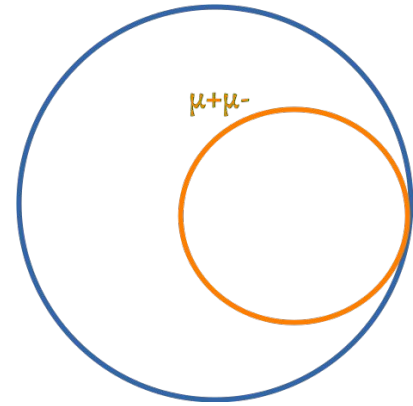


*Lecture (Part I) + Hands-on Exercise (Part II)
on*



The Muon Collider “problem”



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Part I

Introduction to μ -Col
Physics benchmarks
Key design parameters
Challenges

Why a μ -Col?

A paradigm-shifting machine: first collider to combine the energy reach of a hadron collider with the precision of a lepton collider.

200x
Heavier than e^-

~10⁶x less synchrotron energy than electrons,
enabling TeV-scale circular lepton collisions

Point-like
Fundamental lepton

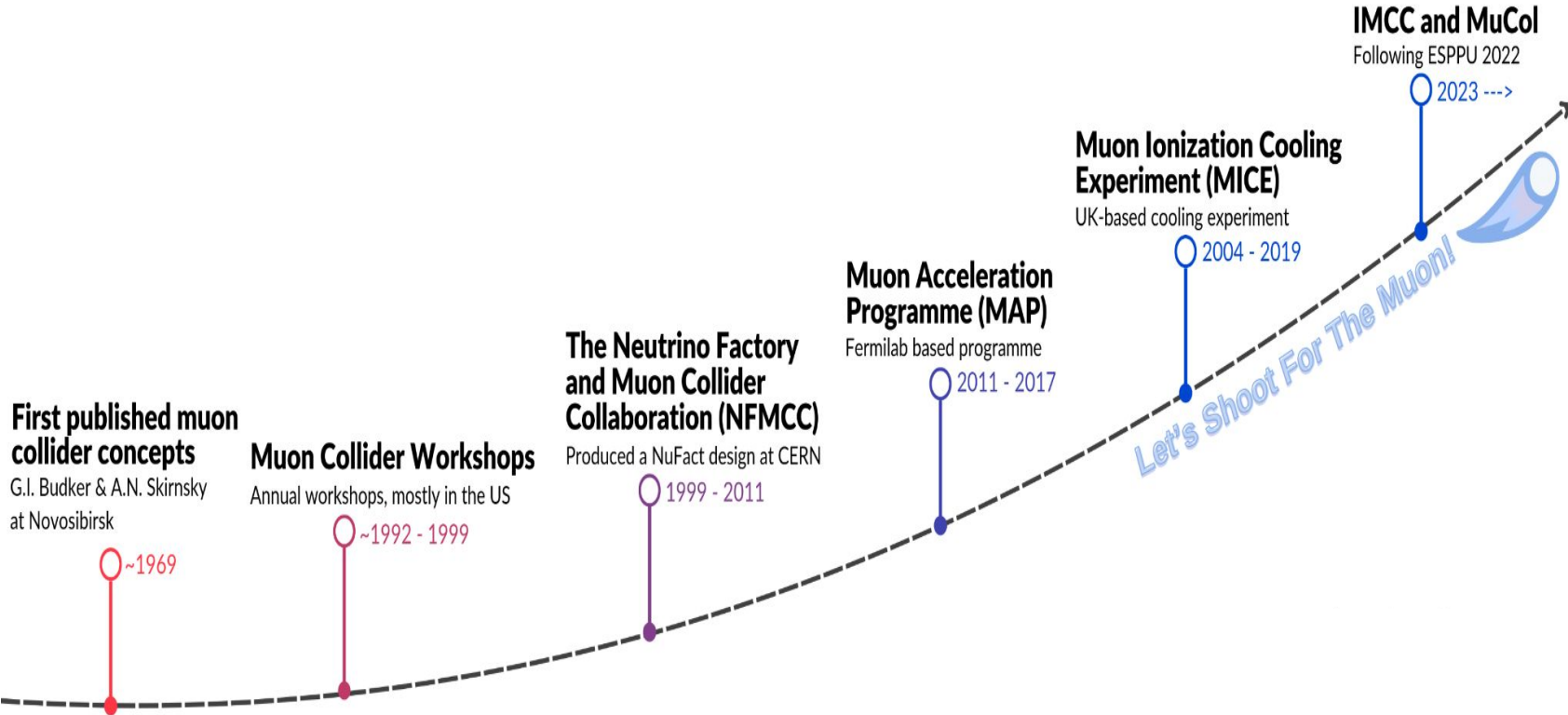
No quark substructure. Collisions have a
well-defined initial state, no PDF uncertainties

Compact
10 km ring @ 10 TeV

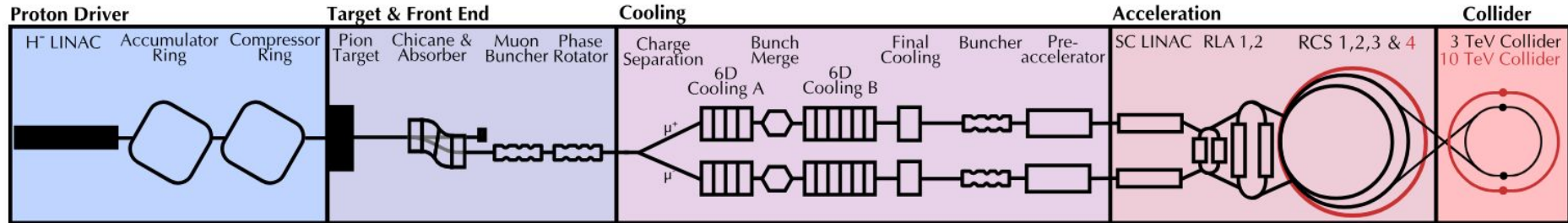
Equivalent physics reach to a 100 km pp collider,
cost- and energy-efficient

Time dilation
 $\gamma \sim O(10^4)$ @ $v=c$

Lifetime long enough to undergo several rotations
and collide



Conceptual layout of μ -Col



For $E_{\text{COM}} = 10$ TeV: 10 km ring \rightarrow Single-bunch μ^+/μ^- beams ($\sim 2 \times 10^{12}$ muons/bunch) \rightarrow 30 kHz bunch-crossing frequency \rightarrow instantaneous luminosity \sim $20 \times 10^{34} \text{ cm}^{-2}\text{s}^{-1}$

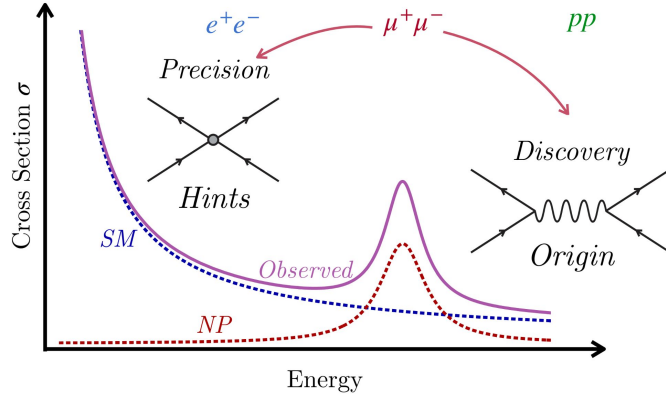
10x inst. Lumi. as LHC

\sim 3x inst. Lumi. as HL-LHC

In total 5 years of operation, projected to collect 10 ab^{-1}

Physics potential

The ability to do both is what makes muon colliders the most scientifically interesting future collider option.



- Higgs s-channel production, direct access to higgs total width @ MeV precision.
- Weak boson fusion (WBF) dominant process, study electroweak precision at sub-permille level
- Top yukawa coupling to $<1\%$ via tH production
- HH production via VBF $\sim 10x$ more events than HL-LHC
- Higgs trilinear coupling λHHH at 5% precision
- Quartic coupling (H^4) accessible for the first time at 10 TeV
- New heavy gauge boson (or SUSY particles pair) production up to 10 (5) TeV in mass
- Couplings to muon can probe unique leptophilic scenarios
- ...

Also possible to carry out auxiliary experiments with highly collinear and energetic neutrino beam from muons decay - complimentary to future long baseline experiments.

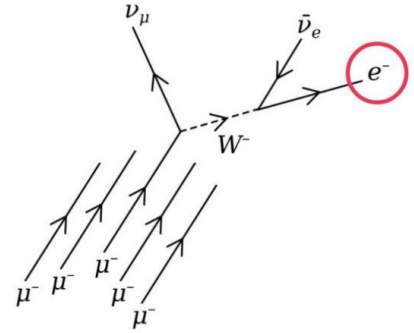
Beam-Induced Backgrounds (BIB)

Multi-TeV muon decays produce TeV-scale electrons!
(Going straight into the detector volume if not stopped)

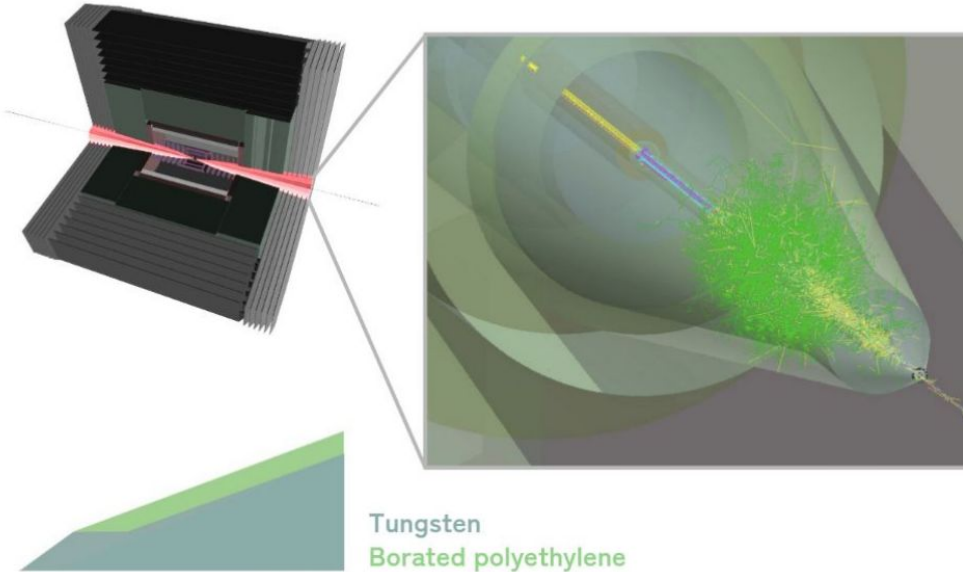
In addition, other charged & neutral secondary particles also produced from interaction with the surrounding material, all traveling towards the interaction point.

This is bad because:

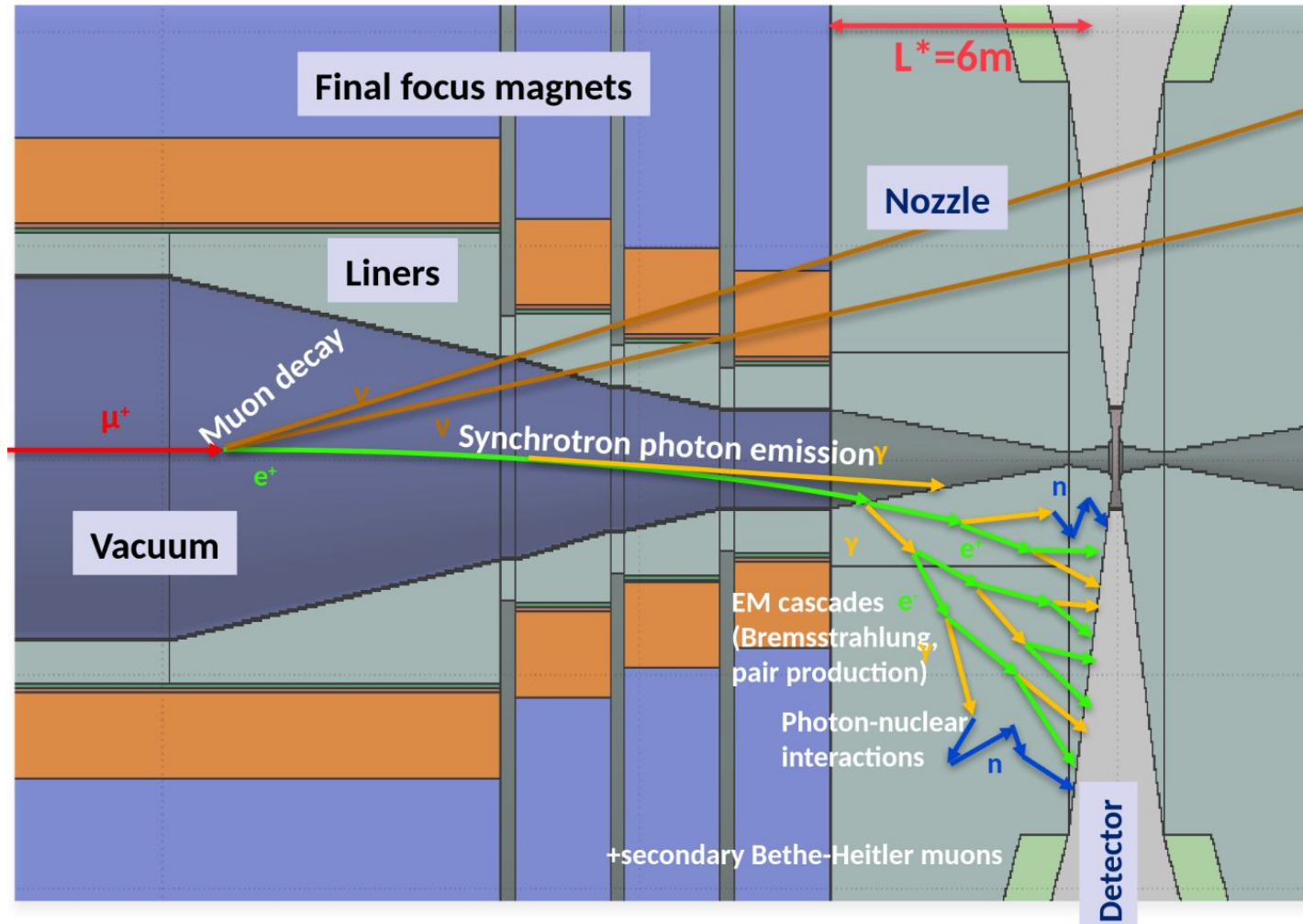
- Damages the detector components over time due to high radiation
- Early onset of detector electronics, even before the muon collisions - resulting in loss of signal
- Pollutes collision environment - harder to cleanly reconstruct and identify the physics objects



Shielding from nozzles

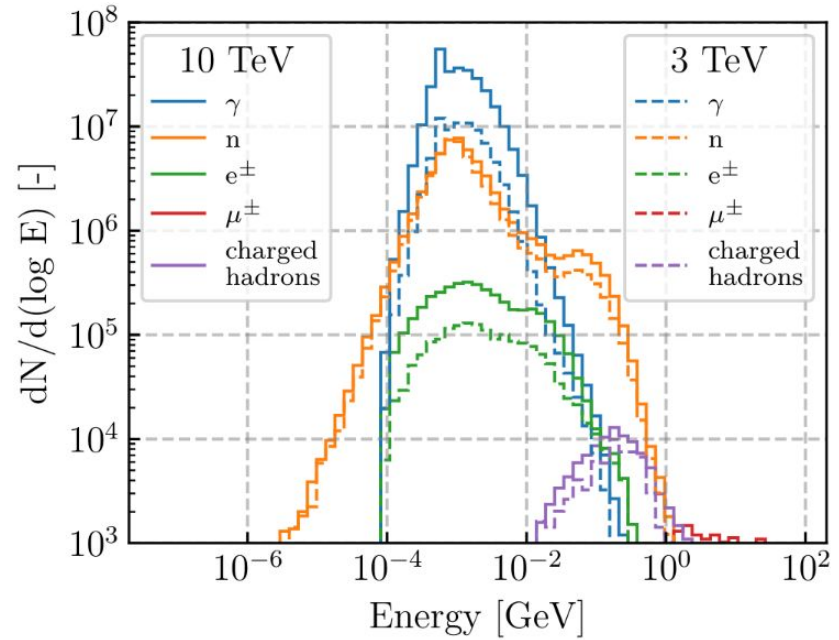
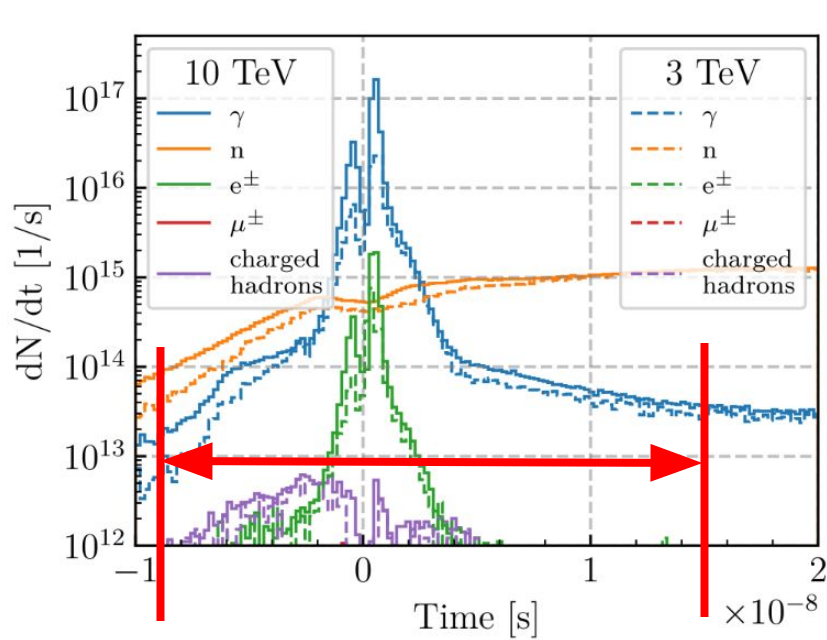


- Integrated in the MDI design, very close up to the IR.
- Reduces BIB by several orders of magnitude.
- Changes BIB composition: highly energetic particles diffuse into soft secondaries.
- In addition, collider lattice design (magnets placement for final focusing) also updated to reduce BIB, e.g. using shorter straight section.



BIB characteristics

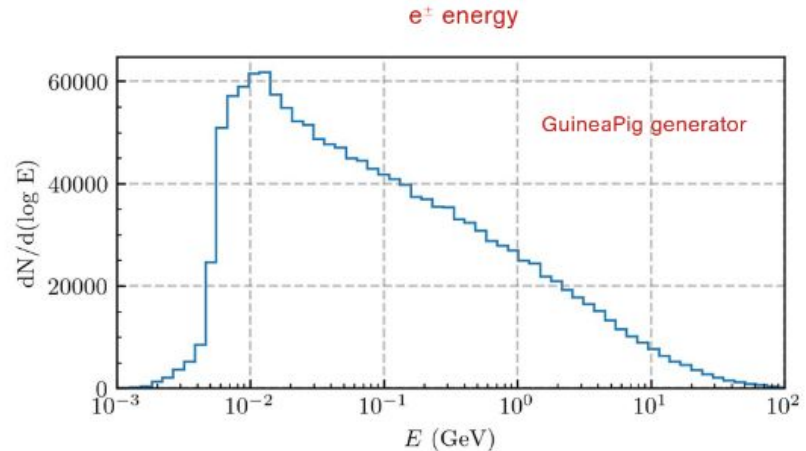
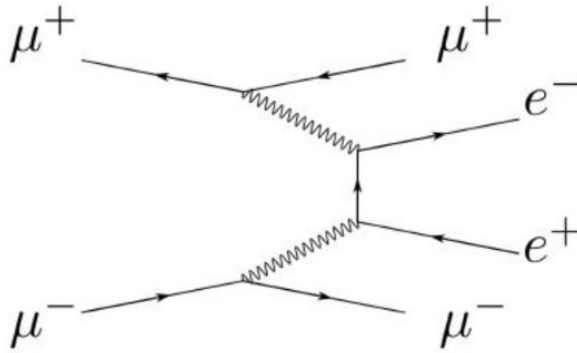
Long out-of-time tail of soft particles without much dependence on collider energy.



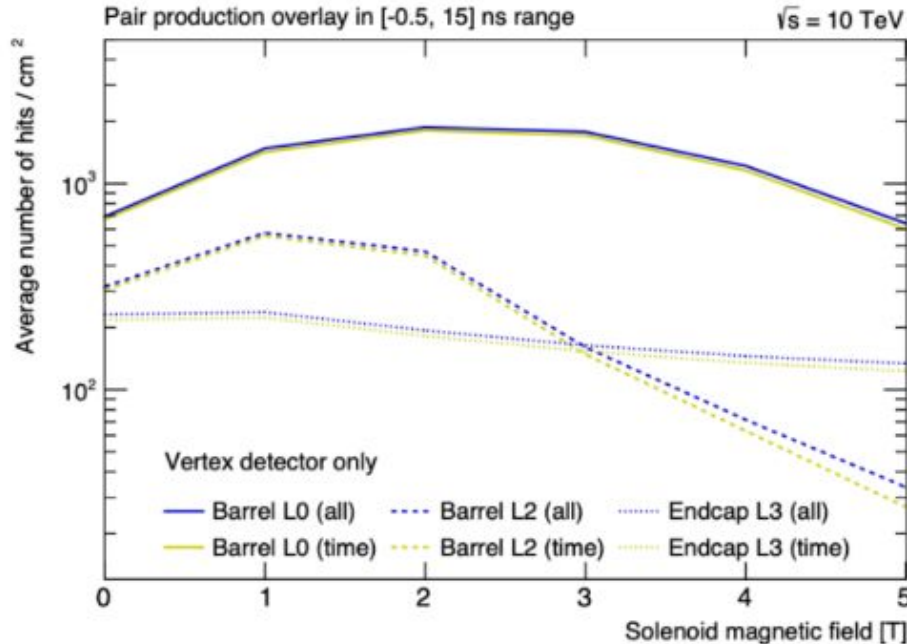
$O(10^8)$ >100 KeV photons, $O(10^7)$ $>10^{-5}$ eV neutrons and $O(10^6)$ >100 KeV e^+/e^-

Incoherent Pair Production (IPP)

- Low energy e+e- pair production from real or virtual photons emitted by muons in the counter-rotating bunches.
- Produced at the interaction point, hence higher time-coincidence with signal.
- Higher energy tail as compared to BIB.



IPP mitigation

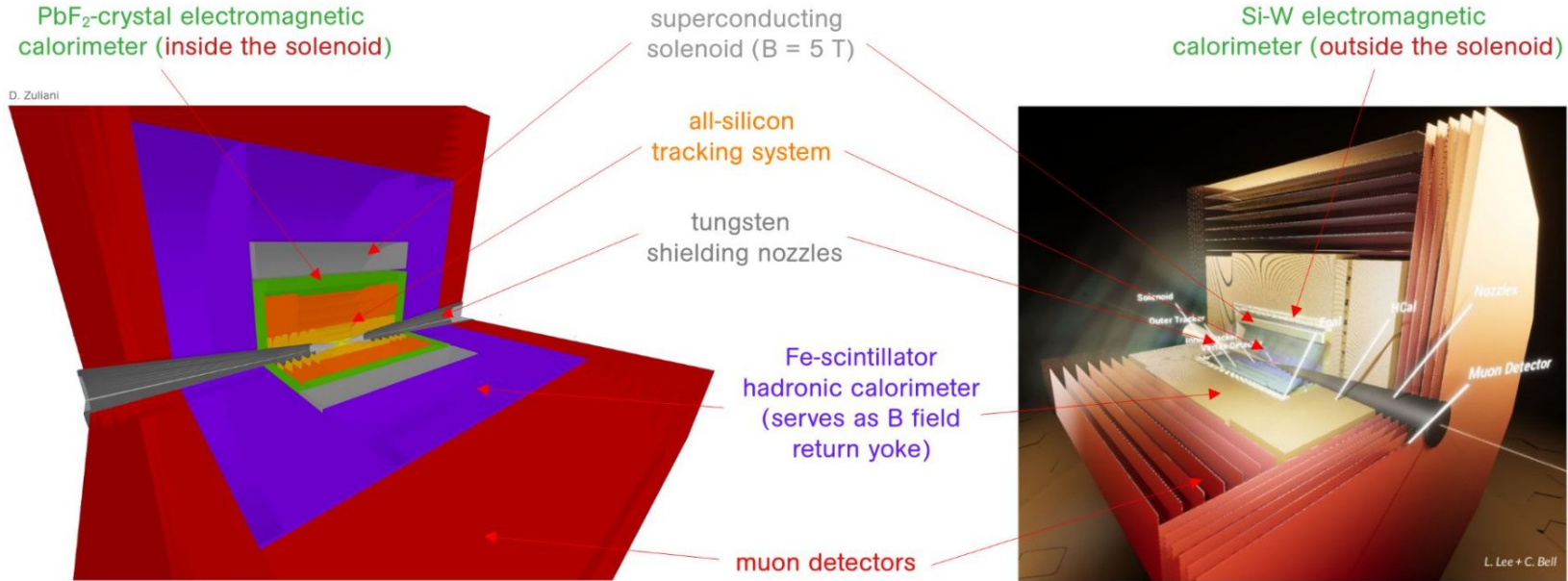


Increasing the magnetic field (e.g. 5T) in the tracking volume will sweep the e⁺e⁻ from IPP out of the detector, to a large extent.

Only small flux of particles will affect the physics of the muon collision event.

(Left out of today's exercise)

10 TeV detectors design



MUSIC

(MUon System for Interesting Collisions)

MAIA

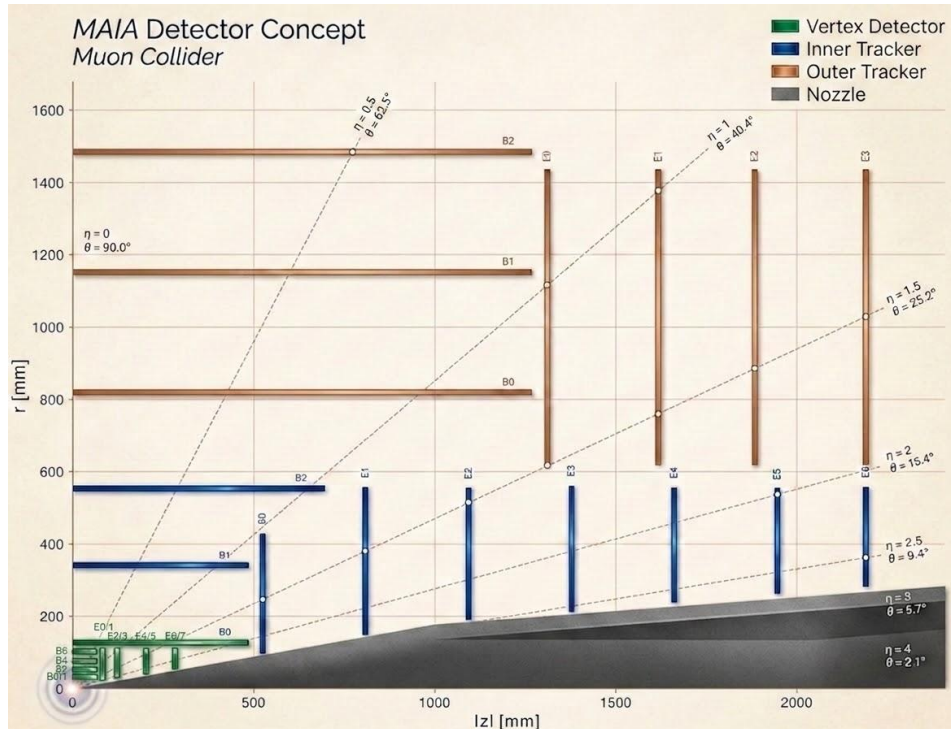
(Muon Accelerator Instrumented Apparatus)

Key design parameters

Requirement	Baseline		Aspirational
	$\sqrt{s} = 3 \text{ TeV}$	$\sqrt{s} = 10 \text{ TeV}$	
Angular acceptance	$ \eta < 2.5$	$ \eta < 2.5$	$ \eta < 4$
Minimum tracking distance [cm]	~ 3	~ 3	< 3
Forward muons ($\eta > 5$)	–	tag	$\sigma_p/p \sim 10\%$
Track σ_{p_T}/p_T^2 [GeV^{-1}]	4×10^{-5}	4×10^{-5}	1×10^{-5}
Photon energy resolution	$0.2/\sqrt{E}$	$0.2/\sqrt{E}$	$0.1/\sqrt{E}$
Neutral hadron energy resolution	$0.5/\sqrt{E}$	$0.4/\sqrt{E}$	$0.2/\sqrt{E}$
Timing resolution (tracker) [ps]	$\sim 30 - 60$	$\sim 30 - 60$	$\sim 10 - 30$
Timing resolution (calorimeters) [ps]	100	100	10
Timing resolution (muon system) [ps]	~ 50 for $ \eta > 2.5$	~ 50 for $ \eta > 2.5$	< 50 for $ \eta > 2.5$
Flavour tagging	b vs c	b vs c	b vs c , s -tagging
Boosted hadronic resonance ID	h vs W/Z	h vs W/Z	W vs Z

Tracker design

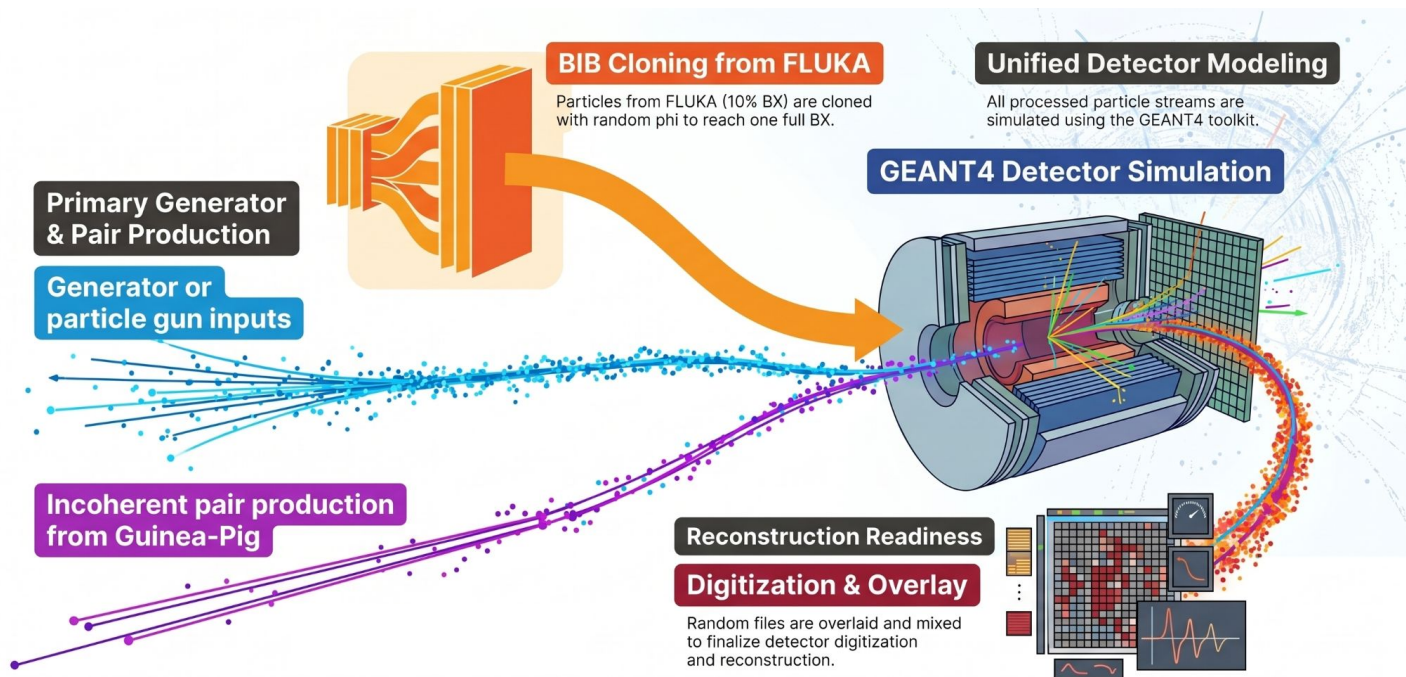
All silicon-based, high spatial precision, fast timing, high radiation tolerance, low material budget



	Vertex Detector	Inner Tracker	Outer Tracker
Sensor type	pixels	macro-pixels	macro-pixels
Barrel Layers	4	3	3
Endcap Layers (per side)	4	7	4
Cell Size	$25\ \mu\text{m} \times 25\ \mu\text{m}$	$50\ \mu\text{m} \times 1\ \text{mm}$	$50\ \mu\text{m} \times 10\ \text{mm}$
Sensor Thickness	$50\ \mu\text{m}$	$100\ \mu\text{m}$	$100\ \mu\text{m}$
Time Resolution	30 ps	60 ps	60 ps
Spatial Resolution	$5\ \mu\text{m} \times 5\ \mu\text{m}$	$7\ \mu\text{m} \times 90\ \mu\text{m}$	$7\ \mu\text{m} \times 90\ \mu\text{m}$

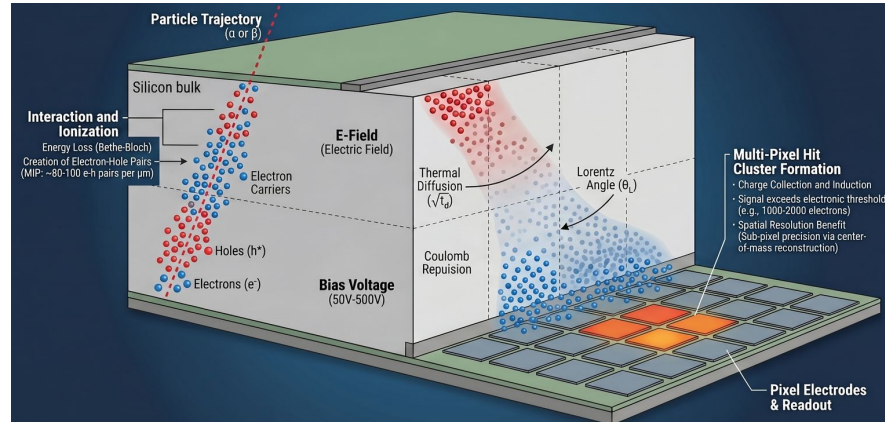
- First vertex barrel layer and all vertex endcap layers are implemented as double-layers, with 2 mm gap.
- Currently, assuming silicon planar sensors but future technology choice based on 3D, LGADs, or MAPS sensors R&D.

Simulating μ -Collider environment



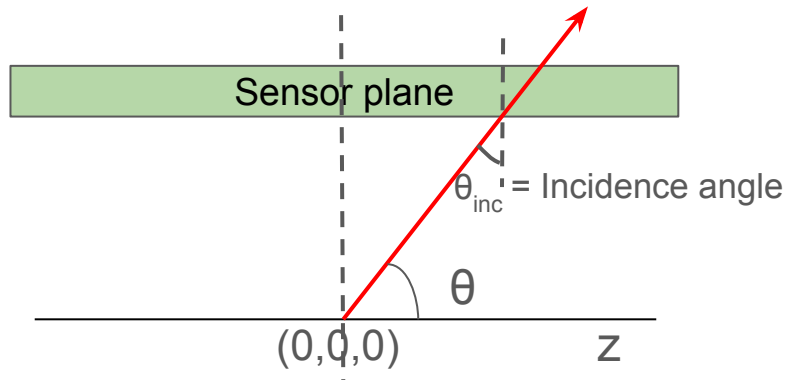
Tracker detector digitization

- **Particle Ionization:** When a charged particle travels through the silicon planar sensor, it ionizes the material and generates electron-hole pairs along its trajectory.
- **Charge Drift:** A high bias voltage applied creates an electric field in the depleted zone. This field separates the electron-hole pairs and forces them to drift toward the collection electrodes (pixel “hits”).
- **Cloud Expansion:** As the charge cloud drifts toward the pixels, it spreads out and grows in size. This expansion is driven by thermal diffusion and Coulomb repulsion.
- **Cluster Formation:** A "hit cluster" forms when the charge cloud is split and collected by two or more adjacent pixels.

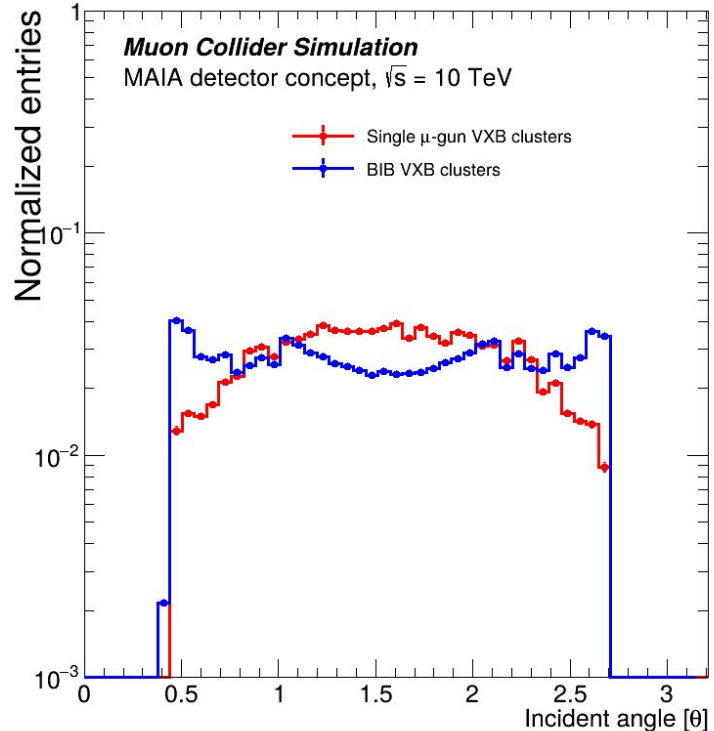


Signal vs BIB

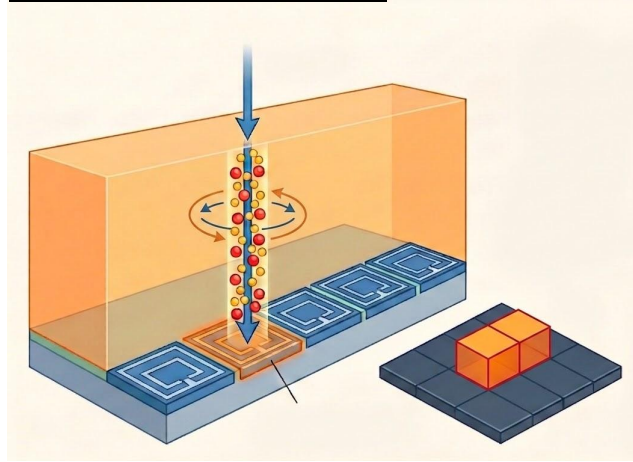
- Single muon particle gun with $p_T = 0$ to 5 TeV and $|\eta| < 2.4$ (signal) & BIB



- Given signal has normal incidence (since high p_T particles), and BIB has shallow incidence, how does the pixel hit cluster shape change?

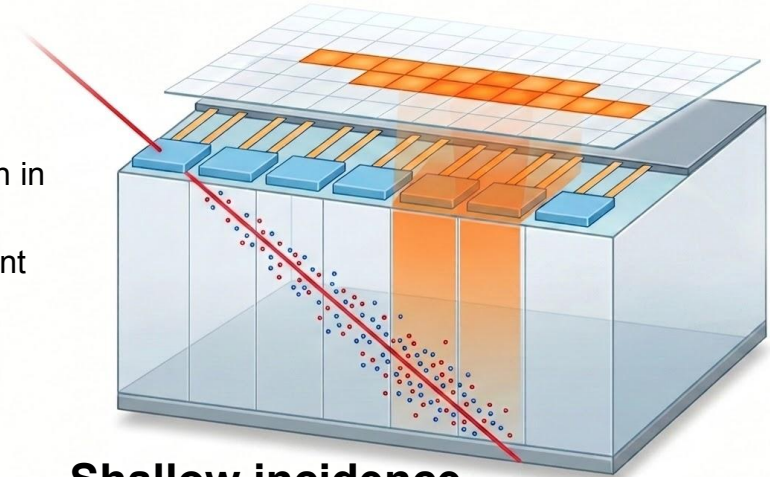


Normal incidence



- Short, straight vertical column of electron-hole pairs through the silicon.
- Charge sharing only due to lateral expansion of the charge cloud (thermal diffusion and Coulomb repulsion) or lateral deflection from a magnetic field (Lorentz drift).
- Resulting hit cluster is highly compact, typically triggering only 1-2 pixels.

- Traveling diagonally and passing through a longer physical path in the silicon before exiting.
- Electron-hole pairs directly into the territories of multiple adjacent pixels (irrespective of diffusion and drift).
- Overall size of the cluster grows rapidly with angle.
- Elongated or multi-hit pixel cluster.



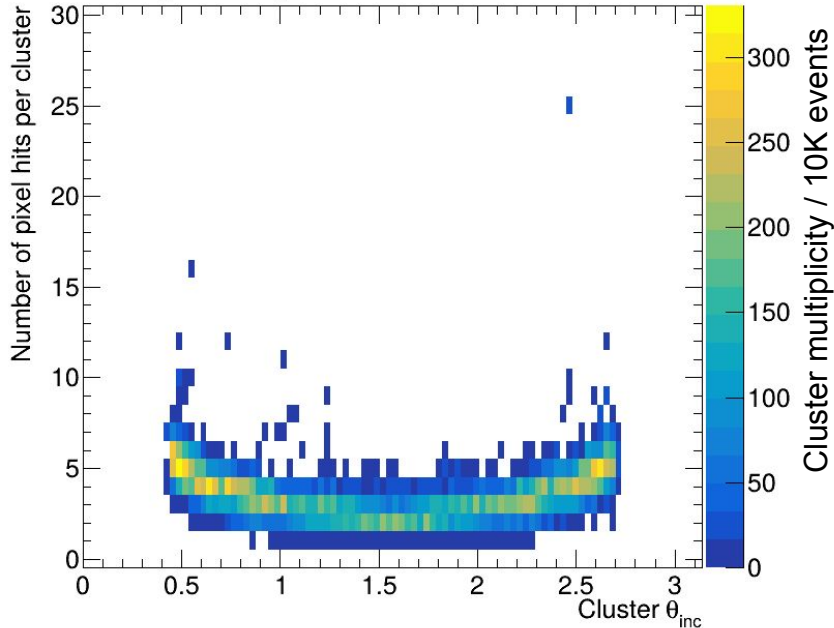
Shallow incidence

Simulation results: Innermost tracker layer

Muon Collider Simulation

MAIA detector concept, $\sqrt{s} = 10$ TeV

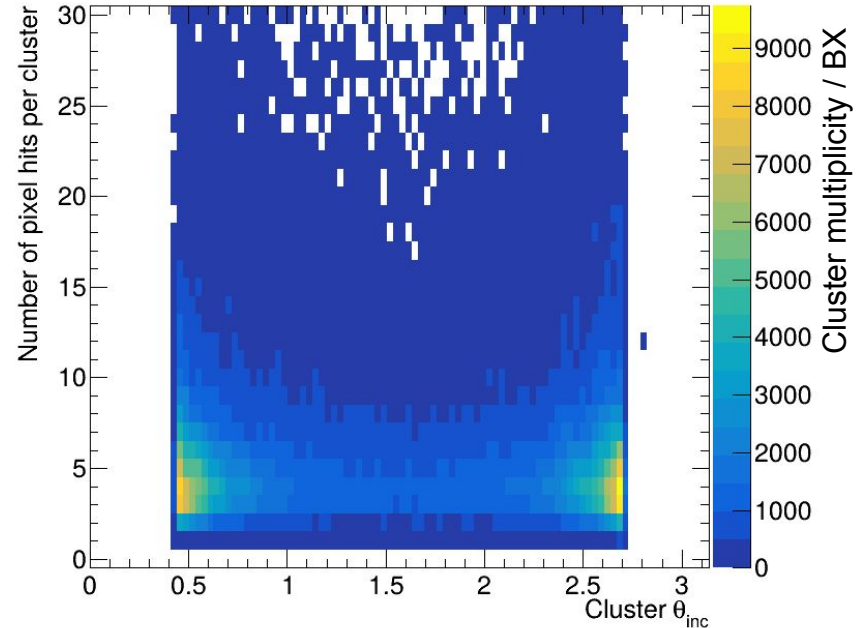
Single muon gun, VXB L0



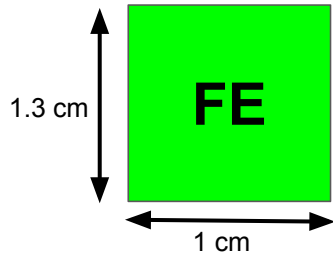
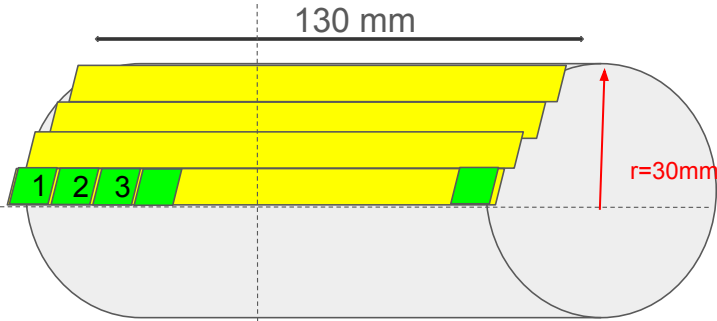
Muon Collider Simulation

MAIA detector concept, $\sqrt{s} = 10$ TeV

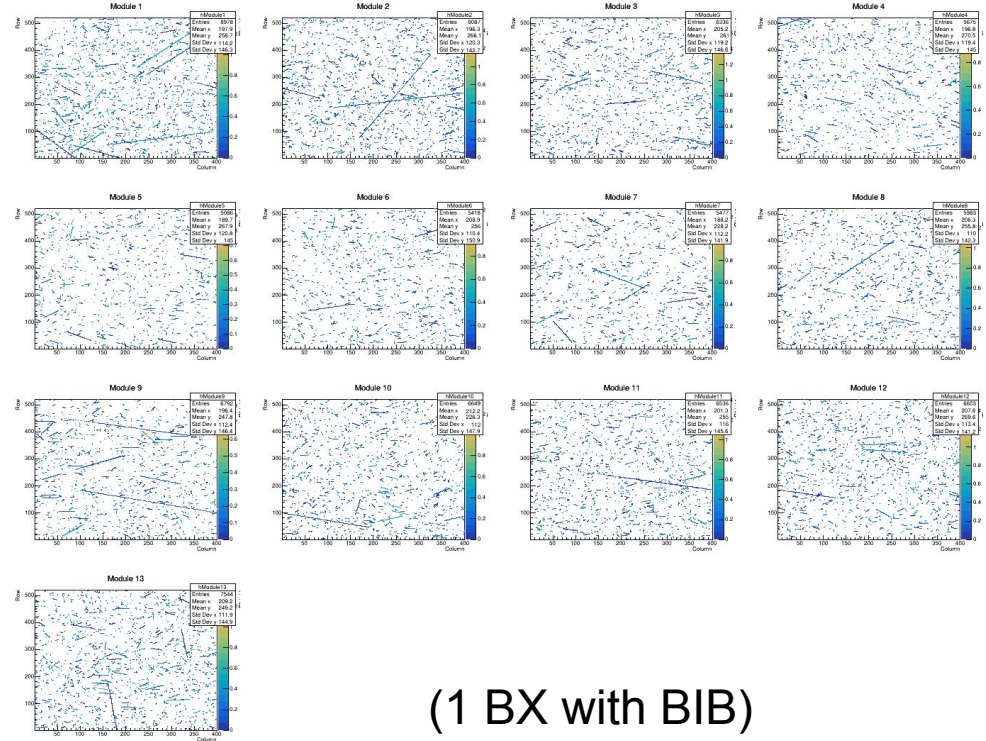
BIB: EU24 lattice, QGSP_BERT, VXB L0



Pixel Hit-map of VXB L0



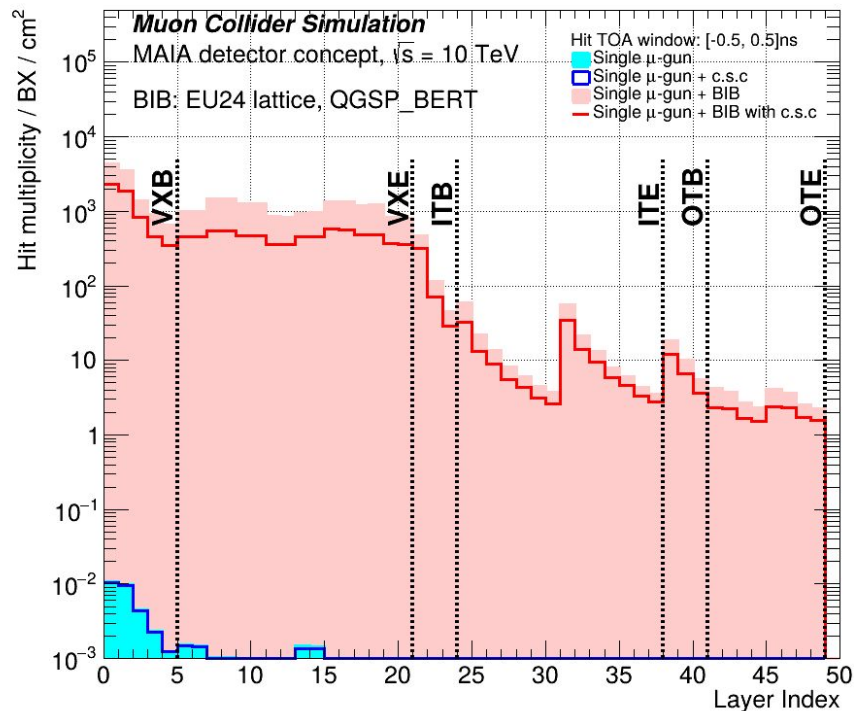
Total pixels ~ 520 x 400 pixels



(1 BX with BIB)

Tracker hit occupancy

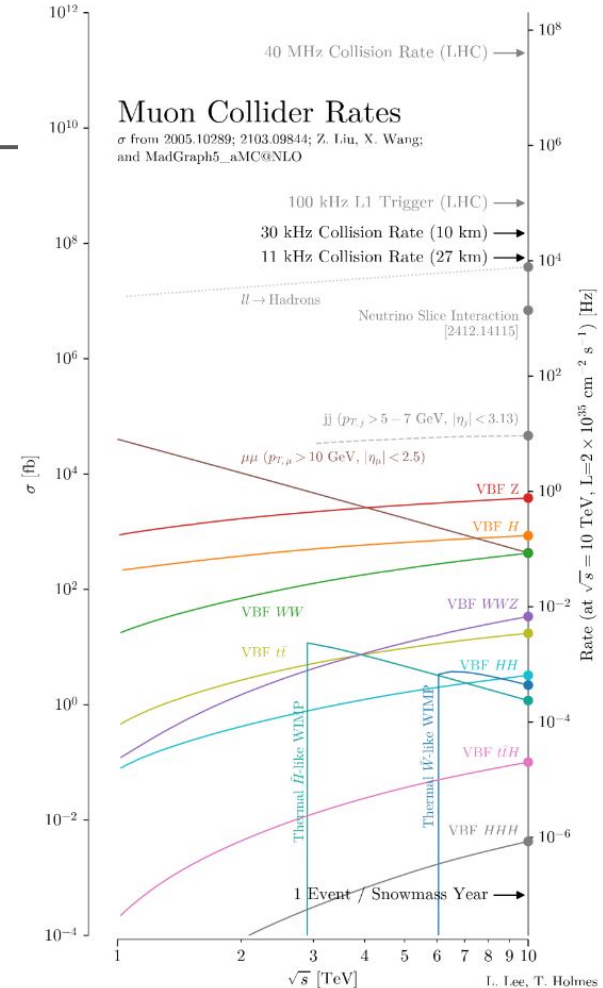
Very high hit multiplicities per BX in the innermost layers of the detectors.



- ~4000 hits/BX/cm² in VXB L0
- ~16000 pixel hits on FE (with RD53-like design, 153600 pixels)
- ~10% tracker occupancy!!
- Compared to ATLAS ITk requirement for HL-LHC = 1%

Event rates

- Bunch crossing (BX) rate ~ 30 kHz i.e. 30000 events/sec
- Physics processes at 10 TeV (in the order of decreasing rates):
 - VBF Z ~ 1 Hz i.e. 1 event/sec
 - VBF H ~ 0.1 Hz i.e. 1 event/ 10 secs
 - VBF WW, $\mu\mu \rightarrow \mu\mu \sim 0.08$ Hz
 - VBF WWZ, VBF tt ~ 0.005 Hz
 - ...
- Average number of interactions per BX (or effective pileup) = sum of rates of all processes/BX rate $\sim 10^{-5}$ to 10^{-6} (ignoring inclusive jets production).
- That is, roughly 1-10 interesting physics events per million BXs!
- That is, most of the BXs are just ... uneventful, but full of BIB.



What do we want to do?

i.e. keep only interesting events (triggered-readout)?

Or stream all data (triggerless readout) but reducing readout data volume?

Can we classify between signal and BIB clusters in an event? (Online or offline)

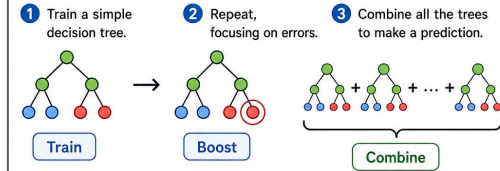
Part II

Signal vs BIB pixel-hit clusters (offline design)
The BDT vs. The Transformer

Apply a Boosted Decision Tree to Particle Gun Samples

A BDT (Boosted Decision Tree) is a method that combines many simple decision trees to make better predictions.

How it works:

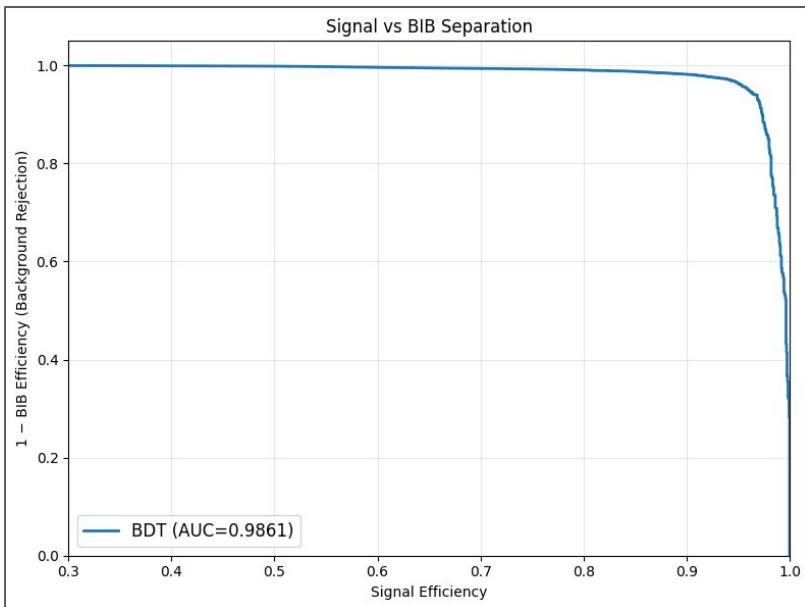


Cluster Features

Energy	Time	R
Size X	Size Y	Total Size
RMS X	RMS Y	
Skew X	Skew Y	
Incident Angle	Aspect	Eccentricity

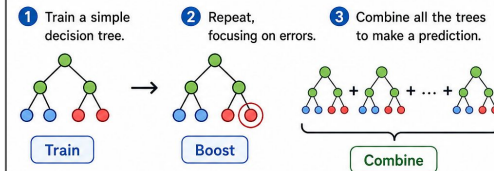
Apply a Boosted Decision Tree to Particle Gun Samples

Super good! No room for improvement



A BDT (Boosted Decision Tree) is a method that combines many simple decision trees to make better predictions.

How it works:



Cluster Features

Energy	Time	R
Size X	Size Y	Total Size
RMS X	RMS Y	
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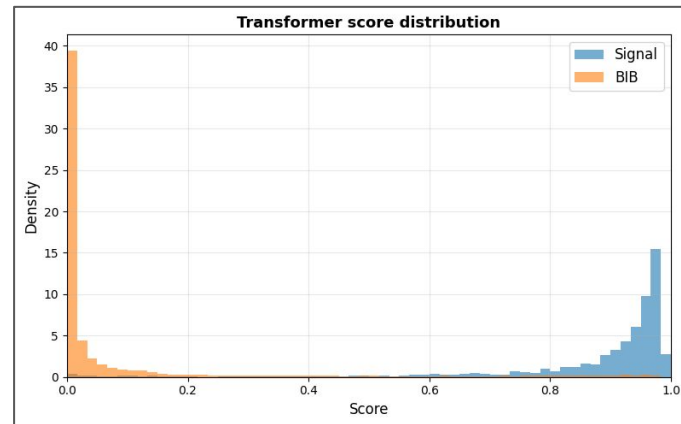
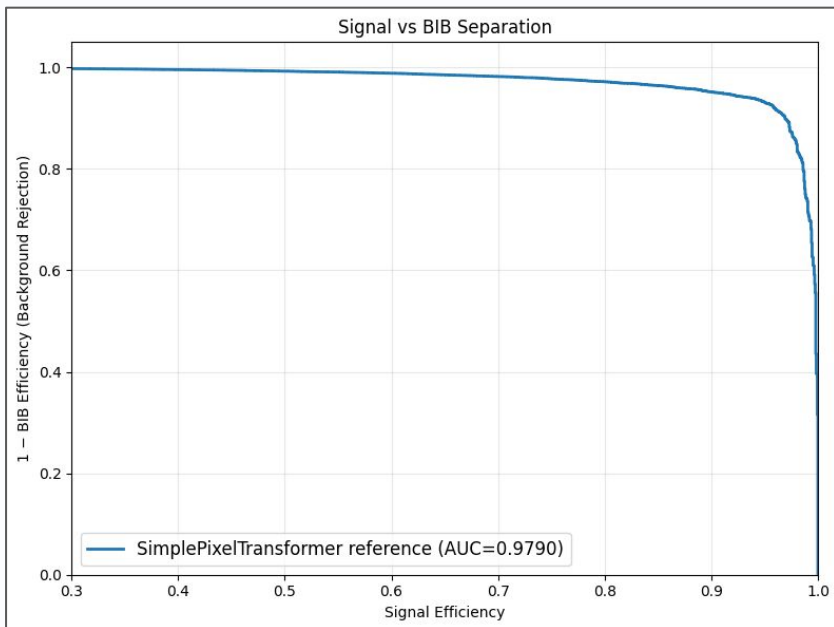
Apply the Transformer to Particle Gun Samples

Raw Hit
Features

Energy	Time
X Position	Y Position

Apply the Transformer to Particle Gun Samples

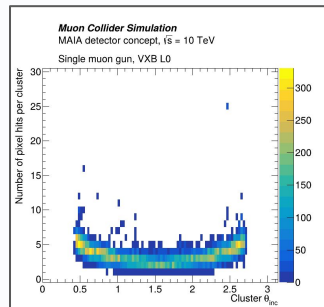
Super good! But slightly worse than the BDT



Raw Hit
Features

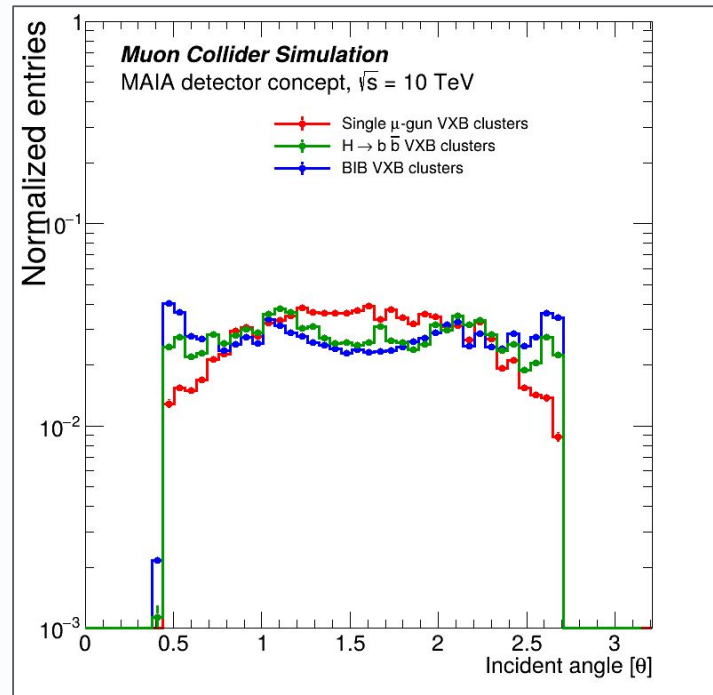
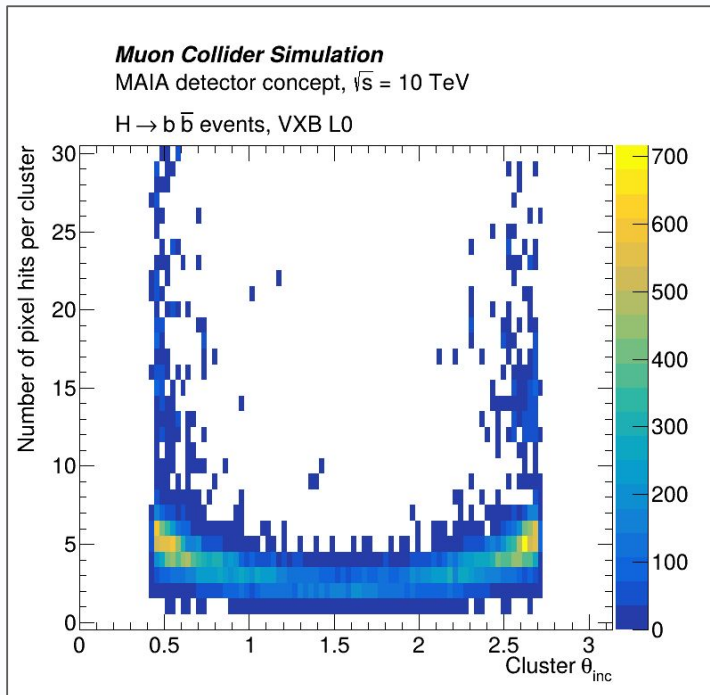
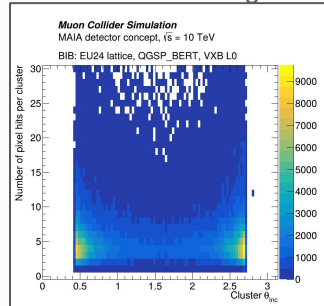
Energy	Time
X Position	Y Position

Switching to $H \rightarrow b\bar{b}$ Signal Events

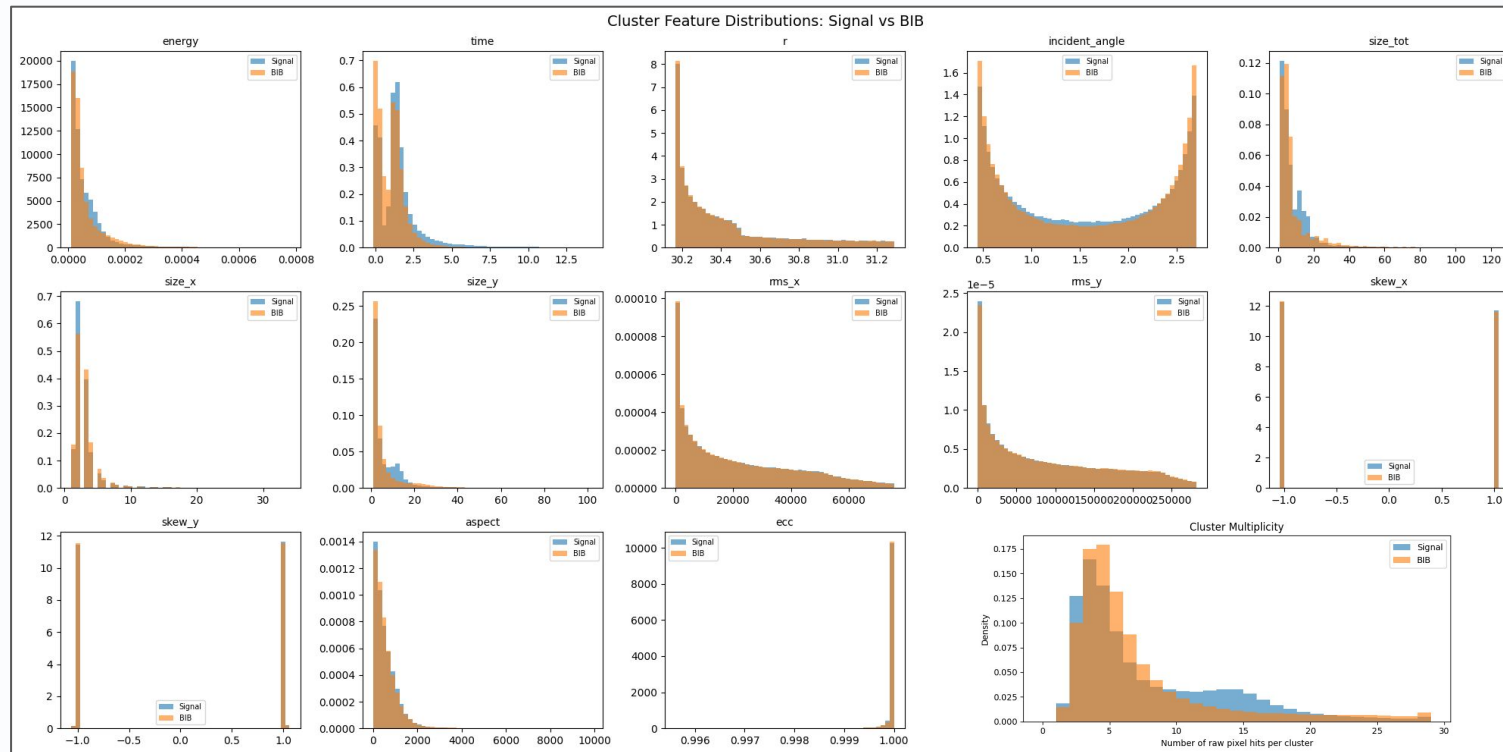


Particle Gun

Beam-Induced Background

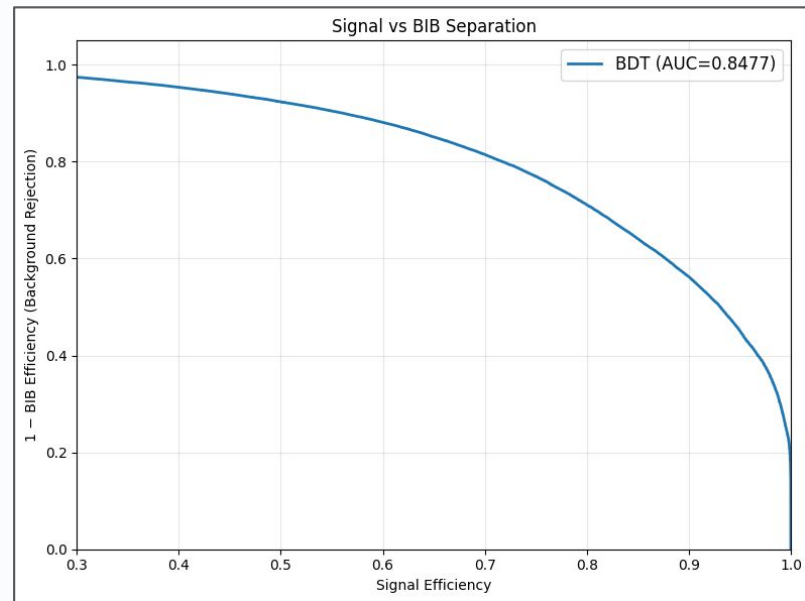
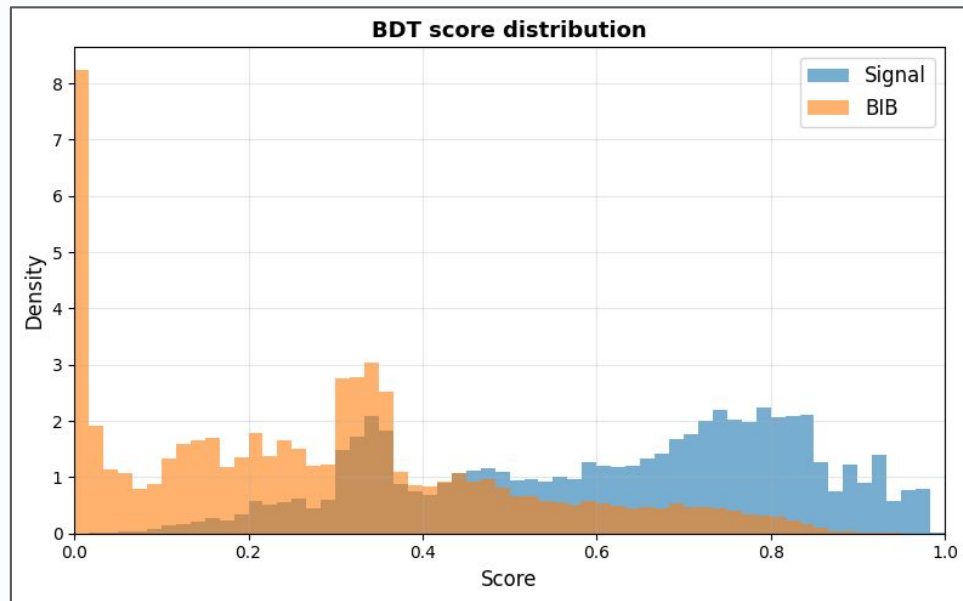


Feature Distributions



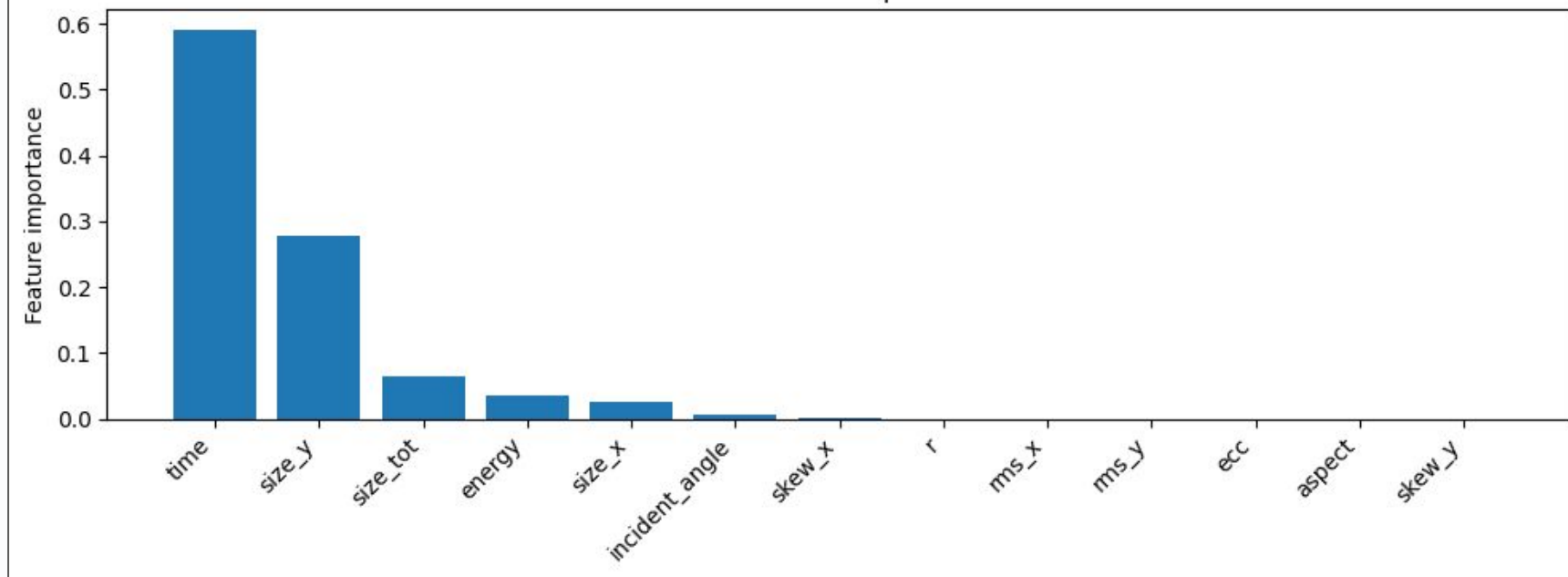
Apply BDT to $H \rightarrow bb$ Samples

Lots of room for improvement!



BDT Tells Us About Important Features

BDT Feature Importance



Why Would a Transformer Help Here?

Raw Hit Features

Energy	Time
X Position	Y Position

Cluster Features

Energy	Time	R
Size X	Size Y	Total Size
RMS X	RMS Y	
Skew X	Skew Y	
Incident Angle	Aspect	Eccentricity

Can the Transformer learn these?

Or maybe even more important quantities?

Raw Hits are a ragged data type. (Zero padded)



We can mask entries in the Transformer

Setting Up the Tutorial

	Login Node	Shared GPU Node	Exclusive CPU Node	Exclusive GPU Node	Configurable Job
Perlmutter	<input type="button" value="start"/>	<input type="button" value="start"/>	<input type="button" value="start"/>	<input type="button" value="start"/>	<input type="button" value="start"/>
Resources	Use a login node shared with other users, outside the batch queues.	Use a single GPU on a node within a job allocation using defaults.	Use your own node within a job allocation using defaults.	Use multiple compute nodes with specialized settings.	
Use Cases	Visualization and analytics that are not memory intensive and can run on just a few cores.	Work that fits on a single GPU, and uses at most a quarter of a GPU node's CPU cores and host memory.	Visualization, analytics, machine learning that is compute or memory intensive but can be done on a single node.	Multi-node analytics jobs, jobs in reservations, custom project charging, and more.	

<https://jupyter.nerisc.gov>

Configurable Job

Server Options

Account ("_g" suffix will be added as needed):

Constraint:

QOS:

cpus-per-task (GPU node has 128 cpus, CPU node has 256 cpus):

gpus-per-task (node has 4 GPUs):

nodes (maximum of 4 for jupyter QOS):

ntasks-per-node:

Reservation:

time (time limit in minutes):

Setting Up the Tutorial

1. Go to the Terminal
2. Go to the Repo:
`cd ~/2026-gatech`
3. Update the Repo:
`git add -u`
`git commit -m"past tutorials"`
`git pull`
4. Set up the environment:
`cd sessions/04_muon_col/tutorial`
`source setupTutorialEnv.sh`
5. Open the notebook:
`02_simple_transformer_tutorial.ipynb`
6. Set the Kernel to `pytorch-2.6.0`

Please record the AUC value of your best Transformer training at the end of the session to this spreadsheet -

<https://docs.google.com/spreadsheets/d/1Q2ISRGGdE4QYXJ82086jcRxQP5nhCUqv9Kh0Ku8BKNQ/edit?usp=sharing>

Also, give brief details about the exact method you tried!