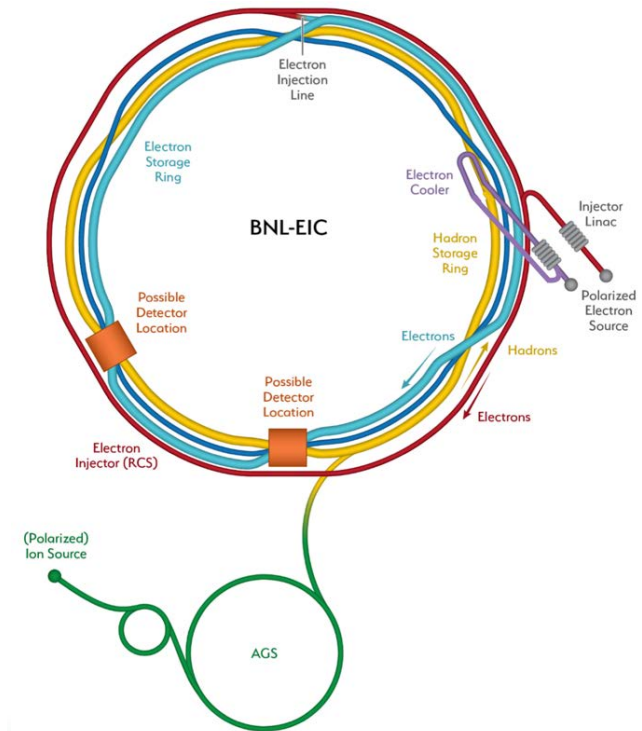


EIC Detector R&D

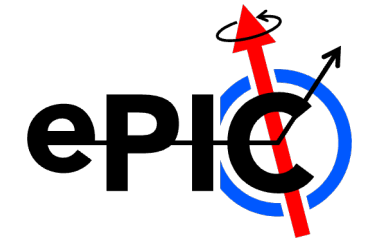
Peter Jones (EIC UK PI),

Laura Gonella (ePIC SVT Technical Coordinator)

University of Birmingham

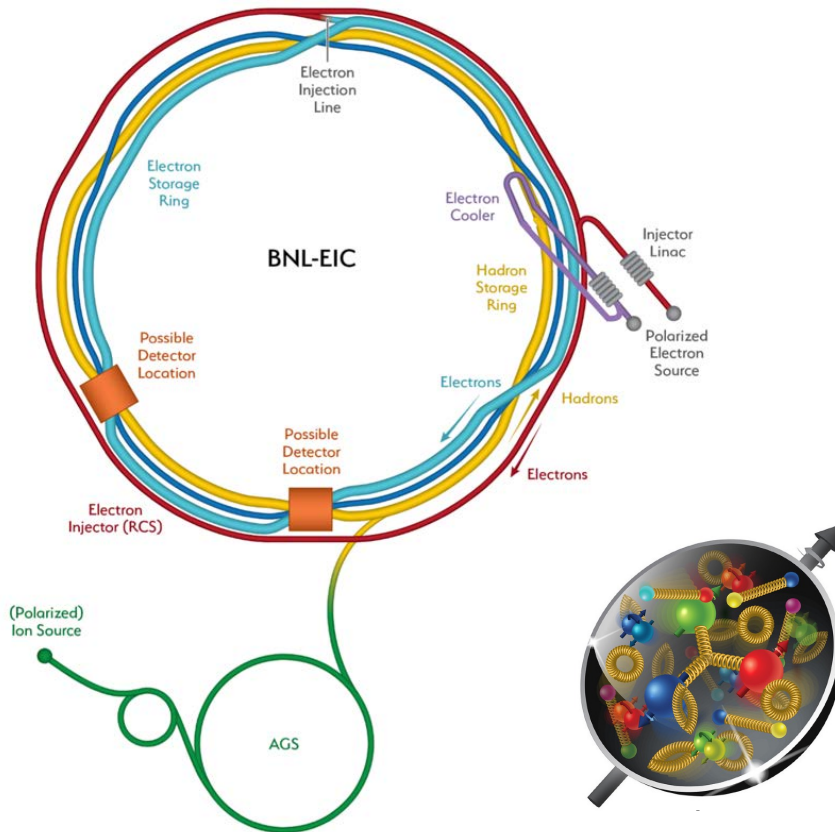


Electron-Ion Collider (EIC)



- Overview of the facility

The EIC is to be built at the Brookhaven National Laboratory (BNL) incorporating the existing Relativistic Heavy Ion Collider (RHIC)



- Uniqueness

World's first polarised electron, polarised proton/light-ion collider

World's first polarised electron, heavy-ion collider

- Overarching science questions

How does the mass and spin of the nucleon arise from its constituents?

What are the emergent properties of dense systems of gluons?

- US Project Overview

Total Project Cost = \$2.4B incl. contingency

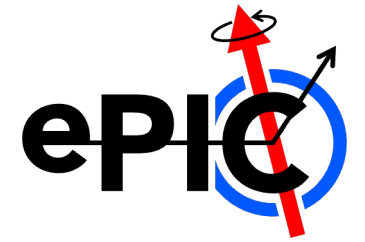
Covers approx. 90% of the accelerator and 66% of one detector (the project detector)

Currently in R&D and prelim. design phase

Start of construction expected 2025

Start of operations expected 2032

UK Project Overview



▪ UKRI Infrastructure Preliminary Activity

EIC Detector R&D awarded £2.97m

Duration 2.5 years (Oct 2021 – Mar 2024)

Detector R&D work packages:

WP1 – MAPS: silicon tracking and vertex reconstruction in the central detector

WP2 – Timepix: high-rate tracking of scattered electrons in the far-backward detector region

WP3 – Polarimetry: developing new technology to measure recoil nucleon polarisation

Funded institutes:

Birmingham, Brunel, Glasgow, Lancaster, Liverpool, York, STFC/DL, STFC/RAL (TD and PPD)

Aims of this phase are/were:

- (i) Establish technical and scientific leadership in the EIC project detector collaboration (ePIC)
- (ii) Define the size and scope of the UK's contribution to detector construction

▪ UKRI Full Infrastructure Project

Total request £58.8m, 100% FEC, incl. contingency

Duration 7+1.75 years (Jul 2025 – Mar 2034)

Contains 3 Detector WPs and 1 Accelerator WP

Detector WPs are:

WP1 – Silicon Tracker

WP2 – Electron Tagger

WP3 – Luminosity Monitor (New)

Plan to pursue Polarimetry development via US EIC Generic R&D program

Peer Review and STFC prioritisation

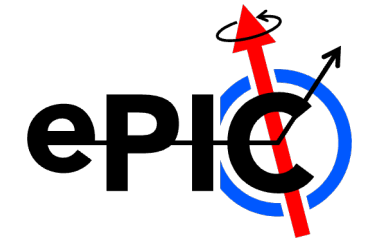
Submitted to UKRI on 24th of July

Decision expected in Q1 2024


Proposal institutes:

Birmingham, Brunel, Glasgow, Lancaster, Liverpool, Oxford, York, STFC/DL, STFC/RAL (TD and PPD)

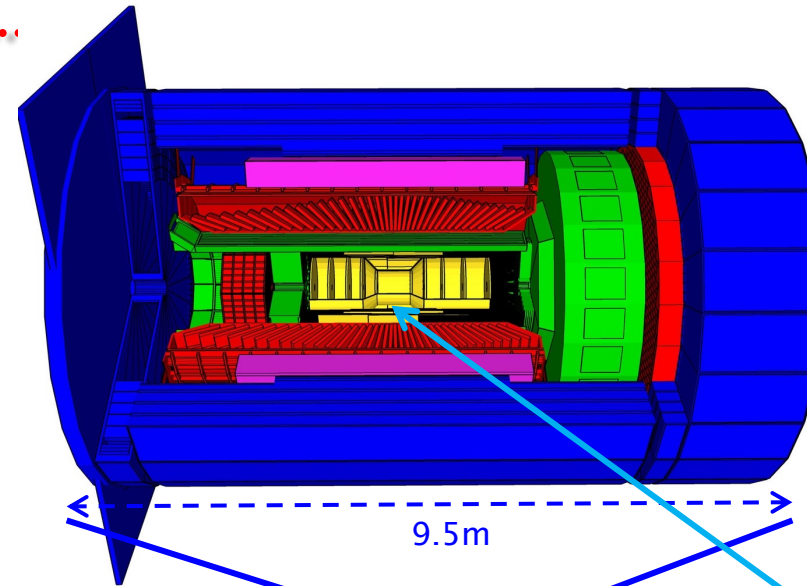
EIC Project Detector



6.10 EIC Detector

- | | |
|---|--|
| 6.10.01 Detector Management | 6.10.08 Electronics |
| 6.10.02 Detect. R&D & Physics Design | 6.10.09 DAQ / Computing |
|  6.10.03 Tracking | 6.10.10 Detector Infrastructure |
| 6.10.04 Particle Identification |  6.10.11 IR Integration & Auxiliary Detectors |
| 6.10.05 Electromagn. Calorimetry | 6.10.12 Detector Pre-Ops & Commiss. |
| 6.10.06 Hadronic Calorimetry | 6.10.13 Detector #2 Development |
| 6.10.07 Magnets | 6.10.14 Polarimetry and Luminosity |

- Hadronic Calorimeters (HCAL)
- Solenoidal Magnet
- E/M Calorimeters (EMCal)
- Time of Flight (ToF), DIRC, RICH detectors
- MPGD trackers
- MAPS tracker

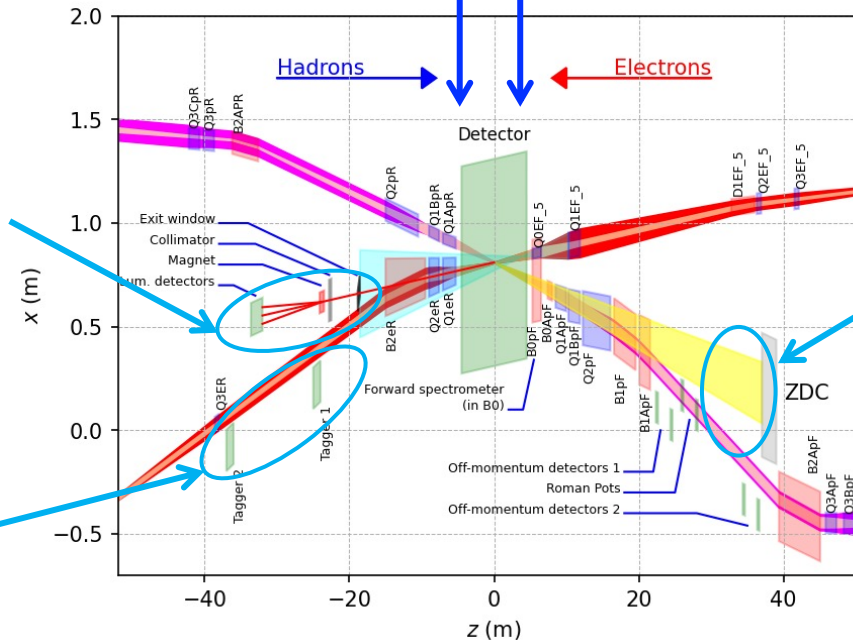


WP1: Silicon Tracker

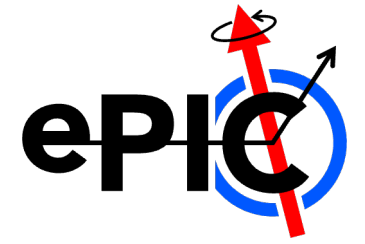
WP3: Luminosity Monitor

WP3: Polarimeter

WP2: Electron Tagger

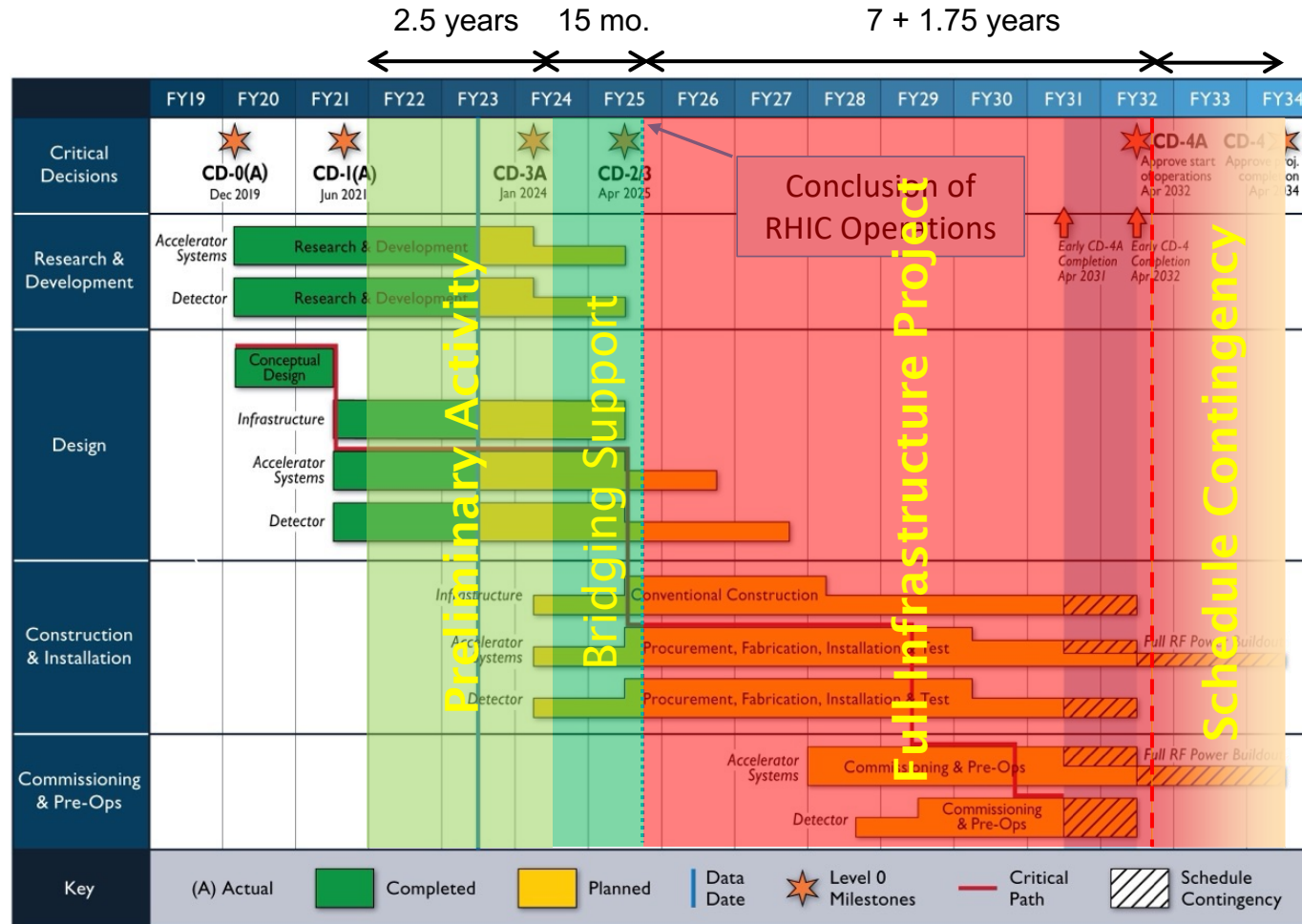
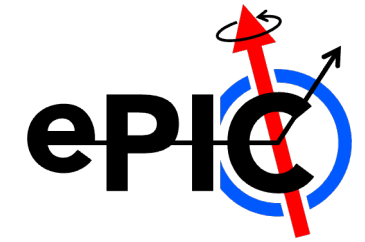


EIC Full Infrastructure Project – Deliverables



- **WP1 – Silicon Tracker:** Precision tracking and vertexing in the central detector
65 nm stitched (wafer-scale) monolithic active pixel sensors; developed in partnership with CERN/ALICE-ITS3
Deliverable: Build ~33% of central silicon tracker.
Institutes: [Birmingham](#), [Brunel](#), [Lancaster](#), [Liverpool](#), [Oxford](#), [STFC RAL](#), [STFC DL](#)
- **WP2 – Electron Tagger:** Precision tracking of low- Q^2 scattered electrons
Low- Q^2 tagger using Timepix pixel sensors.
Deliverable: Build two tracking stations in the far backward region. Timepix4 is the baseline technology.
Institutes: [Glasgow](#), [STFC DL](#) and [Lancaster \(beam impedance studies\)](#)
- **WP3 – Luminosity Monitor:** Bunch-by-bunch measurement of collision luminosity
Design of the luminosity monitor comprising a pair spectrometer (PS) and photon detector (PD)
Deliverables: Build the two calorimeters needed for the PS and half the modules needed for the PD
Institutes: [York](#)
- **WP4 – Accelerator:** Cavity design and cryomodule fabrication
Cavity design and cryomodules for the Energy Recovery Linac that forms part of the hadron beam cooler
Deliverables: Build two cryomodules for the ERL cooler
Institutes: [Lancaster](#) and [STFC DL](#)

EIC Project – Schedule



Critical Decision (CD) Milestones

- CD-0 Approve Mission Need
- CD-1 Approve Cost Range
- CD-2 Approve Baseline Performance
- CD-3 Approve Start Construction
- CD-4A Approve Start of Operations
- CD-4 Approve Project Completion

Upcoming Project Milestones

TDR – Q4 2024

CD2/3 review – Q1 2025

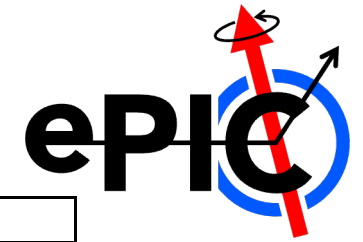
CD2/3 approval – Q2 2025 (April)

NOTE: US Financial Years (FY) = Oct-Sep

- UK-EIC Detector R&D Project
- UK-EIC Detector Construction Project

Schedule shown by Project Director, Jim Yeck, at EIC RRB meeting 3-4 April

ePIC Silicon Vertex Tracker



▪ Precision central tracking and vertexing

Approximately 8.5 m² detector

65 nm MAPS technology driven by physics requirements and validated with simulations

Developed in partnership with ALICE-ITS3

- Proposed ITS3 sensor meets EIC requirements; partnership minimises risk

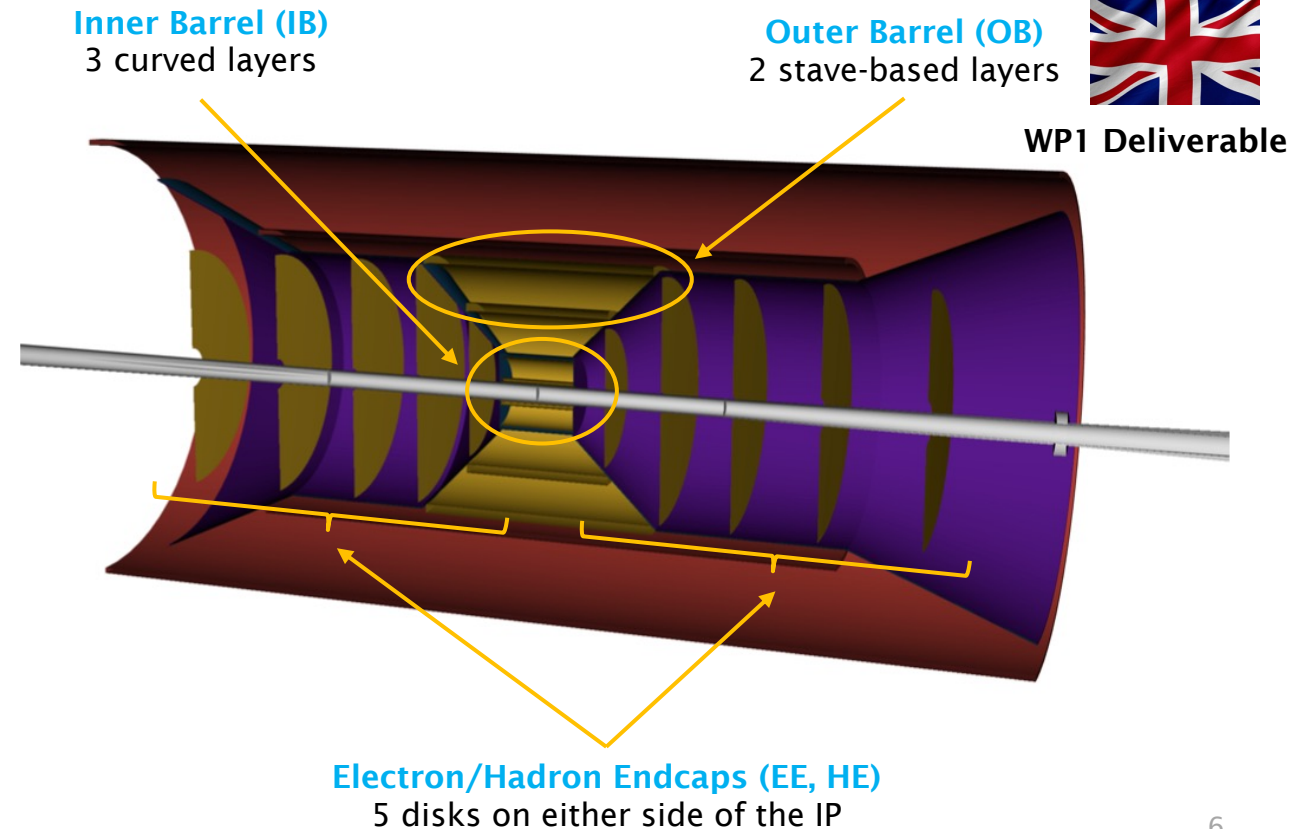
ePIC will use same concept for vertex layers:

- ITS3 wafer-scale stitched sensors, thinned and bent around the beam pipe

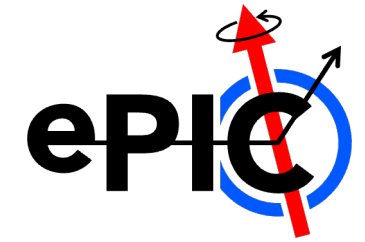
Development needed for the barrel layers and disks:

- large area stitched sensor (not wafer scale), and “conventional” low-mass support structures
- Requires changes to the ITS3 sensor stitching plan and possibly some changes to the digital periphery; pixel matrix unchanged

ePIC SVT Requirements		
Spatial Resolution	~ 5 μm	
Power Consumption	~ 20 mW/cm ²	
Frame Rate	≤ 2 μs	
Material Budget	IB	0.05% X/X ₀
	OB L3	0.25% X/X ₀
	OB L4	0.55% X/X ₀
	EE/HE	0.24% X/X ₀



WP1 – MAPS – UK Technology Developments

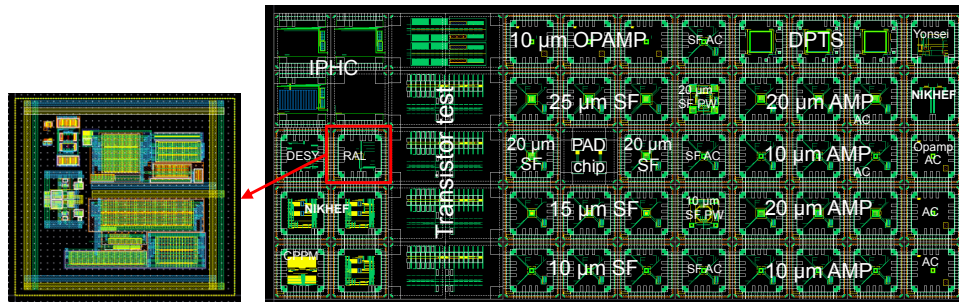


- Large area MAPS sensor

ALICE ITS3 and ePIC SVT first experiments to develop wafer-scale sensors for charged particle tracking

65 nm CMOS imaging technology: 300 mm wafers, stitching, low power

UK (RAL) involved in 65 nm development from the beginning with ITS3 and CERN EP R&D WP1.2



RAL IP Block – MLR (Q4 2020): LDVS receiver and CML transmitter

ER1 (Q4 2022) RAL contributed additional functional blocks for high-speed on-chip data transmission

Plus, redesigned digital libraries for DFM: **Buffers, AND gates, NAND gates, inverters, Filler cells, Flipflops**

- Lightweight support structures

Carbon fibre mechanical support with integrated cooling channels for evaporative cooling

ePIC SVT stave layout not yet defined; work not yet started in earnest

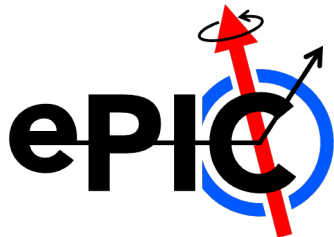
Ideas to move away from conventional flat stave geometry to achieve required stiffness with less material

- Serial powering

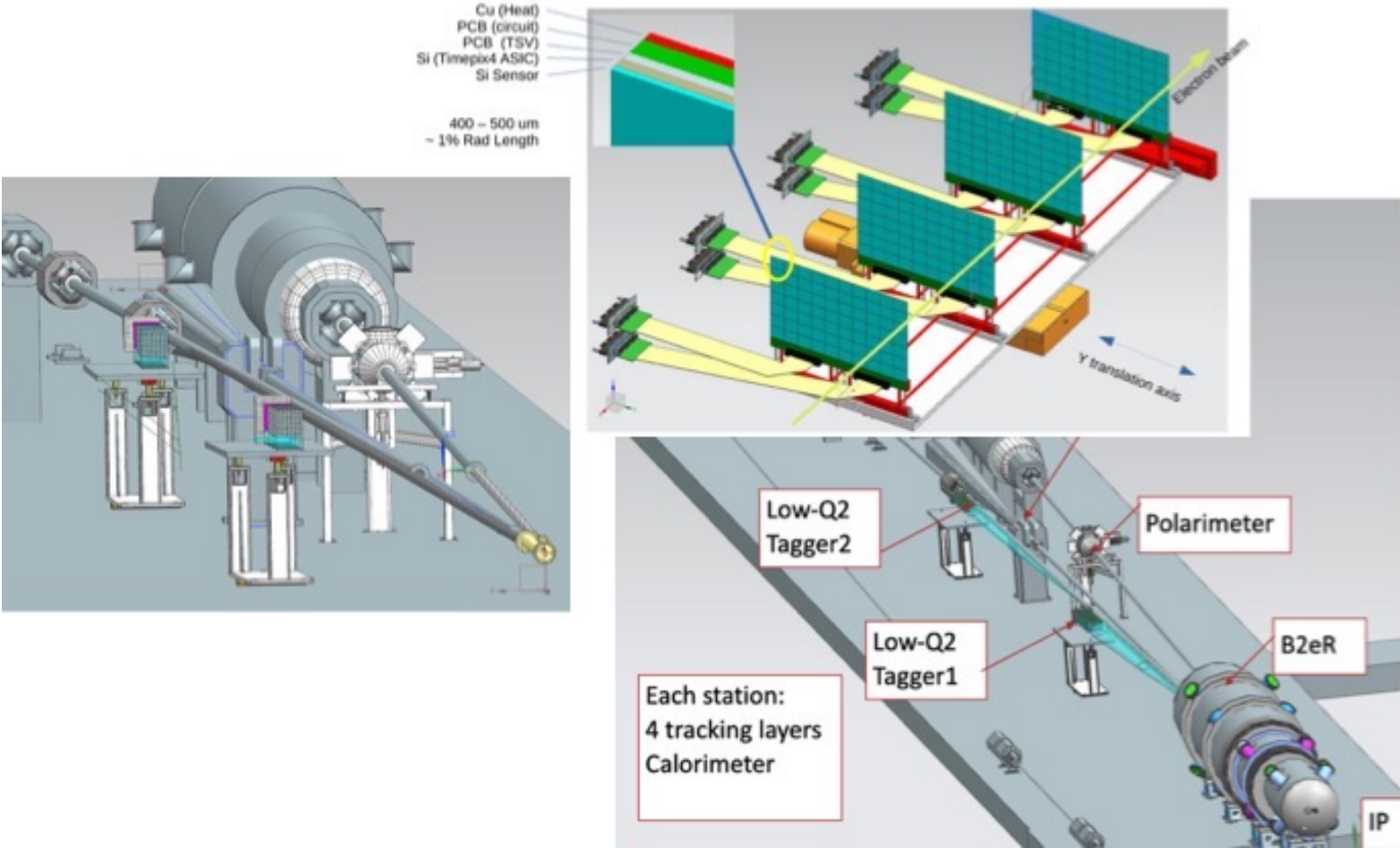
Development of Shunt-LDO regulator in commercial CMOS imaging technology

Development of full serial powering architecture for MAPS tracker for low mass power distribution

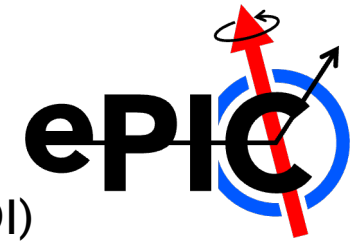
WP2 – Timepix



- ePIC CAD design with Timepix4 tracker



WP2 – Timepix



- Development of Timepix4 high-rate-trackers and readout for EIC applications

Research involving Glasgow Particle Physics and Nuclear Physics Groups (including Medipix collaboration) and NIHKEF

S. Gardner, K. Livingston, D Manueski

- Development of TI-LGAD with Timepix

Research involving Glasgow Particle Physics and Nuclear Physics Groups (including Medipix collaboration)

Proposal to **US EIC Generic R&D Program**

Fabrication and characterisation of the *Trench Isolated Low Gain Avalanche Detectors* for 4D tracking

S. Gardner, D Manueski

G. Paternoster et al. “Trench-Isolated Low Gain Avalanche Diodes (TI-LGADs)”. In: IEEE Electron Device Letters 41.6 (2020), pp. 884–887. doi:10.1109/LED.2020.2991351.

- Machine-Detector Interface (MDI)

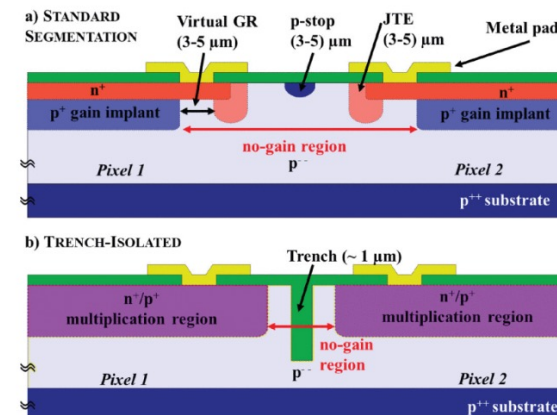
Research involving Glasgow Nuclear Physics and Lancaster Accelerator group on impedance modelling for EIC far-backward detectors

S. Gardner, D. Glazier, K. Livingston, R. Apsimon

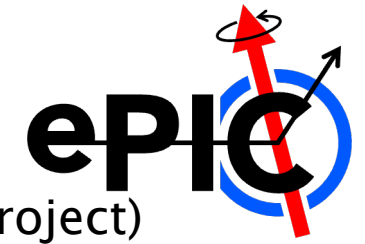
- Data processing technologies

Development of fast-tracking solutions with Graph Neural Networks

S. Gardner, D. Glazier, R Tyson

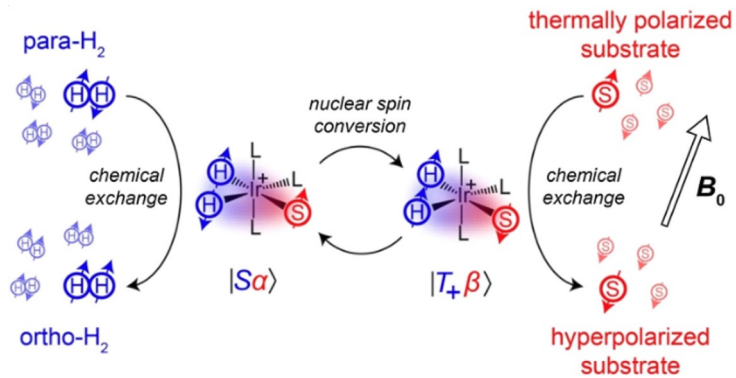


WP3 – Polarimetry / Luminosity Monitor



▪ Polarimetry R&D (Preliminary Activity)

NMR technique: chemical hyperpolarization – transfer nuclear spin order from parahydrogen (pH_2) to substrate molecule via catalyst



Substrate polarisable at room temp with weak field

Maintain polarisation with pH_2 bubbling

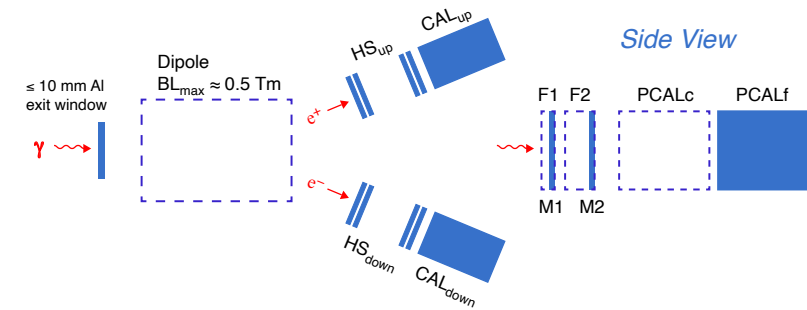
Aiming to develop large volume, active, liquid polarised scattering media with several applications:

1. Detector to measure recoil nucleon polarisation
2. Explore suitability as polarised (frozen) target

Proposal to **US EIC Generic R&D Program**

▪ Luminosity Monitor R&D (Full Project)

Design and fabrication of calorimeter modules for pair spectrometer and direct photon detector



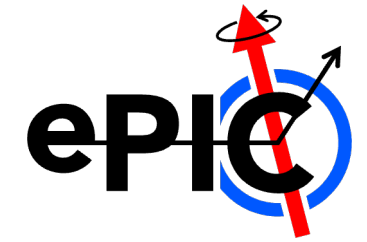
1. R&D to optimise the W/SciFi ratio
2. Investigating ways to improve position resolution that eliminate the need for tracking planes

The x-y vs z shower profiles are expected to provide better constraints on the gravity of the shower

Develops out of AI/ML guided detector design and data analysis for high-rate photon luminosity monitoring and calorimetry

3. Exploration of new methods for linear photon polarisation determination in the GeV energy range

Synergies with UK DRD and ECFA Detector R&D Roadmap



WP1 – MAPS (DRDT 3.1)

Work for the ePIC SVT brings expertise in a new, smaller technology node:

e.g., circuit blocks; stitching methodology for high yield in dense logic design; ...

WP1 – Mechanics and Cooling (DRDT 8.3/8.2)

Scope for collaboration and sharing of ideas / technologies:

e.g., low-mass structures, evaporative cooling and integration of cooling channels, additive manufacturing, fluid system connections, gas cooling

WP1 – Serial Powering (DRDT 7)

Development of serial powering scheme could add to the UK involvement in DRDT 7 projects

▪WP2 – Sensors for 4D tracking (DRDT 3.2)

Developing tracking systems with high-rate capability with Timepix4 and TI-LGADs

▪WP2 – Fast tracking with Graph Neural Networks

DRDT 7.5 – Evaluate and adapt to emerging electronics and data processing technologies

▪WP3 – Active polarised scattering media

Polarisation measurement at future colliders?

▪WP3 – AI/ML guided detector design & analysis

DRDT 7.2 - Develop technologies for increased intelligence on the detector

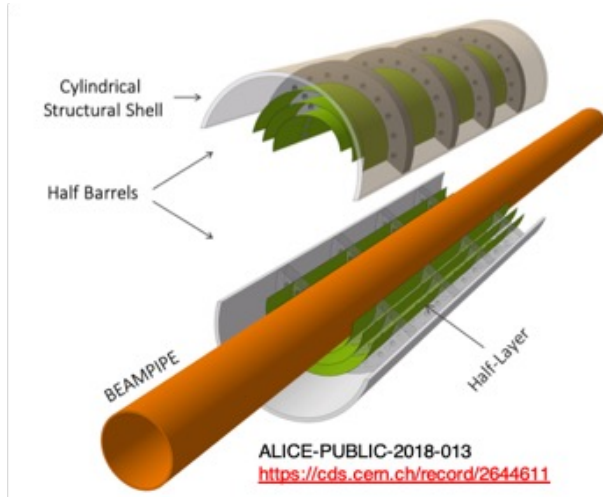
Overarching synergy with UK Strategic R&D towards low-material tracker for e+e-

ePIC SVT OB developed by the UK could be part of the low material tracker demonstrator programme

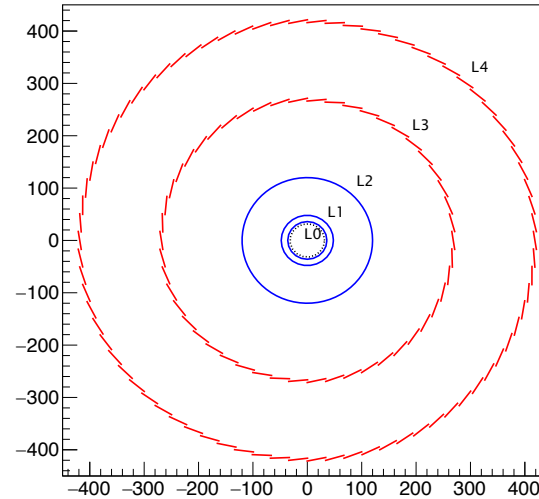
See discussion at <https://indico.stfc.ac.uk/event/781/>



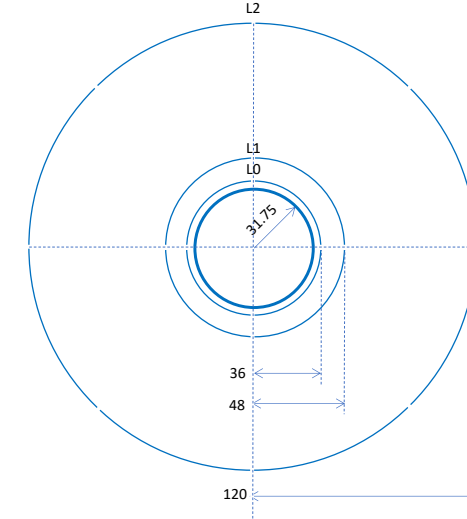
Vertex and Barrel Layers



ALICE-ITS3 development



ePIC-SVT Vertex and Barrel Layers



ePIC-SVT Vertex Layers

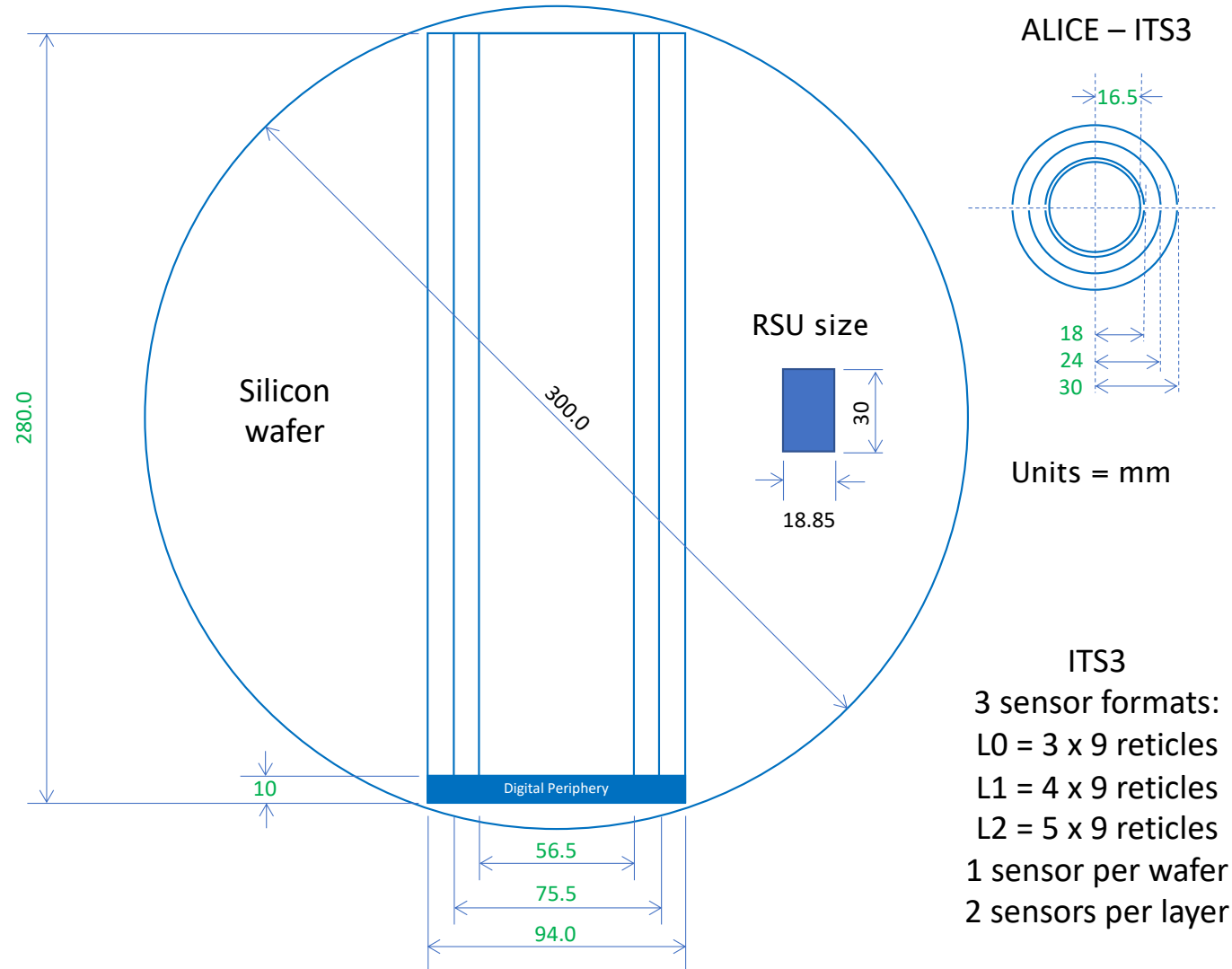
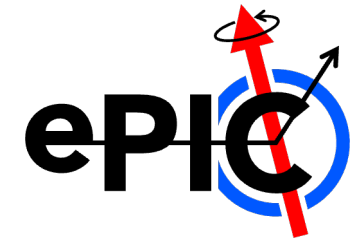
Vertex Layers

Wafer-scale, stitched sensors, thinned and bent around the beam pipe
Use unmodified ITS3 sensors with bespoke support structure
Air cooling

Barrel Layers

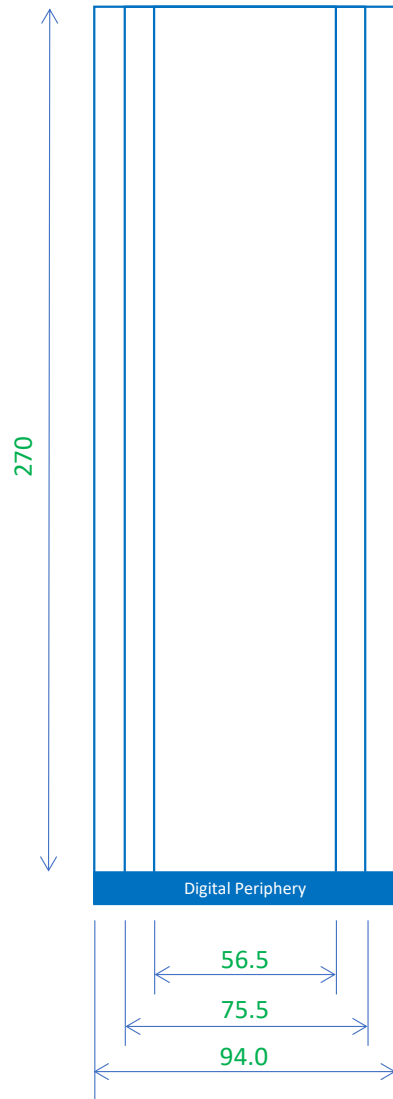
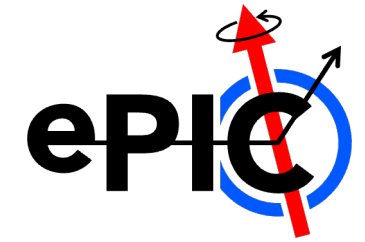
Large-area, but not wafer-scale (yield consideration), stitched sensors
Conventional, low-mass support structures
Two-phase cooling

Backup – ALICE ITS3 Sensor Layout



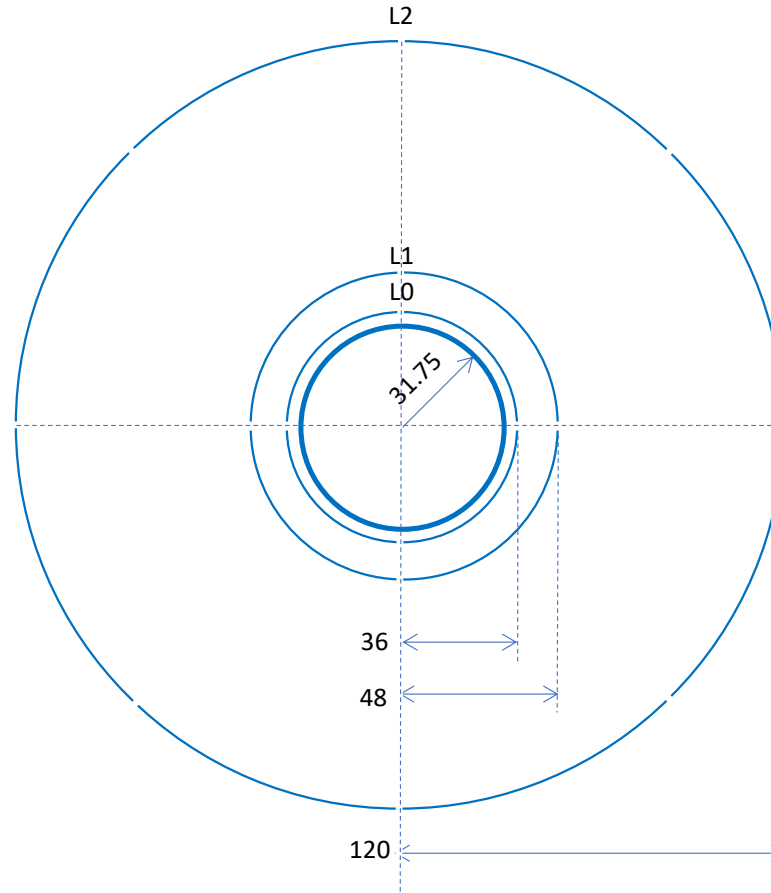
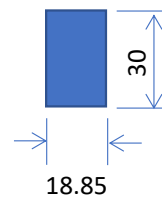
Note: RSU size and dimensions taken from ITS3 Lol – not final

Backup – ePIC Vertex Layers



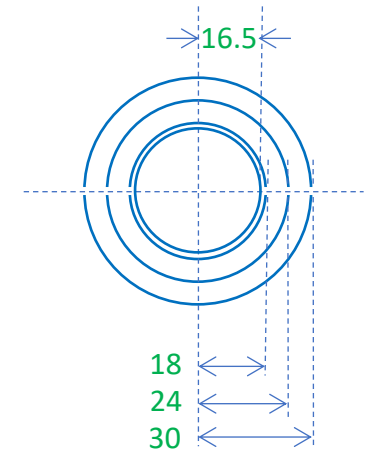
$L0 = 4 \times 56.5; R = 36$
 $L1 = 4 \times 75.5; R = 48$
 $L2 = 8 \times 94.0; R = 120$

ePIC - SVT
 Same 3 sensor formats:
 L0 = 3 x 9 reticles
 L1 = 4 x 9 reticles
 L2 = 5 x 9 reticles
 1 sensor per wafer
 4 or 8 sensors per layer



Units = mm

ALICE – ITS3



Note: RSU size and dimensions taken from ITS3 Lol – not final

- Updated sensor specifications

ER2 Stitched Sensor

ER2 Sensor aims to meet the ITS3 requirements

Layer 0: 12 x 3 repeated units+endcaps

Layer 1: 12 x 4 repeated units+endcaps

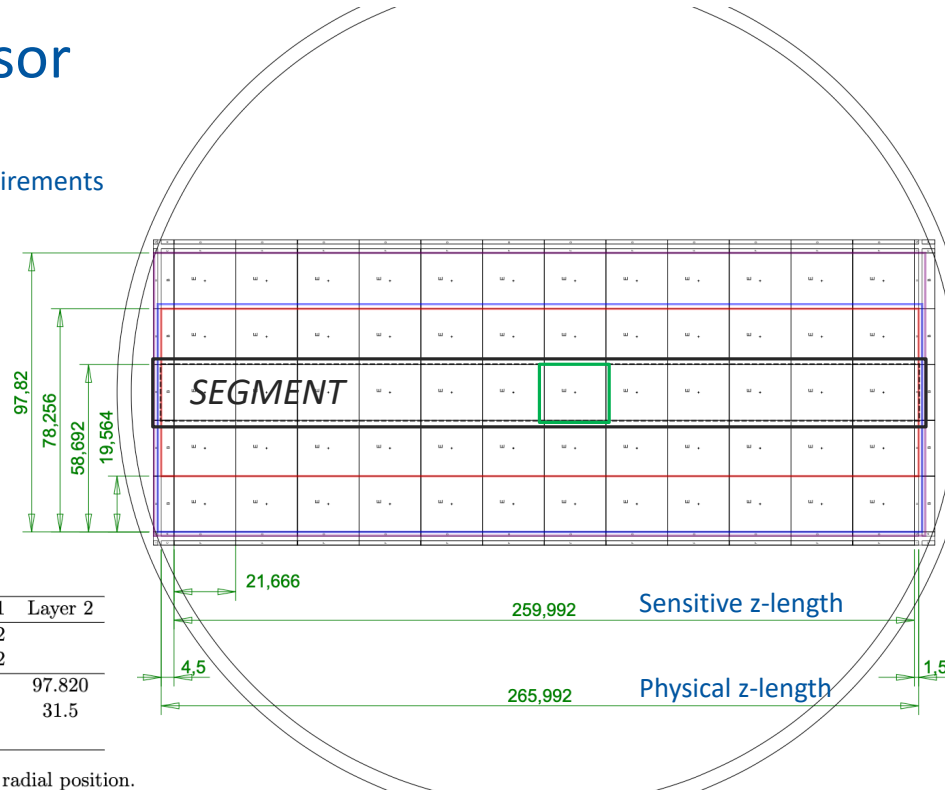
Layer 2: 12 x 5 repeated units+endcaps

 Repeated (Stitched) Sensing Unit

AZIMUTHAL WIDTH UPDATED

IB Layer Parameters	Layer 0	Layer 1	Layer 2
Sensor length [mm]		265.992	
Sensitive length [mm]		259.992	
Sensor azimuthal width [mm]	58.692	78.256	97.820
Radial position [mm]	19.0	25.2	31.5
Equatorial gap [mm]		1.0	

Table 3.2: Design dimensions of the sensor dies and radial position.



Lol: RSU = $18.85 \times 30 \text{ mm}^2$, 9 RSUs per segment, active length = 270 mm

ER1: RSU = $14 \times 25.5 \text{ mm}^2$, 10 RSUs per segment, active length = 255 mm

ER2: RSU = $19.564 \times 21.666 \text{ mm}^2$, 12 RSUs per segment, active length = 260 mm