

Deformations, Moduli Stabilisation and Loop-Corrected Gauge Couplings for Particle Physics on D-Branes

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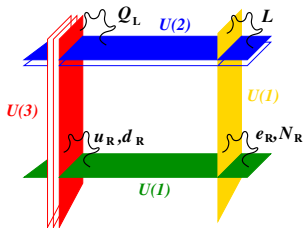
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based on arXiv:1702.WXYZ[hep-th]
with **Isabel Koltermann & Wieland Staessens**

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Motivation: Moduli Dependences of String Vacua



- ▶ plethora of **D6-brane** models with **MSSM** or **GUT** spectrum
- ▶ Kähler moduli v_i : $G_N^{(4)}(v_i, g_{\text{string}}, M_{\text{string}})$
- ▶ complex structure moduli ζ_j : $\frac{1}{g_a^2}(\zeta_j, g_{\text{string}})$
- ▶ @ 1-loop: $\frac{1}{g_a^2}(v_i, \zeta_j, g_{\text{string}})$
- ▶ ...

$$\int_{\mathbb{R}^{1,9}} e^{-2\Phi} R_{(10)} \rightarrow \boxed{\frac{\text{Vol}_6}{g_{\text{string}}^2}} \int_{\mathbb{R}^{1,3}} R_{(4)}$$

$$\int_{\mathbb{R}^{1,3} \times \Pi_3^a} e^{-\Phi} \text{tr} F_{\mu\nu} F_{(7)}^{\mu\nu} \rightarrow \boxed{\frac{\text{Vol}_3}{4 g_{\text{string}}}} \int_{\mathbb{R}^{1,3}} \text{tr} F_{\mu\nu} F_{(4)}^{\mu\nu}$$

Standard *a priori* assumption:

- ▶ moduli not stabilised - unless fluxes
 - ▶ no known particle physics vacua beyond twisted torus

Argue here:

- ▶ presence of D-branes stabilises (part of the **c.s.**) moduli

Motivation cont'd: Deformations & 1-Loop Effects

here: IIA string theory with D6-branes; IIB via mirror Kähler \leftrightarrow complex str.

Field theoretic expectation:

- ▶ SUSY D6-branes wrap *special Lagrangian (sLag)* 3-cycles
- ▶ deformations either:
 - ▶ SUSY via $\langle \zeta_j \rangle \propto$ FI parameter \leftarrow modulus stabilised
 - ▶ constitute flat directions of $\frac{1}{g_s^2}$ \leftarrow stronger/weaker possible

1-loop gauge thresholds:

- ▶ can also take *negative* values
- ▶ compete with deformations

... so far only explicitly known for simple backgrounds

Questions:

- ▶ how many stabilised moduli?
- ▶ can $M_{\text{string}} \ll M_{\text{GUT}}$ appear?

- ▶ Motivation
- ▶ D6-brane set-up & moduli
- ▶ Description of deformations
- ▶ 1-loop results
- ▶ Conclusions & Outlook

D6-Brane Set-Up: Type IIA Orientifolds

special Lagrangians:

- ▶ needed for SUSY D6-branes
- ▶ symplectic geometry & *sLags* - very limited knowledge

see e.g. Joyce '01-03; Morrison, Plesser '15

- ▶ need also O6-planes for model building
 - ▶ IIA requires anti-holomorphic involution on CY_3

partial results for hypersurfaces in weighted projective spaces by Palti '09

- ▶ **here:** T^6/Γ as background (with $\mathbb{Z}_2 \times \mathbb{Z}_2 \subset \Gamma$)

- ▶ **advantage:**

- ▶ geometry (e.g. metric) well-known
- ▶ CFT tools for vector-like spectrum & effective field theory

- ▶ **disadvantage:**

- ▶ not all *singularities* resolvable/deformable ← duality arguments ↯?
- ▶ tiny class of backgrounds with set of CY_3

D6-Brane Set-Up: $T^6/(\Gamma \times \Omega\mathcal{R})$ with $\mathbb{Z}_2 \times \mathbb{Z}_2 \subset \Gamma$

notation: $T^6 = \otimes_{i=1}^3 T^2_{(i)}$

$$T^4_{(i)} = T^2_{(j)} \times T^2_{(k)}$$

Hodge numbers:

- ▶ singularities at $\mathbb{Z}_2 \times \mathbb{Z}_2$ fixed loci: $e^{(i)}$ at each $\mathbb{C}^2_{(i)}/\mathbb{Z}_2^{(i)}$
- ▶ $\mathbb{Z}_2^{(j,k)}$ acts with phase $\eta = \pm 1$ on $\mathbb{Z}_2^{(i)}$ -twisted sector:

without/with discrete torsion

- ▶ $\eta = +1$: 2-cycle per singularity
- ▶ $\eta = -1$: 3-cycle instead $e^{(i)} \otimes [1\text{-cycle on } T^2_{(i)}]$
 - ▶ suitable for D6-brane model building
 - ▶ $T^6/(\mathbb{Z}_2 \times \mathbb{Z}_2)$ has $(h^{11}, h^{21}) = (3_{\text{bulk}}, 3_{\text{bulk}} + 3 \times 16_{\mathbb{Z}_2})$
 - ▶ can add \mathbb{Z}_3 symmetry for model building:

$$\boxed{T^6/(\mathbb{Z}_2 \times \mathbb{Z}_6)} \simeq (T^2_{(1)} \times T^4_{(1)}/\mathbb{Z}_6)/\mathbb{Z}_2^{(3)} \text{ has}$$
$$(h^{11}, h^{21}) = (3_{\text{bulk}} + 8_{\mathbb{Z}_3} + 2 \times 4_{\mathbb{Z}'_6}, 1_{\text{bulk}} + [6 + 2 \times 4]_{\mathbb{Z}_2} + [2 + 2]_{\mathbb{Z}_3 + \mathbb{Z}_6})$$

Fractional 3-cycles:

- ▶ unimodular lattice contains

$$\boxed{\Pi^{\text{frac}} = \frac{\Pi^{\text{bulk}} + \sum_i \Pi^{\mathbb{Z}_2^{(i)}}}{4}}$$

- ▶ $\Pi^{\mathbb{Z}_2^{(i)}}$ couples to $\leq h^{21}_{\mathbb{Z}_2^{(i)}}$ deformation moduli

General considerations:

- ▶ $\Pi^{\text{frac}} = \frac{\Pi^{\text{bulk}} + \sum_i \Pi^{\mathbb{Z}_2^{(i)}}$ couples to (some) twisted moduli
- ▶ N D6-branes $\rightsquigarrow U(N)$
 - ▶ $U(1)$ D-term vanishes $\Leftrightarrow \Pi^{\text{frac}}$ is $sLag$
 - ▶ related twisted moduli stabilised \Leftrightarrow FI term for $\langle \zeta_j \rangle \neq 0$
- ▶ not all couplings generate D-term: e.g. $USp(2N)$ or $SO(2N)$
 - ▶ no D-term $\Leftrightarrow \Pi^{\text{frac}}$ is $sLag$ for any deformation

Orientifold symmetry:

- ▶ IIA requires anti-holomorphic involution \mathcal{R}
- ▶ $(h_+^{11}, h_-^{11}) = (4_{\mathbb{Z}'_6}, 3_{\text{bulk}} + 8_{\mathbb{Z}_3} + 4_{\mathbb{Z}'_6})$ - one \mathbb{Z}'_6 sector does not have any scalars that could resolve the singularities
- ▶ $(h^{21} + 1)$ $\Omega\mathcal{R}$ -even + $(h^{21} + 1)$ $\Omega\mathcal{R}$ -odd 3-cycles
 - ▶ deformation SUSY \Leftrightarrow only $\Omega\mathcal{R}$ -even contribution to $\Pi^{\mathbb{Z}_2^{(i)}}$

Deformations con't: Hypersurface Technique

Blaszczyk, G.H., Koltermann '14-15 & G.H., Koltermann, Staessens '17

- ▶ use \mathbb{P}_{112}^2 with coord. (x_i, v_i, y_i) to describe $T_{(i)}^2$

$$-y_i^2 + F_i(x_i, v_i) \stackrel{!}{=} 0 \quad F_i(x_i, v_i) = 4v_i x_i^3 - g_2^{(i)} v_i^3 x_i - g_3^{(i)} v_i^4$$

- ▶ $g_3^{(i)} = 0$: square torus

- ▶ $g_2^{(i)} = 0$: hexagonal lattice

- ▶ take product and impose $\mathbb{Z}_2 \times \mathbb{Z}_2$ symmetry: $y_i \xrightarrow{\mathbb{Z}_2} -y_i$

$$(T^2)^3 / (\mathbb{Z}_2 \times \mathbb{Z}_2) \simeq \{-y^2 + F_1 F_2 F_3 = 0\} \quad \text{with } y \equiv y_1 y_2 y_3$$

- ▶ **deform** fixed points $\alpha\beta \in T_{(i)}^4 \equiv T_{(j)}^2 \times T_{(k)}^2$:

$$-y^2 + F_1 F_2 F_3 + \sum_{i \neq j \neq k \neq i} \sum_{\alpha\beta} \varepsilon_{\alpha\beta}^{(i)} F_i \delta F_j^{(\alpha)} \delta F_k^{(\beta)} \stackrel{!}{=} 0$$

with $\delta F_j^{(\alpha)}(x_j, v_j)$ also polynomials of degree 4

deformation method based on Vafa, Witten '95

Deformations con't: $sLags$

$sLags$: probe $\text{Re} \int_{\Pi_a} \Omega_3 > 0$ and $\text{Im} \int_{\Pi_a} \Omega_3 = 0$

- ▶ specify calibration via anti-holomorphic involution $\sigma_{\mathcal{R}}$
- ▶ in general too complicated \rightsquigarrow concentrate on anti-linear maps

$$\begin{pmatrix} x_i \\ v_i \end{pmatrix} \rightarrow A \begin{pmatrix} \bar{x}_i \\ \bar{v}_i \end{pmatrix}, \quad y_i \rightarrow e^{i\beta} \bar{v}_i \quad \text{s.t.} \quad \bar{A}A = \mathbf{1}, \quad \sigma_{\mathcal{R}}(F_i(x_i, v_i)) = e^{-2i\beta} F(\bar{x}_i, \bar{v}_i)$$

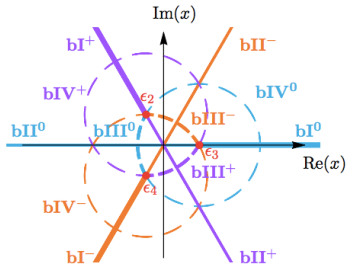
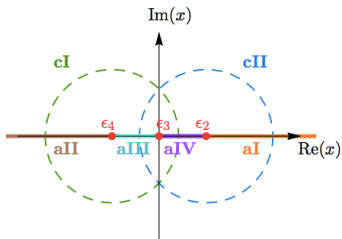
- ▶ two different calibrations β and $\beta + \pi$ per given A
 \rightsquigarrow integration path Π_a specified by (A_a, β_a)
- ▶ impose SUSY products of one-cycles @ orbifold point

$\mathbb{Z}_3 \times \Omega\mathcal{R}$ **symmetry:**

- ▶ \mathbb{Z}_3 : need for hexagonal tori
& identification of $\mathbb{Z}_2 \times \mathbb{Z}_2$ deformations $\varepsilon_{\alpha\beta}^{(i)}$ under \mathbb{Z}_3
- ▶ $\Omega\mathcal{R}$ -invariance: only **real** deformation parameters

Lagrangian lines on square untitled torus T^2				
(n^i, m^i)	displacement	condition in x	label	picture
$\pm(1, 0)$	0	$\epsilon_2 \leq x$	aI	
	1	$\epsilon_4 \leq x \leq \epsilon_3$	aIII	
	continuous	$ x - \epsilon_4 ^2 = 2\epsilon_4^2 + \epsilon_2\epsilon_3$	cI	
$\pm(0, 1)$	0	$x \leq \epsilon_4$	aII	
	1	$\epsilon_3 \leq x \leq \epsilon_2$	aIV	
	continuous	$ x - \epsilon_2 ^2 = 2\epsilon_2^2 + \epsilon_4\epsilon_3$	cII	

Lagrangian lines on hexagonal torus T^2				
(n^i, m^i)	displacement	condition in x	label	picture
$\pm(1, 0)$	0	$1 \leq x$	bI ⁰	
	1	$ x - 1 ^2 = 3, \text{Re}(x) \leq -1/2$	bIII ⁰	
$\pm(-1, 2)$	0	$x \leq 1$	bII ⁰	
	1	$ x - 1 ^2 = 3, -1/2 \leq \text{Re}(x)$	bIV ⁰	
$\pm(0, 1)$	0	$1 \leq \xi^2 x$	bI ⁻	
	1	$ \xi^2 x - 1 ^2 = 3, \text{Re}(\xi^2 x) \leq -1/2$	bIII ⁻	
$\pm(2, -1)$	0	$\xi^2 x \leq 1$	bII ⁻	
	1	$ \xi^2 x - 1 ^2 = 3, -1/2 \leq \text{Re}(\xi^2 x)$	bIV ⁻	
$\pm(1, -1)$	0	$1 \leq \xi x$	bI ⁺	
	1	$ \xi x - 1 ^2 = 3, \text{Re}(\xi x) \leq -1/2$	bIII ⁺	
$\pm(1, 1)$	0	$\xi x \leq 1$	bII ⁺	
	1	$ \xi x - 1 ^2 = 3, -1/2 \leq \text{Re}(\xi x)$	bIV ⁺	



Deformations cont'd: Examples on $\mathbb{Z}_2 \times \mathbb{Z}_6$ Backgrd.

Ecker, G.H., Staessens '14-15

- ▶ extensive computer scans boil down to prototypes

$$SU(3)_a \times USp(2)_b \times U(1)_\gamma \times SU(4)_h \times \mathbb{Z}_3 \subset U(3)_a \times USp(2)_b \times U(1)_c \times U(1)_d \times U(4)_h$$

$$SU(3)_a \times USp(2)_b \times USp(2)_c \times \begin{cases} \mathbb{Z}_3 & \text{I} \\ \widetilde{U(1)}_{B-L} & \text{II} \end{cases} \subset U(3)_a \times USp(2)_b \times USp(2)_c \times U(h)^2$$

$$SU(4)_a \times USp(2)_b \times USp(2)_c \times \begin{cases} SU(6) & \text{I} \\ SU(2) & \text{II} \end{cases} \subset U(4)_a \times USp(2)_b \times USp(2)_c \times U(h)$$

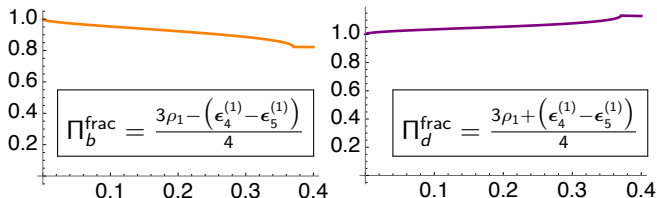
- ▶ equivalent @ orbifold point:
 - ▶ closed & open string spectrum
 - ▶ gauge couplings (tree + 1-loop)

Counting of stabilised complex structure moduli & flat directions with $1/\epsilon^2_{D6}$ dependence
 $x \in \{a, b, c, d, h_{1,2}\}$

$\mathbb{Z}_2 \times \mathbb{Z}_6$	ϱ	$\epsilon_{0,1,2}^{(1)}$	$\epsilon_3^{(1)}$	$\epsilon_{4+5}^{(1)}$	$\epsilon_{4-5}^{(1)}$	$\epsilon_{1,2}^{(2)}$	$\epsilon_{3,4}^{(2)}$	$\epsilon_{1,2}^{(3)}$	$\epsilon_{3,4}^{(3)}$	#stab
MSSM	none	none	a, c, h	$[b, d]_{\text{flat}}$	c, d	none	a, d, h	none	6	
L-R I	none	$h_{1,2}$	$a, d, h_{1,2}$	a, d	$[b, c]_{\text{flat}}$	$h_{1,2}$	none	a, d	none	9
L-R II	none	$h_{1,2}$	$a, d, h_{1,2}$	a, d	$[b, c]_{\text{flat}}$	$[a, b, c, d, h_{1,2}]_{\text{flat}}$	none	$a, d, h_{1,2}$	none	7
L-R IIb	none	$h_{1,2}$	$a, d, h_{1,2}$	a, d	$[b, c]_{\text{flat}}$	$[a, b, c, d]_{\text{flat}}$	$[h_{1,2}]_{\text{flat}}$	a, d	$h_{1,2}$	9
L-R IIc	none	none	a, d	a, d	$[b, c, h_{1,2}]_{\text{flat}}$	h_1	h_2	a, d, h_1	h_2	10
PS I	none	none	a, h	$[b, c]_{\text{flat}}$	$[a, b, c, h]_{\text{flat}}$	none	a, h	none	4	
PS II	none	h	a, h	a	$[b, c]_{\text{flat}}$	$[a, b, c, h]_{\text{flat}}$	none	a, h	none	7

Deformations: Flat Direction of MSSM Example

- ▶ $USp(2)_b$ and $U(1)_d \subset U(1)_Y$ feel flat direction $\epsilon_{4-5}^{(1)} < 0$



- ▶ weak interaction on b slightly stronger for $\epsilon_{a-5}^{(1)} \neq 0$
- ▶ hypercharge slightly weaker

Caveat on 'stabilised' moduli:

- ▶ compensation by charged matter vev in D-terms
 - ▶ only bifundamentals under $U(N) \times U(N)$ ($cd^{(l)}$)_{MSSM}
 - ▶ only if string derived field theory couplings exist

1-Loop Corrections to Gauge Couplings @ Orbifold Point

Why?

- ▶ deformations by **twisted** moduli change couplings @ tree-level
- ▶ **untwisted** moduli enter 1-loop corrections
 - ▶ only known at orbifold point
 - ▶ independent of *absolute* choice of $\mathbb{Z}_2 \times \mathbb{Z}_2$ eigenvalues
 - ▶ can - *in principle* - contribute to hierarchy $M_{\text{string}} \ll M_{\text{GUT}}$

G.H., Ripka, Staessens '12

Unusual feature here:

- ▶ net O6-plane charge along **one** direction on $T_{(1)}^2$
- ▶ Einstein-Hilbert $\rightsquigarrow \frac{M_{\text{Planck}}^2}{M_{\text{string}}^2} = \frac{4\pi}{g_{\text{string}}^2} v_1 v_2 v_3$ with $v_1 = R_1^{(1)} R_2^{(1)}$
- ▶ DBI action $\rightsquigarrow \frac{8\pi^2}{g_{SU(3)_a/SU(4)_h, \text{tree}}^2} = \frac{\pi}{2\sqrt{6}} \sqrt{\frac{R_1^{(1)}}{R_2^{(1)}}} \frac{M_{\text{Planck}}}{M_{\text{string}}}$
 $\rightsquigarrow M_{\text{string}} \ll M_{\text{Planck}}$ can be compensated by $R_2^{(1)} \gg R_1^{(1)}$

... spoiled by 1-loop effects??

1-Loop Corrections

- **Kähler moduli** v_i enter via parallel D6-branes

$$\Lambda_{0,0}(v) \equiv -\frac{1}{4\pi} \ln(\eta(iv)) \xrightarrow{v \rightarrow \infty} \frac{v}{48}$$

$$\Lambda_{\tau,\sigma}(v) \equiv -\frac{1}{4\pi} \ln\left(e^{-\frac{\pi\sigma^2 v}{4}} \frac{|\vartheta_1\left(\frac{\tau-i\sigma v}{2}, iv\right)|}{\eta(iv)}\right) \xrightarrow{v \rightarrow \infty} \frac{[3(1-\sigma)^2 - 1] v}{48} - \delta_{\sigma,0} \frac{\ln[2 \sin(\frac{\pi\tau}{2})]}{4\pi}$$

- **sign** depends on discrete brane data (τ, σ)
- **sum** over sector-by-sector (Annulus + Möbius strip) e.g.

$$\frac{\Delta_{SU(3)_a}^{A+\mathcal{M}, \text{MSSM}}}{2} \xrightarrow{v \gg 1} 2\pi v_1 + \frac{\pi}{3} \left(v_2 + c_{1,1}^{\frac{1}{2}} (v_2 - v_3) \right) - \ln \left(\left(\frac{R_1^{(1)}}{R_2^{(1)}} v_1 \right)^6 v_2 \right) - 12$$

$$\frac{\Delta_{SU(4)_h}^{A+\mathcal{M}, \text{MSSM}}}{2} \xrightarrow{v \gg 1} 2\pi v_1 + \frac{\pi}{3} \left(-v_2 + c_{1,1}^{\frac{1}{2}} (v_2 - v_3) \right) - \ln \left(\left(\frac{R_1}{R_2} v_1 \right)^6 v_2^{-1} \right) - 7$$

- $v_1 \gg 1$ disfavoured by $1/g_a^2 \sim \mathcal{O}(1) \rightsquigarrow R_1^{(1)} \ll R_2^{(1)}$ ⚡
- for $v_2 \gg 1$, $SU(4)_h$ more strongly coupled than $SU(3)_a$
- for $v_1 \approx 1$ and $v_2 = v_3 \lesssim 6$: $M_{\text{string}} \sim M_{\text{GUT}}$, $\Delta_{SU(3)_a}^{A+\mathcal{M}, \text{MSSM}} < 0$

G.H., Koltermann, Staessens to appear

- ▶ **deformations** of T^6/Γ with $\mathbb{Z}_2 \times \mathbb{Z}_2 \subset \Gamma$ can be described by **hypersurface formalism**
- ▶ **identifications & reality** conditions of deformation parameters under $\mathbb{Z}_3 \times \Omega\mathcal{R}$
- ▶ **D6-brane** couples $\Omega\mathcal{R}$ -**odd** \rightsquigarrow **stabilisation** @ orbifold point
- ▶ *all* D6-branes couple (at most) $\Omega\mathcal{R}$ -**even** \rightsquigarrow **flat** direction
 - ▶ mild change in gauge couplings for small deformation
 - ▶ lifts degeneracies of tree-level gauge couplings
 - ▶ depends on *absolute* $\mathbb{Z}_2 \times \mathbb{Z}_2$ eigenvalues
- ▶ **competing** effect: **1-loop** corrections
 - ▶ only computable @ orbifold point
 - ▶ depend on *relative* $\mathbb{Z}_2 \times \mathbb{Z}_2$ eigenvalues
 - ▶ concrete models disfavour very low M_{string}

Open questions:

- ▶ low M_{string} disfavoured:
generic feature or artefact of concrete model?
- ▶ any (fine-tuned) model **matching all pheno** couplings?
- ▶ needed: **exact** results for low-energy **effective field theory**
 - ▶ @ orbifold point:
not even Möbius strip contributions for $\delta \frac{1}{g_a^2}$ fully understood;
Yukawas ...
 - ▶ generic CY_3 ???

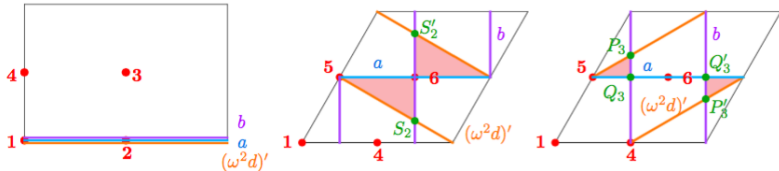
Appendix

Ex: MSSM on rigid D6-branes on $T^6/(\mathbb{Z}_2 \times \mathbb{Z}_6 \times \Omega\mathcal{R})$

Ecker, G.H., Staessens '15

D6-brane configuration of a global 5-stack MSSM model on the aAA lattice

	wrapping #	$\frac{\text{Angle}}{\pi}$	$\mathbb{Z}_2^{(i)}$ eigenv.	$(\vec{\tau})$	$(\vec{\sigma})$	gauge gr.
a	(1, 0; 1, 0; 1, 0)	(0, 0, 0)	(+ + +)	(0, 1, 1)	(0, 1, 1)	$U(3)$
b	(1, 0; -1, 2; 1, -2)	$(0, \frac{1}{2}, -\frac{1}{2})$	(- - +)	(0, 1, 0)	(0, 1, 0)	$USp(2)$
c	(1, 0; -1, 2; 1, -2)	$(0, \frac{1}{2}, -\frac{1}{2})$	(- + -)	(0, 1, 1)	(0, 1, 1)	$U(1)$
d	(1, 0; -1, 2; 1, -2)	$(0, \frac{1}{2}, -\frac{1}{2})$	(+ - -)	(0, 0, 1)	(0, 0, 1)	$U(1)$
h	(1, 0; 1, 0; 1, 0)	(0, 0, 0)	(- - +)	(0, 1, 1)	(0, 1, 1)	$U(4)$



- ▶ **Green-Schwarz mech.:** $\prod_{x \in \{a, c, d, h\}} U(1)_x \rightarrow U(1)_Y \times \mathbb{Z}_3$
 - ▶ perturbatively $U(1)_{\text{massive}}^3 \supset U(1)_{PQ} = U(1)_c - U(1)_d$
 - ▶ non-pert. only: $SU(3) \times SU(2) \times U(1)_Y \times \mathbb{Z}_3 \times SU(4)_{\text{hidden}}$

Ex: MSSM spectrum on $T^6/(\mathbb{Z}_2 \times \mathbb{Z}_6 \times \Omega\mathcal{R})$

Ecker, G.H., Staessens '15

► **MSSM matter** of $(SU(3)_a \times USp(2)_b \times SU(4)_h)_{U(1)_Y}^{(U(1)_{PQ}, \mathbb{Z}_3)}$:

$$3 \times [(\mathbf{3}, \mathbf{2}, \mathbf{1})_{1/6}^{(0),0} + 2 \times (\bar{\mathbf{3}}, \mathbf{1}, \mathbf{1})_{1/3}^{(1),1} + (\mathbf{3}, \mathbf{1}, \mathbf{1})_{-1/3}^{(1),1} + (\bar{\mathbf{3}}, \mathbf{1}, \mathbf{1})_{-2/3}^{(1),1}]$$

$$+ 3 \times [(\mathbf{1}, \mathbf{2}, \mathbf{1})_{1/2}^{(1),1} + 2 \times (\mathbf{1}, \mathbf{2}, \mathbf{1})_{-1/2}^{(1),1} + (\mathbf{1}, \mathbf{1}, \mathbf{1})_0^{(-2),1} + (\mathbf{1}, \mathbf{1}, \mathbf{1})_1^{(0),0}]$$

$$= 3 \times [Q_L + 2 \times d_R + \bar{d}_R + u_R] + 3 \times [H_u/\bar{L} + 2 \times L + \nu_R + e_R]$$

► **Higgses:** $3 \times [(\mathbf{1}, \mathbf{2}, \mathbf{1})_{1/2}^{(1),1} + h.c.] + \tilde{2} \times [(\mathbf{1}, \mathbf{2}, \mathbf{1})_{1/2}^{(-1),2} + h.c.]$

► **axions:** $3 \times [\Sigma^{cd} + \tilde{\Sigma}^{cd}] = 3 \times [(\mathbf{1}, \mathbf{1}, \mathbf{1})_0^{(-2),1} + h.c.]$

► **SM vector-like states:** $(5_{\text{Anti}_b} + 4_{\text{Adj}_c} + 5_{\text{Adj}_d}) \times (\mathbf{1}, \mathbf{1}, \mathbf{1})_0^{(0),0} +$

$$+ [2 \times (\mathbf{3}, \mathbf{1}, \bar{\mathbf{4}})_{1/6}^{(0),1} + (\mathbf{3}, \mathbf{1}, \mathbf{4})_{1/6}^{(0),2} + 2 \times (\mathbf{3}_A, \mathbf{1}, \mathbf{1})_{1/3}^{(0),0} + h.c.]$$

$$+ [3 \times (\mathbf{1}, \mathbf{1}, \mathbf{1})_1^{(0),0} + (\mathbf{1}, \mathbf{1}, \mathbf{1})_1^{(-2),1} + 2 \times (\mathbf{1}, \mathbf{1}, \mathbf{6}_A)_0^{(0),1} + h.c.]$$

$$+ 3 \times (\mathbf{1}, \mathbf{2}, \mathbf{4})_0^{(0),2} + 6 \times (\mathbf{1}, \mathbf{1}, \bar{\mathbf{4}})_{-1/2}^{(-1),0} + 3 \times (\mathbf{1}, \mathbf{1}, \bar{\mathbf{4}})_{1/2}^{(-1),0} + 3 \times (\mathbf{1}, \mathbf{1}, \mathbf{4})_{1/2}^{(-1),1}$$