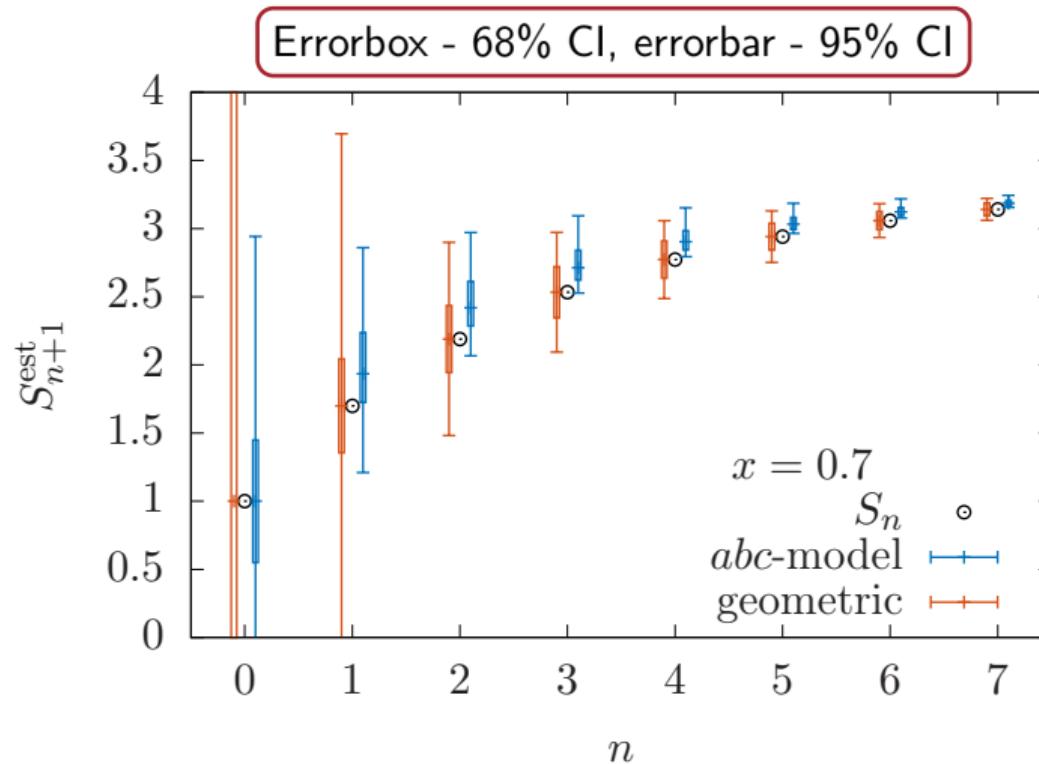
$$P(\delta_{n+1} | \boldsymbol{\delta}_n) = \frac{\int da db dc P_{abc}(\boldsymbol{\delta}_{n+1} | a, b, c) P_0(a, b, c)}{\int da db dc P_{abc}(\boldsymbol{\delta}_n | a, b, c) P_0(a, b, c)}.$$

Draw posterior distribution with increasing number of input terms



Confidence intervals for geometric and abc models

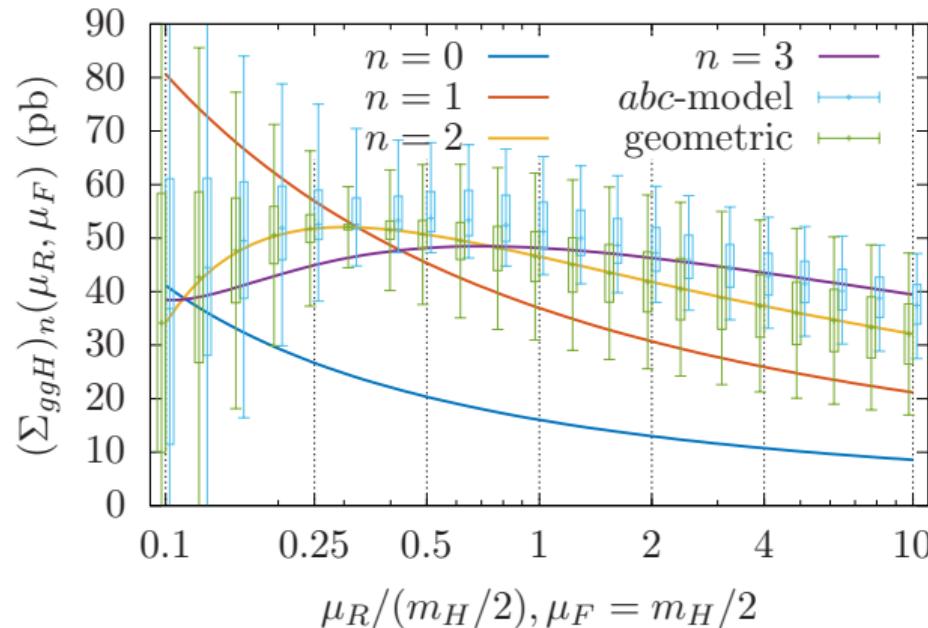
Define confidence interval $\text{CI}_x = [\Sigma_x^{\text{low}}, \Sigma_x^{\text{upp}}]$ containing $x\%$ of posterior probability.



abc-model CIs successfully anticipates the location of $n + 1$ term.

Higgs cross-section from gluon fusion

Compare $(\Sigma_{ggH})_n$ at N^3LO with Bayesian inference from $n = 0, 1, 2$ at fixed scale.



- Generally *abc*-model CI encompass N^3LO result.
- Geometric model is peaked at FAC-point, where NNLO correction vanish.

How to combine inferences at different (unphysical scales)?

Prescriptions for scale dependent observables

- 1 **Scale-marginalization (sm)**: Interpret scale as hidden model parameter

Bonvini (2020) [2]

$$P_{\text{sm}}(\Sigma|\Sigma_n) = \int d\mu P_0(\mu) P(\Sigma|\Sigma_n(\mu)) \frac{P(\Sigma_n(\mu))}{\int d\mu' P_0(\mu') \Sigma_n(\mu')}.$$

$P_0(\mu)$ – flat prior on $\log \mu_0/F \leq \log \mu \leq \log F \mu_0$

- 2 **Scale-averaging (sa)**: Treat scale just as a label and average over

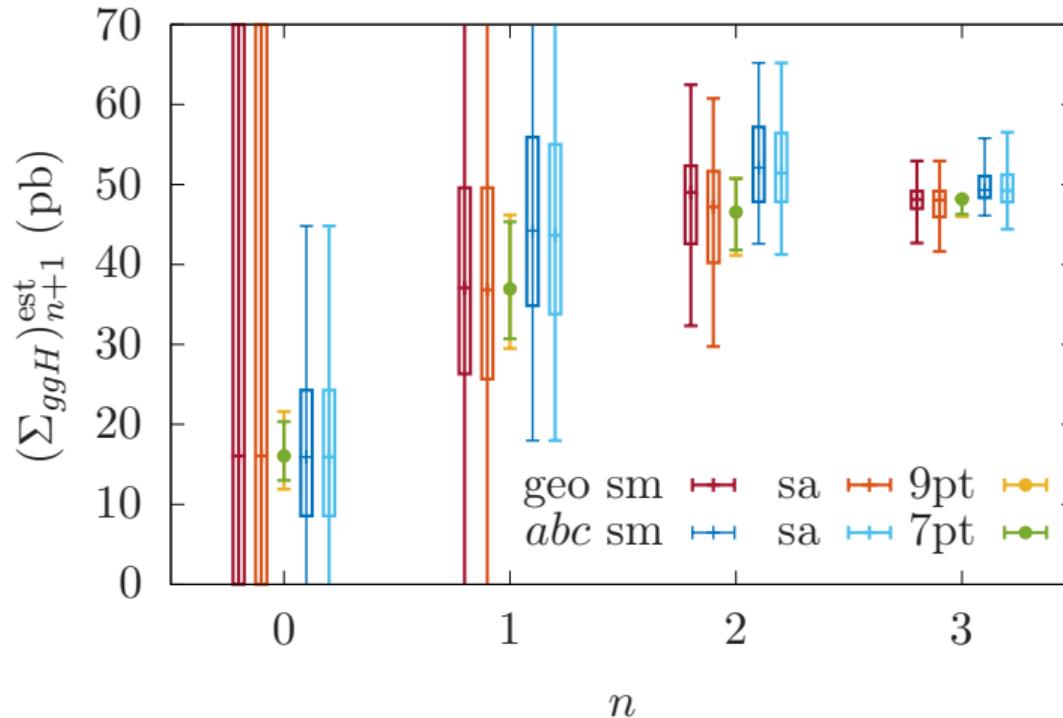
Duhr, Huss, AM, Szafron, to appear soon

$$P_{\text{sa}}(\Sigma|\Sigma_n) = \int d\mu w(\mu) P(\Sigma|\Sigma_n(\mu)).$$

$w(\mu)$ – flat weight on $\log \mu_0/F \leq \log \mu \leq \log F \mu_0$

We employ Gauss-Legendre quadrature to reuse existing scale variation points
⇒ no new perturbative calculations are needed!

Comparison of prescriptions and models for higgs fusion



- *abc*-model anticipates positive MHO
- scale variation interval comparable to 68% CIs

Summary

Showed today:

- Two Bayesian models: symmetric geometric and *abc*-model
- Two prescriptions for scale: scale-averaging and scale-marginalization
- Application to gluon fusion Higgs production up to N^3LO .

Much more in the paper:

Duhr, Huss, AM, Szafron, to appear soon

- Analysis of hidden biases associated with scale prescription choice.
- Dependence on model priors and scale intervals.
- Derived relation between scale variation interval and CIs in Bayesian models.
- Many more explicit examples of observables (inclusive and differential).

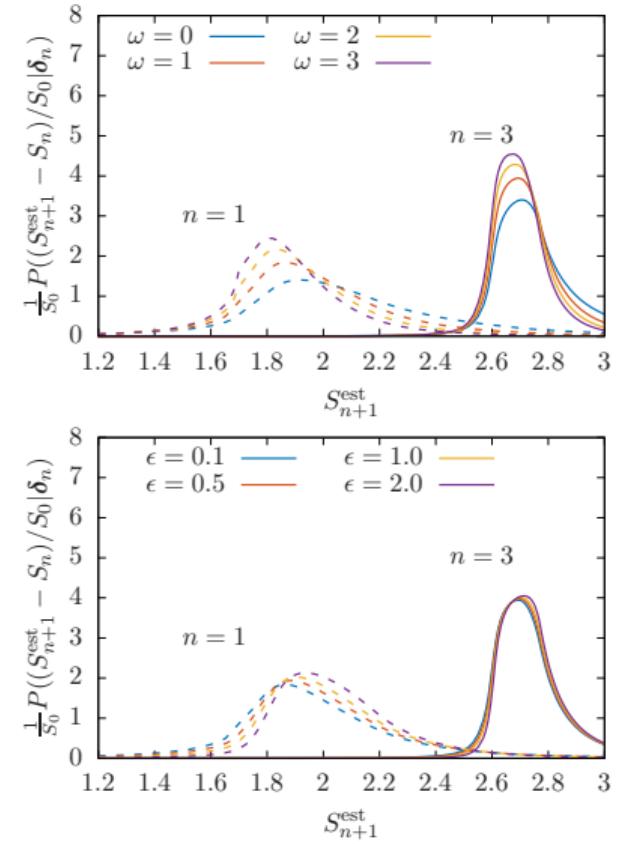
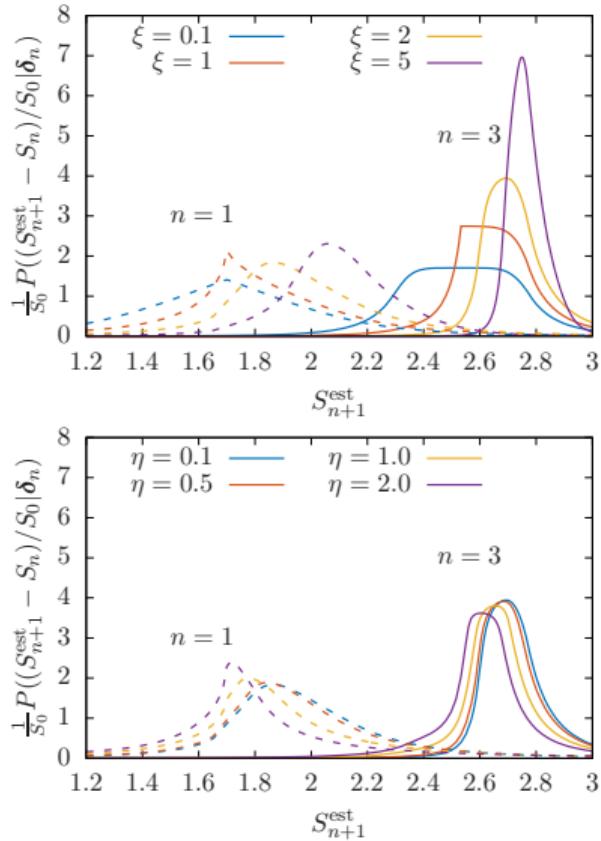
Bayesian inference is a powerful framework to estimate MHO, but careful analysis is required.

Bibliography I

- [1] Matteo Cacciari and Nicolas Houdeau. Meaningful characterisation of perturbative theoretical uncertainties. *JHEP*, 09:039, 2011, 1105.5152.
- [2] Marco Bonvini. Probabilistic definition of the perturbative theoretical uncertainty from missing higher orders. *Eur. Phys. J.*, C80(10):989, 2020, 2006.16293.

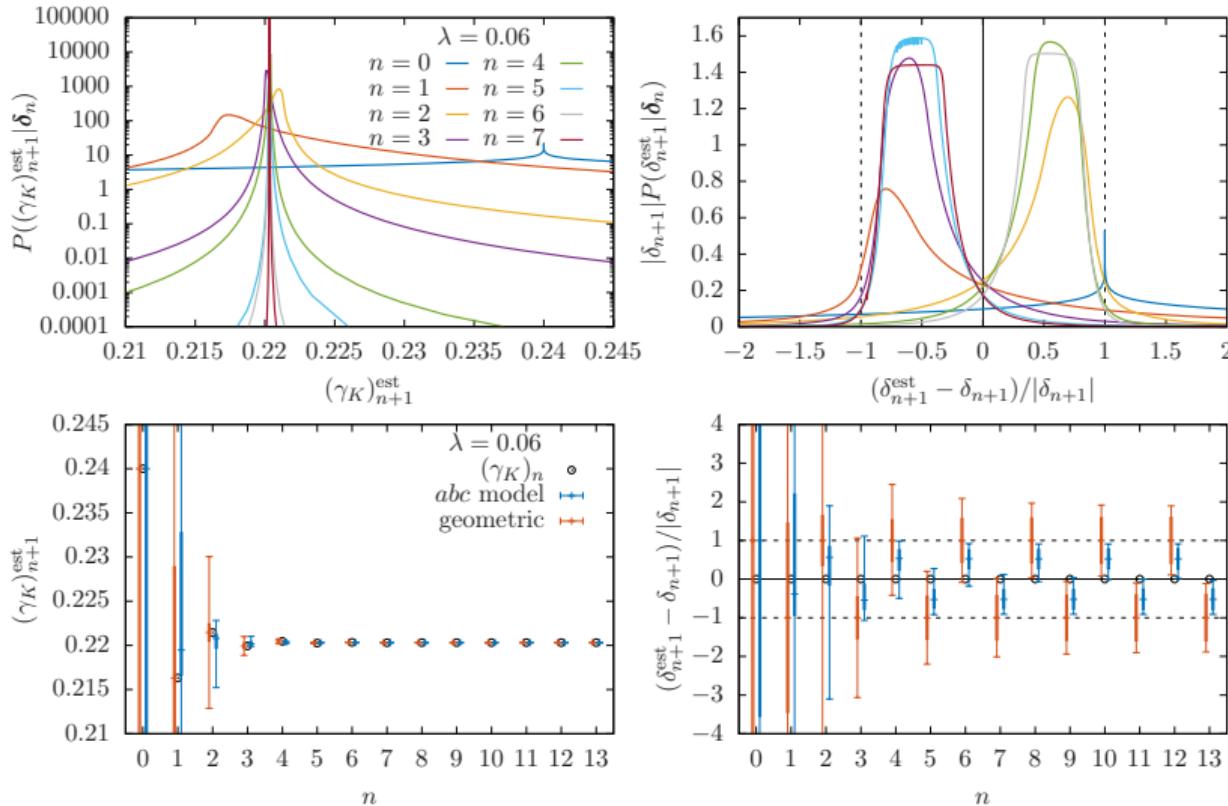
Backup

Dependence of priors for *abc*-model



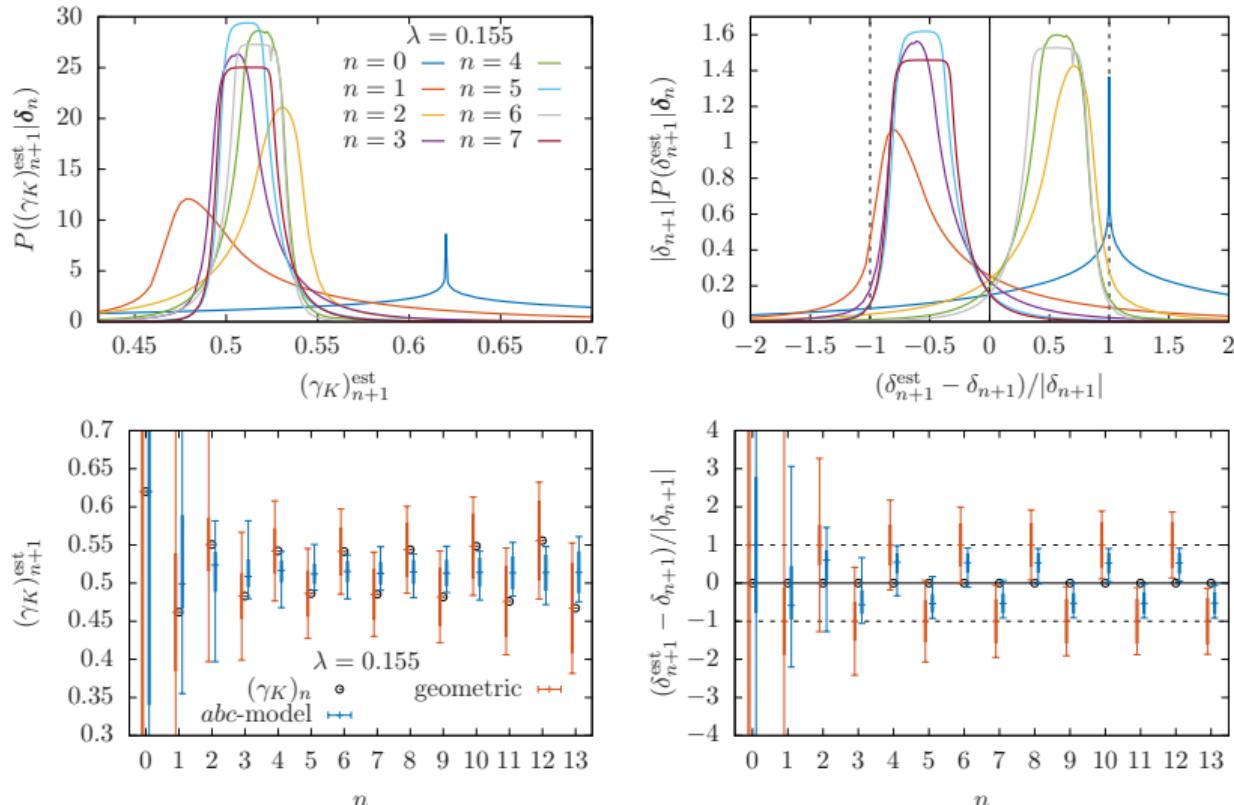
Anomalous cups dimension in supersymmetric Yang-Mills

Can be computed to arbitrary order. Has finite radius of convergence in coupling λ .



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Integration quadrature and relation to scale variation

For smooth scale dependence integral can be approximated by 3-point quadrature

$$P_{\text{sa}}(\Sigma|\Sigma_n) \approx w_- P(\Sigma|\Sigma_n(\mu_0/2)) + w_0 P(\Sigma|\Sigma_n(\mu_0)) + w_+ P(\Sigma|\Sigma_n(2\mu_0)).$$

