

Differential Calculus

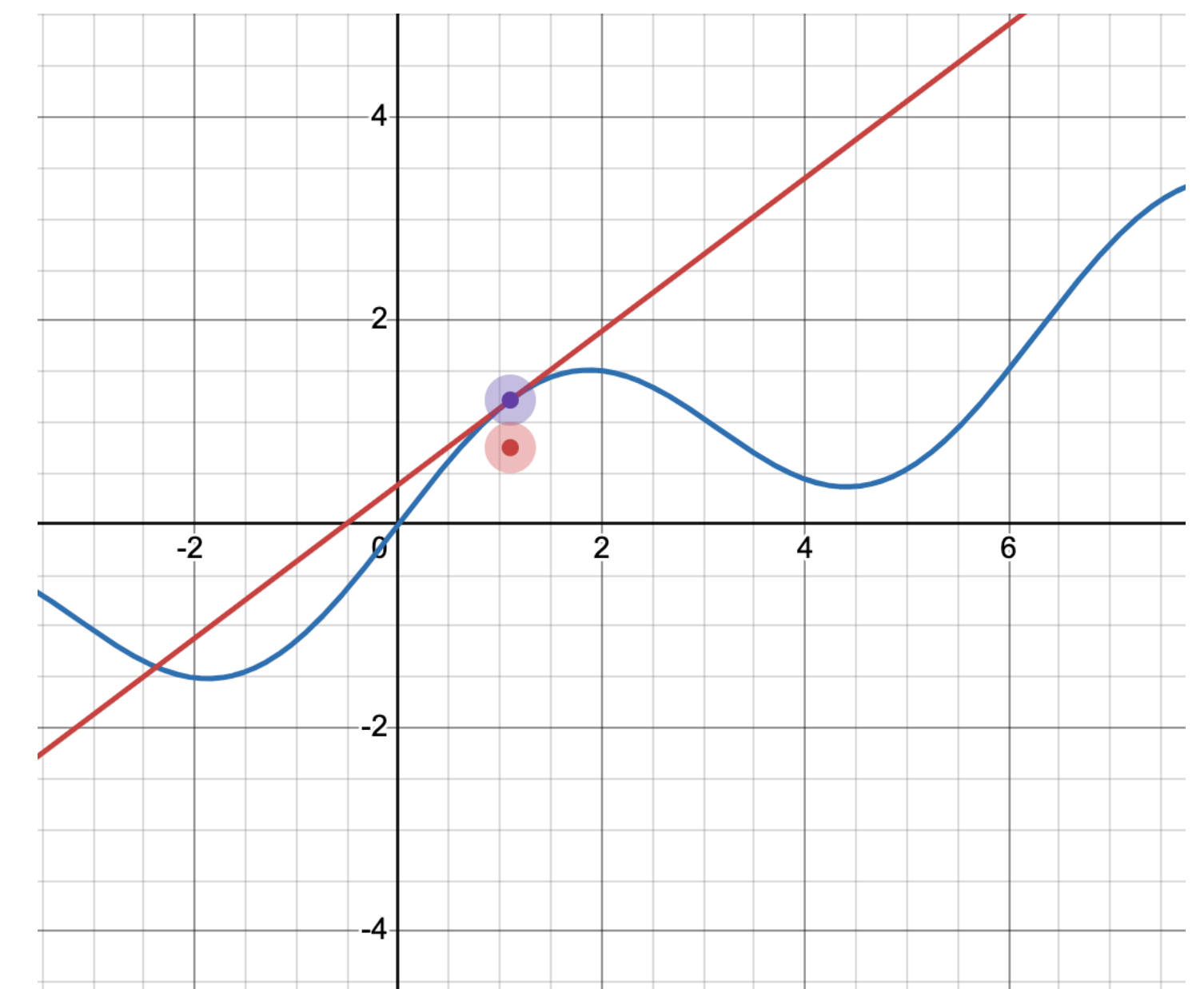
Chris Palmer, July 9th, 2024

Definition with limits

- When you first learn derivatives you had to use this (and find a way to factor out h from the numerator) to compute derivatives.

- $$\frac{df}{dx}(x = a) = \lim_{h \rightarrow 0} \frac{f(a + h) - f(a)}{h}$$

- This relates directly to the graphical definition of the slope of the tangent line at $x = a$.
- One should always be able to start from an infinite table of numbers and draw an infinite number of derivatives.
 - No model needed.



Derivative to remember

- Polynomials

- $f(x) = ax^n$ $\frac{df}{dx} = ?$

- Sine/Cosine

- $g(t) = A \sin(\omega t)$ $\frac{dg}{dt} = ?$

- $h(\omega) = B \cos(\omega t)$ $\frac{dh}{d\omega} = ?$

- Exponential

- $l(T) = l_0 e^{aT}$ $\frac{dl}{dT} = ?$

- Logarithms

- $k(s) = k_0 \ln(s)$ $\frac{dk}{ds} = ?$

Derivative to remember

- Polynomials

- $f(x) = ax^n$ $\frac{df}{dx} = anx^{n-1}$

- Sine/Cosine

- $g(t) = A \sin(\omega t)$ $\frac{dg}{dt} = A\omega \cos(\omega t)$

- $h(\omega) = B \cos(\omega t)$ $\frac{dh}{d\omega} = -Bt \sin(\omega t)$

- Exponential

- $l(T) = l_0 e^{aT}$ $\frac{dl}{dT} = l_0 a e^{aT}$

- Logarithms

- $k(s) = k_0 \ln(s)$ $\frac{dk}{ds} = \frac{k_0}{s}$

$$f(x) = \sqrt{x}$$

$$g(t) = \left(\frac{1}{2}\right)^t$$

$$h(\omega) = \frac{10}{\omega^3}$$

$$L(I) = 10 \log \left(\frac{I}{I_0} \right)$$

Chain rule

- Peel away the functions like layers on an onion.

- $f(x) = g(h(x)); \quad \frac{df}{dx} = \frac{dg}{dh} \frac{dh}{dx}$

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- $f(t) = \sin(e^{At})$

- What are g and h ? Compute the derivative.

- Got time? $h(x) = \ln(\sqrt{x^2 + 1})$

Product rule

- $h(x) = f(x)g(x); \quad \frac{dh}{dx} = \frac{df}{dx}g + f\frac{dg}{dx}$
- Explain that in words to your partner.

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- $h(x) = f(x)g(x); \quad \frac{dh}{dx} = \frac{df}{dx}g + f\frac{dg}{dx}$
- Explain that in words to your partner.
- Let's say that $h(x) = \frac{f(x)}{g(x)}$; use the product rule to derive the "quotient rule".
 - Hint: you need the chain rule too.

Product rule

- $h(x) = f(x)g(x); \quad \frac{dh}{dx} = \frac{df}{dx}g + f\frac{dg}{dx}$
- Take turns working through these with a partner.
 - $h(x) = (x^2 - 4)(x^3 + x)$
 - $y = y_0 \tan x$
 - $P(t) = \frac{Ae^{-at}}{t^2 - 3}$

Product rule

- $h(x) = f(x)g(x)k(x); \quad \frac{dh}{dx} = \frac{df}{dx}gk + f\frac{dg}{dx}k + fg\frac{dk}{dx}$
- Explain that in words again.

Product rule

- $h(x) = f(x)g(x)k(x); \quad \frac{dh}{dx} = \frac{df}{dx}gk + f\frac{dg}{dx}k + fg\frac{dk}{dx}$
- Take turns with a partner.
 - $f(x) = (x^2 - 3)(x + 2)(x + 4)$
 - $g(t) = e^{at} \frac{\sin \omega t}{\cos 2\omega t}$

Example: Delta Functions

- $$\delta(g(x)) = \sum_{x_i \in \{x_i | g(x_i) = 0\}} \frac{1}{|g'(x_i)|} \delta(x - x_i)$$
- Compute $\delta(g(x))$ when $g(x) = (x - 3)(x + 1)(x + 2)$.

Implicit differentiation

- If one cannot solve for a single variable, one can still find the derivative by differentiating each term and solving for the derivative you want.
- For example, what is $\frac{dy}{dx}$ when $x^2 - xy - y^2 - 2y = 0$.

Parametric derivatives

- Let's say we know position as a function of time.
 - $\vec{r}(t) = (x(t), y(t))$, how do find $\frac{dy}{dx}$?

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- $\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}}$

- $\vec{r}(t) = \left(v_0 t, -\frac{g}{2} t^2 \right)$; find $\frac{dy}{dx}$

Euler-Langrange Equation

- $$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0$$

- Where $L = T - U$

- Simple pendulum

- What are T and U ?

- Evaluate Euler-Langrange Equation