

BESSY II BEAMLINE CONTROL SYSTEM STATUS & FUTURE PLANS

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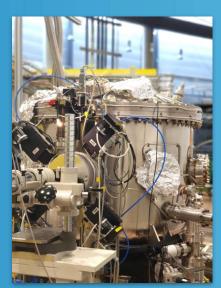
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Motion Control Hardware



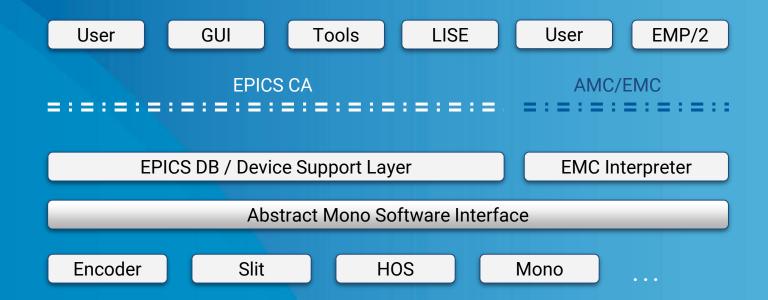




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Motion Control Software





Obsolescence Management – Issues & Solutions

EPICS 3.14 Branch	 Update to EPICS 7 Involves OS: Upgrade to Linux / RTEMS / VxWorks V6.8 Involves Hardware: CPU Boards / IPC
Old OMS Motion Controllers	 Fast upgrade: MAXv (OMS) / Geobricks Full stack: Omron, Beckhoff TwinCAT, Newpor, Galil, Aerotech, OMS,
Heidenhain Encoders RON905	 Incremental Encoders Absolute Encoders -> More hardware involved Interface to motion controller
Old DT motion controllers	Power Brick or comparable full stack motion controllers
VME Crates / CPU Boards	 CAN Bus > Other field bus with Ethercat and IPC? Serial Connection, Involves AMC > EMP/2 and others Analog/Digital IO has to be replaced
GUI	EPICS: Python, C++ or Java



Choosing the Motion Control Concept

- Long term availability and support
- Continuously deliver small high quality upgrades
- Hardware decisions as late as possible
- Compact industrial design

→ Lean Software development with agile work cycles



THANK YOU FOR YOUR ATTENTION!