



AI in medical imaging

Status, opportunities, pitfalls and challenges

Dr Mitra Safavi-Naeini

Principal Physicist - ANSTO

Science. Ingenuity. Sustainability.

ANSTO We are the national nuclear science and technology agency

Operating safely for over 60 years

Home of Australia's landmark research infrastructure



Lucas Heights | NSW



Main campus

Clayton | VIC



Australian Synchrotron

Camperdown | NSW



Cyclotron



Artificial intelligence: what is intelligence?





Big Data

Three Vs:

- Volume: Exponential increase
- Velocity: Rate at which it is produced
- Variety: Different formats with no or little structure



- There is an additional one that matches medical data:
 - Veracity: Data might be incomplete, noisy, not meaningful, uncertain, ambiguous and inconsistent.













Is it AI?



ANSTO

https://www.technologyreview.com/2018/11/10/139137/is-this-ai-we-drew-you-a-flowchart-to-work-it-out/

What is machine learning?

- All useful programs "learn" something
- Learning is improving at a task (set of skills) with experience
 - Experience = Data
 - The more data the better
 - However, more data requires more computational power and storage

"Field of study that gives computers the ability to learn without being explicitly programmed." ~Arthur Samuel (1959)



Data What is machine learning?

Conventional programming



Example: Newton-Raphson method

$$x_1 = x_0 - f(x_0)/f'(x_0)$$







---- Cost



What is machine learning?

Conventional programming



Machine Learning





Conventional programming



Basic paradigm

Observe a set of examples: training data

Infer something about the underlying model: inference engine

Use inference to make predictions about unseen data:
 test data

$\textbf{Training dataset} \rightarrow \textbf{Inference Engine} \rightarrow \textbf{Test dataset}$





Uribe et al., 2019 "Machine Learning in Nuclear Medicine: Part 1—Introduction" JNM, 60 (4) 451-458; **DOI:** 10.2967/jnumed.118.223495

ANSTO

Supervised, semi-supervised, unsupervised learning



Example: segmentation and quantification



Striatal dopamine transporter binding

E. Montagnon et al., 2020 "Deep learning workflow in radiology: a primer". Insights Imaging 11, 22 (2020). <u>https://doi.org/10.1186/s13244-019-0832-5</u>



Status: what works?

- New Image reconstruction methods
- Quality assessment algorithms
- Triaging of cases to find similar patient data and diagnostic classification
- Lesion and disease detection and classification
- Segmentation, identification and feature extraction (radiomics) and quantification





What are the challenges? What is on the horizon?

- Diversification of learning for prognosis and predictive information.
- Building trust and reliability in the models
- Labelling the unlabelled image-data using unsupervised learning.
- Fairness and bias mitigation and understanding the limits of our algorithms.



Garbage in - garbage out!

Learning

- Declarative knowledge (memorising)
 - Accumulation of individual facts
 - Limitations: Storage capacity and observation time

- Imperative knowledge (generalisation)
 - Deduce new facts from old facts
 - Limitation: accuracy of deduction process (assuming that past can predict the future)



Demonstration: Brain tumour segmentation

- This is an example from Matlab, using the Deep Learning toolbox.
- The first and most important part of any ML solution is training data
- This example uses segmented MRI brain images from the BraTS data set from the Medical Segmentation decathlon (<u>http://medicaldecathlon.com/</u>)



Training data

- The data set includes 750 MRI images of brains with tumours, 484 of which have been manually labelled as **tumour** or **background**. These are what we will use.
 Image dimensions: 240 (h) x 240 (w) x 155 (d) x 4
 - (scan modality)
- Labelled images are divided into three subsets:
 - **Training** (400) to train the neural network
 - Validation (29) to monitor over/underfitting during training
 - Testing (55) to evaluate the performance of the trained network



MRI image sample





Preprocessing and preparation of training data

- Volume and label images are converted from NIFTI to Matlab binary format
- To reduce the memory and processing burden, the images are cropped to remove non-brain regions
- 16 132x132x132 subsets ('patches') of each image are randomly selected as training samples
- Patches are normalised so we don't have to do this later during training (faster to just do it once)



Constructing the network

- We will use U-Net, an encoder/decoder convolutional neural network (CNN) which is widely used for image segmentation
- A default 3D U-Net network is constructed; input dimension is the patch size (132x132x132x4) and output dimension is 44x44x44x2 (due to the use of 'valid' style padding on each patch - no zero-padding is used)
- The input and output layers are modified from defaults
 - Input layer does not need to do normalisation (already done during preprocessing)
 - Output layer is changed to a dicePixelClassificationLayer for better segmentation of small tumour regions

Training hyperparameters

- The main training hyperparameters of interest (and suggested values):
 - Use the **adam** optimiser (popular choice for segmentation)
 - Specify which data you are using for validation, and how often to validate (e.g. every 400 iterations)
 - Maximum number of training epochs (passes through all training data - e.g. 50)
 - Initial learning rate (0.0005), mode of decrease ('piecewise') and rate of decrease (x0.95 every 5 epochs)
 - MiniBatchSize make larger if you have more GPU memory (but you might be better off with larger patch size)



Training

• This is the easy part - one line of code!

[net, info] = trainNetwork (dsTrain, lgraph, options);

- Igraph is the network, dsTrain is our training datastore and options are our training options
- Important: save the resulting network **net** for future use
 it will be about 60 MB
- Takes roughly 30 hours to train on a powerful GPU/CPU system - *much* slower without a GPU



Applying the trained network

Since the input size of the network is smaller than the dimension of the training data, we step through the input image size with a stride equal to the output patch size, and extract patches equal to the input patch size.
Each patch is segmented:

patchSeg = semanticseg (patch, net);

 The resulting segmented patches are then stitched back together and the final image is cropped to the original size



Ground truth (L) and segmented (R)

Performance

- The network performs very well. Results for testing data show that:
 - ~98% of the network-classified voxels agree with the ground truth (true positive + true negative)
 - Jaccard score is > 95% for all evaluated images
 - Dice similarity score > 99.9% for background and > 95% for tumour
- The approach can be generalised to other image segmentation problems





Original example:

https://au.mathworks.com/help/vision/ug/segment-3d-braintumor-using-deep-learning.html

Commented code:





Thank you



Email Address: mitras@ansto.gov.au

