

# ROTATING NEUTRON STARS

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# Spacetime Metric

For a stationary, axisymmetric perfect fluid:

$$ds^2 = -e^{2\nu} dt^2 + e^{2\psi} (d\phi - \omega dt)^2 + e^{2\mu} (d\varpi^2 + dz^2)$$

Assumptions:

1. **Stationary** : Killing vector  $t^\alpha$  which is *timelike* at spatial infinity
2. **Axisymmetric**: Killing vector  $\phi^\alpha$  which is *spacelike* everywhere, vanishes on a *symmetry axis* and whose orbits are *closed curves*
3. **Asymptotically flat** :  $t_\alpha t^\alpha \rightarrow -1$  ,  $\phi_\alpha \phi^\alpha \rightarrow +1$  ,  $t_\alpha \phi^\alpha \rightarrow 0$  , at spatial inf.

From 1., 2., 3.  $\Rightarrow t^\alpha$  and  $\phi^\alpha$  *commute*

$\Rightarrow$  we can *choose* coordinates  $t$  and  $\phi$  such that  $t^\alpha$  and  $\phi^\alpha$  are *coordinate vectors*:

$$t^\alpha = \frac{\partial}{\partial t} \quad \text{and} \quad \phi^\alpha = \frac{\partial}{\partial \phi}$$

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# Assumption of Circularity

The flow is *circular*, if the 4-velocity  $u^\alpha$  and the charge current density  $J^\alpha$  are *toroidal*

$$u^{[\alpha} t^\beta \phi^{\gamma]} = 0 \Rightarrow u^\alpha = \{u^t, 0, 0, u^\phi\}$$

$$J^{[\alpha} t^\beta \phi^{\gamma]} = 0 \Rightarrow J^\alpha = \{J^t, 0, 0, J^\phi\}$$

The latter condition is satisfied by *poloidal* magnetic fields.

These conditions imply that  $T_{\alpha\beta}$  satisfies:

$$t^\delta T_{\delta[\alpha} t_\beta \phi_\gamma] = 0 \Leftrightarrow T^\alpha_t = \text{linear combination of } t^\alpha, \phi^\alpha$$

$$\phi^\delta T_{\delta[\alpha} t_\beta \phi_\gamma] = 0 \Leftrightarrow T^\alpha_\phi = \text{linear combination of } t^\alpha, \phi^\alpha$$

which leads to the following identities for the Killing vectors:

$$t_{[\alpha;\beta} t_\gamma \phi_\delta] = 0$$

$$\phi_{[\alpha;\beta} t_\gamma \phi_\delta] = 0$$

One can then show that  $t^\alpha$  and  $\phi^\alpha$  are everywhere *orthogonal* to the 2-surfaces formed by the integral curves of the remaining two coordinates  $x^1$  and  $x^2$

$$\Rightarrow g_{t1} = g_{t2} = g_{\phi1} = g_{\phi2} = 0$$

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# Quasi-Isotropic Coordinates

The nonzero components of the metric involving  $t$  and  $\phi$  are written as *invariant combinations* of the Killing vectors:

$$g_{tt} = t^\alpha t_\alpha = -e^{2\nu} + \omega^2 e^{2\psi}$$

$$g_{t\phi} = t^\alpha \phi_\alpha = -\omega e^{2\psi}$$

$$g_{\phi\phi} = \phi^\alpha \phi_\alpha = e^{2\psi}$$

Then

$$g_{\alpha\beta} = \begin{bmatrix} -e^{2\nu} + \omega^2 e^{2\psi} & 0 & 0 & -\omega e^{2\psi} \\ & g_{11} & g_{12} & 0 \\ & \text{sym.} & g_{22} & 0 \\ & & & e^{2\psi} \end{bmatrix}$$

If one chooses *orthogonal coordinates*  $x^1$  and  $x^2$ , then  $g_{12}=0$ .

For the remaining components, one can choose an *isotropic gauge*, in which the  $(x^1, x^2)$  sub-space is *conformally flat*:

e.g. *cylindrical-like* coordinates:  $e^{2\mu}(d\varpi^2 + dz^2)$

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# Rotation of the Fluid

The ratio of the two components of the 4-velocity

$$\Omega \equiv \frac{u^\phi}{u^t} = \frac{d\phi/ds}{dt/ds} = \frac{d\phi}{dt}$$

is the *angular velocity* as seen by a *nonrotating observer at infinity*.

The normalization of  $u^\alpha$  specifies  $u^t$  :

$$u^\alpha u_\alpha = -1 \Rightarrow u^t = \frac{e^{-\nu}}{\sqrt{1 - (\Omega - \omega)^2 e^{2(\psi - \nu)}}}$$

If we set

$$v = (\Omega - \omega) e^{\psi - \nu}$$

Then

$$u^\alpha = \frac{e^{-\nu}}{\sqrt{1 - v^2}} \{1, 0, 0, \Omega\}$$

Since  $\phi^\alpha$  is a Killing vector, there is a conserved specific angular momentum for freely-falling observers:

$$u_\phi = (\Omega - \omega) e^{2\psi} u^t$$

Thus, *zero-angular momentum* observers (ZAMO's) with  $u_\phi = 0$ , are rotating with an angular velocity  $\Omega = \omega$  w.r.t. infinity (*dragging of inertial frames*)!

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# 3-Velocity

We can define an orthonormal tetrad frame attached to the ZAMO:

$$\begin{aligned}\omega^{(0)} &= e^\nu dt \\ \omega^{(1)} &= e^\mu d\varpi \\ \omega^{(2)} &= e^\mu dz \\ \omega^{(3)} &= e^\psi (d\phi - \omega dt)\end{aligned}$$

in which the metric becomes Minkowskian:  $g_{\alpha\beta} = \text{diag}\{-1, 1, 1, 1\}$ .

Transforming the 4-velocity from the coordinate frame to the *ZAMO* tetrad, one finds the components:

$$u^{(\alpha)} = \frac{1}{\sqrt{1-v^2}} \{1, 0, 0, v\}$$

Therefore,  $v$  is the *3-velocity* measured by the *ZAMO*.

# Proper Circumference

The *proper circumference* of a spatial circle at  $\varpi$ ,  $z$  and  $t=\text{const.}$  is

$$C = 2\pi\sqrt{g_{\phi\phi}} = 2\pi e^{\psi}$$

Thus, the *circumferential radius* is defined as

$$R := C/(2\pi) = e^{\psi}$$

Since  $R=\varpi$  at infinity, we can redefine:

$$e^{\psi} = \varpi B e^{-\nu}$$

Notice that *in vacuum*, one can *absorb*  $B$  in the definition of  $\varpi$  and  $z$  (only *three metric functions* are required).

In the *spherical limit*:  $B = 1$ ,  $\mu = -1$

$$\Rightarrow ds^2 = -e^{2\nu} dt^2 + e^{-2\nu} (d\varpi^2 + dz^2 + \varpi^2 d\phi^2)$$

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# Time Dilation and Redshifts

At a given location  $\varpi, z$ , the proper time for the *ZAMO* ( $d\phi = \omega dt$ ) is:

$$d\tau = e^\nu dt$$

Thus,  $e^\nu$  is the *time dilation* factor between the proper time for the *ZAMO* and coordinate time at infinity.

The *redshift* of emitted photons can be found from

$$z = \frac{\omega_E}{\omega_\infty} - 1$$

where

$$\frac{\omega_E}{\omega_\infty} = \frac{-p_\alpha u^\alpha}{-p_\alpha t^\alpha}$$

For photons emitted in the *forward* (+) or *backward* (-) direction at the equator:

$$p^\alpha = \text{const.} \times [t^\alpha + (e^{\nu-\psi} \pm \omega)\phi^\alpha]$$

so that

$$\{z_F, z_B\} = \left( \frac{1 \mp v}{1 \pm v} \right)^{1/2} \frac{e^{-\nu}}{1 \pm \omega e^{\psi-\nu}} - 1$$

while, for photons emitted at the *pole*, along the symmetry axis:

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# Summary, so far

The metric of a stationary, axisymmetric star with purely circular flow is:

$$ds^2 = -e^{2\nu} dt^2 + e^{2\psi} (d\phi - \omega dt)^2 + e^{2\mu} (d\varpi^2 + dz^2)$$

where three metric functions have an invariant meaning:

$e^\nu$  (*time dilation*)

$e^\psi$  (*circumferential radius*)

$\omega$  (*dragging of inertial frames*)

while  $e^{2\mu}$  is a *conformal factor* for the geometry of the  $(\varpi, z)$  2-planes.

The *angular velocity* is measured by an *observer at infinity*

$$\Omega \equiv \frac{u^\phi}{u^t} = \frac{d\phi}{dt}$$

while the *3-velocity*  $v$  is measured by the *zero-angular-momentum observer (ZAMO)*.

# Description of the Fluid

For a perfect fluid, we define the following *intensive properties*, all measured by an observer *comoving* with the fluid:

$n$  *baryon number density*

$\rho$  *baryon mass density*

$e$  *total energy density*

$p$  *isotropic pressure*

$\varepsilon$  *specific internal energy*

$h$  *specific enthalpy*

$s$  *specific entropy*

where

$$e = \rho(1 + \varepsilon)$$

$$h = \frac{e + p}{\rho}$$

The *equation of state* can be considered to be of the form

$$p = p(\rho), \quad e = e(\rho) \quad \text{barotropic (cold stars)}$$

$$p = p(\rho, s), \quad e = e(\rho, s) \quad \text{general (hot stars)}$$

If we assume that the fluid is *nonmagnetized*, then the stress-energy tensor is

$$T_{\alpha\beta} = (e + p)u_{\alpha}u_{\beta} + pg_{\alpha\beta}$$

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# The Magnetized Fluid (I)

In relativistic MHD, one defines “electric” and “magnetic” 4-vectors

$$\begin{aligned} E^\alpha &= F^{\alpha\beta} u_\beta \\ B^\alpha &= {}^*F^{\alpha\beta} u_\beta \end{aligned}$$

where  $F^{\alpha\beta}$  is the Faraday tensor and  ${}^*F^{\alpha\beta}$  its dual. The two vectors have only three non-vanishing components normal to the 4-velocity:

$$E_\alpha u^\alpha = B_\alpha u^\alpha = 0$$

Ohm’s law relates the “electric” 4-vector to the current density  $J^\alpha$

$$\sigma E^\alpha = J^\alpha + u_\beta J^\beta u^\alpha$$

In the *ideal MHD* approximation, the *conductivity*  $\sigma$  is assumed to be *infinite*. In order for  $J^\alpha$  to be finite:

$$E^\alpha = 0$$

so that only  $B^\alpha$  is needed to describe ideal MHD.

The usual electric field 3-vector  $E^i$  coincides with the normal components of  $E^\alpha$  in a comoving frame. Thus, in ideal MHD, *there is no electric field in the comoving frame*.

# The Magnetized Fluid (II)

The Faraday tensor becomes

$$\begin{aligned}F^{\alpha\beta} &= \epsilon^{\alpha\beta\gamma\delta} u_\gamma B_\delta \\ *F_{\alpha\beta} &= u^\alpha B^\beta - u^\beta B^\alpha\end{aligned}$$

and the stress-energy tensor of the E/M field is

$$\begin{aligned}T^{\alpha\beta} &= \frac{1}{4\pi} (F^{\alpha\sigma} F^\beta{}_\sigma - \frac{1}{4} g^{\alpha\beta} F_{\lambda\mu} F^{\lambda\mu}) \\ &= \frac{1}{4\pi} (B^2 u^\alpha u^\beta + \frac{1}{2} B^2 g^{\alpha\beta} - B^\alpha B^\beta)\end{aligned}$$

To a first approximation, we can assume that the total stress-energy tensor is

$$\begin{aligned}T^{\alpha\beta} &= (e + p) u^\alpha u^\beta + p g^{\alpha\beta} \\ &\quad + \frac{1}{4\pi} (B^2 u^\alpha u^\beta + \frac{1}{2} B^2 g^{\alpha\beta} - B^\alpha B^\beta)\end{aligned}$$

In addition, if the flow is circular, the Faraday tensor is given by a *vector potential*

$$F_{\alpha\beta} = A_{\beta,\alpha} - A_{\alpha,\beta}$$

with components:

$$A_\alpha = \{A_t, 0, 0, A_\phi\}$$

# The Equations of Structure

To obtain a self-consistent equilibrium solution, we need:

4 components of the *Einstein field equations*, for  $\nu$ ,  $\psi$ ,  $\omega$ , and  $\mu$

$$G_{\alpha\beta} = 8\pi T_{\alpha\beta}$$

2 components of the *fluid conservation equations* for the specific enthalpy  $h$  and the angular velocity  $\Omega$

$$T^{\alpha\beta}_{;\alpha} = 0$$

$$(\rho u^\alpha)_{;\alpha} = 0$$

2 components of *Maxwell's equations* for  $A_\tau$ ,  $A_\phi$

$$*F^{\alpha\beta}_{;\beta} = 0$$

$$F^{\alpha\beta}_{;\beta} = 4\pi J^\alpha$$

An nonmagnetized equilibrium solution is *uniquely determined*, once we *specify*:

$p=p(\rho, s)$ ,  $e=e(\rho, s)$       *equation of state*

$\Omega=\Omega(\varpi, z, A)$       *rotation law*

$\rho_c$       *central density*

$r_p/r_e$       *axes ratio*

# The Einstein Field Equations

The 4 components of the Einstein field equations can be derived, e.g. in the *ZAMO* tetrad. The  $R_{(t)(t)}$ ,  $R_{(t)(\phi)}$  and  $R_{(t)(t)} + R_{(\phi)(\phi)}$  components yield 3 *elliptic* equations:

$$\begin{aligned}\nabla \cdot (B \nabla \nu) &= \frac{1}{2} \varpi^2 B^3 e^{-4\nu} \nabla \omega \cdot \nabla \omega + 4\pi B e^{2\mu} \left[ \frac{(e+p)(1+v^2)}{1-v^2} + 2p \right] \\ \nabla \cdot (\varpi^2 B^3 e^{-4\nu} \nabla \omega) &= -16\pi \varpi B^2 e^{2(\mu-\nu)} \frac{(e+p)v}{1-v^2} \\ \nabla \cdot (\varpi \nabla B) &= 16\pi \varpi B e^{2\mu} p\end{aligned}$$

where  $\nabla$  is the 2-dimensional *flat-space* Laplacian operator.

For *nonmagnetized stars*, one can use the *Ricci identities*  $R_{(\varpi)(\varpi)} = R_{(z)(z)}$  and  $R_{(\varpi)(z)} = 0$ , to construct a *first-order differential equation* for the metric function  $\mu$ .

For *magnetized stars*, one can still construct an *elliptic equation* for  $\mu$  from the remaining components of the Einstein equations.

The elliptic equations can be written in *integral form*, using appropriate *Green's functions*.

# RNS code

Metric:

Stergioulas & Friedman, 1995

$$2\nu \rightarrow \gamma + \rho$$

$$2\psi \rightarrow \gamma - \rho$$

$$\mu \rightarrow \alpha$$

Then:

$$ds^2 = -e^{\gamma+\rho} dt^2 + e^{\gamma-\rho} r^2 \sin^2 \theta (d\phi - \omega dt)^2 + e^{2\alpha} (dr^2 + r^2 d\theta^2)$$

Set:

$$\cos \theta \rightarrow \mu$$

Convert field equations using *Green's functions*

Differential form:

Integral form:

$$\Delta[\rho e^{\gamma/2}] = S_\rho(r, \mu),$$

$$\left( \Delta + \frac{1}{r} \frac{\partial}{\partial r} - \frac{1}{r^2} \mu \frac{\partial}{\partial \mu} \right) \gamma e^{\gamma/2} = S_\gamma(r, \mu),$$

$$\left( \Delta + \frac{2}{r} \frac{\partial}{\partial r} - \frac{2}{r^2} \mu \frac{\partial}{\partial \mu} \right) \omega e^{(\gamma-2\rho)/2} = S_\omega(r, \mu),$$



$$\rho = -\frac{1}{4\pi} e^{-\gamma/2} \int_0^\infty dr' \int_{-1}^1 d\mu' \int_0^{2\pi} d\phi' r'^2 S_\rho(r', \mu') \frac{1}{|\mathbf{r} - \mathbf{r}'|}$$

$$r \sin \theta \gamma = \frac{1}{2\pi} e^{-\gamma/2} \int_0^\infty dr' \int_0^{2\pi} d\theta' r'^2 \sin \theta' S_\gamma(r', \theta') \log |\mathbf{r} - \mathbf{r}'|,$$

$$r \sin \theta \cos \phi \omega = -\frac{1}{4\pi} e^{(2\rho-\gamma)/2} \int_0^\infty dr' \int_0^\pi d\theta' \int_0^{2\pi} d\phi' r'^3 \sin^2 \theta' \cos \phi' S_\omega(r', \theta') \frac{1}{|\mathbf{r} - \mathbf{r}'|}$$

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Komatsu, Eriguchi & Hachisu  
(1989) method

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Differential form:

Integral form:

$\Delta[\rho e^{\gamma/2}] = S_\rho(r, \mu),$ $\left( \Delta + \frac{1}{r} \frac{\partial}{\partial r} - \frac{1}{r^2} \mu \frac{\partial}{\partial \mu} \right) \gamma e^{\gamma/2} = S_\gamma(r, \mu),$ $\left( \Delta + \frac{2}{r} \frac{\partial}{\partial r} - \frac{2}{r^2} \mu \frac{\partial}{\partial \mu} \right) \omega e^{(\gamma-2\rho)/2} = S_\omega(r, \mu),$	$\Rightarrow$	$\rho = -\frac{1}{4\pi} e^{-\gamma/2} \int_0^\infty dr' \int_{-1}^1 d\mu' \int_0^{2\pi} d\phi' r'^2 S_\rho(r', \mu') \frac{1}{ \mathbf{r} - \mathbf{r}' },$ $r \sin \theta \gamma = \frac{1}{2\pi} e^{-\gamma/2} \int_0^\infty dr' \int_0^{2\pi} d\theta' r'^2 \sin \theta' S_\gamma(r', \theta') \log  \mathbf{r} - \mathbf{r}' ,$ $r \sin \theta \cos \phi \omega = -\frac{1}{4\pi} e^{(2\rho-\gamma)/2} \int_0^\infty dr' \int_0^\pi d\theta' \int_0^{2\pi} d\phi' r'^3 \sin^2 \theta' \cos \phi' S_\omega(r', \theta') \frac{1}{ \mathbf{r} - \mathbf{r}' }.$
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# RNS code

Equation for  $\alpha$  is an ordinary ODE:

$$\begin{aligned} \alpha_{i\mu} = & -v_{i\mu} - \{(1 - \mu^2)(1 + rB^{-1}B_{i,r})^2 + [\mu - (1 - \mu^2)B^{-1}B_{i,\mu}]^2\}^{-1} \\ & \left[ \frac{1}{2}B^{-1}\{r^2B_{i,rr} - [(1 - \mu^2)B_{i,\mu}]_{i,\mu} - 2\mu B_{i,\mu}\}[-\mu + (1 - \mu^2)B^{-1}B_{i,\mu}] \right. \\ & + rB^{-1}B_{i,r}\left[\frac{1}{2}\mu + \mu rB^{-1}B_{i,r} + \frac{1}{2}(1 - \mu^2)B^{-1}B_{i,\mu}\right] \\ & + \frac{3}{2}B^{-1}B_{i,\mu}[-\mu^2 + \mu(1 - \mu^2)B^{-1}B_{i,\mu}] - (1 - \mu^2)rB^{-1}B_{i,\mu r}(1 + rB^{-1}B_{i,r}) \\ & - \mu r^2 v_{i,r}^2 - 2(1 - \mu^2)r v_{i,\mu} v_{i,r} + \mu(1 - \mu^2)v_{i,\mu}^2 - 2(1 - \mu^2)r^2 B^{-1}B_{i,r} \\ & \times v_{i,\mu} v_{i,r} + (1 - \mu^2)B^{-1}B_{i,\mu}[r^2 v_{i,r}^2 - (1 - \mu^2)v_{i,\mu}^2] + (1 - \mu^2)B^2 e^{-4v} \\ & \times \left[\frac{1}{4}\mu r^4 \omega_{i,r}^2 + \frac{1}{2}(1 - \mu^2)r^3 \omega_{i,\mu} \omega_{i,r} - \frac{1}{4}\mu(1 - \mu^2)r^2 \omega_{i,\mu}^2 + \frac{1}{2}(1 - \mu^2) \right. \\ & \left. \times r^4 B^{-1}B_{i,r} \omega_{i,\mu} \omega_{i,r} - \frac{1}{4}(1 - \mu^2)r^2 B^{-1}B_{i,\mu}[r^2 \omega_{i,r}^2 - (1 - \mu^2)\omega_{i,\mu}^2]\right], \end{aligned}$$

Cook, Shapiro & Teukolsky (1994)

compactified radial coordinate  $s$ :

$$r = r_e \frac{s}{1 - s}$$

$$r = 0 \rightarrow s = 0$$

$$r = r_e \rightarrow s = 0.5$$

$$r = \infty \rightarrow s = 1$$

# Hydrostationary Equilibrium

The conservation of the stress-energy tensor leads to the equations of motion

$$\frac{1}{e+p} \nabla p + u_\phi u^t \nabla \Omega - \frac{1}{e+p} (J^\phi - \Omega J^t) \nabla A_\phi = \nabla (\ln u^t)$$

For stationary configurations, this equation is integrable in special cases, e.g.

(i) Cold, nonmagnetized models:

$$\text{if } u_\phi u^t = F(\Omega) \Rightarrow \ln \left( \frac{h}{u^t} \right) + \int F(\Omega) d\Omega = \text{const.}$$

(ii) Cold, magnetized models:

$$\text{if } \Omega = \text{const.} \text{ and } \frac{J^\phi - \Omega J^t}{e+p} = f(A_\phi) \\ \Rightarrow \ln \left( \frac{h}{u^t} \right) - \int f(A_\phi) dA_\phi = \text{const.}$$

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# Maxwell's Equations

From

$$F^{\alpha\beta}{}_{;\beta} = 4\pi J^\alpha$$

one finds two *elliptic equations* for  $A_t$  and  $A_\phi$ . These can be written in *integral form*.

## Conserved Quantities Along the Flow

For the stationary, axisymmetric and circular flow:

$$\mathcal{L}_u(hu_t) = 0 \quad \text{Bernoulli's law}$$

$$\mathcal{L}_u(hu_\phi) = 0 \quad \text{cons. of specific angular momentum}$$

$$\mathcal{L}_u\omega_{\alpha\beta} = 0 \quad \text{cons. of circulation}$$

where the *relativistic vorticity*  $\omega_{\alpha\beta}$  is defined as

$$\omega_{\alpha\beta} = (hu_\beta)_{;\alpha} - (hu_\alpha)_{;\beta}$$

# The Virial Theorems

The well-known Newtonian Virial theorem for equilibrium configurations

$$2T + (3\gamma - 1)U + W = 0$$

has been generalized in GR by Bonazzola & Gourgoulhon

$$\begin{aligned} \lambda_3 \equiv & 4\pi \int_0^{+\infty} \int_0^\pi \left[ 3p + (\varepsilon + p) \frac{v^2}{1 - v^2} \right] e^{2\mu + \psi} r \, dr \, d\theta \\ & \times \left\{ \int_0^{+\infty} \int_0^\pi \left[ \partial\nu\partial\nu - \frac{1}{2}\partial\mu\partial\psi \right. \right. \\ & + \frac{e^{2\mu - 2\psi}}{2} r \sin^2 \theta \left( \frac{\partial\mu}{\partial r} + \frac{1}{r \tan \theta} \frac{\partial\mu}{\partial\theta} \right) \\ & + \frac{1}{4r} (1 - e^{2\mu - 2\psi} r^2 \sin^2 \theta) \left( \frac{\partial\psi}{\partial r} + \frac{1}{r \tan \theta} \frac{\partial\psi}{\partial\theta} \right. \\ & \left. \left. - \frac{1}{r \sin^2 \theta} \right) - \frac{3}{8} e^{2\psi - 2\nu} \partial\omega\partial\omega \right] e^\psi r \, dr \, d\theta \left. \right\}^{-1}, \end{aligned}$$

A 2-D Virial theorem has also been found:

$$\lambda_2 \equiv \frac{8\pi \int_0^{+\infty} \int_0^\pi \left[ p + (\varepsilon + p) \frac{v^2}{1 - v^2} \right] e^{2\mu} r \, dr \, d\theta}{\int_0^{+\infty} \int_0^\pi \left[ \partial\nu\partial\nu - \frac{3}{4} e^{2\psi - 2\nu} \partial\omega\partial\omega \right] r \, dr \, d\theta},$$

# Equilibrium Quantities

Using the unit normal  $\hat{n}^\alpha$  to the  $t=\text{const.}$  spacelike surfaces and the proper volume

$$dV = \sqrt{|^3g|} d^3x$$

one can define various *extensive* equilibrium quantities

$$M = \int \left( T_{\alpha\beta} - \frac{1}{2} g_{\alpha\beta} T \right) t^\alpha \hat{n}^\beta dV \quad \textit{gravitational mass}$$

$$M_0 = \int \rho u_\alpha \hat{n}^\alpha dV \quad \textit{baryon mass}$$

$$U = \int \rho \epsilon u_\alpha \hat{n}^\alpha dV \quad \textit{internal energy}$$

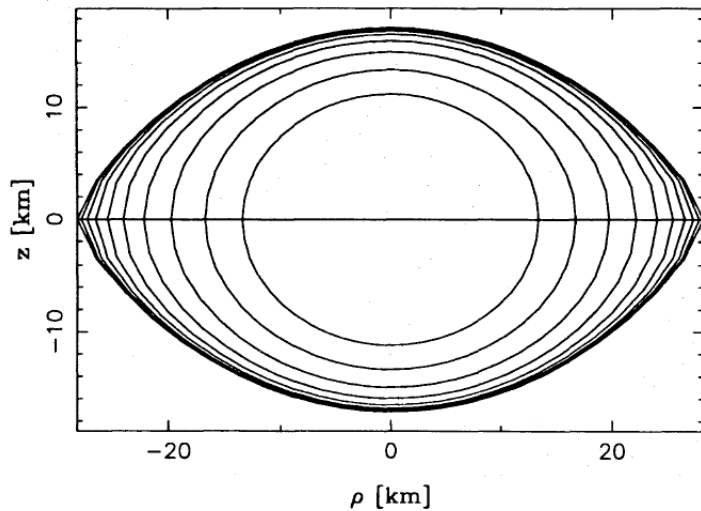
$$J = \int T_{\alpha\beta} \phi^\alpha n^\beta dV \quad \textit{angular momentum}$$

$$T = \frac{1}{2} \int \Omega dJ \quad \textit{rotational energy}$$

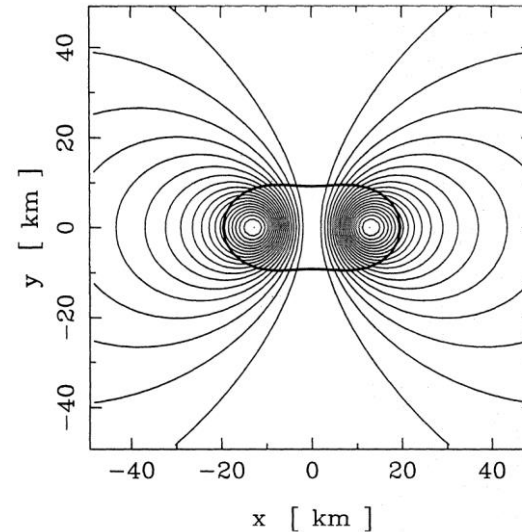
$$W = M - (M_0 + U + T) \quad \textit{gravitational binding energy}$$

$$I = J/\Omega \quad \textit{moment of inertia}$$

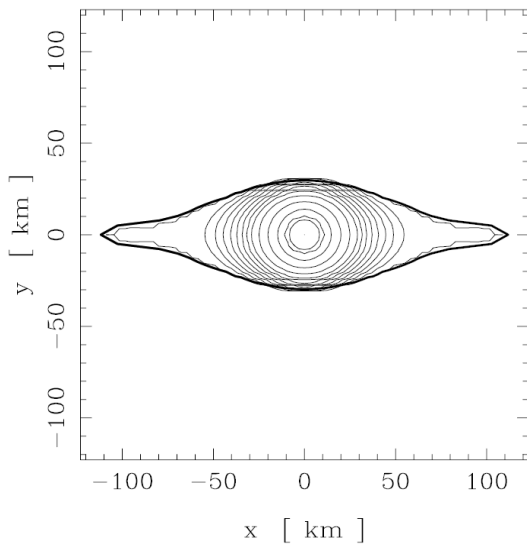
# Examples of Equilibrium Models



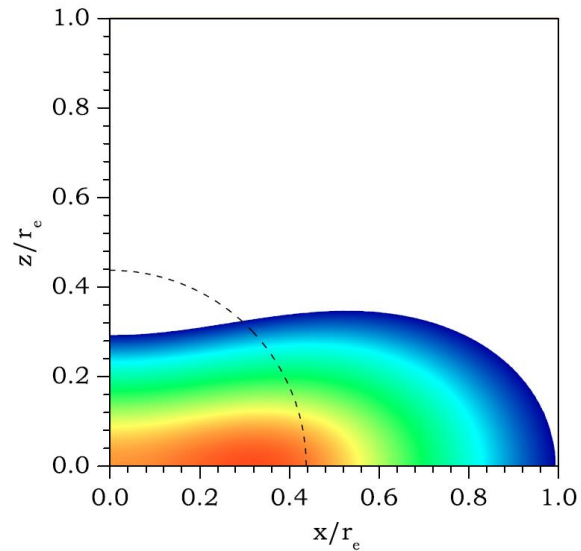
Bonazzola et al. 1993



Bocquet et al. 1995



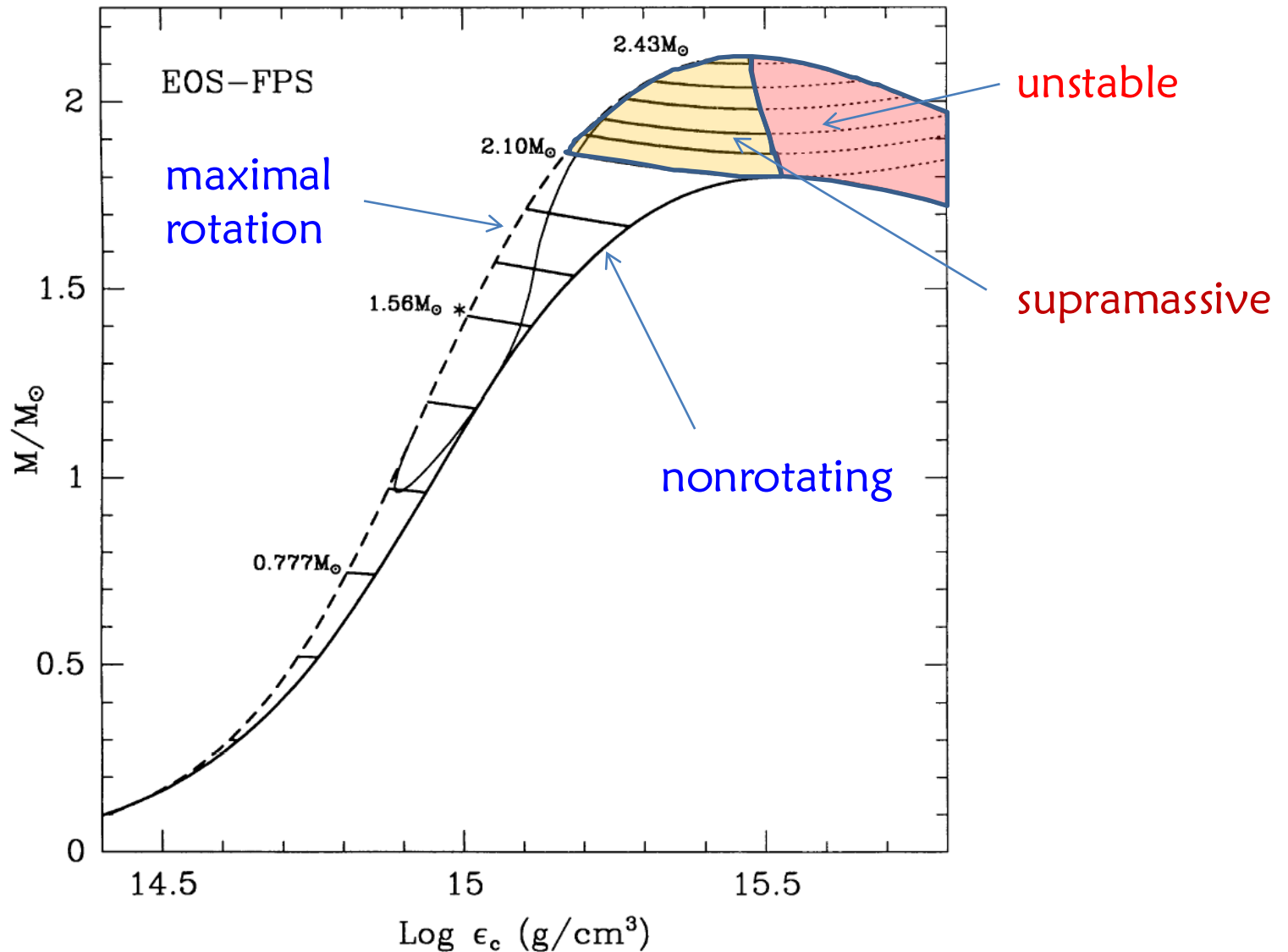
Goussard et al. 1998



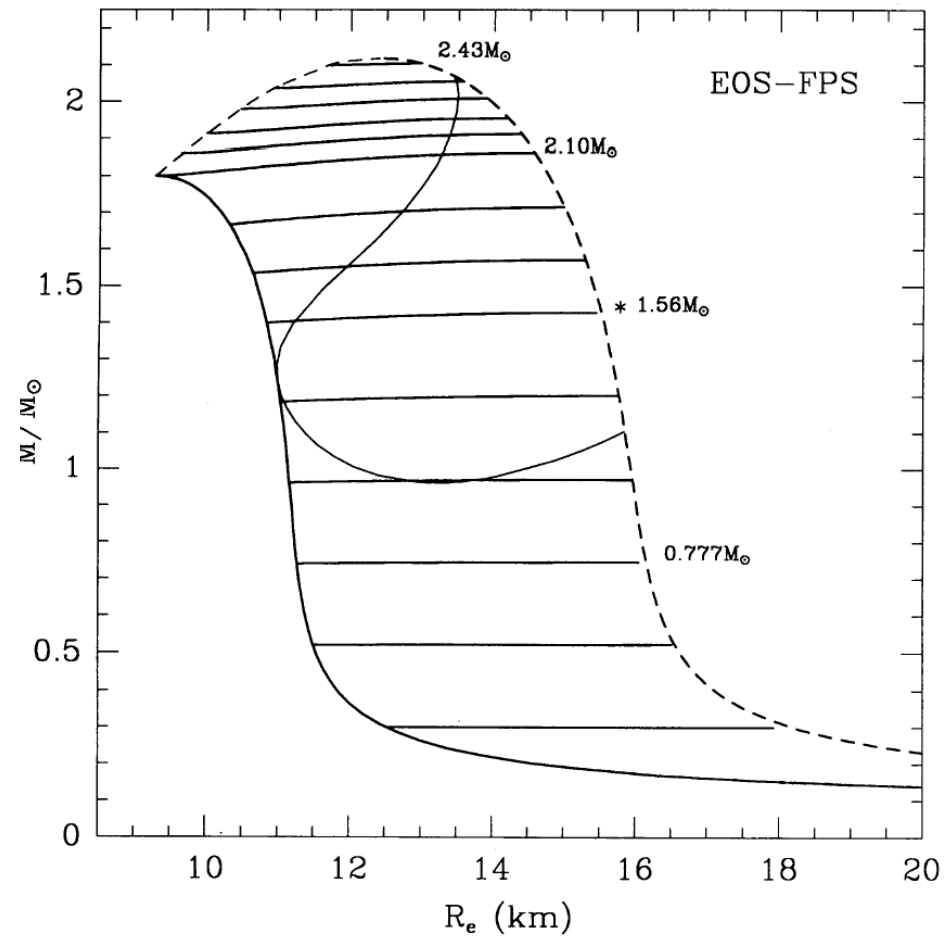
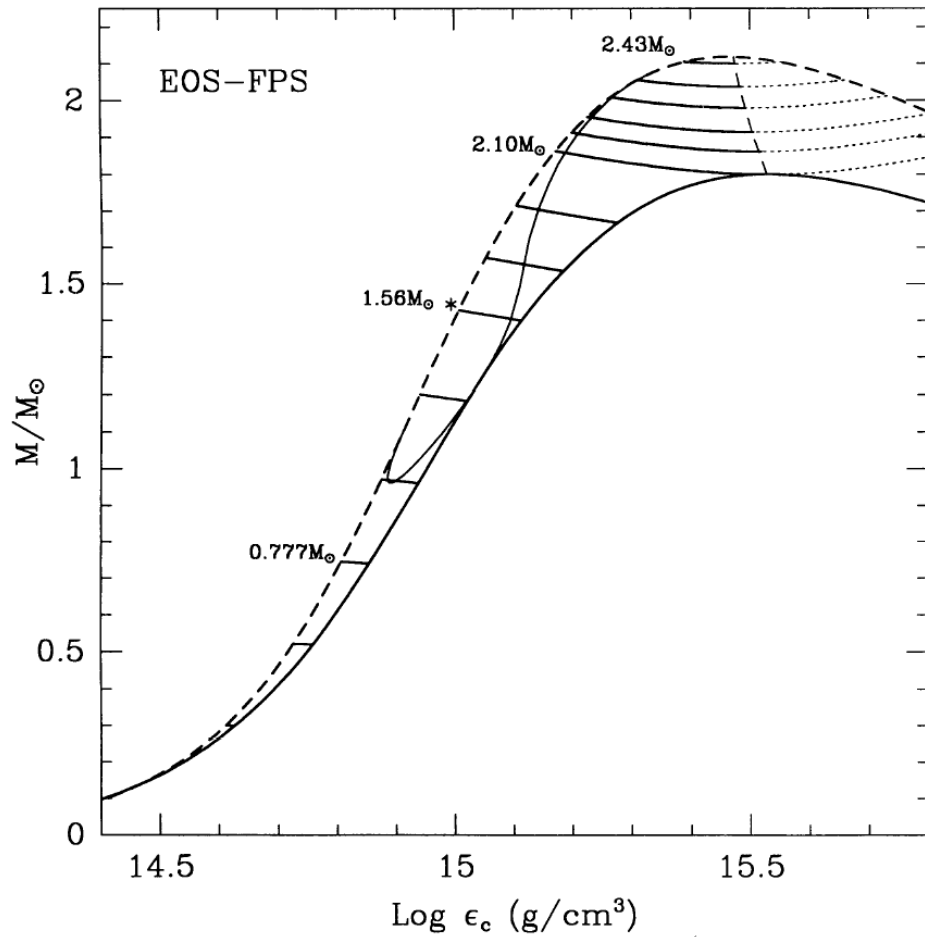
N. S., Apostolatos & Font, 2004

# Equilibria of Rotating Stars

Uniformly rotating equilibrium models for a realistic neutron star equation of state.

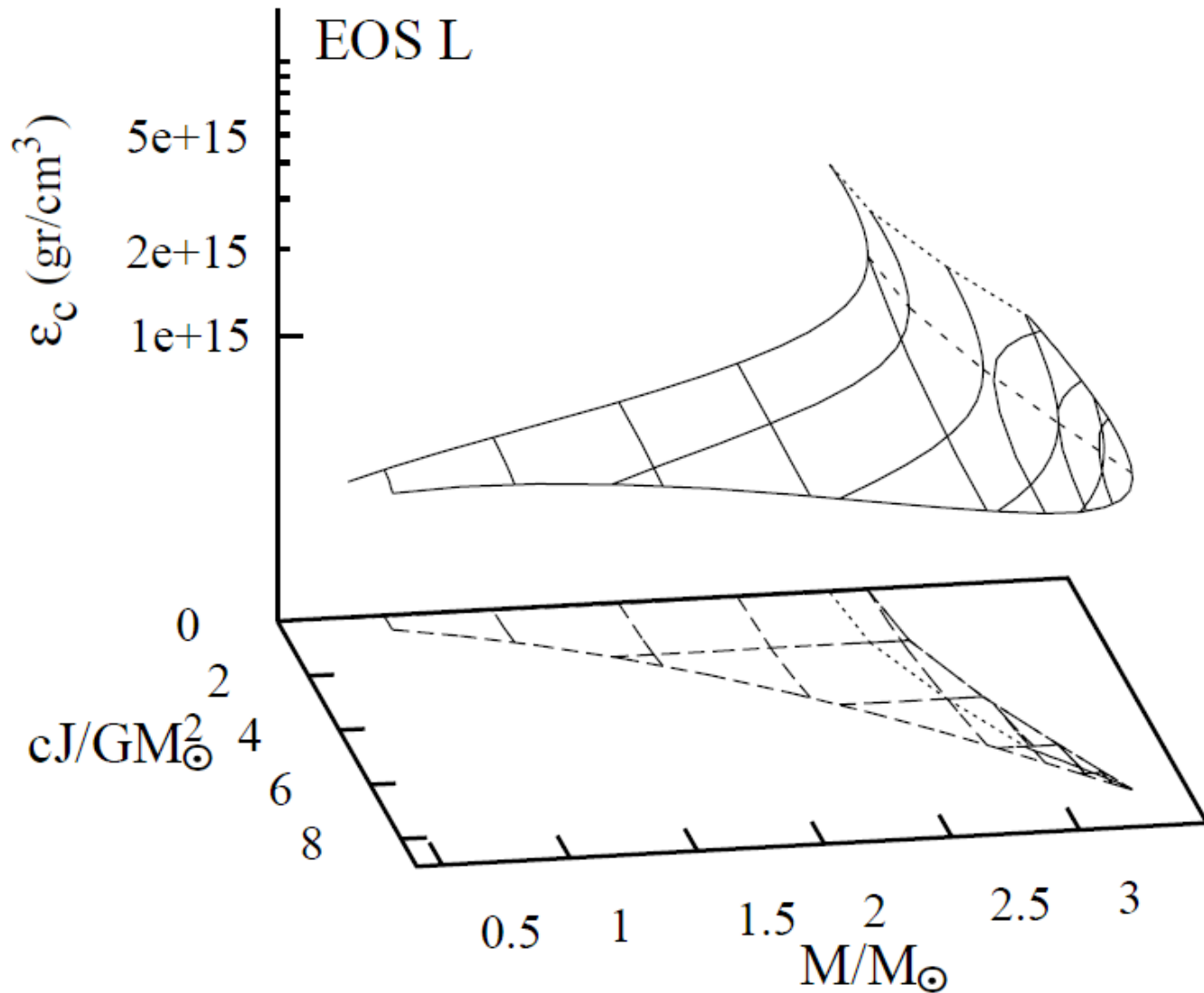


# Equilibrium Sequences (I)



(Cook, Shapiro & Teukolsky 1994)

# Equilibrium Sequences (II)



(N. S., Friedman 1995)

# Comparison of Different Codes

*N.S., Living Reviews in Relativity (2003)*

	AKM	Lorene/ rotstar	SF (260 × 400)	SF (70 × 200)	BGSM	KEH
$\bar{p}_c$	1.0					
$r_p/r_e$	0.7				$1 \times 10^{-3}$	
$\bar{\Omega}$	1.41170848318	$9 \times 10^{-6}$	$3 \times 10^{-4}$	$3 \times 10^{-3}$	$1 \times 10^{-2}$	$1 \times 10^{-2}$
$\bar{M}$	0.135798178809	$2 \times 10^{-4}$	$2 \times 10^{-5}$	$2 \times 10^{-3}$	$9 \times 10^{-3}$	$2 \times 10^{-2}$
$\bar{M}_0$	0.186338658186	$2 \times 10^{-4}$	$2 \times 10^{-4}$	$3 \times 10^{-3}$	$1 \times 10^{-2}$	$2 \times 10^{-3}$
$\bar{R}_{\text{circ}}$	0.345476187602	$5 \times 10^{-5}$	$3 \times 10^{-5}$	$5 \times 10^{-4}$	$3 \times 10^{-3}$	$1 \times 10^{-3}$
$\bar{J}$	0.0140585992949	$2 \times 10^{-5}$	$4 \times 10^{-4}$	$5 \times 10^{-4}$	$2 \times 10^{-2}$	$2 \times 10^{-2}$
$Z_p$	1.70735395213	$1 \times 10^{-5}$	$4 \times 10^{-5}$	$1 \times 10^{-4}$	$2 \times 10^{-2}$	$6 \times 10^{-2}$
$Z_{\text{eq}}^f$	-0.162534082217	$2 \times 10^{-4}$	$2 \times 10^{-3}$	$2 \times 10^{-2}$	$4 \times 10^{-2}$	$2 \times 10^{-2}$
$Z_{\text{eq}}^b$	11.3539142587	$7 \times 10^{-6}$	$7 \times 10^{-5}$	$1 \times 10^{-3}$	$8 \times 10^{-2}$	$2 \times 10^{-1}$
GRV3	$4 \times 10^{-13}$	$3 \times 10^{-6}$	$3 \times 10^{-5}$	$1 \times 10^{-3}$	$4 \times 10^{-3}$	$1 \times 10^{-1}$

*AKM: Ansorg et al.*

*Lorene/rotstar + BGSM: Meudon group*

*SF: RNS code*

*KEH: original KEH code (not compactified)*

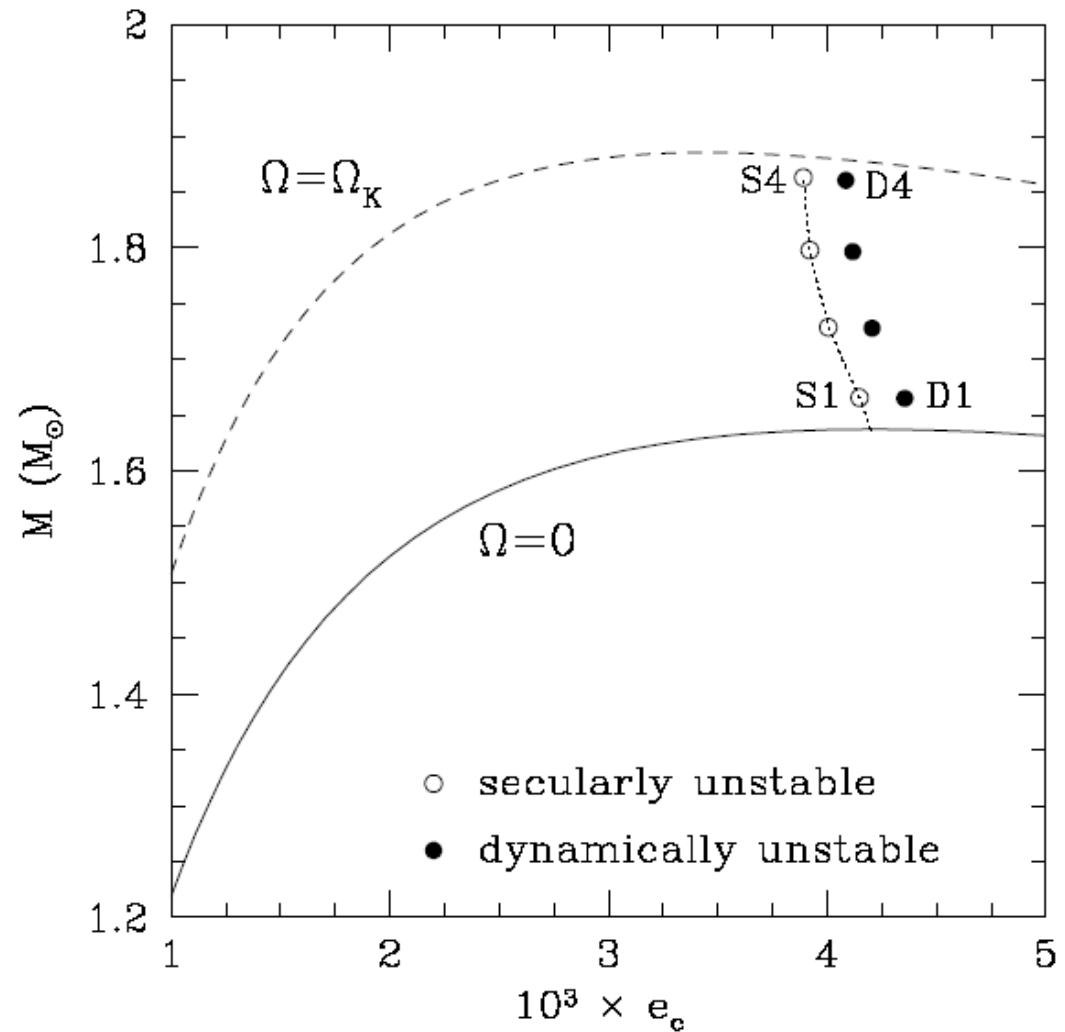
# Axisymmetric Instability to Collapse

Rotating stars are subject to a *secular* axisymmetric instability, if:

$$\left(\frac{\partial M}{\partial \epsilon_c}\right)_J < 0$$

(Friedman, Ipser & Sorkin, 1988).

*Dynamical* instability soon after onset of secular instability.



# DIFFERENTIAL ROTATION

The specific angular momentum measured by proper time of matter is

$$j \equiv u^t u_\phi = j(\Omega)$$

Rotation Law:

$$\Omega = \Omega_c - \frac{(\Omega - \omega) r^2 \sin^2 \theta e^{-2\rho}}{A^2 \left[ 1 - (\Omega - \omega)^2 r^2 \sin^2 \theta e^{-2\rho} \right]}$$

Dimensionless constant:

$$\hat{A} = A/r_e$$

Limits:

$$\hat{A}^{-1} \rightarrow \begin{cases} 0 & \text{uniform rotation} \\ \infty & j - \text{constant rotation law} \end{cases}$$

Specific angular momentum conserved during homologous collapse:

$$j^0 \equiv u_\phi \left( \frac{\varepsilon + p}{\rho_0} \right)$$

Satisfies Rayleigh criterion for local dynamical stability to axisymmetric perturbations:

$$\frac{dj^0}{d\Omega} < 0$$

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