

PICMIC^{*} : An Ultra Precise 4D Detection Concept

^{*} PICosecond subMICron detection concept

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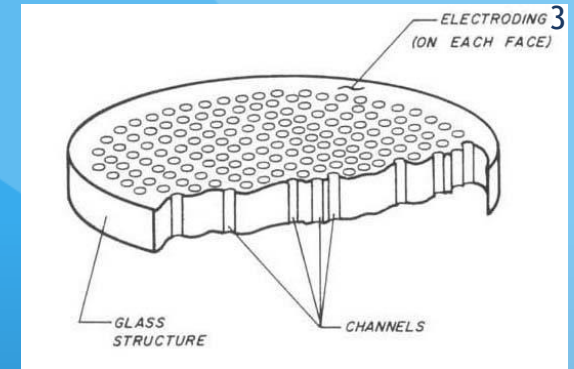
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Outline

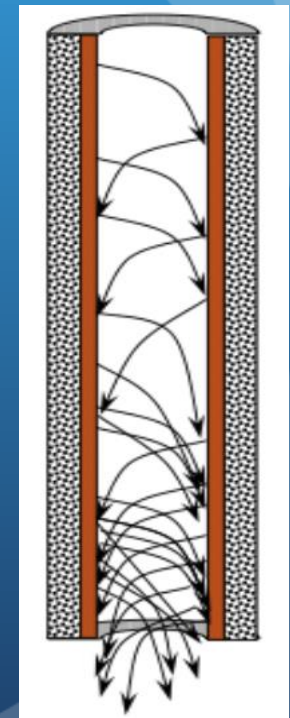
- Introduction
- PICMIC concept
- Time measurement
- Position measurement
- First prototype with MCP and results
- Time and position improvements
- From MCP to NCP

Micro Channel Plate (MCP)

- MCP is considered as the **best timing device** with a few picoseconds of time resolution.
- MCP has an excellent intrinsic spatial resolution since the avalanche produced by the incoming particle is constrained to one of the glass tube whose diameter can be as small as **3 μm**
- MCP are often used for their timing (reaching few to tens ps) while their **spatial resolution is not appropriately exploited.**



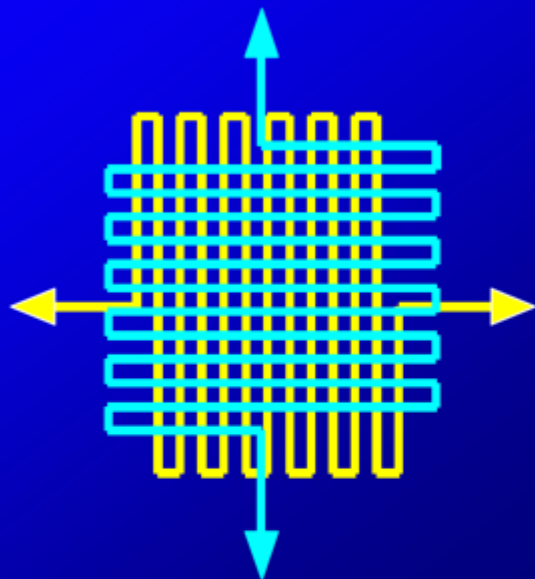
Few μm diameter





Readout Anode Types (partial list)

Courtesy J.Vallegra



Cross Delayline
(XDL)

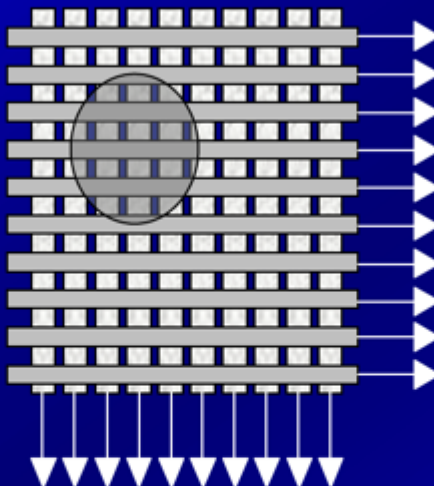
4 amps

Gain $\sim 10^7$

Rate $\sim 200\text{kHz}$

$\Delta t \sim 100\text{ps}$

Few
mm



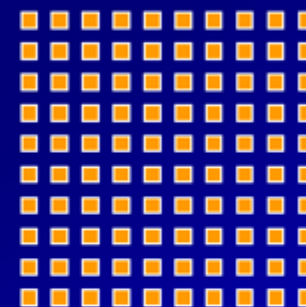
Cross Strip
(XS)

2 x N amps

Gain $\sim 10^6$

Rate $\sim 2\text{MHz}$

$\Delta t \sim 100\text{ps}$



Medipix ASIC
Intensified CCD

N x N amps

Gain $\sim 10^4$

Rate $\sim 200\text{MHz}$

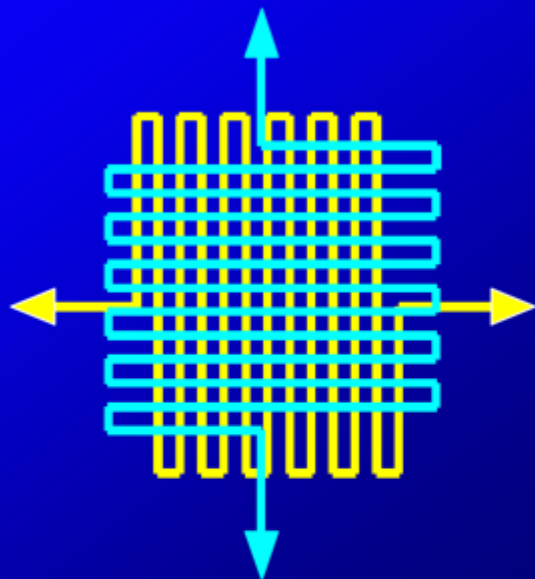
$\Delta t \sim 1\text{ms}$

100
 μm



Readout Anode Types (partial list)

Courtesy J.Vallegra



Cross Delayline
(XDL)

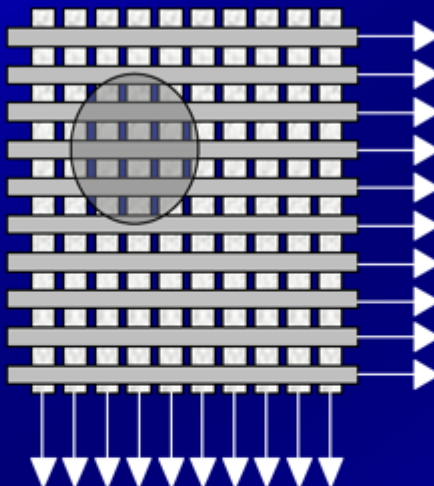
4 amps

Gain $\sim 10^7$

Rate $\sim 200\text{kHz}$

$\Delta t \sim 100\text{ps}$

Few
mm



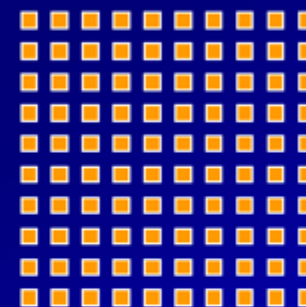
Cross Strip
(XS)

2 x N amps

Gain $\sim 10^6$

Rate $\sim 2\text{MHz}$

$\Delta t \sim 100\text{ps}$



Medipix ASIC
Intensified CCD

N x N amps

Gain $\sim 10^4$

Rate $\sim 200\text{MHz}$

Timpix4: 193 ps lsb

100
 μm

MCP intrinsic spatial resolution is not well exploited as its temporal one

We propose the following scheme :

- ❑ A **transparent grid** placed downstream the MCPs and read out by sensors with excellent **time resolution**. Followed by:
- ❑ A detection **matrix with micrometric pixels** to measure with great **precision the position** of the avalanche while **requiring limited number of electronics channels**.

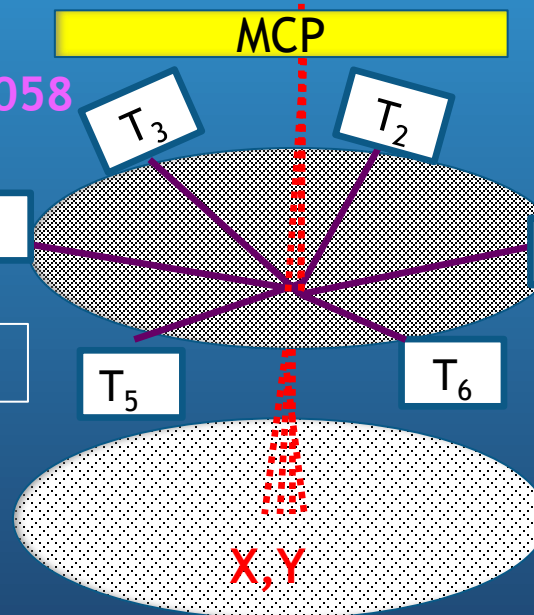
Patented concept:
PCT/EP2020/050058

Metallic Grid

Time + position

Pixels

Position+ time



Concept description

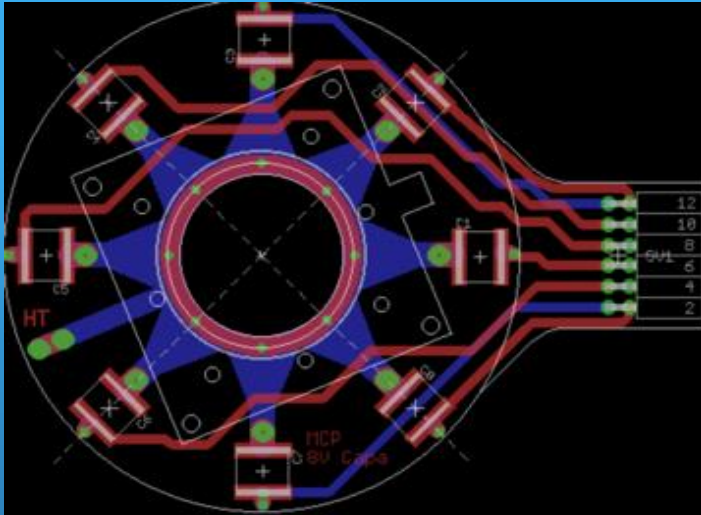
➤ Delay plane concept

The grid can be the metallic anode of the MCP

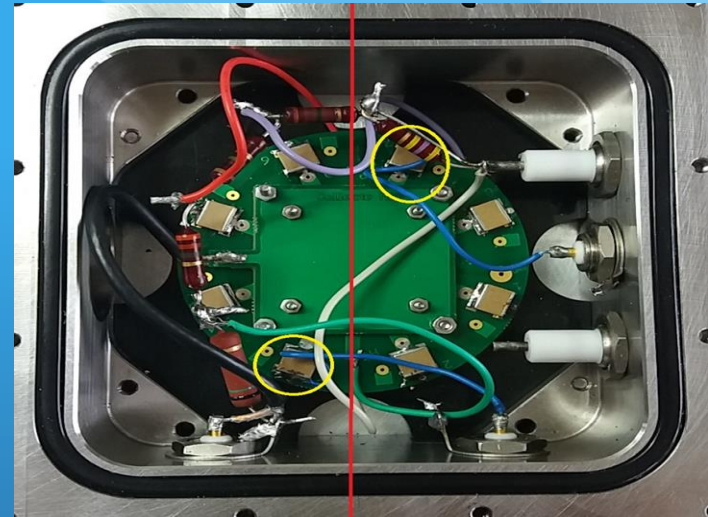
➤ Woven strips → 3d interconnected pixels concept

Use (x,y) to subtract the time propagation on the grid and then

improve on time measurement : $T_{\text{abs}} = \frac{\sum_0^N T_i - T_{i-\text{propag}}}{N}$



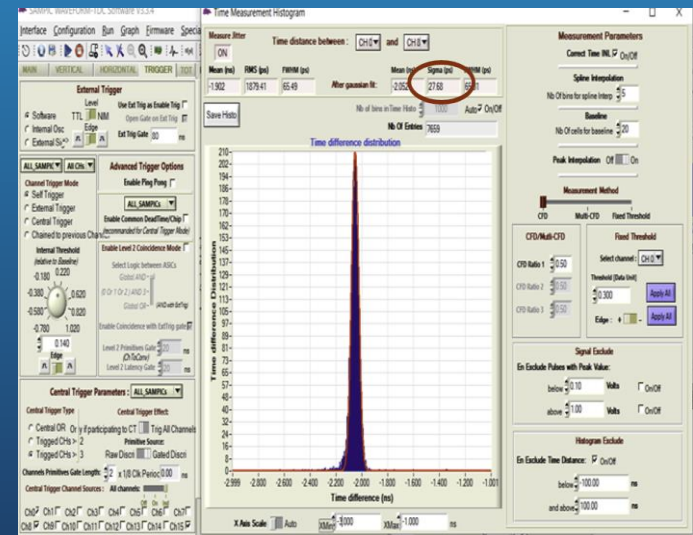
Delay-plane readout



First setup with two MCP of 2.5 cm diameter to validate the delay plane principle



SAMPIC: a waveform digitizer (3ps)



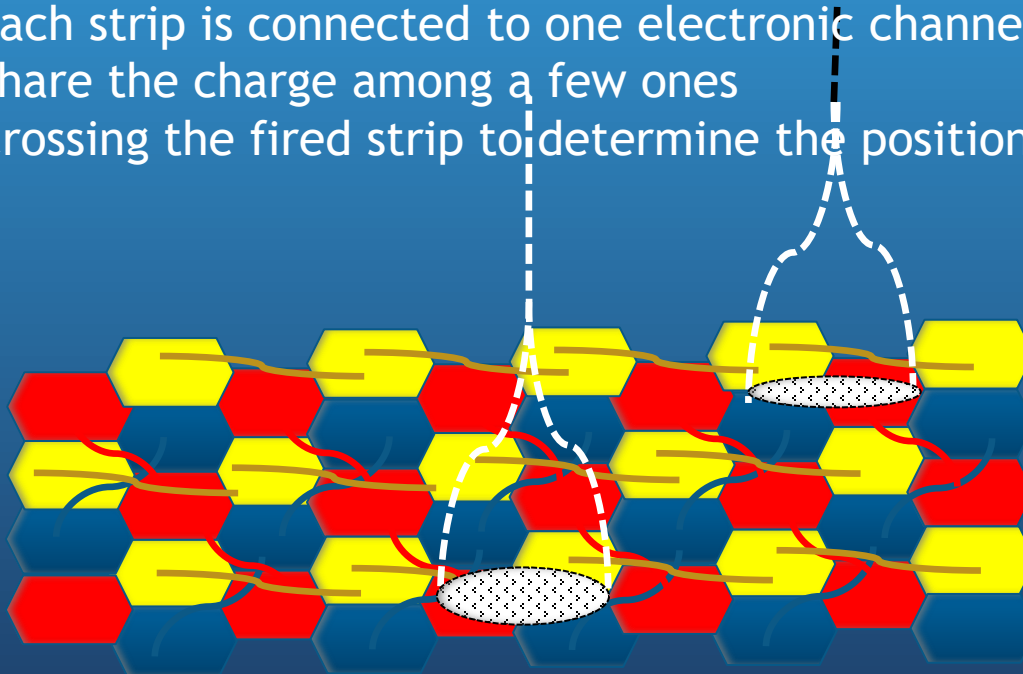
$$\sigma_{T_i-T_j} = 30 \text{ ps} \rightarrow \sigma_T = 8 \text{ ps}$$

Position measurement

PCT/EP2018/053561

To reach few microns resolution with a limited number of electronic channels, a new concept was developed and successfully tested (**Tricot**)

- ❑ Connect the pixels in woven strips in three or more orientations
- ❑ Two neighboring pixels are connected to two different strips of different orientations
- ❑ Each strip is connected to one electronic channel
- ❑ Share the charge among a few ones
- ❑ Crossing the fired strip to determine the position

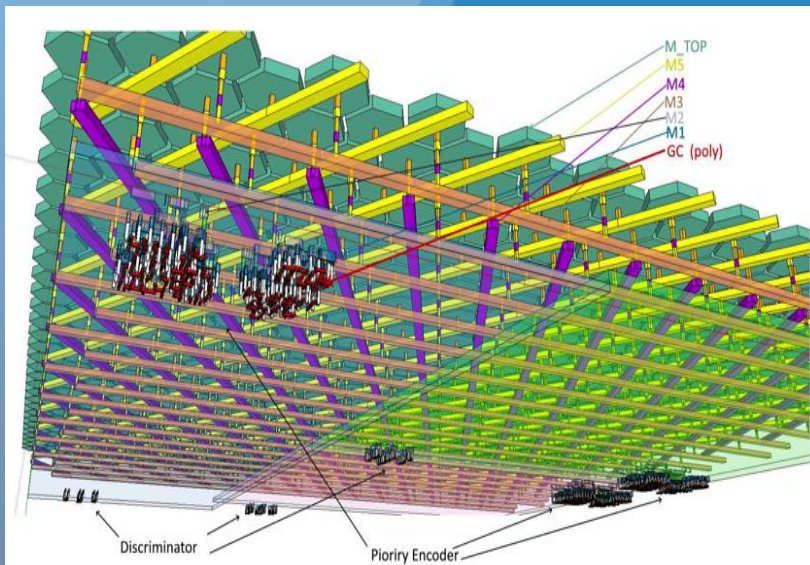


Ambiguity is eliminated thanks to the 3D interconnection

NXN → 3N : Reduction of electronic channels, power consumption and occupancy

Pixel sensor & electronics

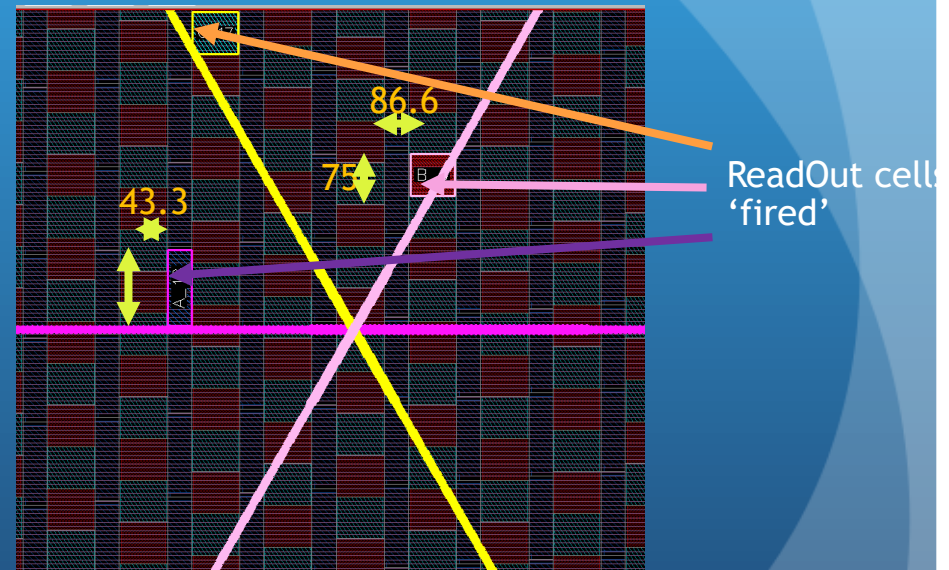
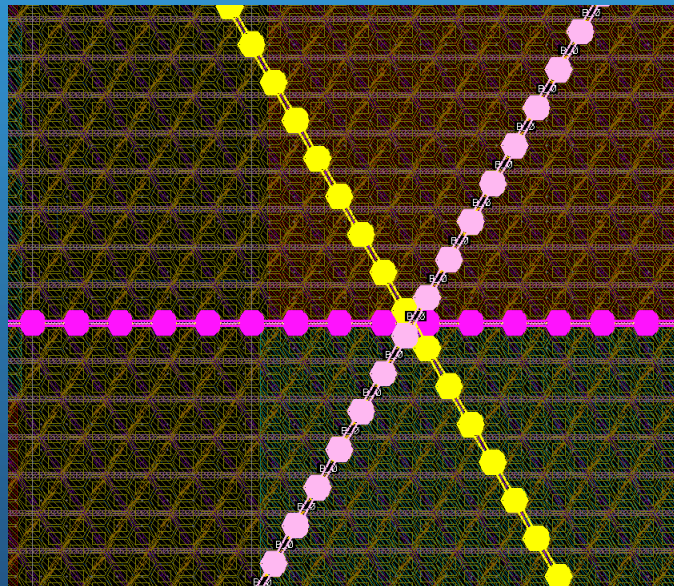
- Pixels of a few microns are needed to exploit the spatial resolution
- Only wafer-based technique can offer such a structure
- TJ 180 nm, 6 metallic layer wafer
- Current conveyer preamplifier
- Priority encoder



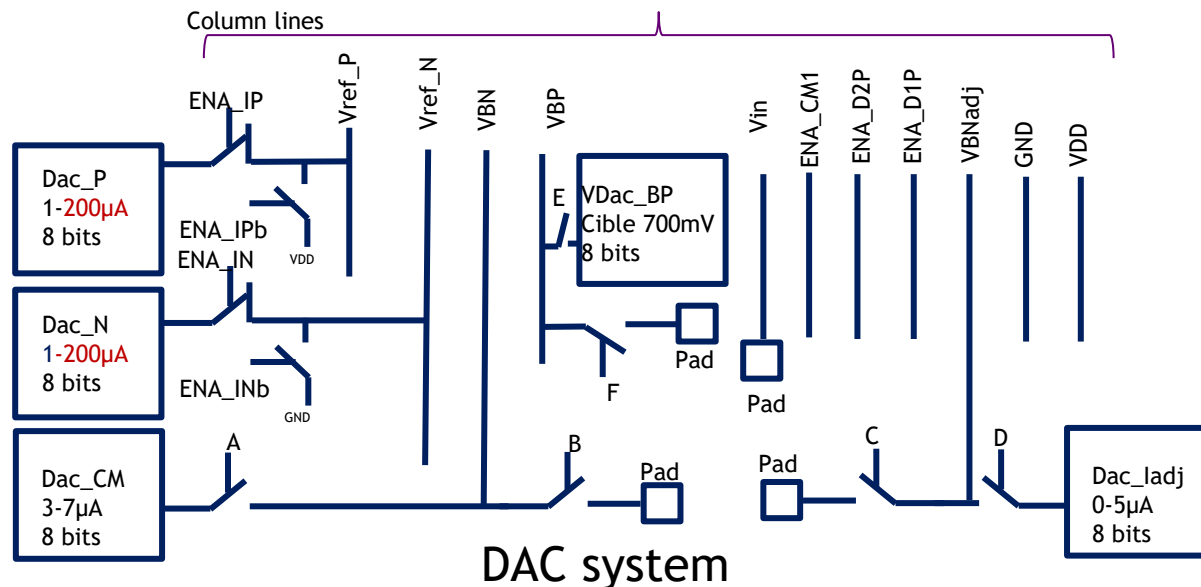
The 2556 RO cells allow reading out the
2 216 000 pixels of 5 μm pitch

Parameters	Value
Design Flow	Cadence DoT flow
Technology	TJ CIS 180nm
Power supplies	1.8V
Power density	>172mW/cm ² (only analog static current)
Die dimension	~7.5x7.5 mm ² (6.5x7.5mm²)
Anode dimension	~22 μm^2 (5 μm hexagonal pitch)
Readout pixel dimension	50 μm x140 μm
Readout matrix	128x54 cells (only 2556 active)
Input clock	40MHz
Read-out port	13-bit parallel
I/O Pad	CMOS
Slow control	I2C
Max data rate (1Mhz hit rate)	390Mbps

The signal is transmitted from the fired pixels to their associated readout cells

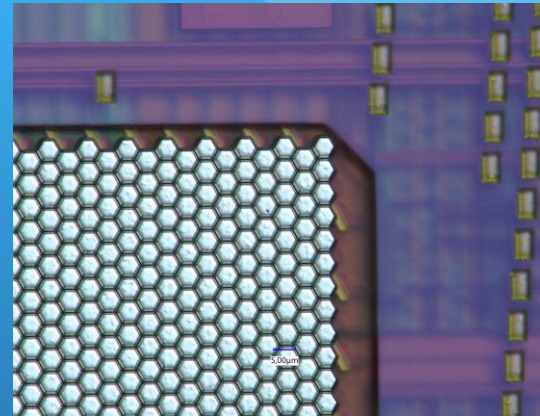
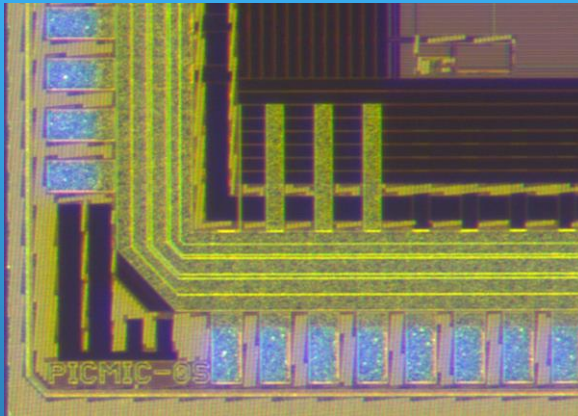


Crossing the lines associated to the fired channels provides the position

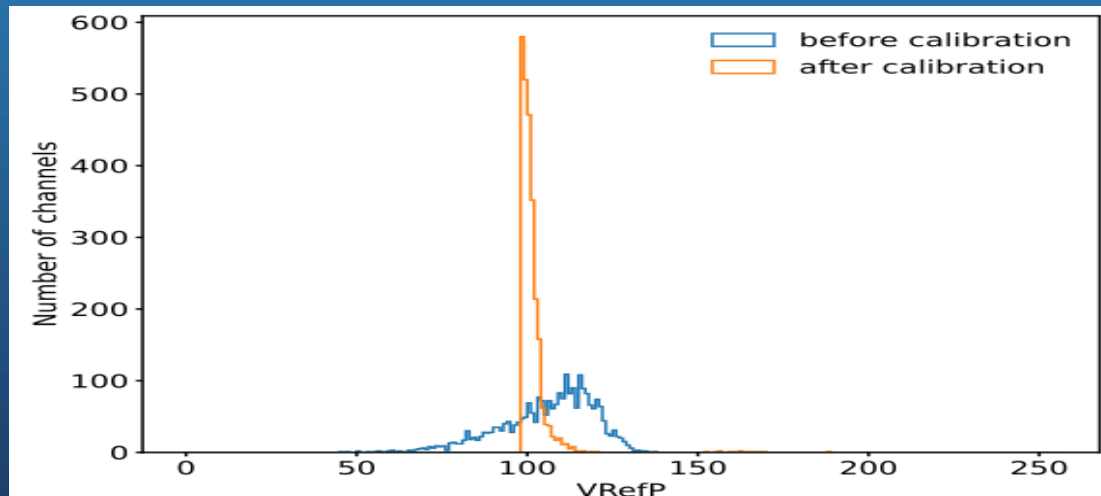


The chip was submitted in November 2021 and received on July 2022

TowerJazz 180 nm

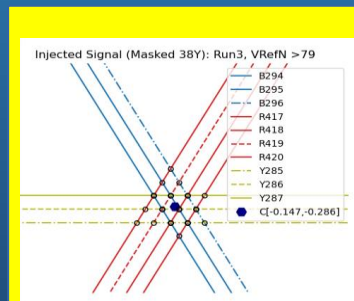
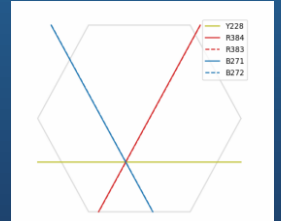
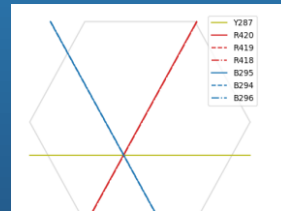
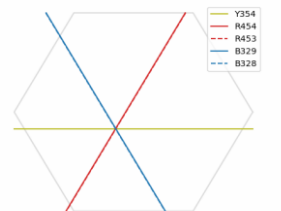
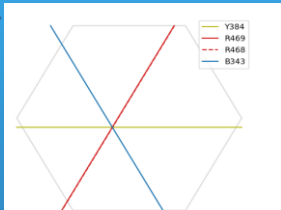
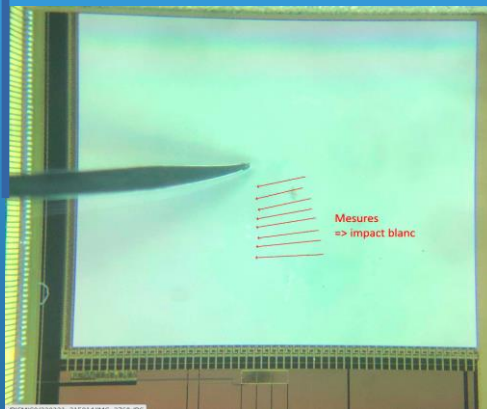
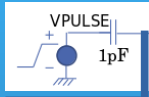


A calibration system was developed to reduce the S-Curve dispersion of the 2556 channels. 3-bit local DAC is used to reduce the dispersion.



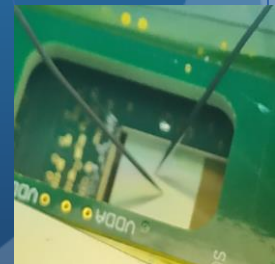
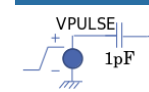
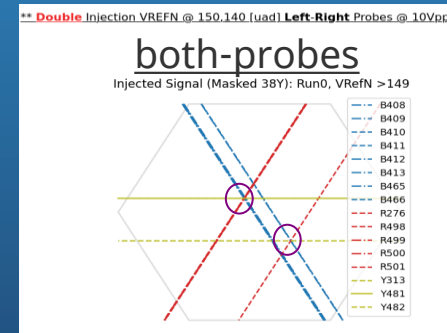
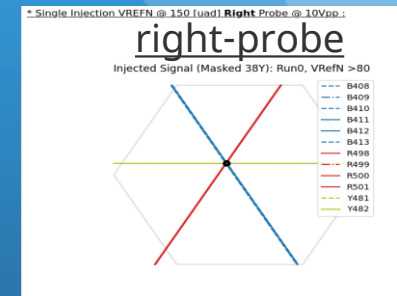
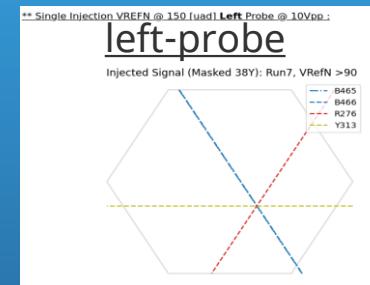
Tests with direct injection using probes

Probe scan from bottom - top



Clustering and centroid estimation

Two probes injection



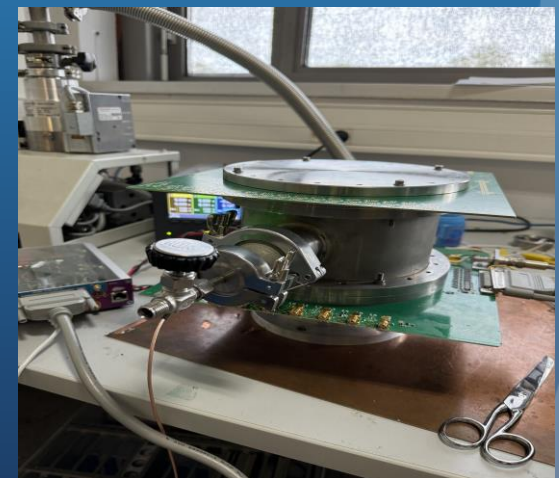
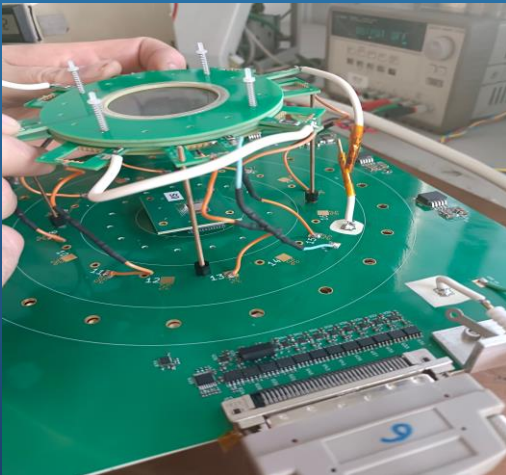
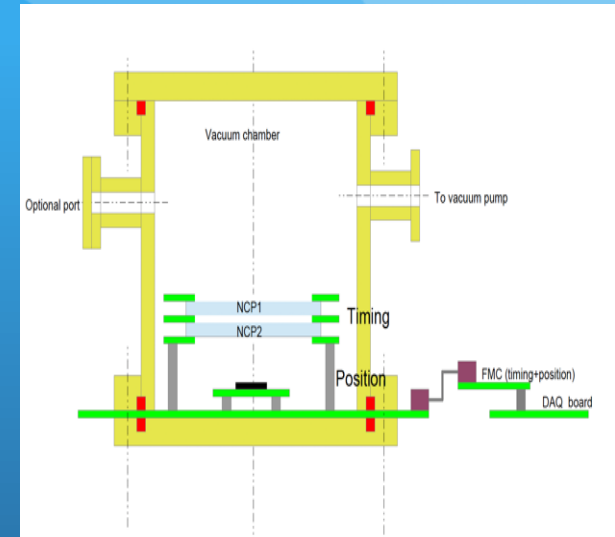
The first PICMIC demonstrator

The first prototype including:

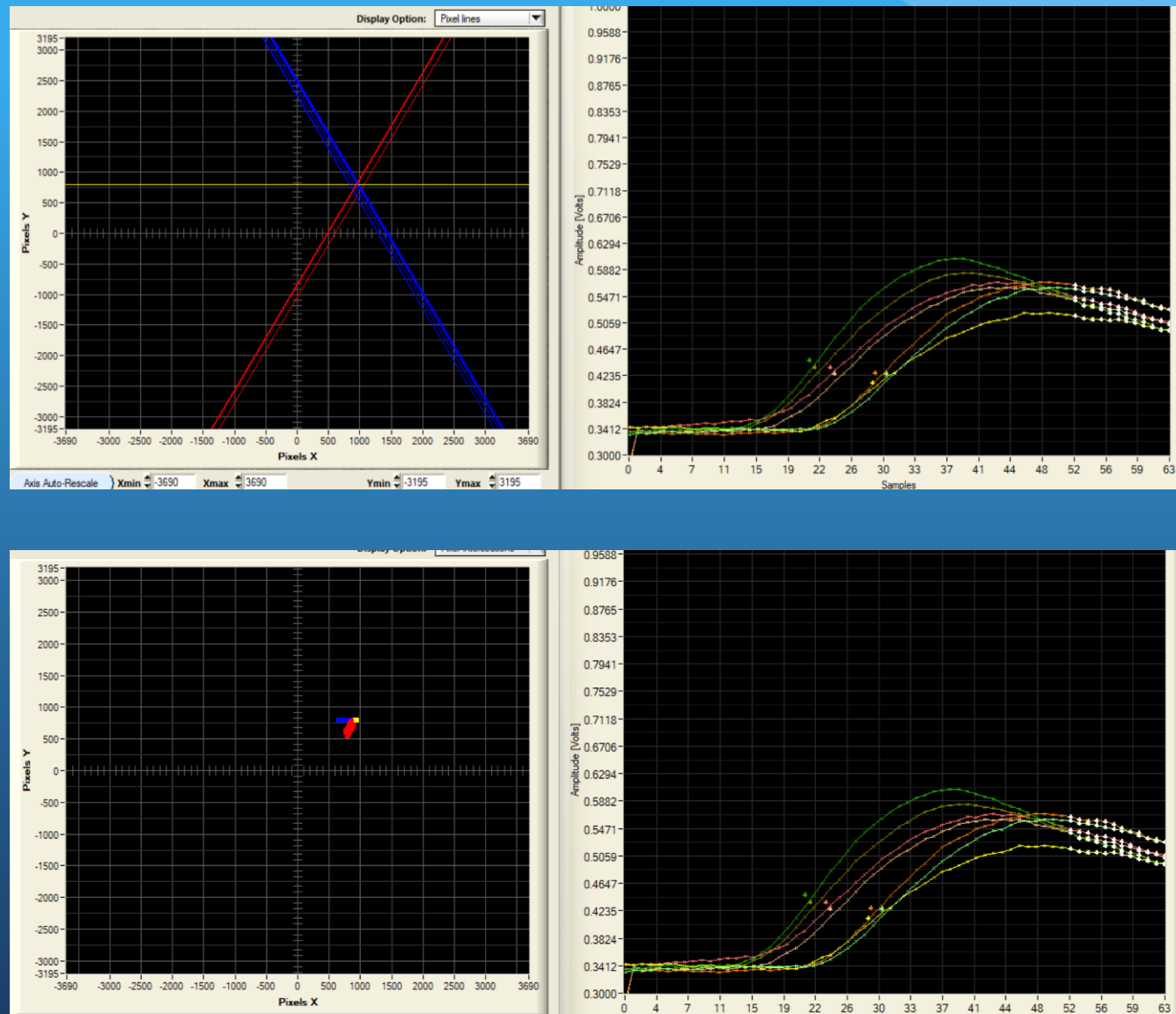
- Two 5-cm diameter MCP (Hamamatsu, Photonis, CBMA)
- A board hosting 16 timing sensors (only 8 were cabled)
- A mezzanine hosting the pixel sensors
- A Master board

All are placed within a vacuum system ($<10^{-5}$ mB)

A DAQ board allowing the synchronization between the time and the position measurement (40 MHz clock).

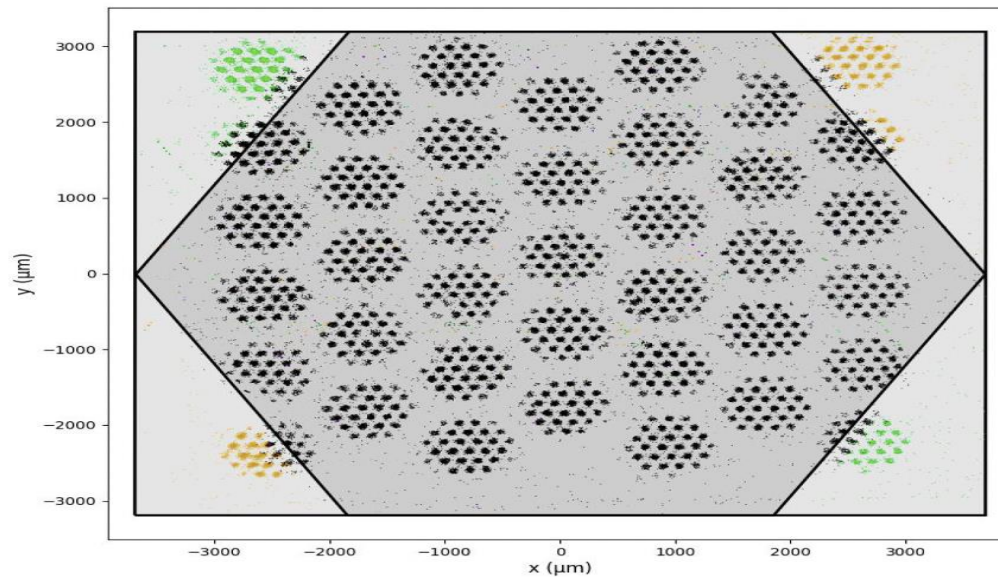
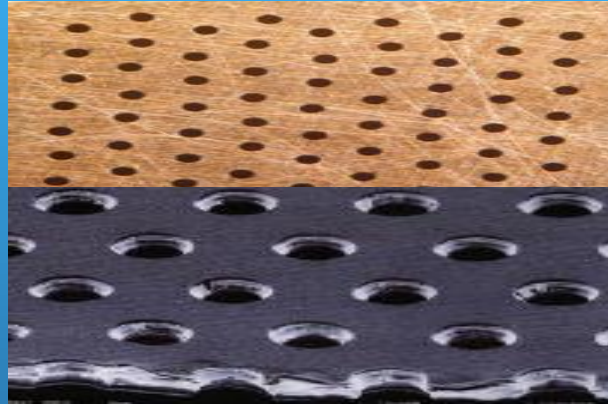


The whole system was tested by using collimated α and γ sources

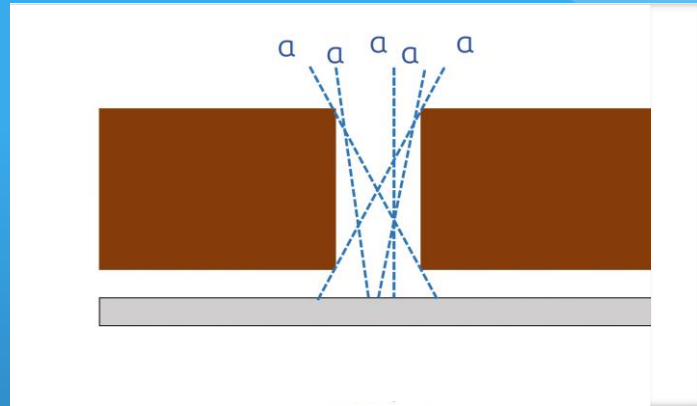


Spatial resolution

α source seen through a holes of 0.3 mm diameter and 0.8 mm pitch
placed on a GEM foil with 50 μ m diameter and 140 μ m pitch

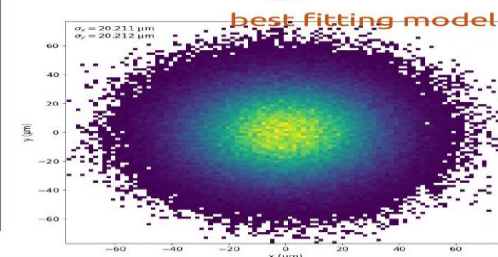
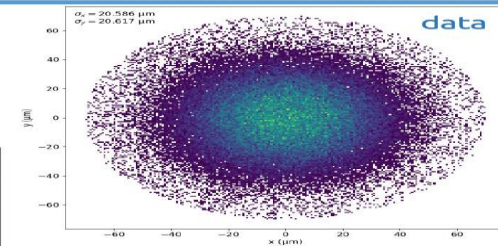
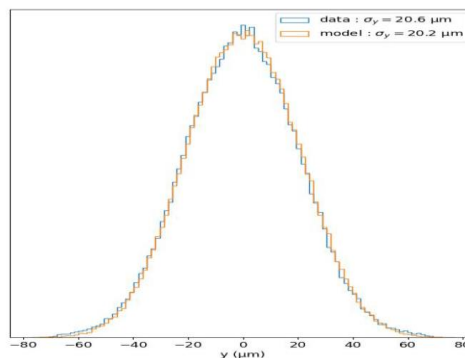
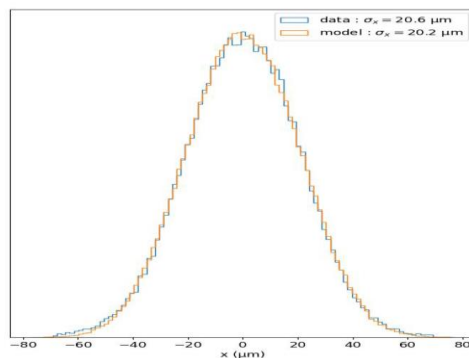


Spatial resolution

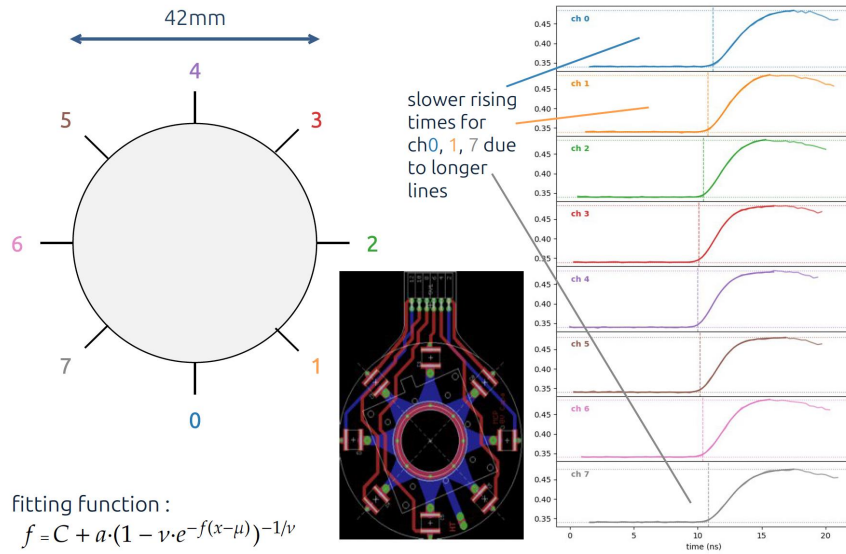


To estimate the spatial resolution, we developed a simulation tool to describe the alpha trajectories and their impact on the MCP. We then convolute the impact with a 2D gaussian distribution. The best data-simulation fit provides the spatial resolution of our detector

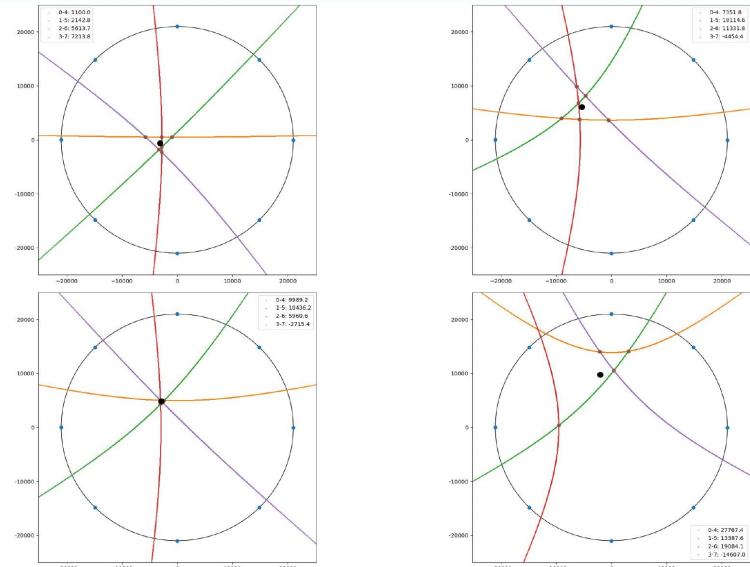
Best fit $\rightarrow \sigma_x, \sigma_y$ of **14.5 μm**



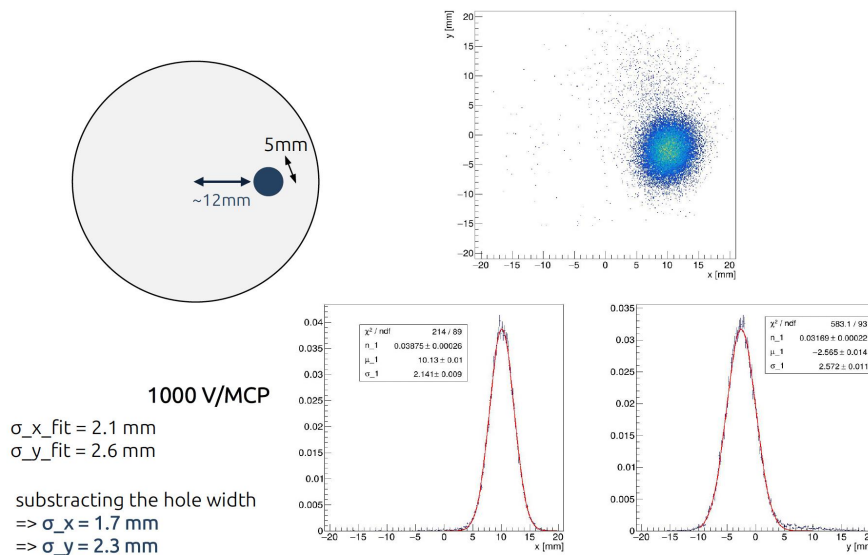
Timing detector



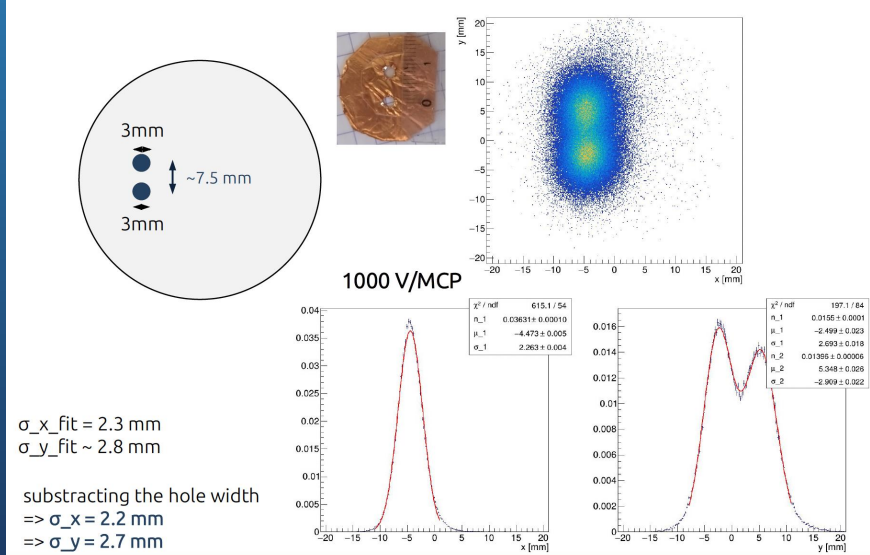
Timing detector – position reconstruction



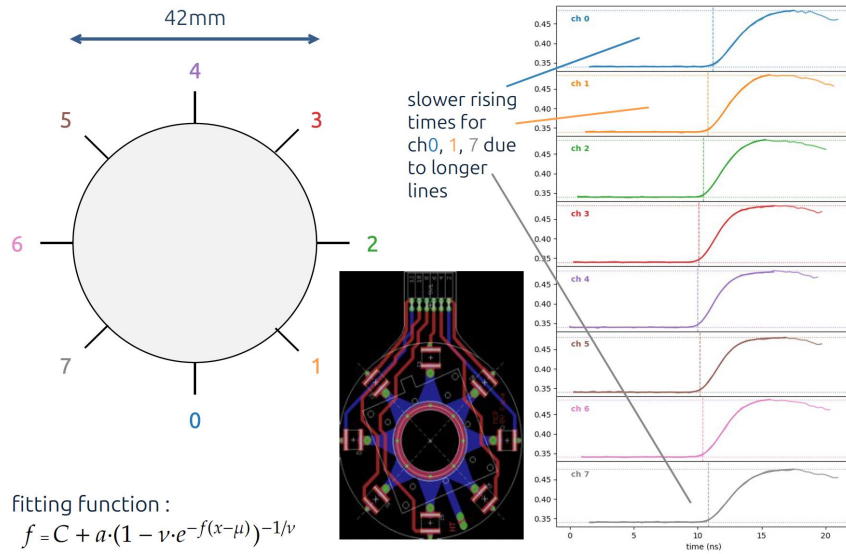
Timing detector – position resolution



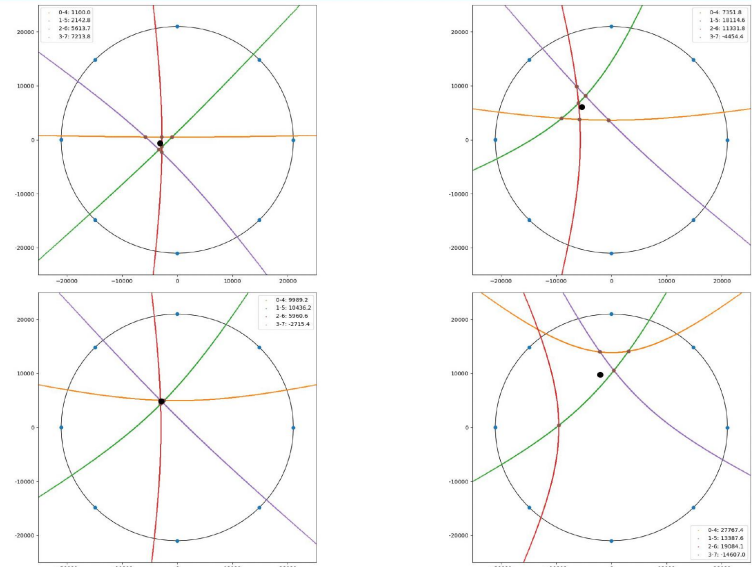
Timing detector – position resolution



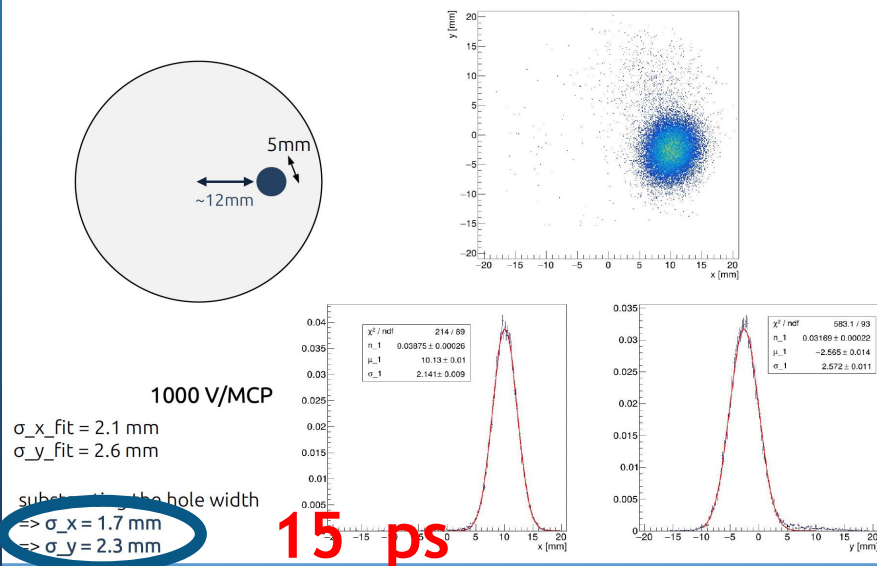
Timing detector



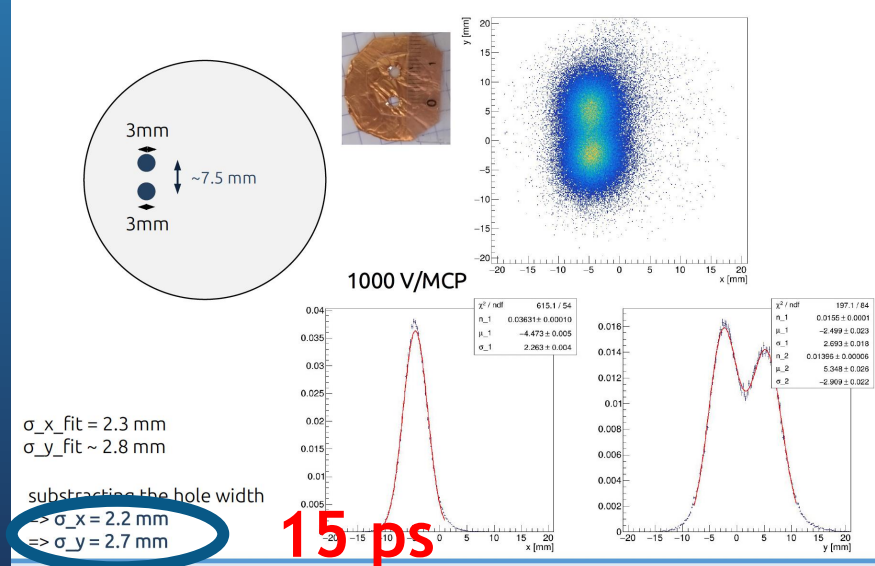
Timing detector – position reconstruction



Timing detector – position resolution

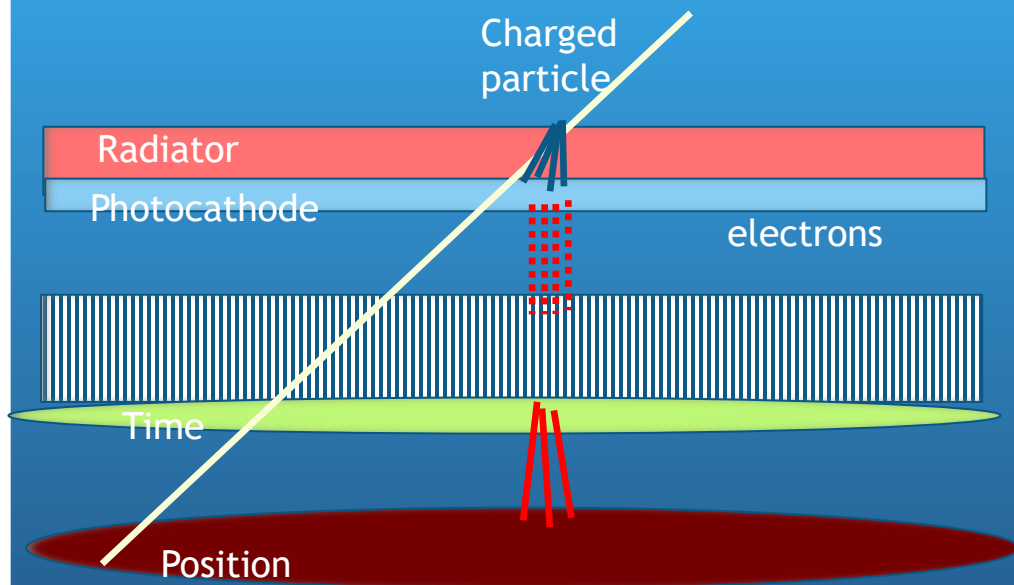


Timing detector – position resolution



Next step

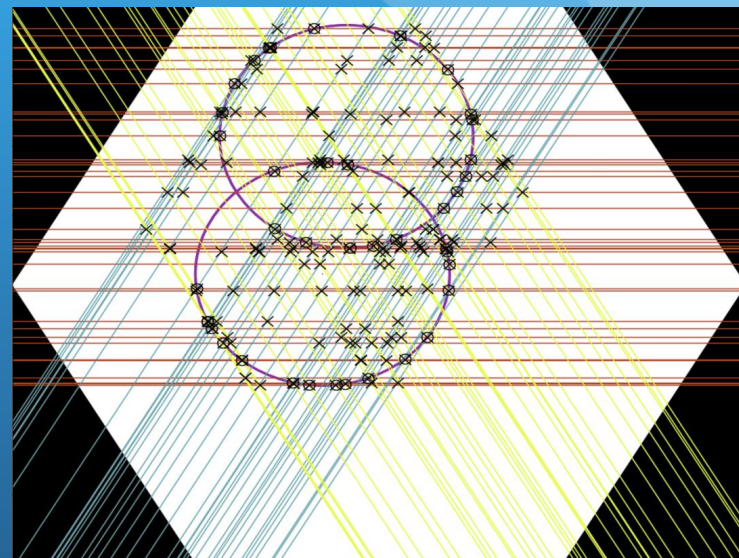
Can we use PICMIC for tracking



Radiator should fulfil two constraints:

- 1) Enough Cerenkov photons are produced
- 2) Small budget material

MgF₂ crystal of 3 mm thickness was coated with DLC @ CERN and will soon be tested on the PICMIC setup

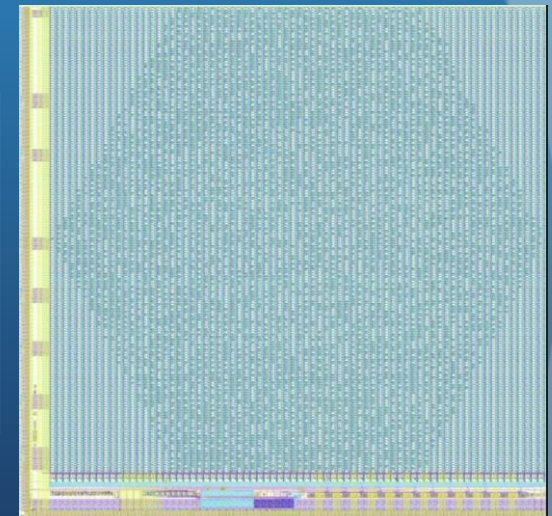
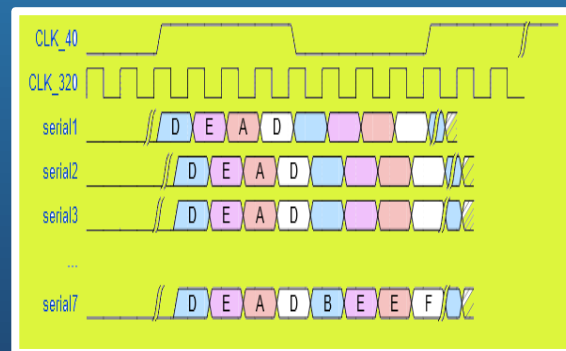
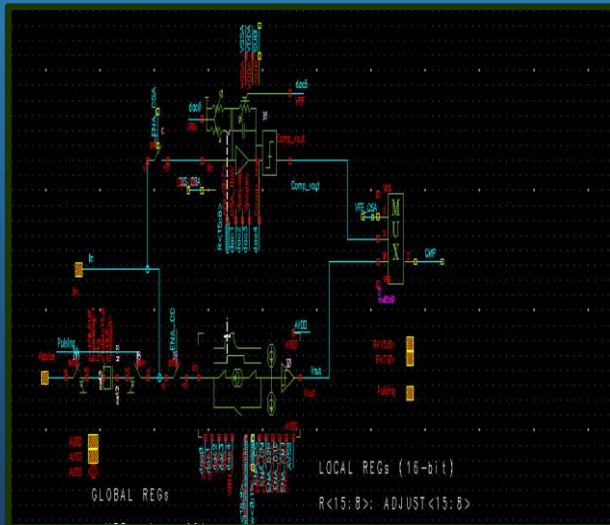


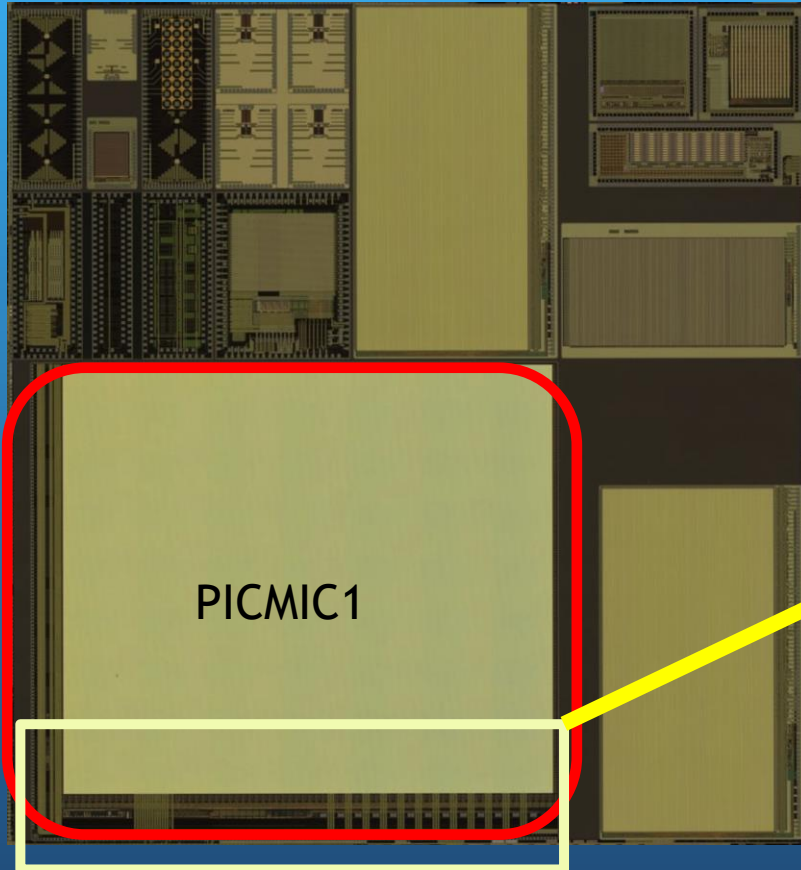
Cherenkov rings construction using Hough Transform

Next step: Spatial Measurement

The PICMIC0 chip was the first attempt to demonstrate the concept. We need to improve on several features:

- Better calibration possibilities (**8 bits DAC**) to get better uniformity
- Higher acquisition rate (**1 Mhz → 10-30 MHz**)
By reading out each column separately
- By increasing the surface of the sensor by a factor of 4 (**1.2 cm x 1.4 cm**)
- Adding a **charge preamplifier** to avoid current smearing problems for long tracks.
- Few channels outputs are directly accessible to test external TDC

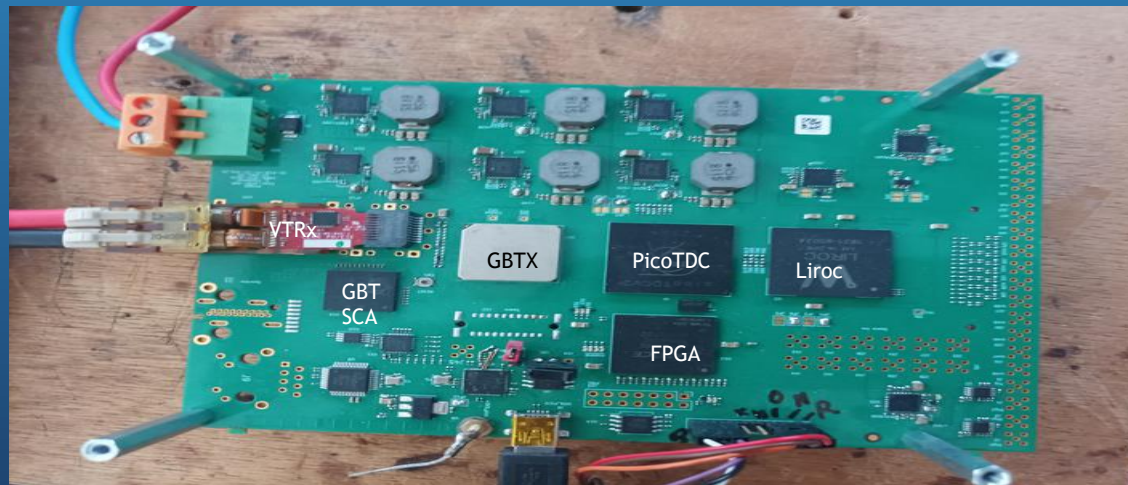




Next step: Time Measurement

SAMPIC is an excellent tool but has a dead time of about $1.25 \mu\text{s}$. Another timing measurement having a TDC with negligible dead time is needed to use PICMIC in higher rate modes.

A board integrating a low-jitter timing preamplifier and discriminator (**LIROC-OMEGA**) as well as a precise TDC (**picoTDC-CERN**) was conceived. The board will use the GBTX developed by the CERN to communicate with the DAQ system.



The board is ready: 10 ps is obtained measured with charge injection of 1 pC

Next step: Acquisition

IDROGEN board that was developed within the DAQGEN of the IN2P3 will be used.



To be able to exploit the IDROGEN board we need:

- ☐ develop appropriate interface/mezzanine boards between the IDROGEN and the timing and position boards.
- ☐ develop an appropriate firmware to synchronize the data

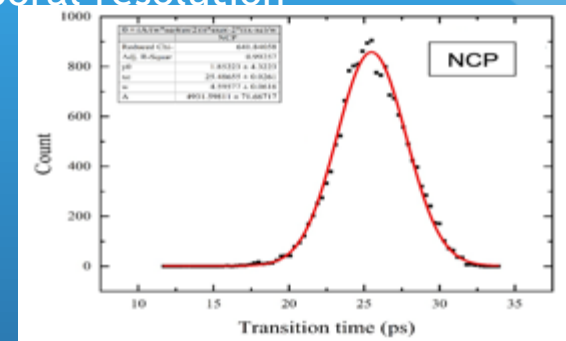
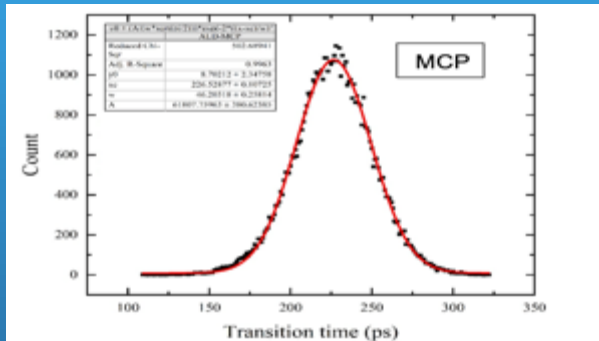
This work is now in an advanced stage. First tests with the board is foreseen before end of 2026

Going beyond the MCP→ NCP

NCP

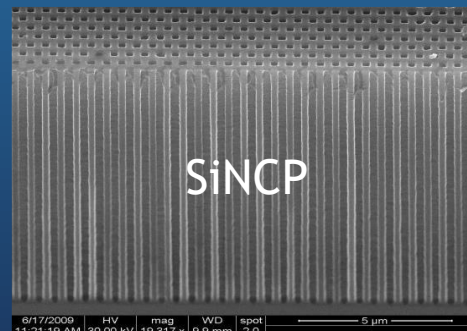
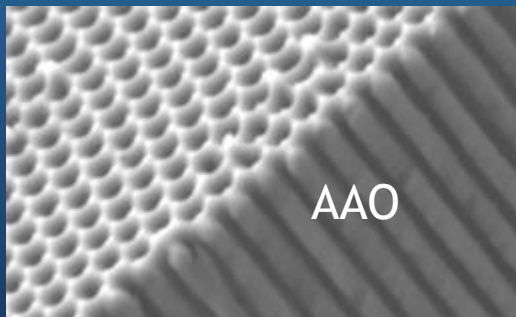
A new kind of MCP that we call NanoChanel Plate (NCP) is being developed. It aims at producing structures with nanoholes that could be coated with emissive and resistive materials.

→ At least ten times better spatial and temporal resolution



Three technologies are followed:

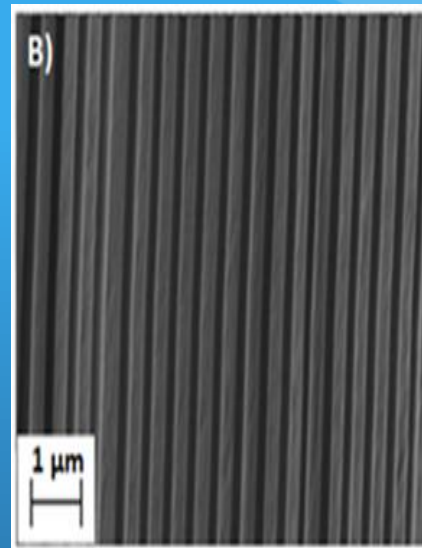
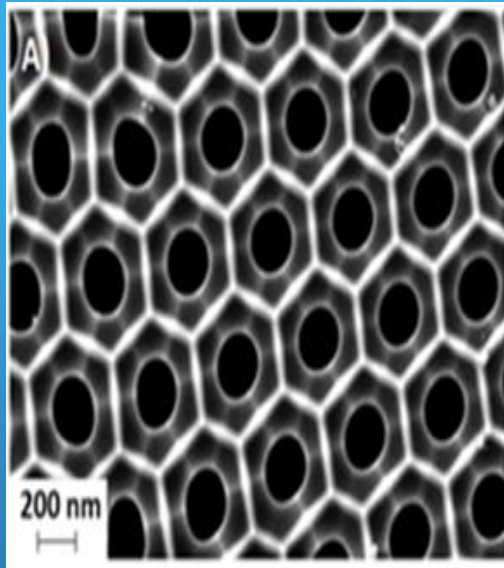
- Anodized Aluminium Oxide AAO (with IMP → ANR NanoPolyPad)
- Silicon electrochemical etching (with INL → ANR NCP)
- Femto-laser digging (with LHC → ANE LAMP?)



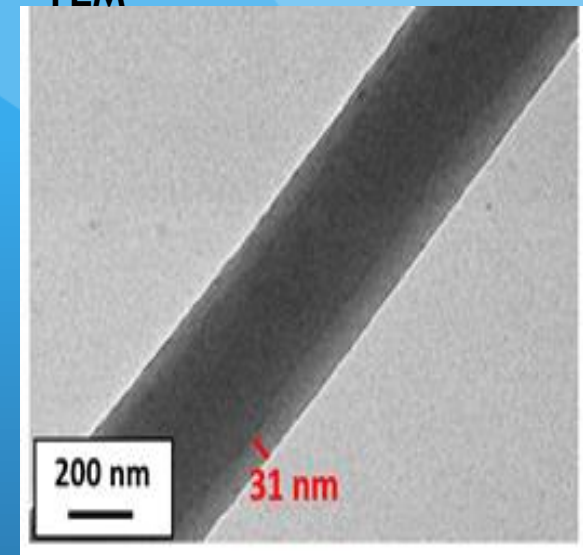
Summary

- The PICMIC concept proposed to to simultaneously exploit the time and position intrinsic resolutions of MCP is validated
- Time resolution of 15 ps has been achieved
- Spatial resolution of 15 μm has been achieved
- New version of PICMIC will allow to exploit the intrinsic resolutions of MCP.
- the system can be used as timing tracker as well as a precise 4D camera.
- A new generation of MCP called NCP with the aim to reach 1 ps and sub-micrometer resolutions are being developed

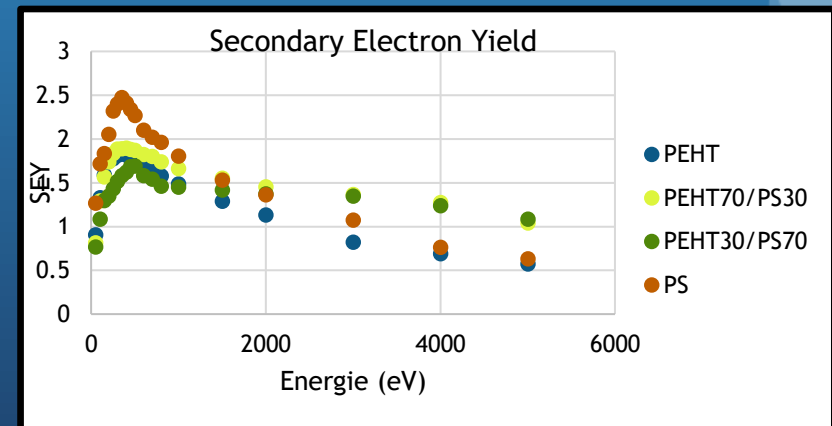
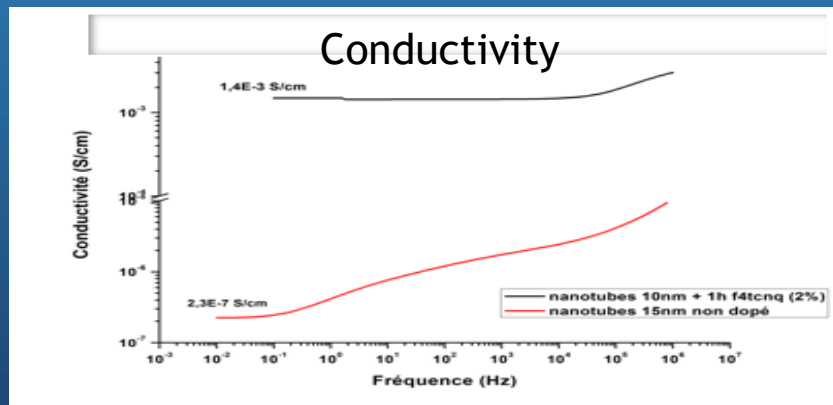
NCP-AAO



TEM



Coating



We are developing a new coating using ALD techniques to reach higher SEY

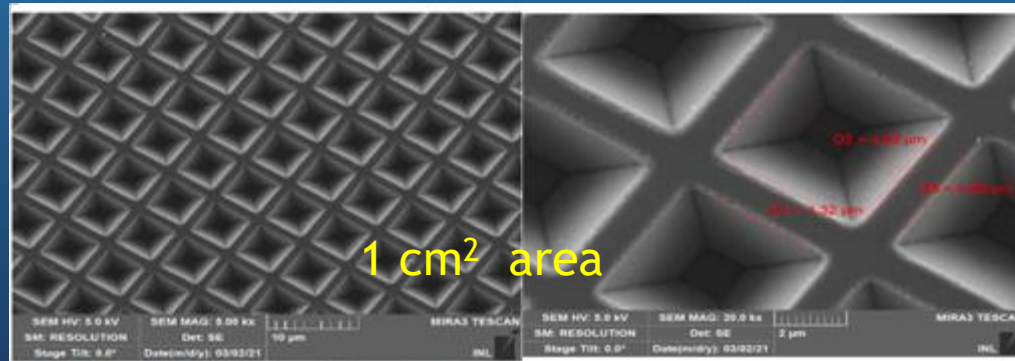
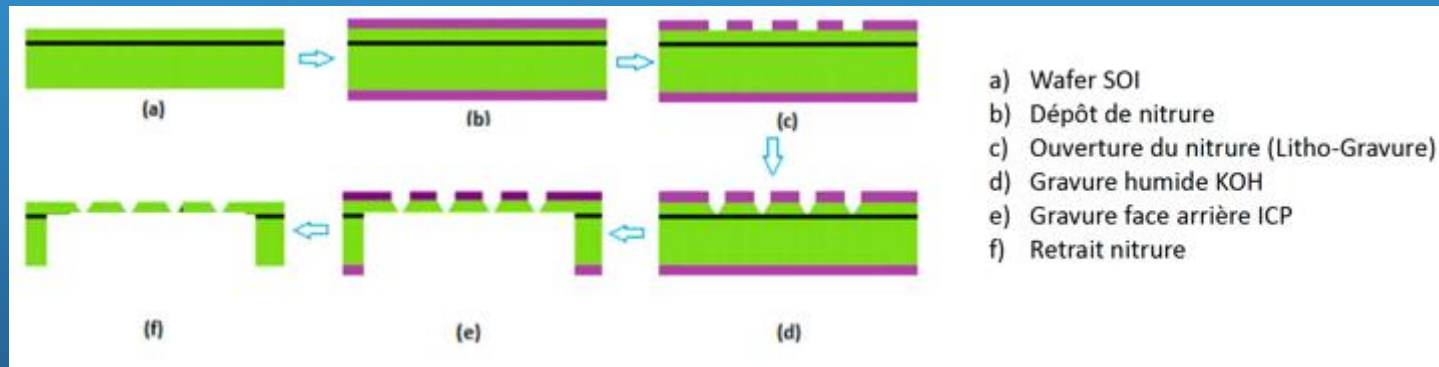
PICMIC for photodetection

We are developing a **highly granular reflective photocathode**.

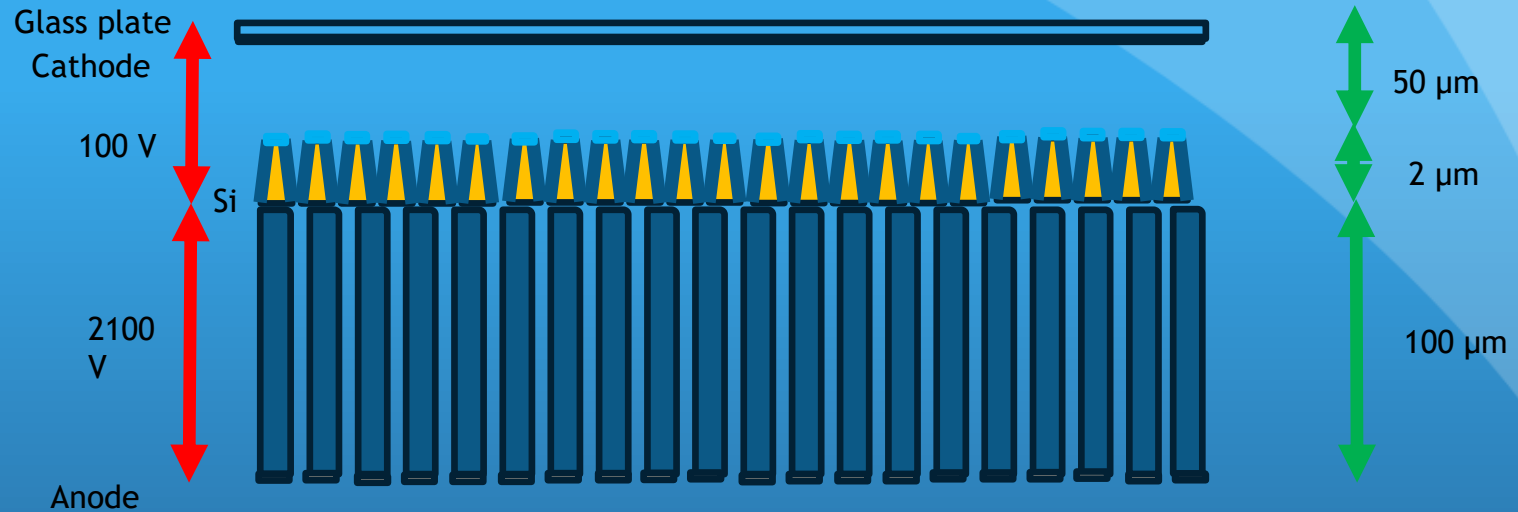
Photocathode is made of holes with conic shape.

- Exploit the high spatial resolution the MCP offers
- Increase the quantum efficiency

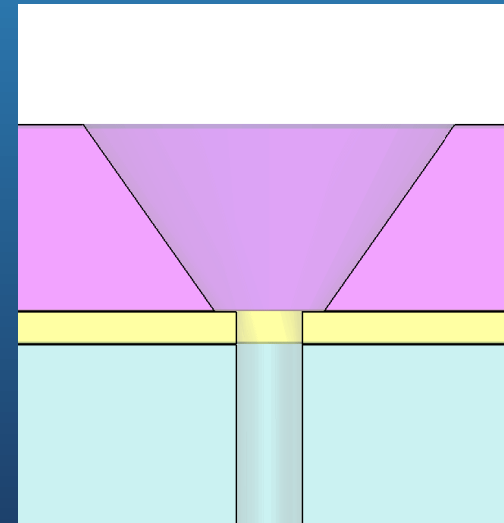
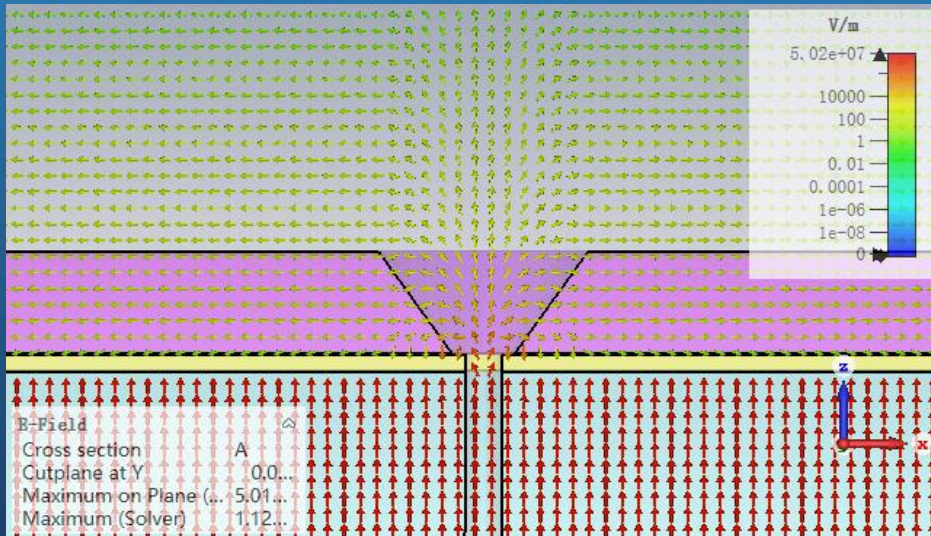
The structure is produced on a silicon wafer will be coated with different kinds of photocathode materials (DLC, B_4C) and then cast on MCP to test PICMIC as a photodetector concept.



PICMIC for photodetection



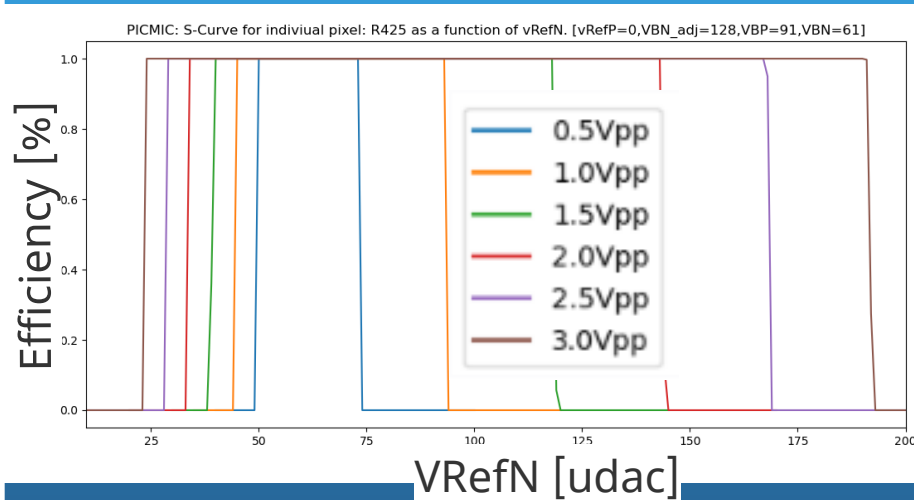
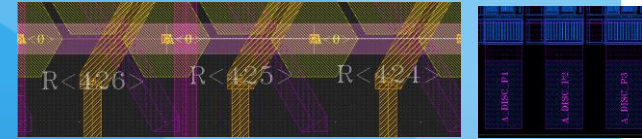
Simulation with CST



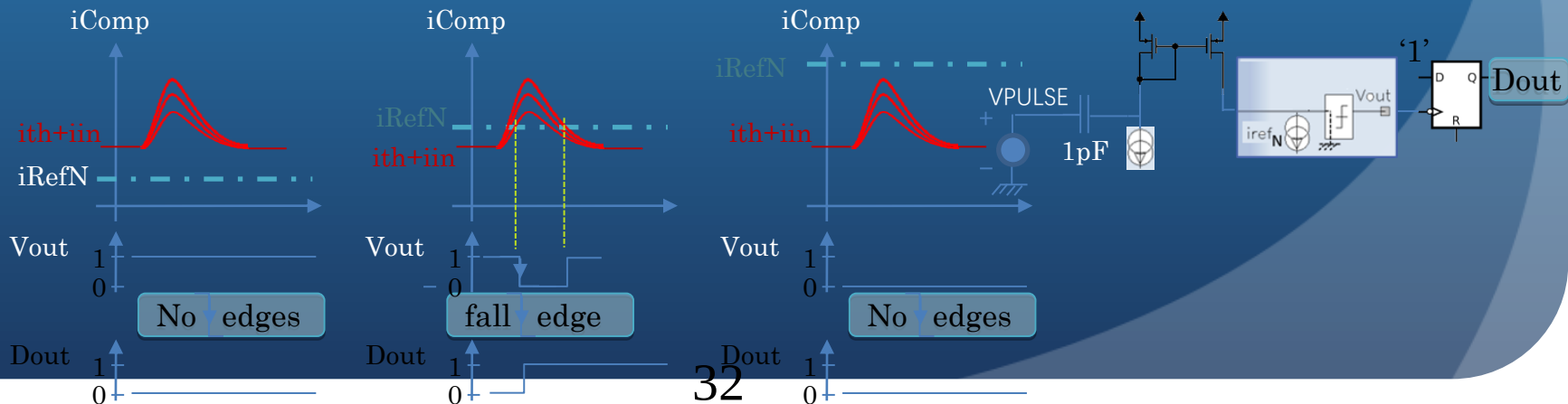
Injections Studies

PICMIC allows external signal injection through the (PAD):

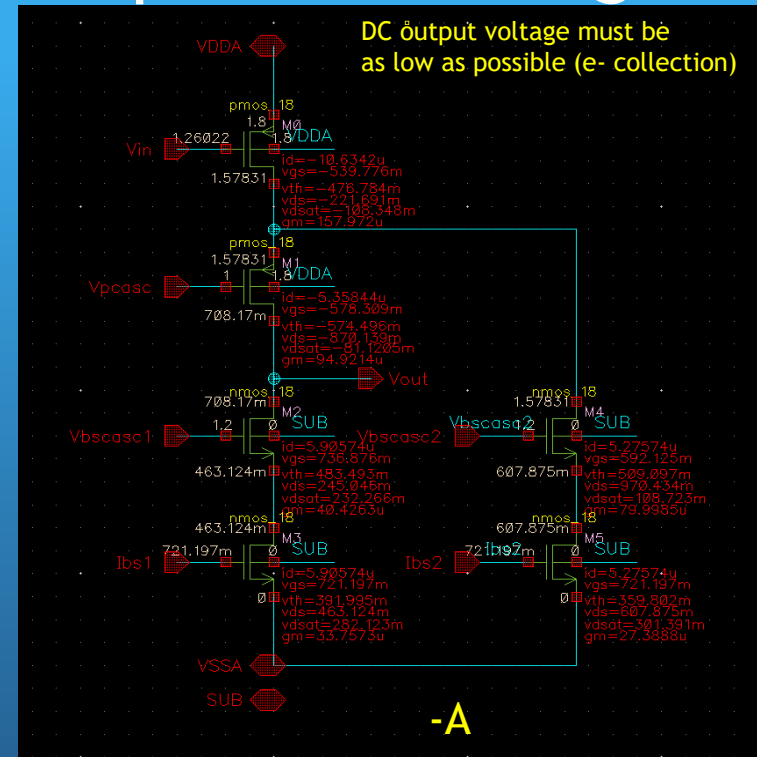
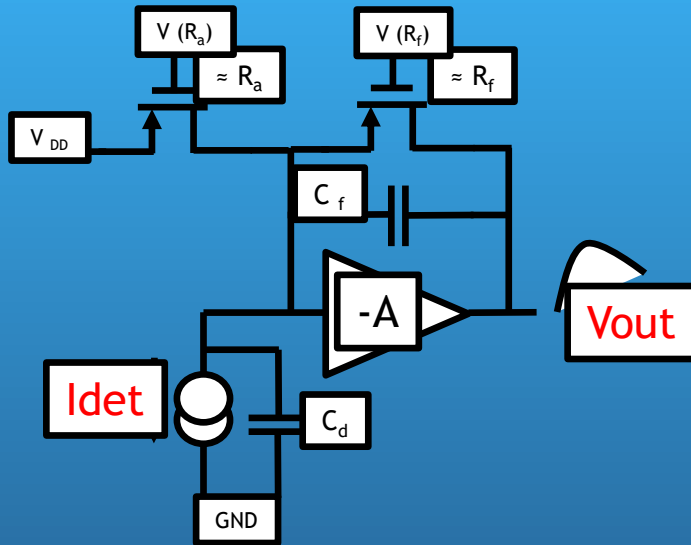
- **R424**[R68,C28], **R425**[R103,C35] and **R426**[R6,C15].
- * it also allows to excite whole columns in the channel matrix (no shown in above layouts).



- Voltage injection through external 1pF, then scan of the threshold of Current Comparator.
- Below the current threshold, the falling edge sensitive does not trig.
- The signal is recorded on falling edge, so above a certain value of iRefN added to threshold current, the comparator does not trig anymore → chapeau!



CSA Architecture from previous design



- R_a and R_f are made of 2 PMOS transistor polarized in triode region
- $V(R_a)$ and $V(R_f)$ could be use to modify the DC output voltage (e^- or h^+ collection)

$$V_{DC_Out} = V_{DC_In} \left(1 + \frac{R_f}{R_a} \right) - \frac{R_f}{R_a} V_{DD}$$

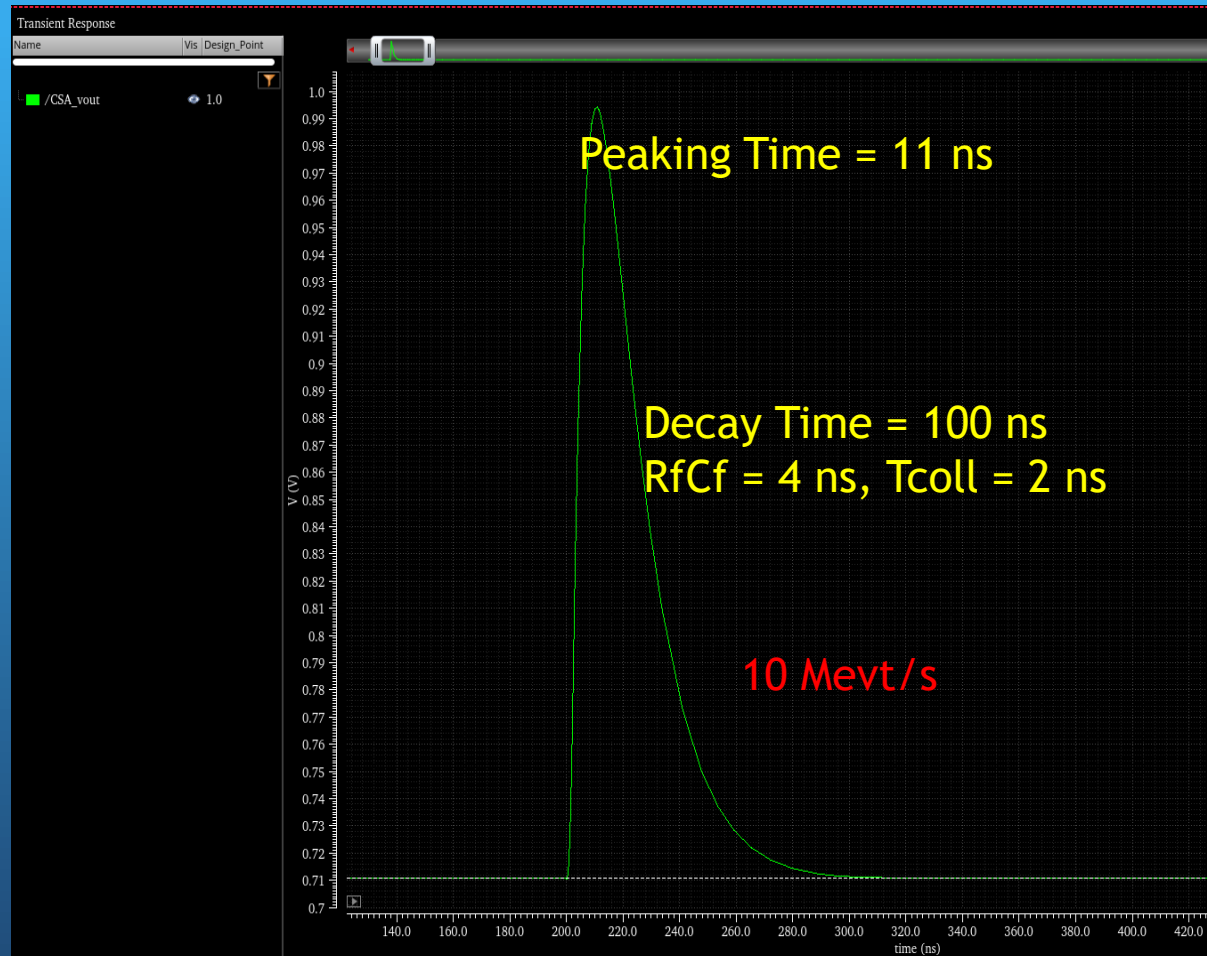
Input signal characteristics

Estimated from Picmic_0

- Input current : 2 μA to 20 μA
- Charge collection time : (1 ns)
- Input charge : ($10^5 e^-$ to $10^6 e^-$) (16 fC to 160 fC)
- Simulation with (8 fC to 80 fC) (factor 2)
- Counting rate : 10 Mevt/s minimum value)
- Detector capacitance
 - $C_d = (7,66 \text{ fF}/50 \mu\text{m}) * 15 \text{ mm} = 2,2 \text{ pF}$ (CSA simulations with 5 pF) ($C_{d\text{-max}} = 5 \text{ pF}$)
 - $2 \text{ pF} < C_d < 5 \text{ pF}$, $C_{d\text{-sim}} = 3 \text{ pF}$
- $\text{ENC} < 0,4 \text{ fC}$ (2500 e^-)
- CSA output signal :
 - Rise time $\approx$ (10 ns)
 - Decay time $\approx$ (100 ns)
 - Output Voltage : qq 100 mV
- Feedback network :
 - $C_f \approx$ (20 fF)
 - $R_f \approx R_a$ (200 $k\Omega$) made with PMOS and could be modified to adjust DC level output

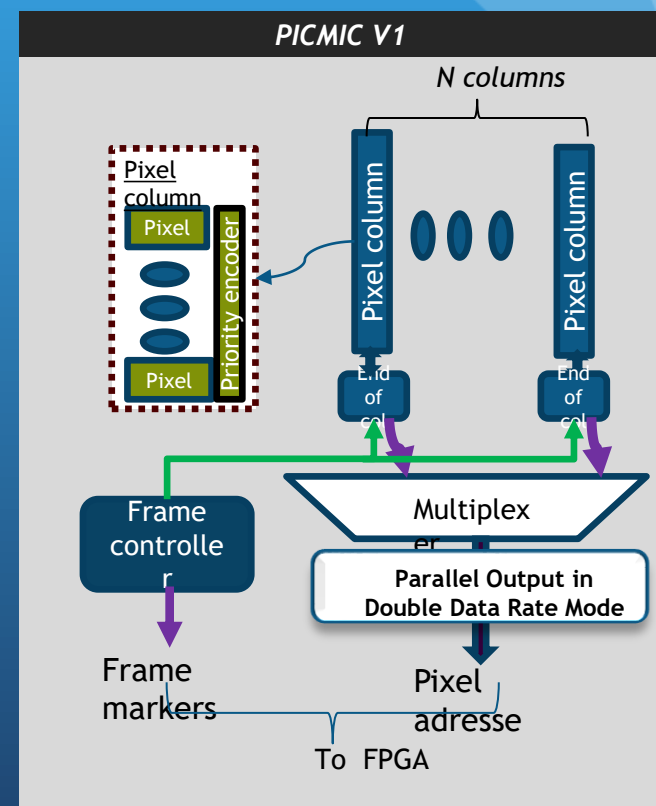
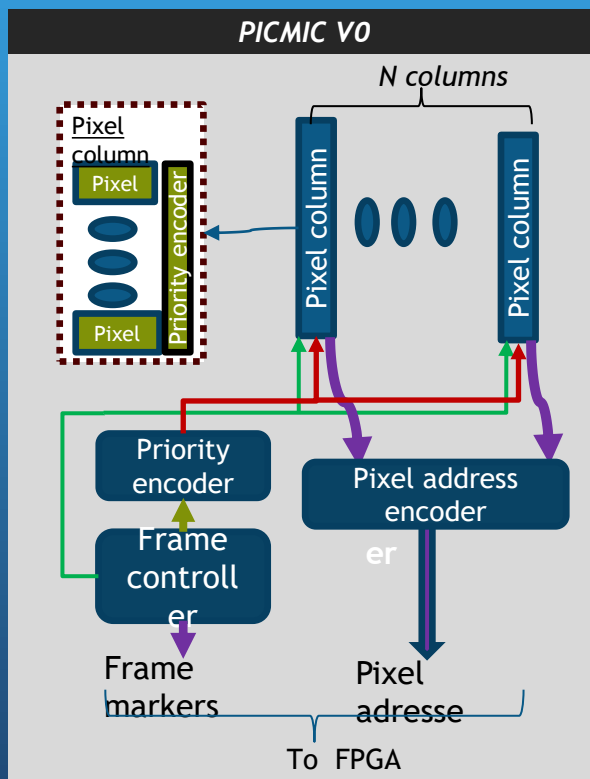
CSA Sim Results

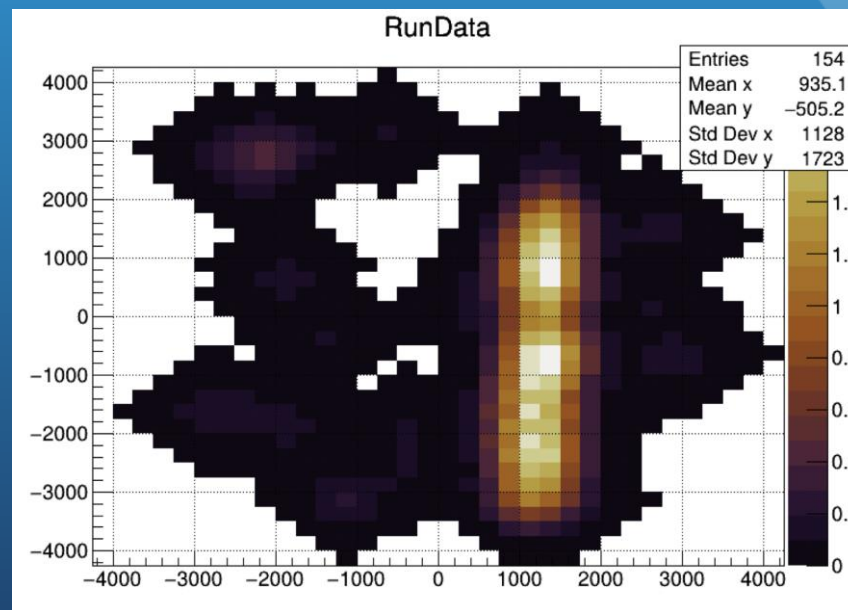
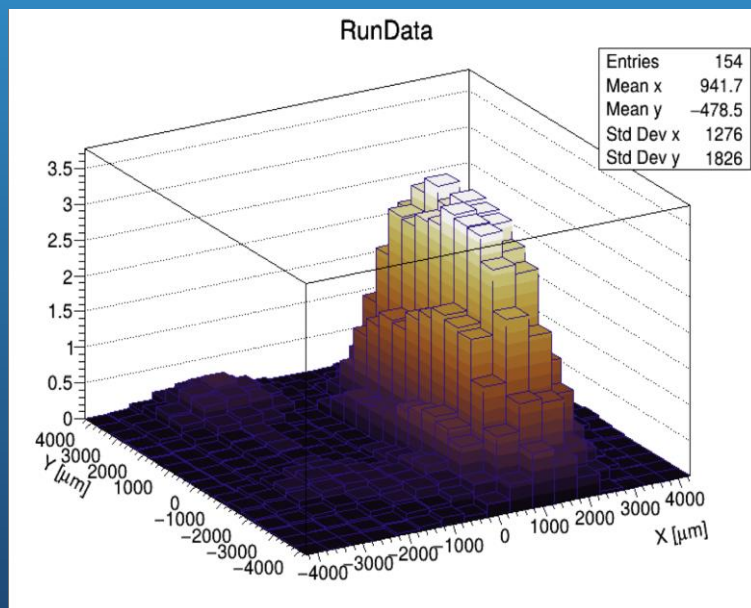
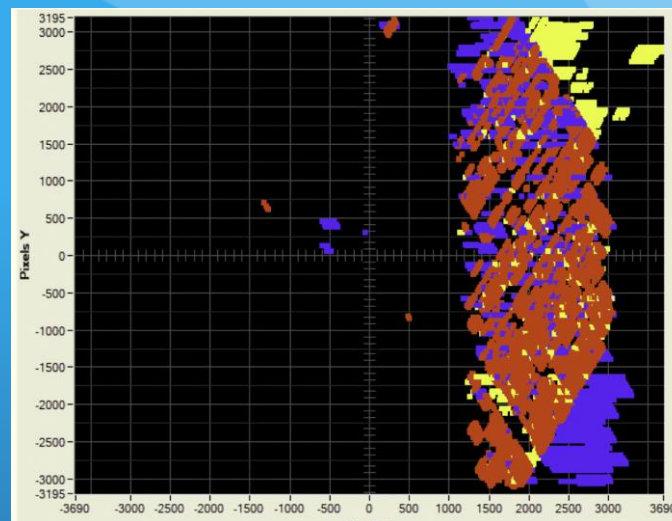
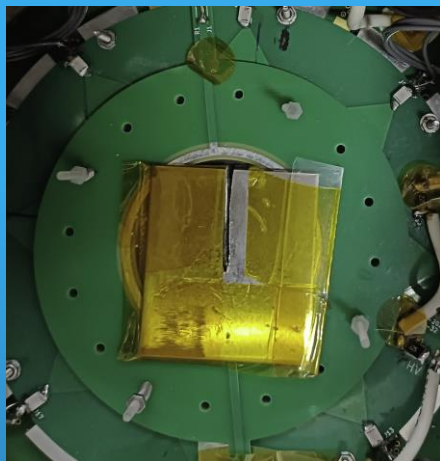
- Feedback network :
 - $C_f \approx 20 \text{ fF}$
 - R_f and $R_a = 200 \text{ k}\Omega$
 - $C_d = 3 \text{ pF}$
- $Q_{in} = 42 \text{ fC}$
- $V_{dc_Out} = 0,715 \text{ V}$
- $V_{dc_In} = 1,26 \text{ V}$
- CSA bias current (input Transistor) : $15 \text{ }\mu\text{A}$
- Output voltage = 310 mV
 ($42 \text{ fC} / 20 \text{ fF} = 2 \text{ V} !$) due to amplifier GBW



DAQ system : PICMIC V0 vs PICMIC V1

Both ASICs employ a *frame-based mechanism* to periodically transmit the addresses of stimuli pixels, but with different readout column modes. The stimulated pixels record information in their in-pixel logic and send it out in the next frame.



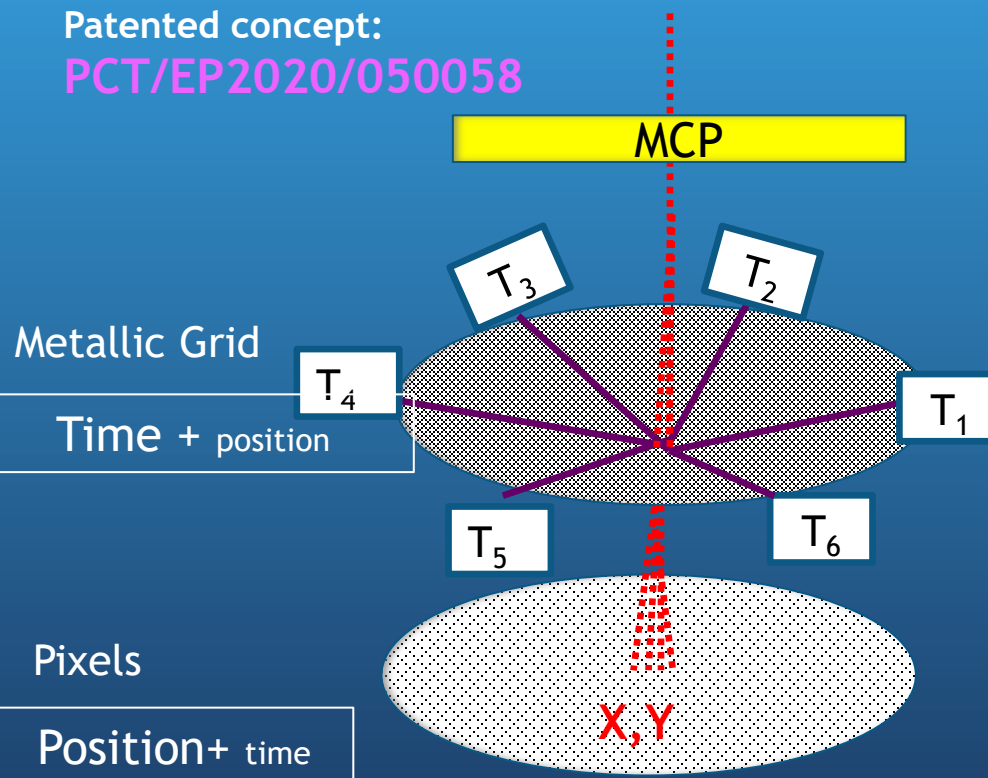


To fully exploit MCP we propose the following scheme:

- ❑ A **transparent grid** placed downstream the MCPs and read out by sensors with excellent **time resolution**. Followed by:
- ❑ A detection **matrix with micrometric pixels** to measure with great **precision the position** of the avalanche while **requiring limited number of electronics channels**.

Patented concept:

PCT/EP2020/050058



Concept description

- ❑ The avalanche crosses a transparent grid connected on its periphery to a few timing sensors
- ❑ The avalanche is then collected by pixels

1- Measure X,Y, from the fired woven strips by crossing them geometrically

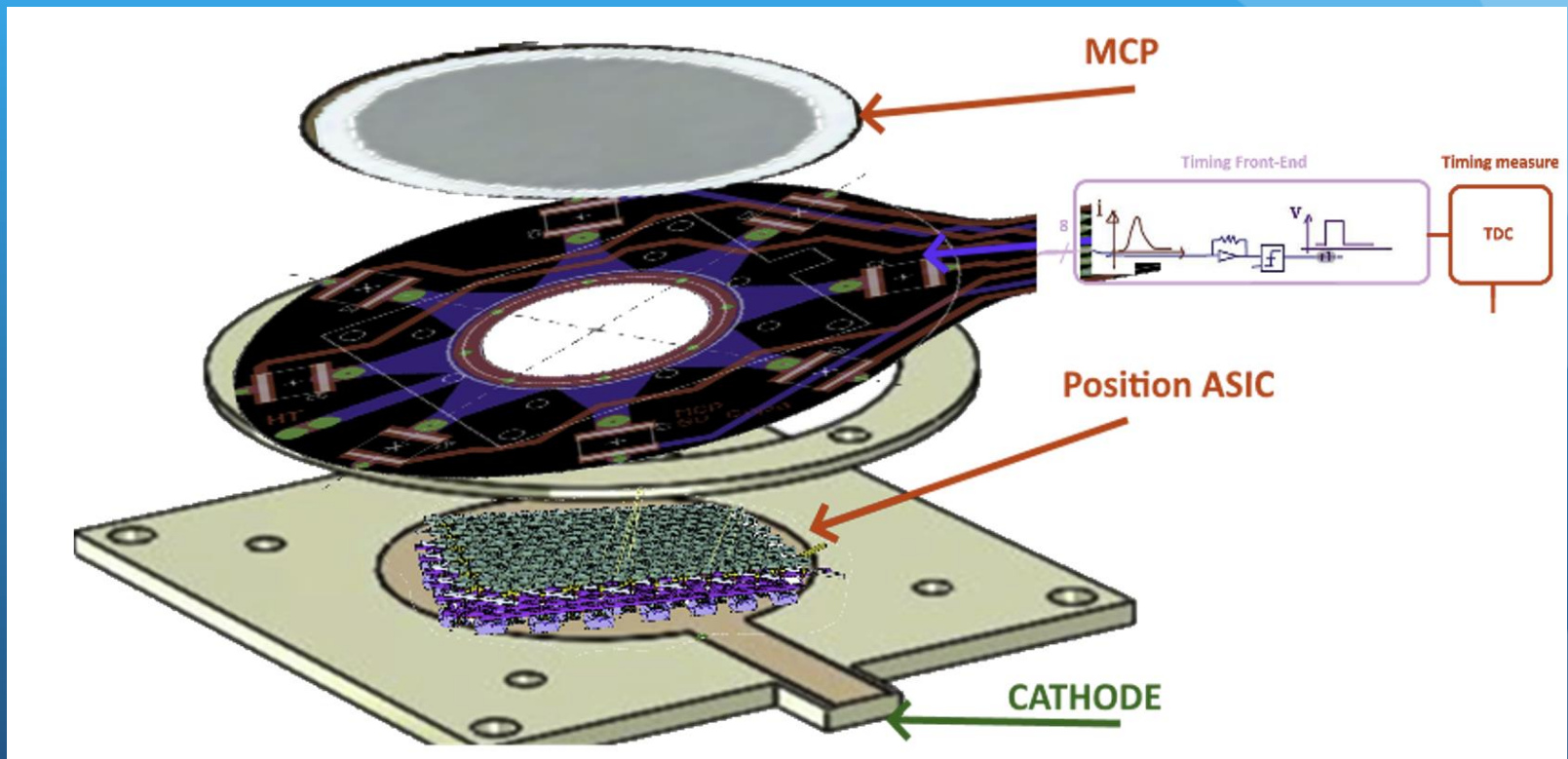
2- Measure T_i (from time sensors)

3-Subtract time propagation using speed propagation and X-Y)

4- average on the $(T_i - T_{i-propag})$

$$T_{abs} = \frac{\sum_0^N T_i - T_{i-propag}}{N}$$

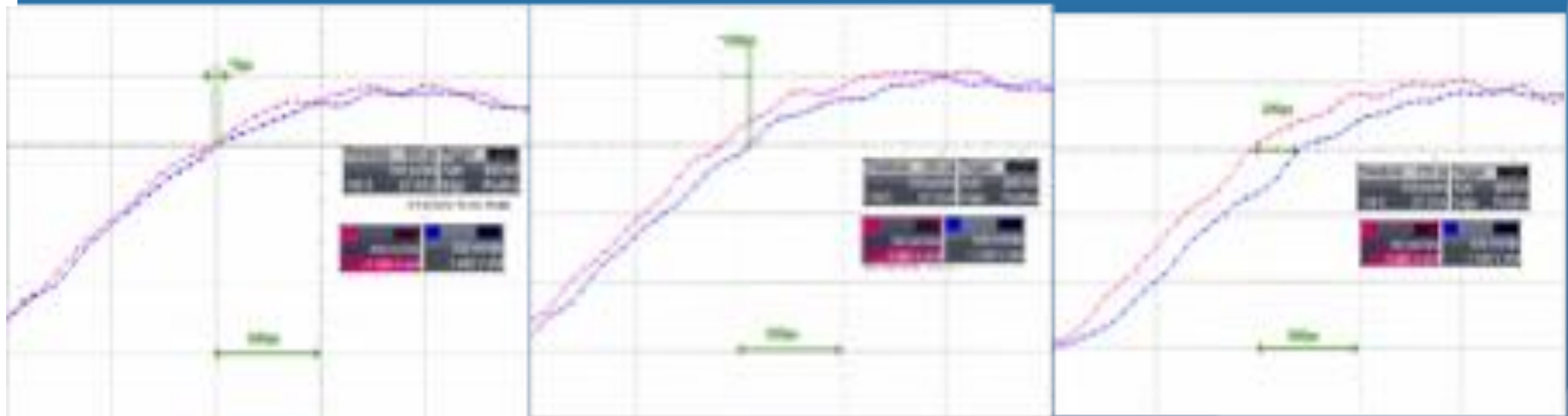
PICMIC: Proof of Concept



Metallic grid is replaced by the 100% transparent MCP grid (metallic anode)

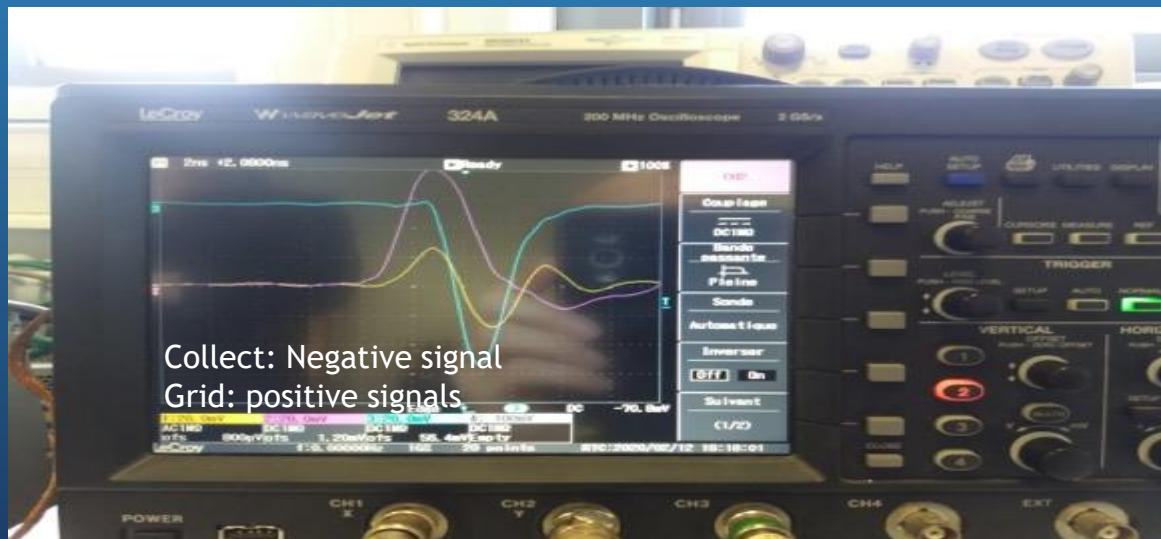
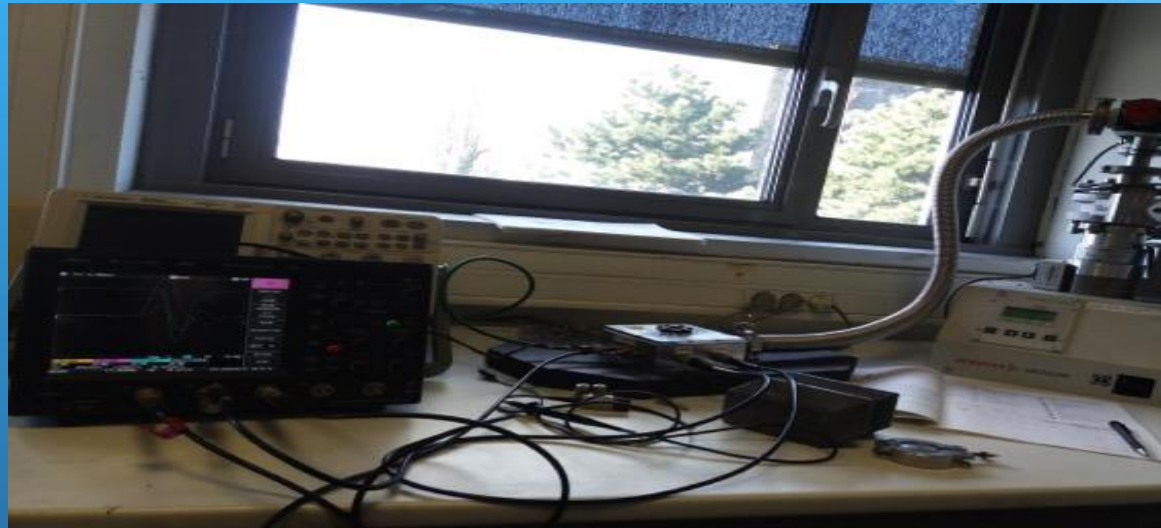
First step: Delay plane concept ?

40

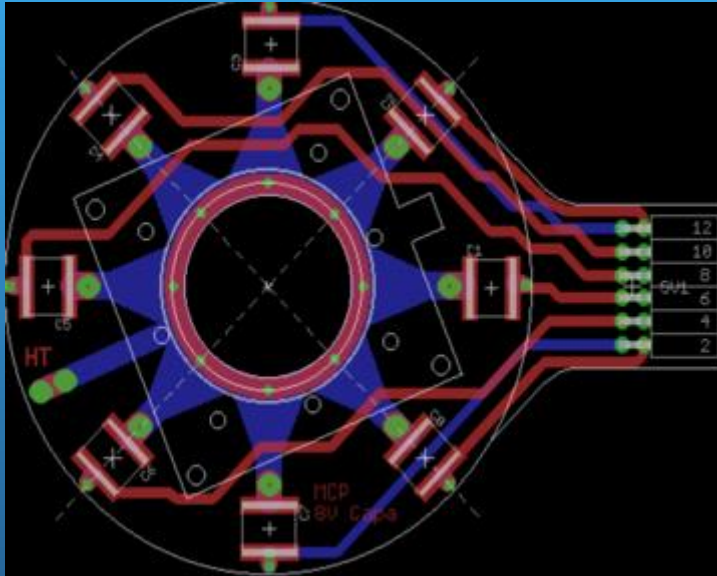


Second step :

Setup with timing sensors+1 large pad (collect) for the position



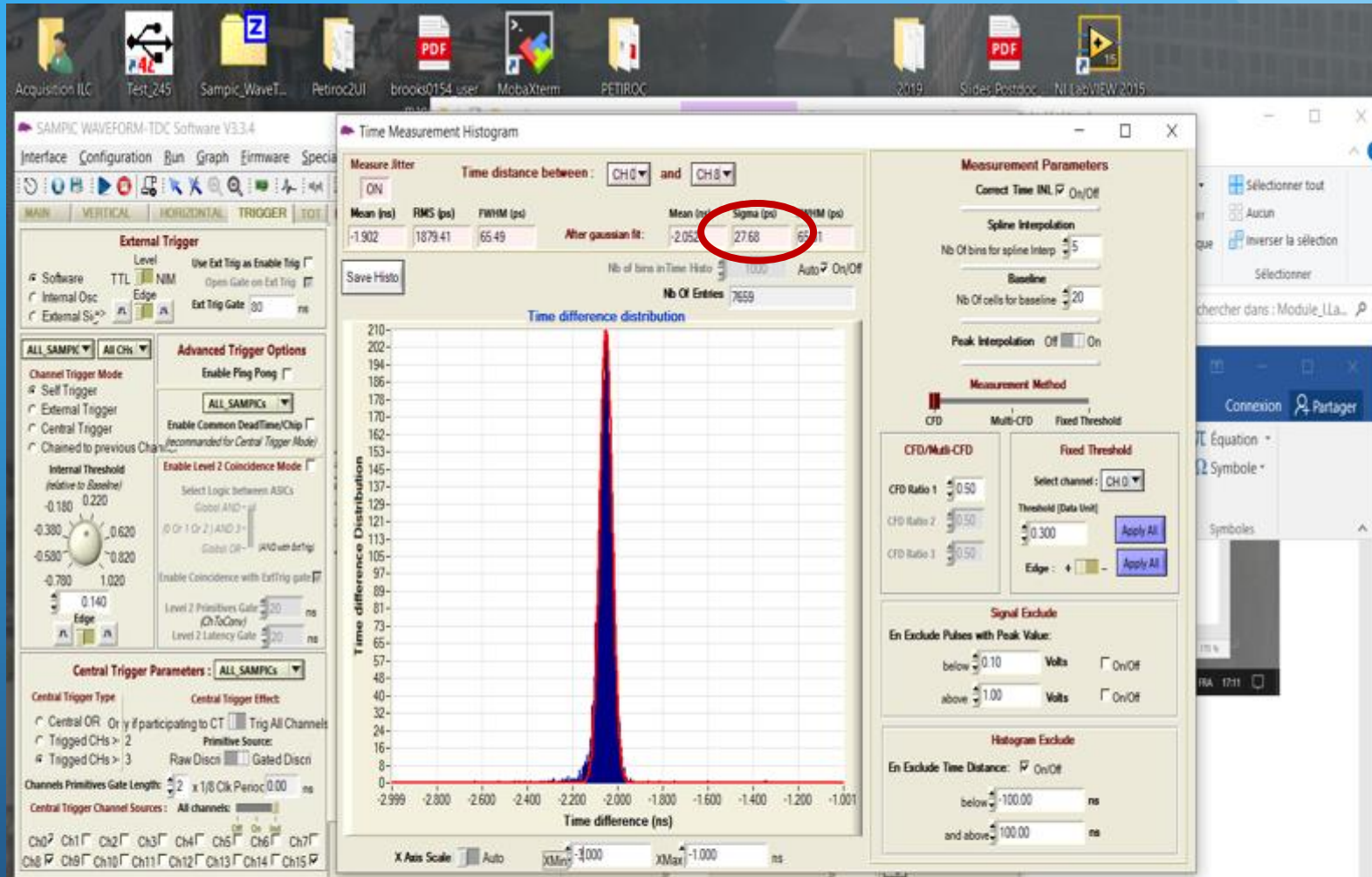
Time Measurement



8-point PCB for the time measurement.
PCB to be in contact with the grid



SAMPIC: TDC ASIC allowing to reach 3 ps time resolution

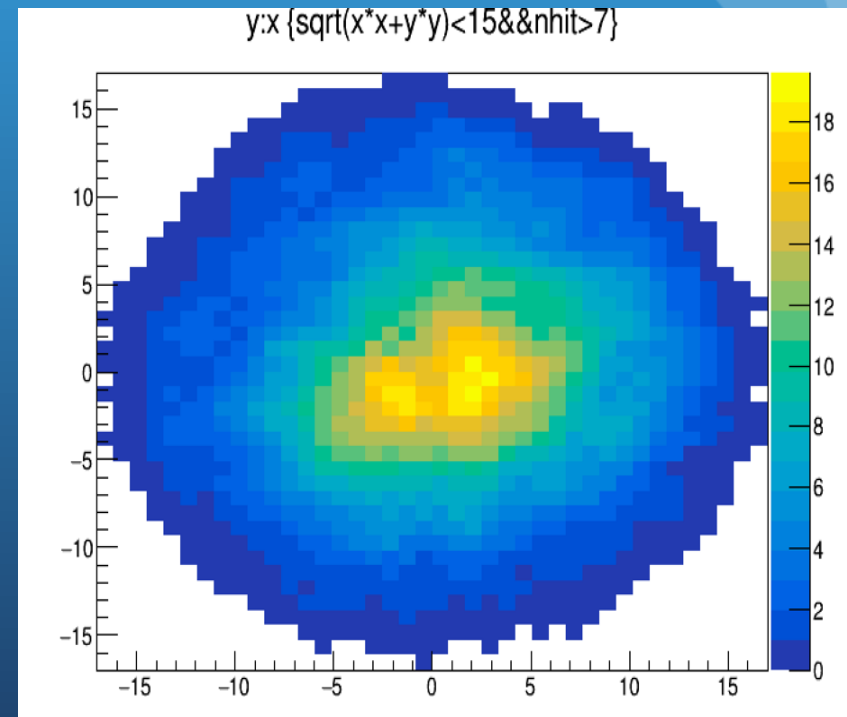
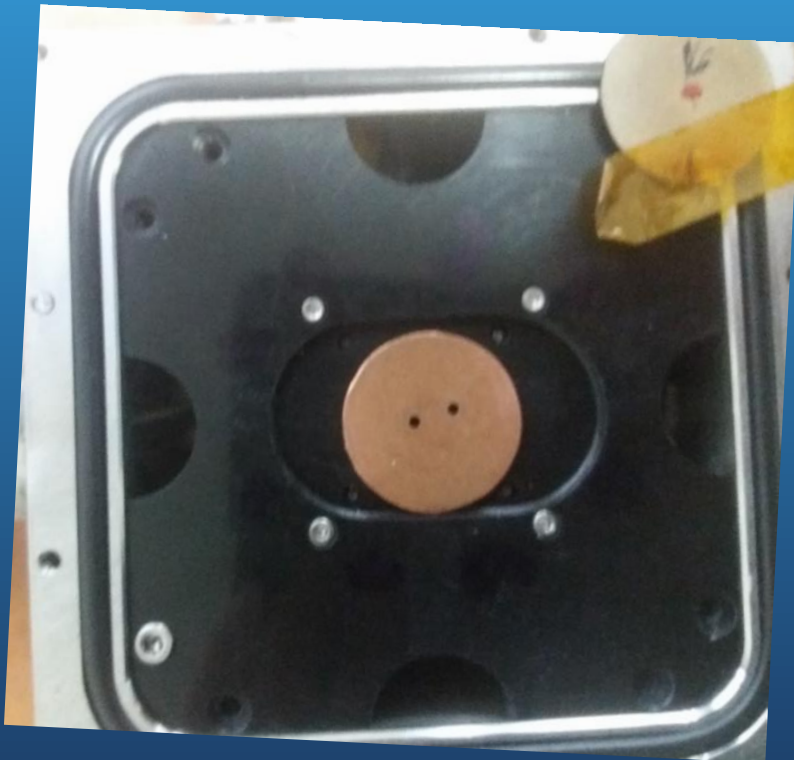


ΔT (ps)

Time difference between two channels

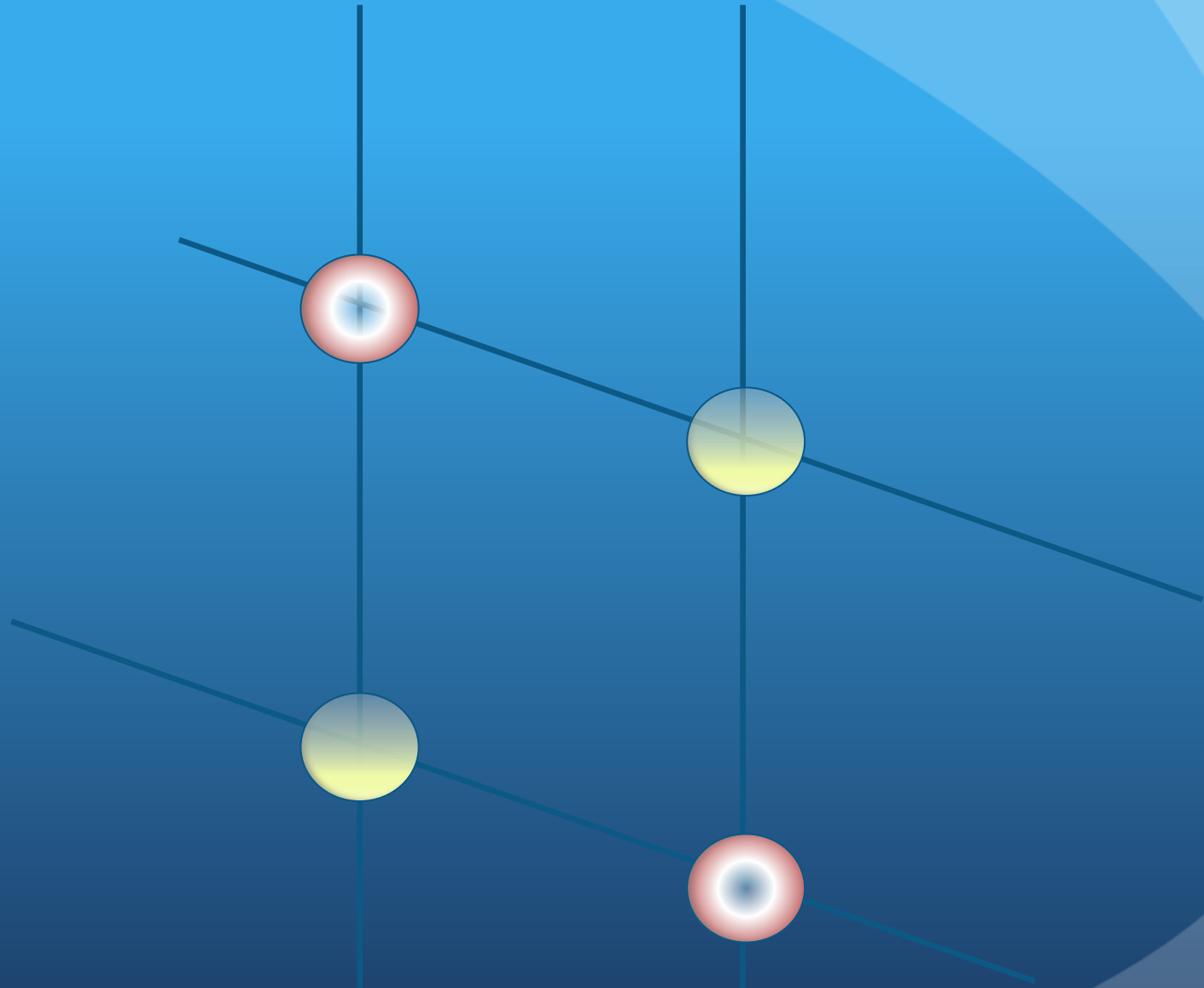
Time measurement → position measurement

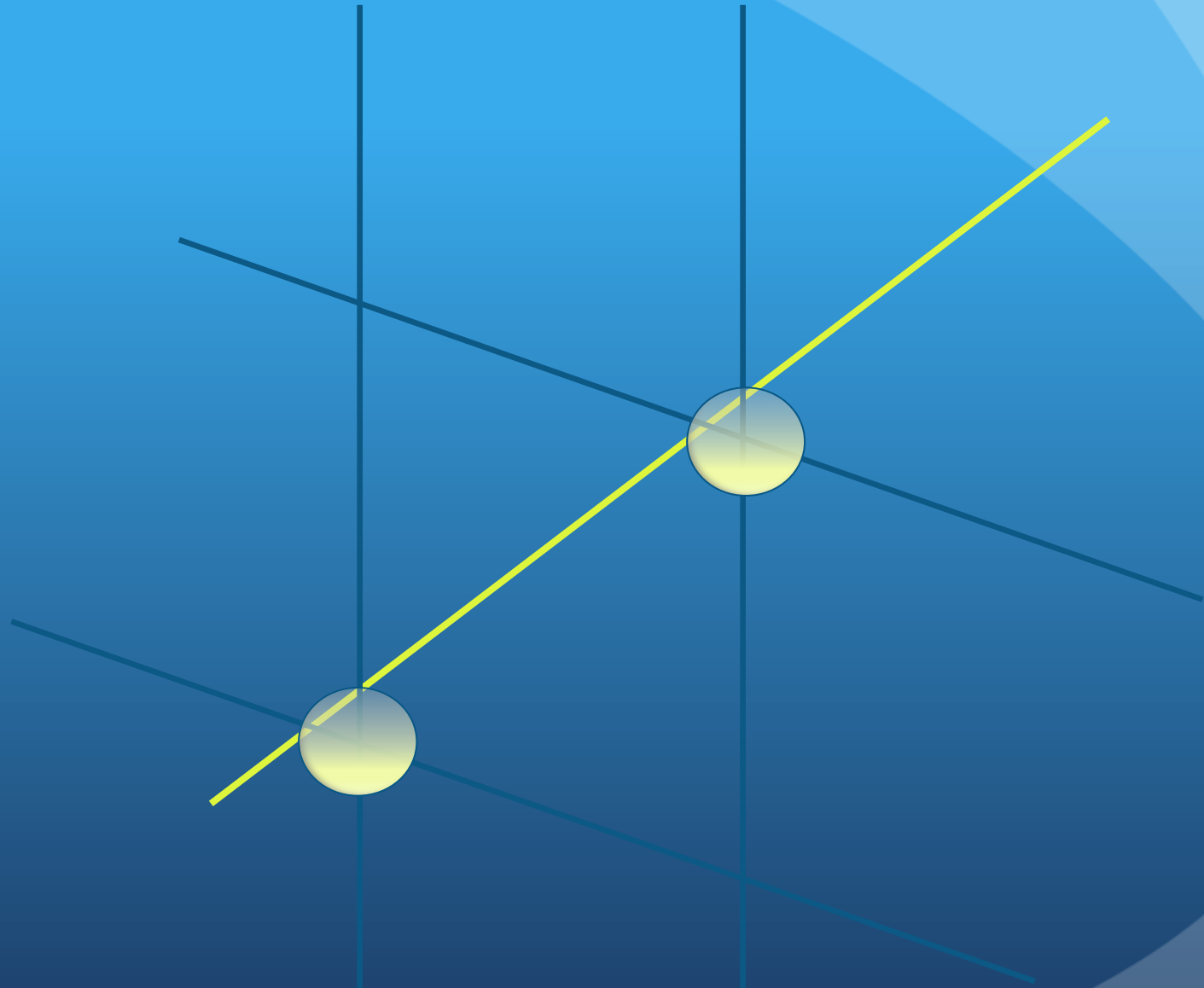
Waiting to have the pixel matrix to measure the position, two algorithms using the difference of time of arrival among the different channels were developed to obtain the position of the hitting particle.

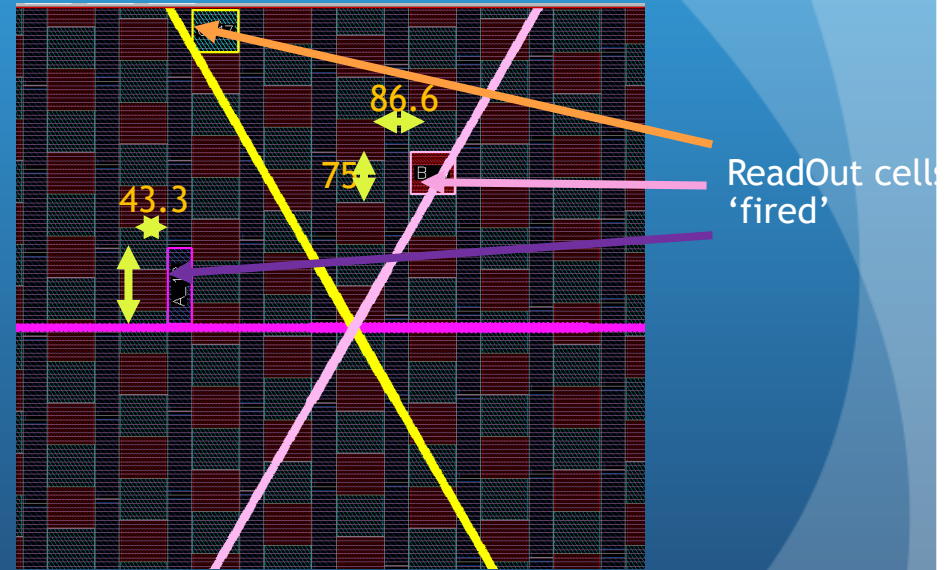


Where is it useful?

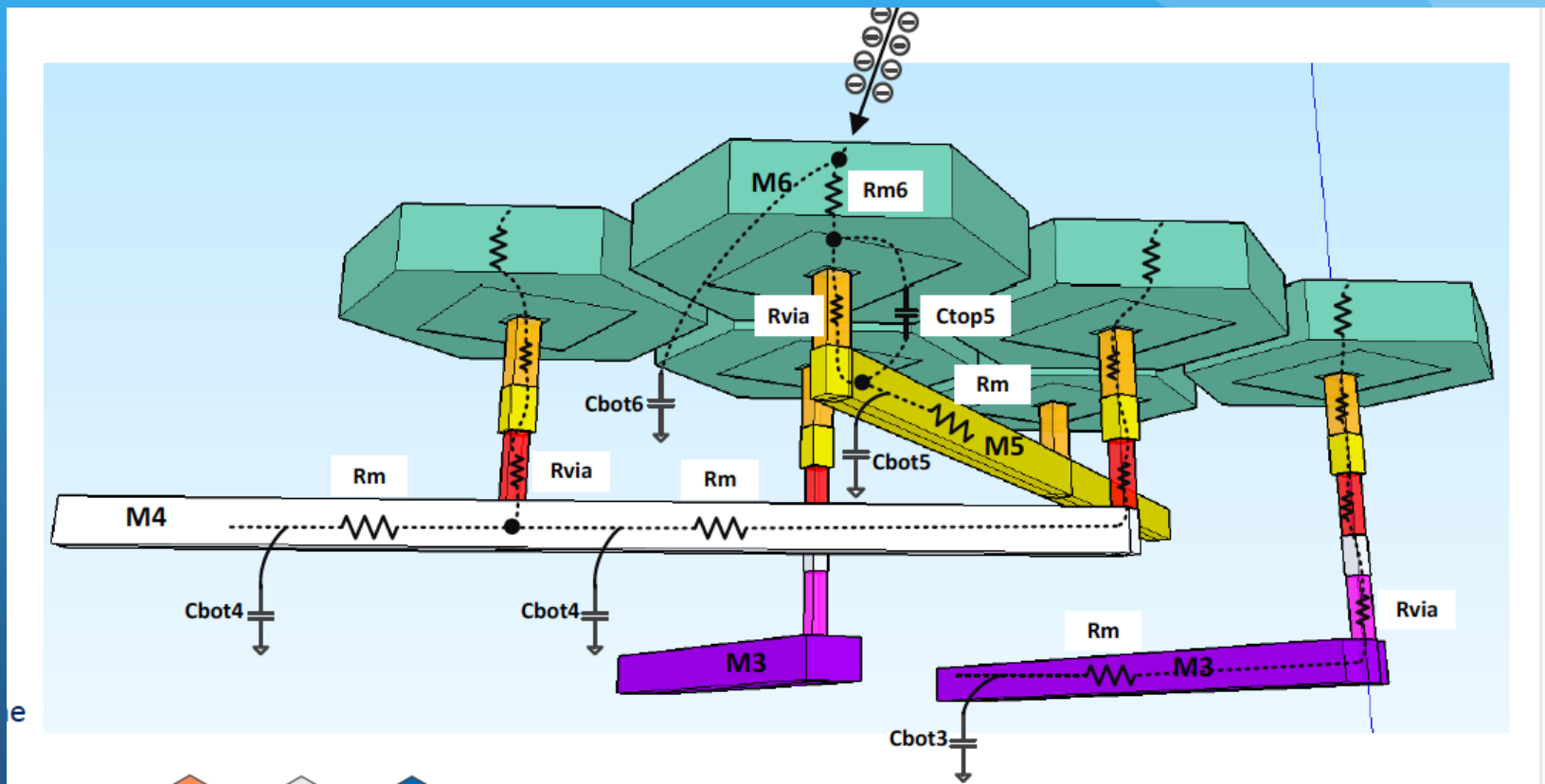
- High Energy Physics,
 - Cerenkov detectors, trackers, etc.. For FCChh /SPPC
- Nuclear Physics
 - Mass Spectrometry (ToF)
- Accelerator
 - Beam monitoring, Streak Camera
- Free Electron laser
 - Analysis of the structures of materials, in particular biological objects (XFEL, LCLS2, Shine)
- Spectrophotometry : FLIM fluorescence lifetime microscopy, Raman spectroscopy, Time-resolved near IR spectroscopy
- Medical equipment : PET Scan, CT-Scan, In-Vitro Assay, Gamma Cameras
- Biotechnology : Flow cytometry, confocal laser microscopy, DNA sequencers, Mass spectrometry
- Environmental measurement : Dust counters, LIDAR (ToF 3D imaging)



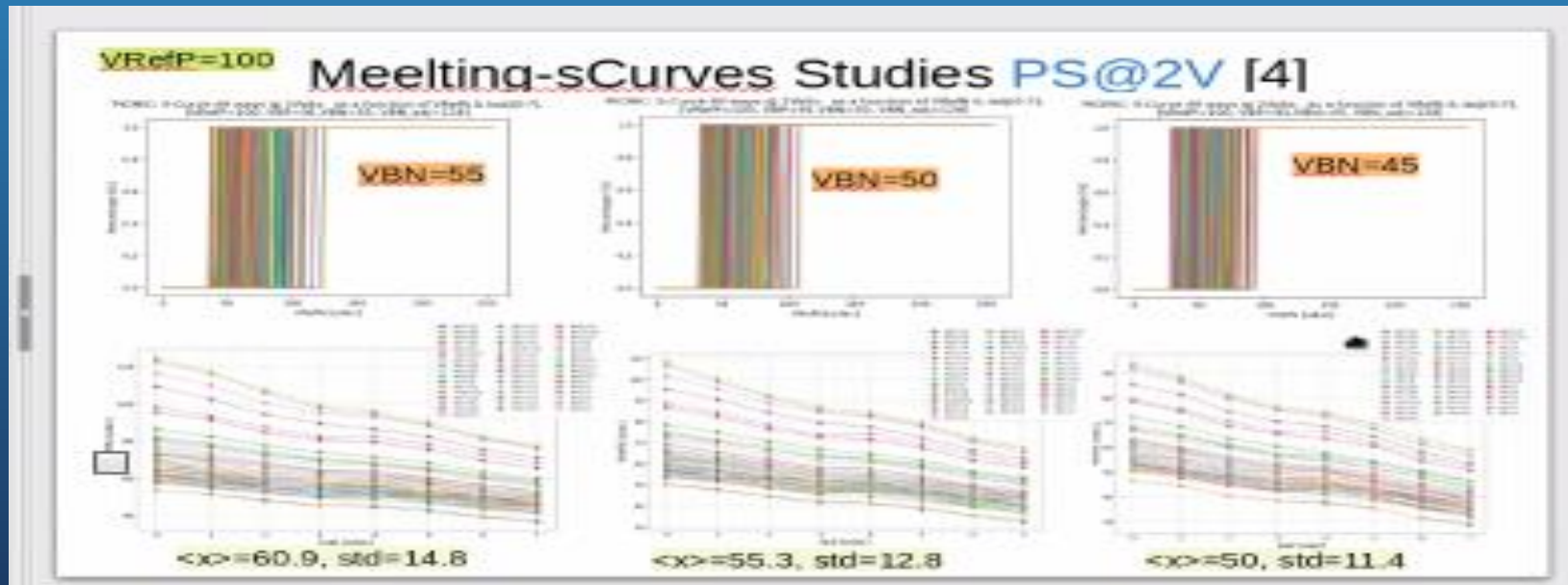




Cross-talk was carefully studied and showed less than 10%.

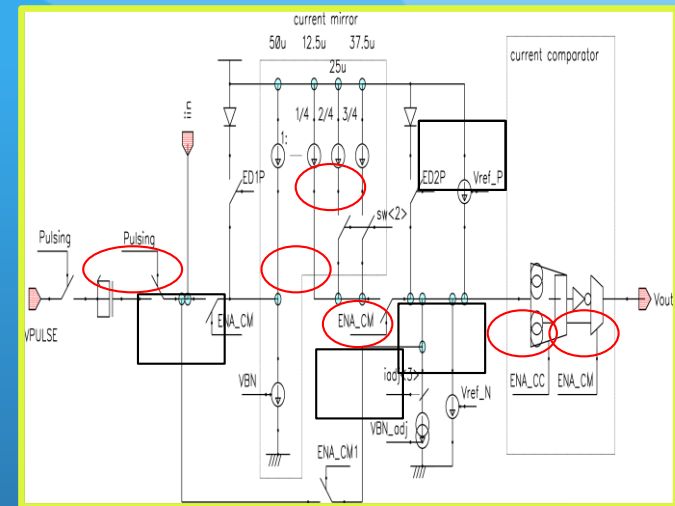


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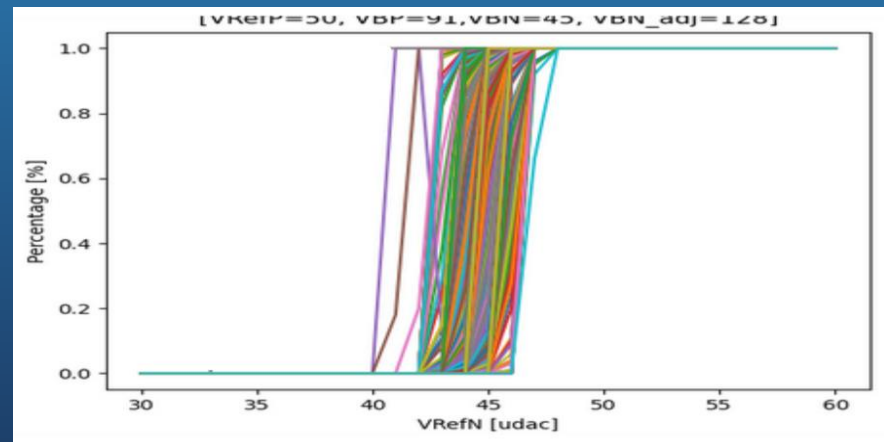
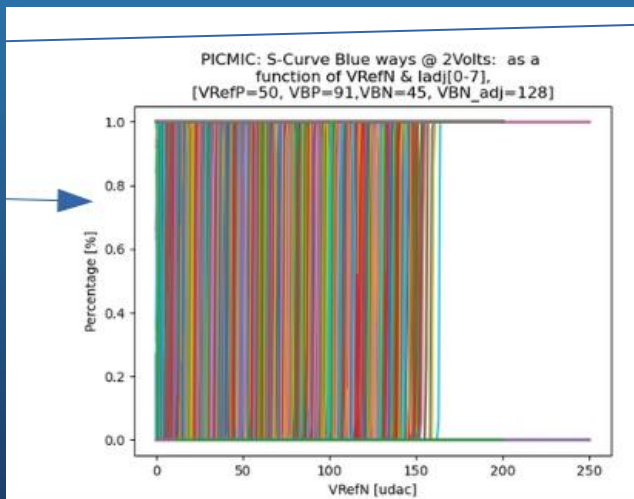


Pedestal threshold calibrations

- 1) Freeze a set of **DAC**(Global) values driven by :
 - small dispersion between s-Curves
 - bigger number of sCurves in a given space of phase vs VRefN(quite sensitive)
- 2) Then, additional scan in **local** values are performed:
 - iadj<3bits>, sw<2bits>, EN_CM, EN_CC.
- 3) To determine value @50% inflection point.
- 4) To select the closest sCurves@50% in VRefN

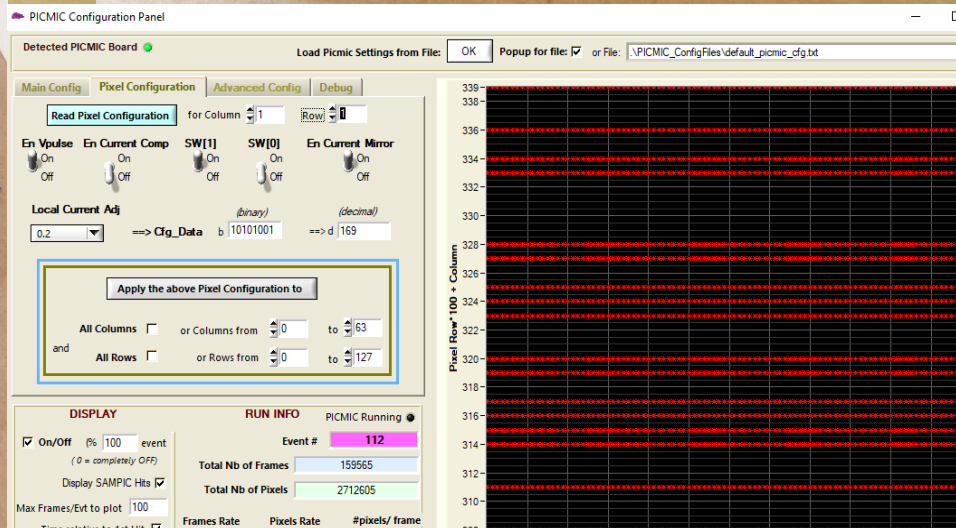
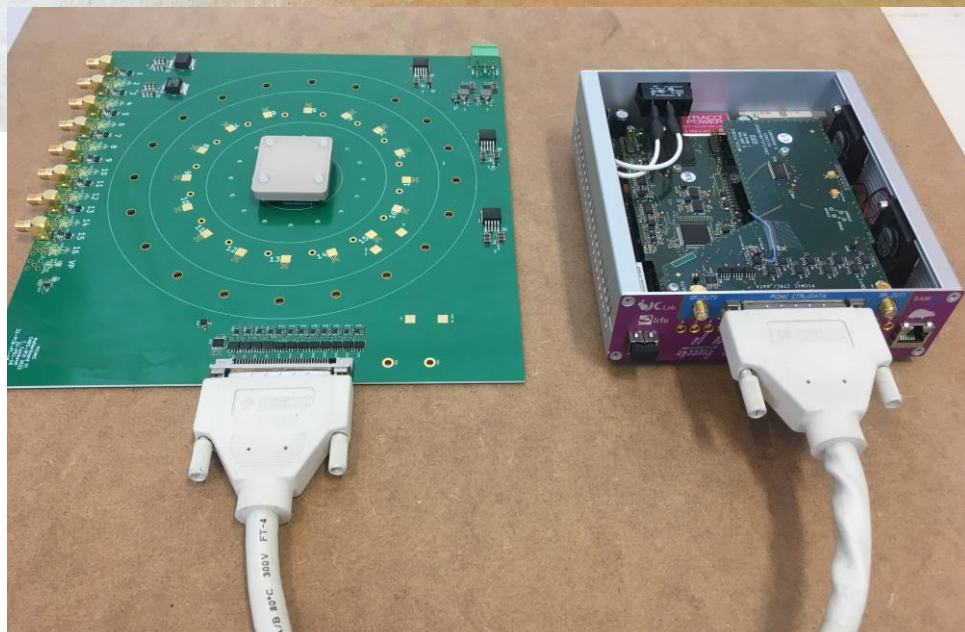


full matched sCurves(VRefN)



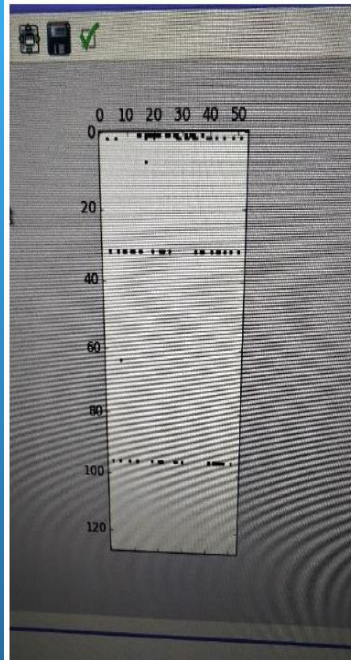
DAQ to read both time (SAMPIC) and PIXEL sensor

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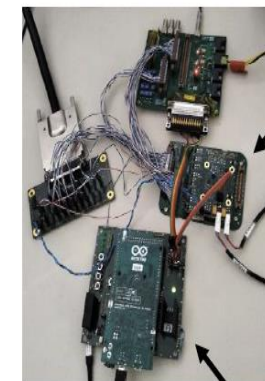
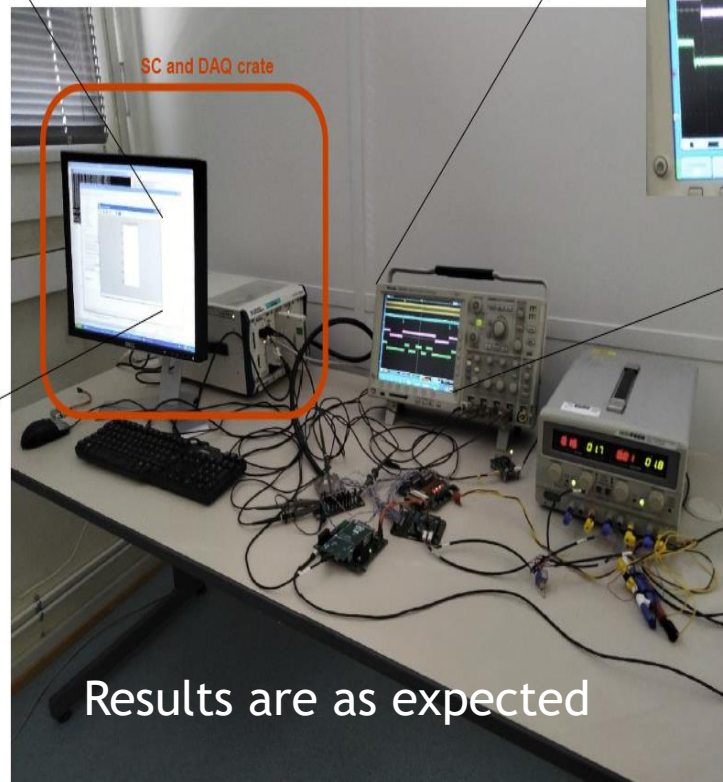
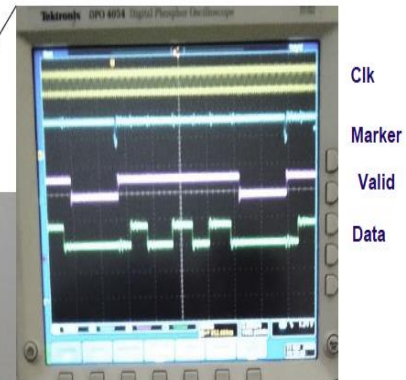
- 40 MHz clock is generated and distributed to the two devices (time, pixels)
- Data are collected by both sorted out with the same counter

Digital test bench



Pulsing pattern applied to pipcmic

Readout from pipcmic

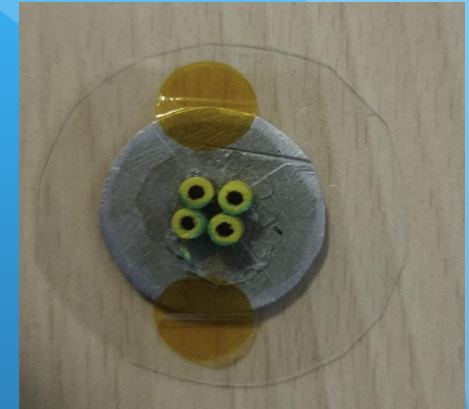


Slow control board

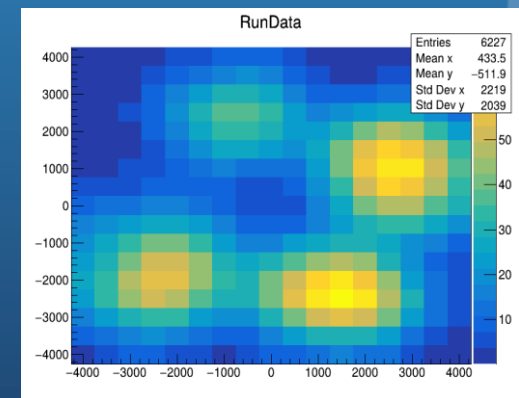
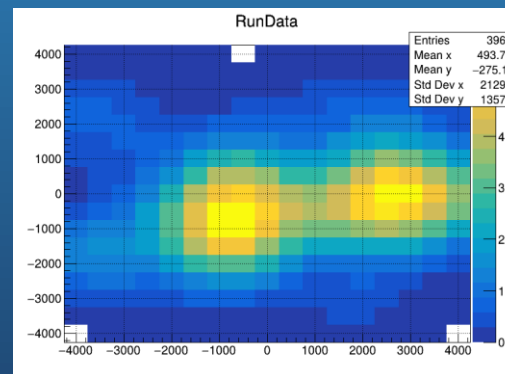
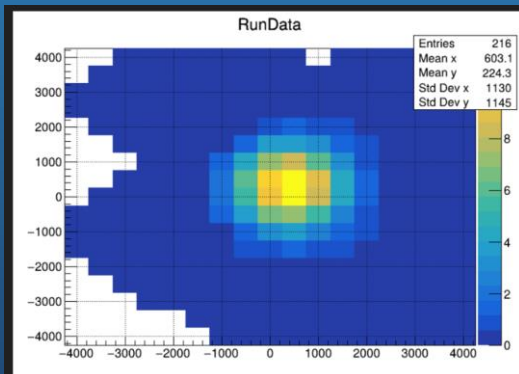
The whole system was tested by using alpha and gamma sources

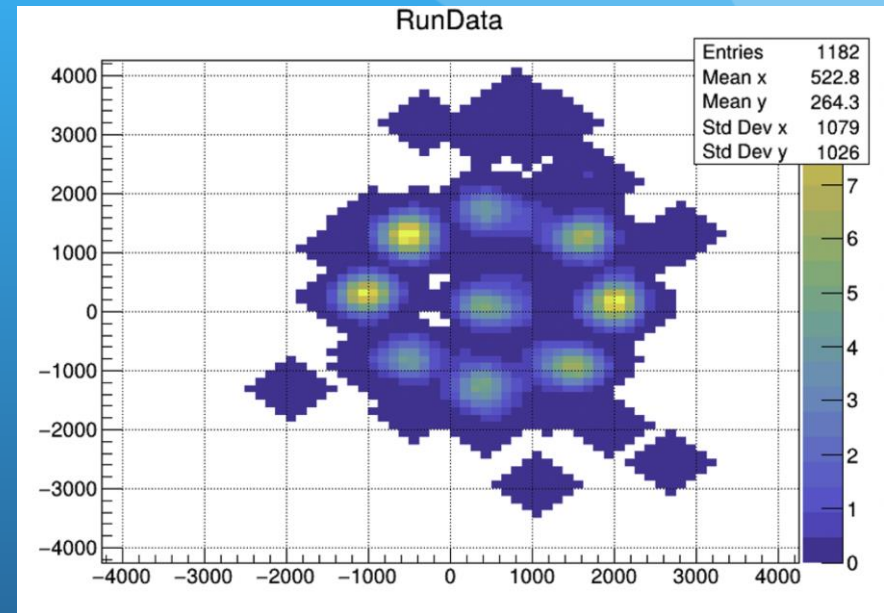


1 mm holes

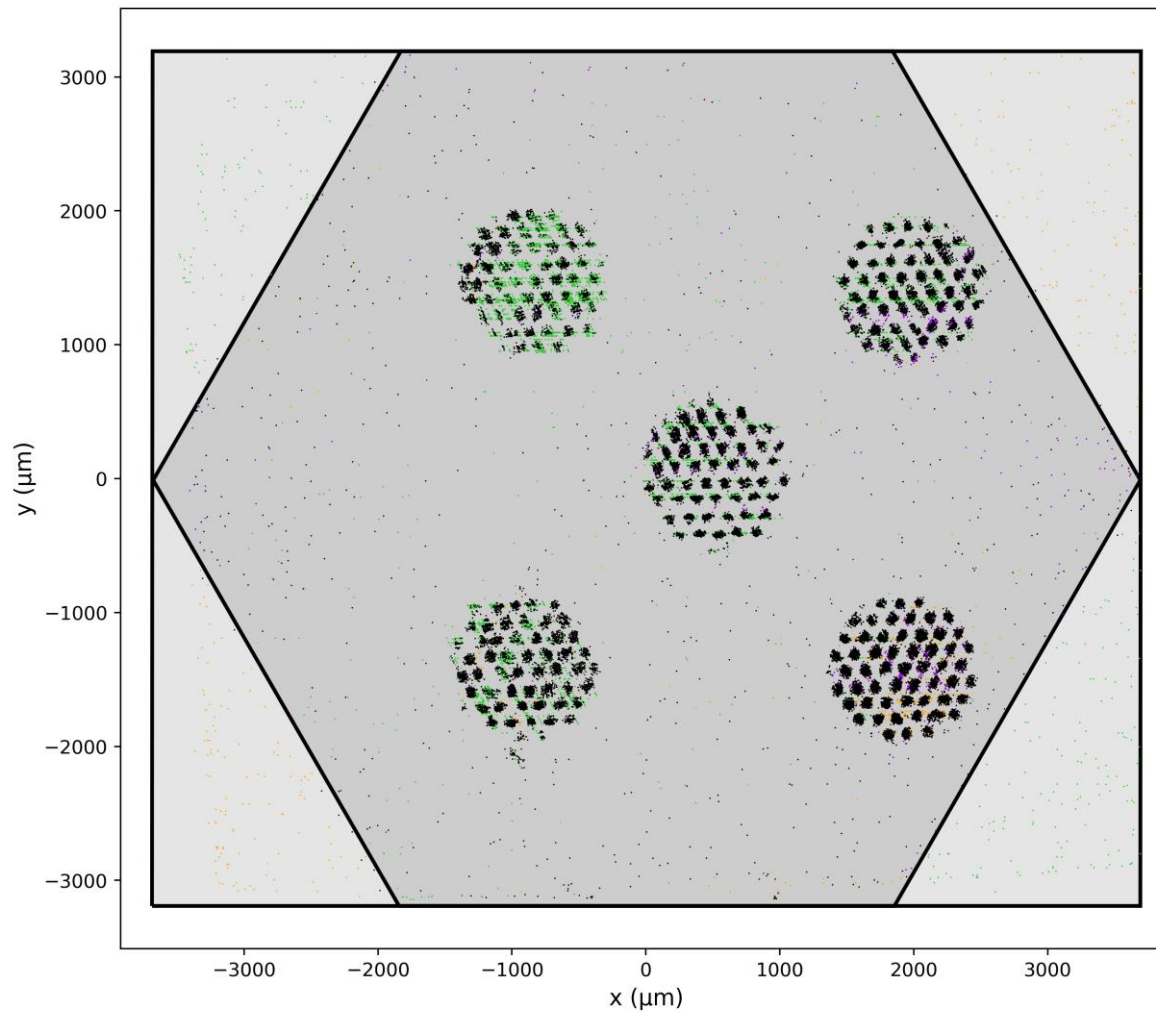


2 mm holes



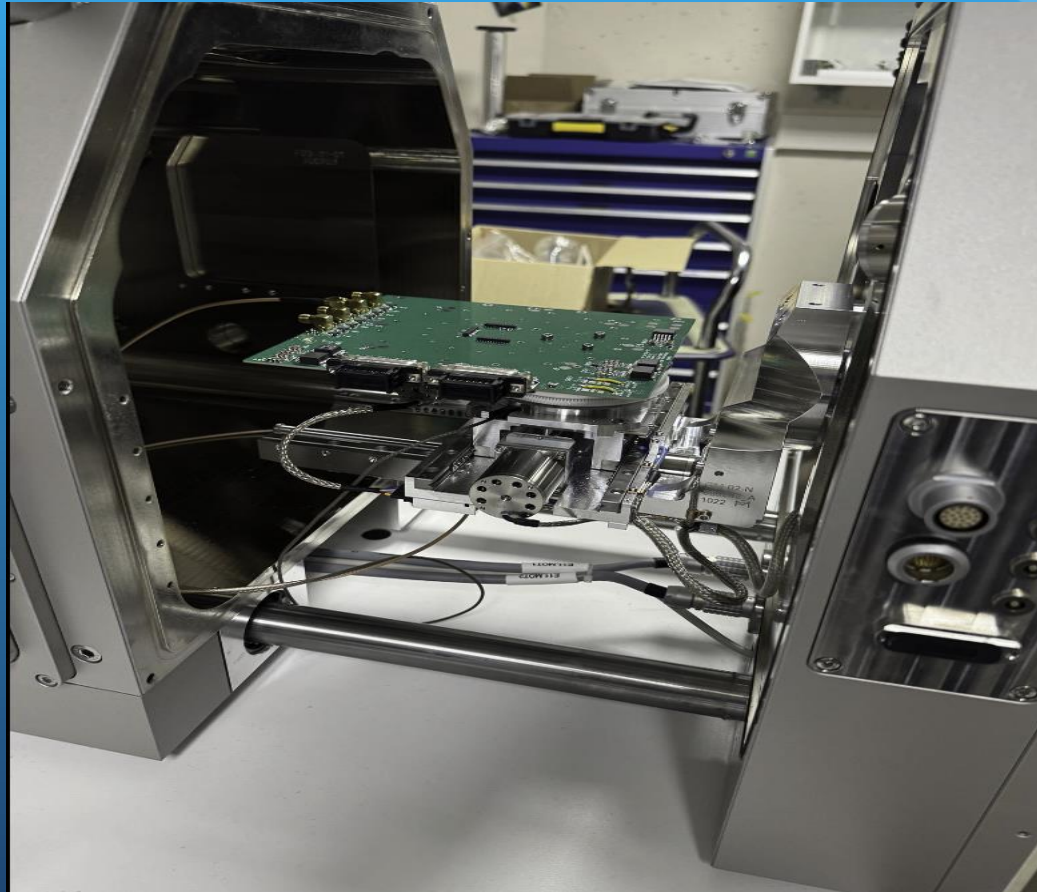


0.5 mm holes



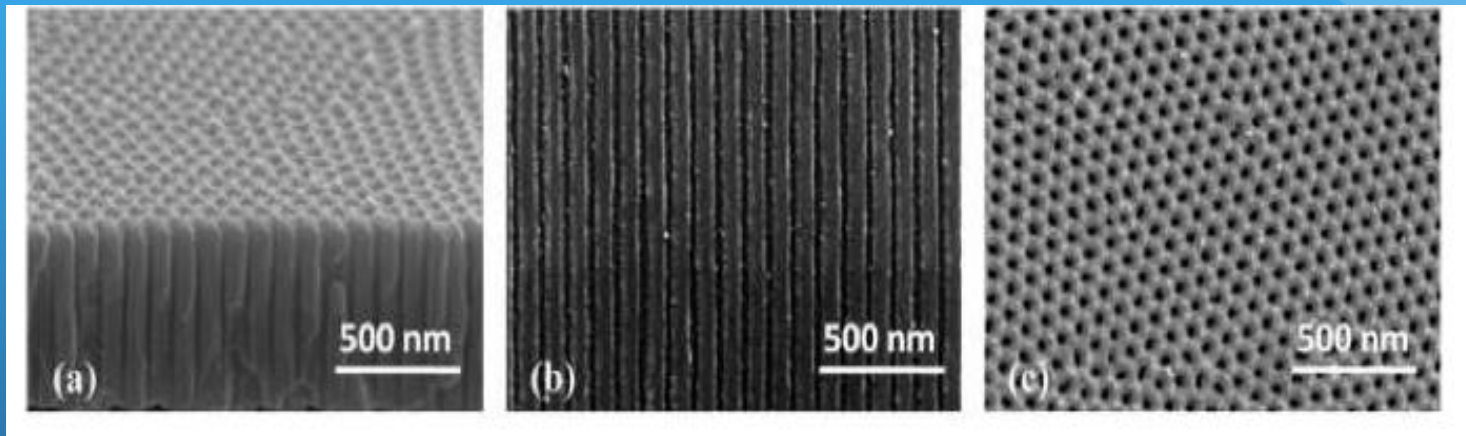
GEM foil+ cooper plate with 3holes of 1 mm diameter eachwith

PICMIC will be soon tested with a channeltron producing single electrons of energy up to 30 keV in a MEB to have independent time and resolution measurement



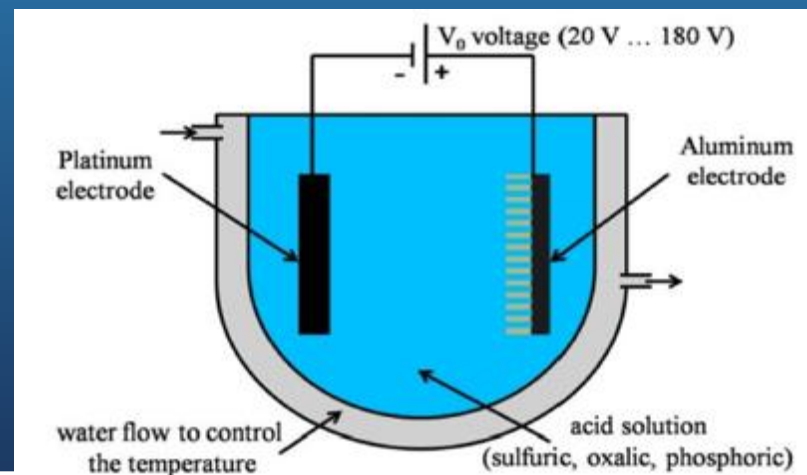
AAO NCP

Nano Channel alumina structure made by electrolyse was invented twenty years ago: H. Masuda, K. Fukuda, Science 268, 1466 (1995)



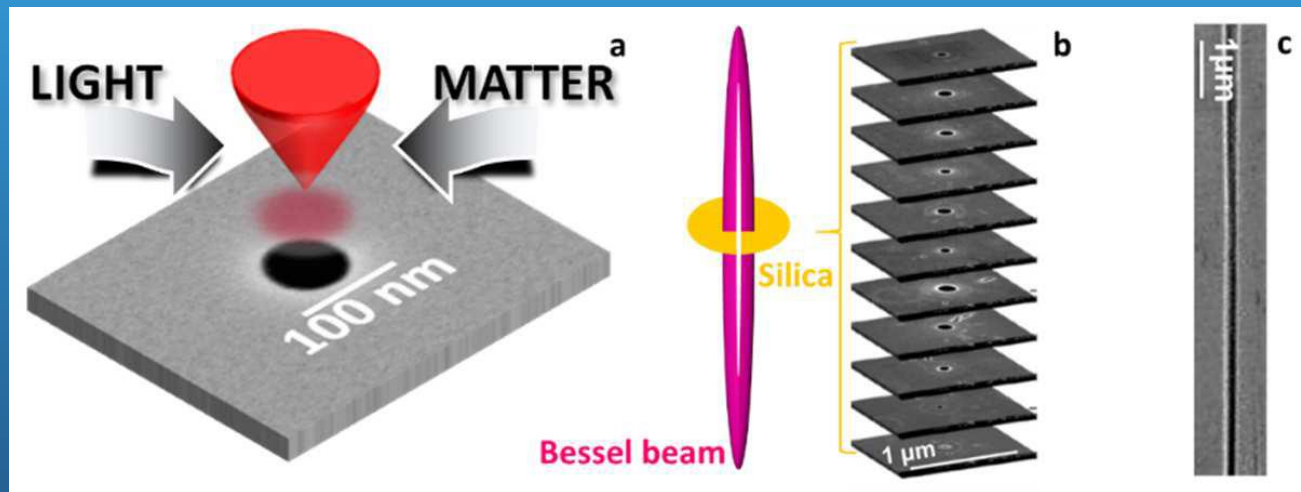
$L/d = 200-300$, L is the plate thickness and d the tube diameter
In principle we should have better timing than that of the MCP
(less dispersion (TTS))

Nanopores are obtained with
simple electrolysis process.

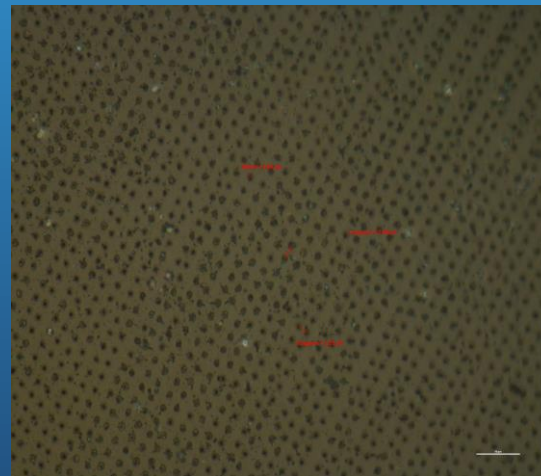
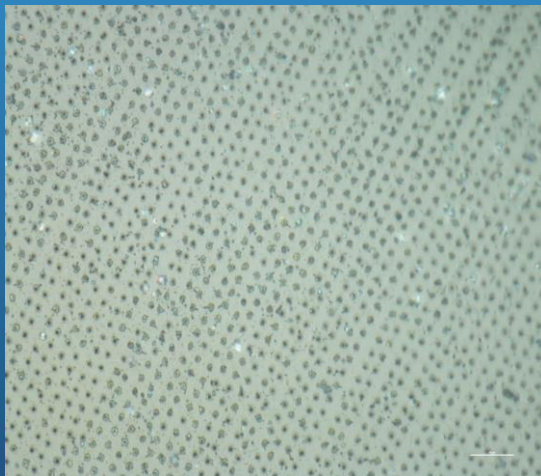
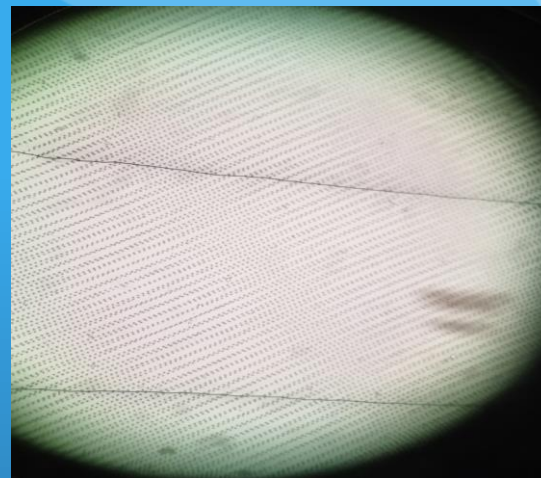
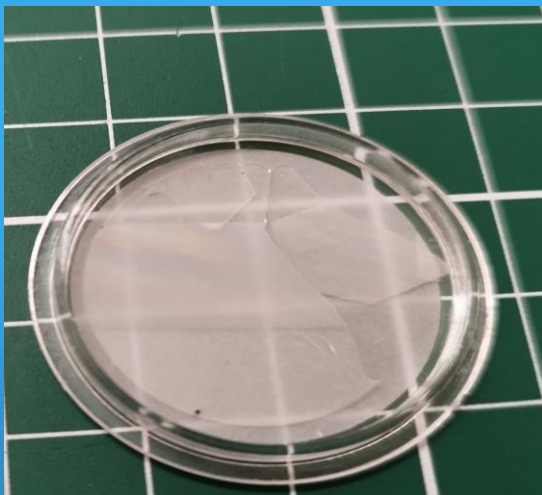


Femto-Laser NCP

The concept is to produce micro/nano-pore using the Femto-Laser techniques Bessel beam allows digging deep in transparent material producing regular pores

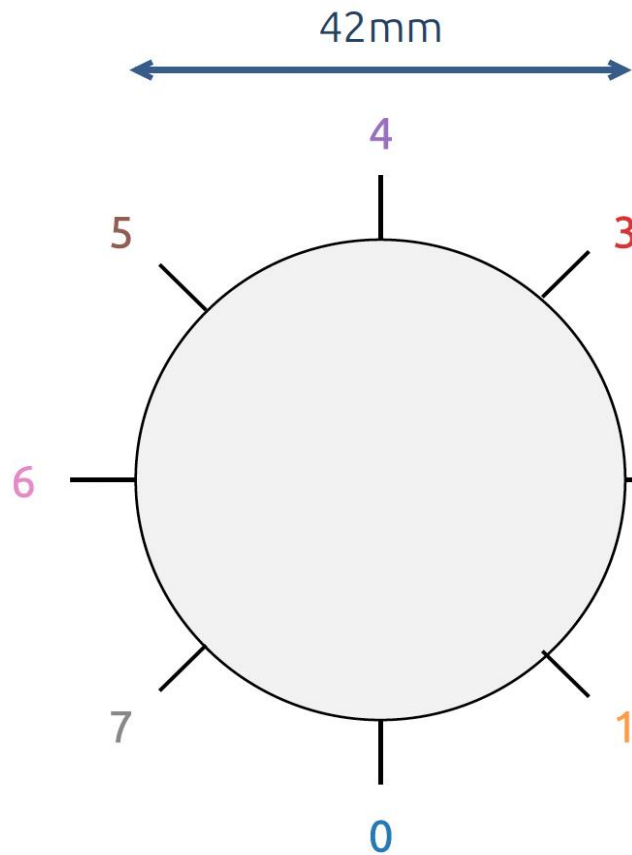


By using lead-glass plates and obtaining high density of pores, one can not only produce NCP but also reduce the tedious chemical process used in MCP fabrication

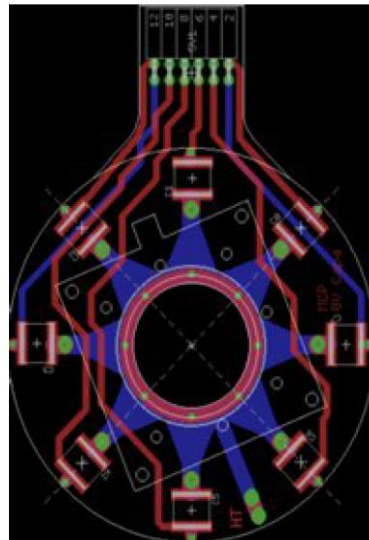


0.4 μm diameter and 2.5 μm pitch

Timing detector

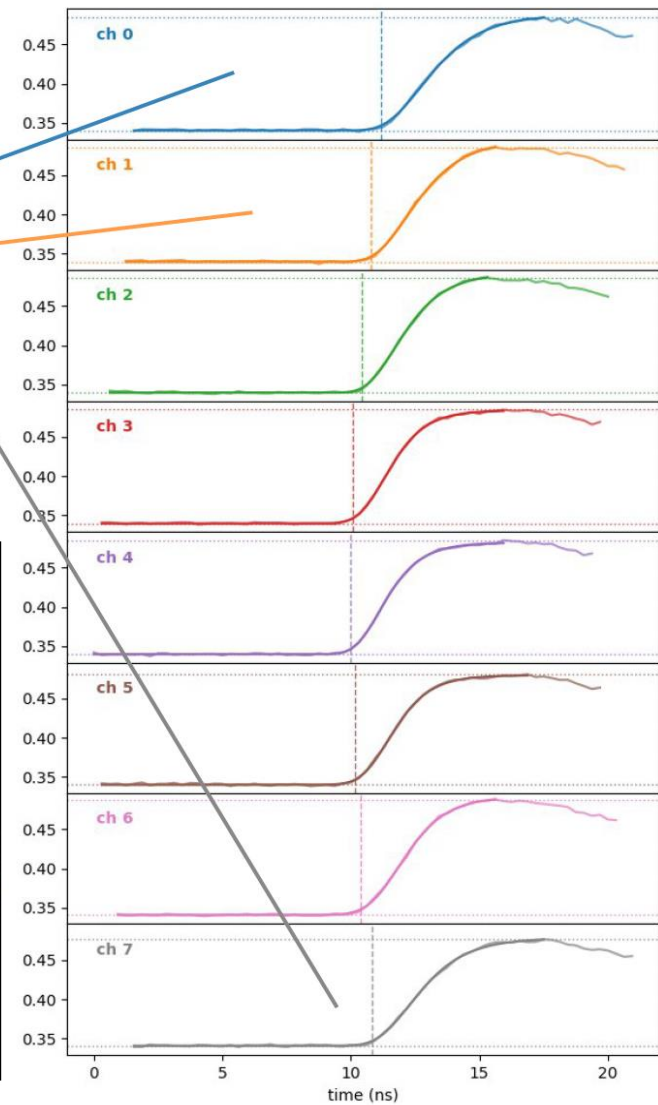


slower rising times for ch0, 1, 7 due to longer lines

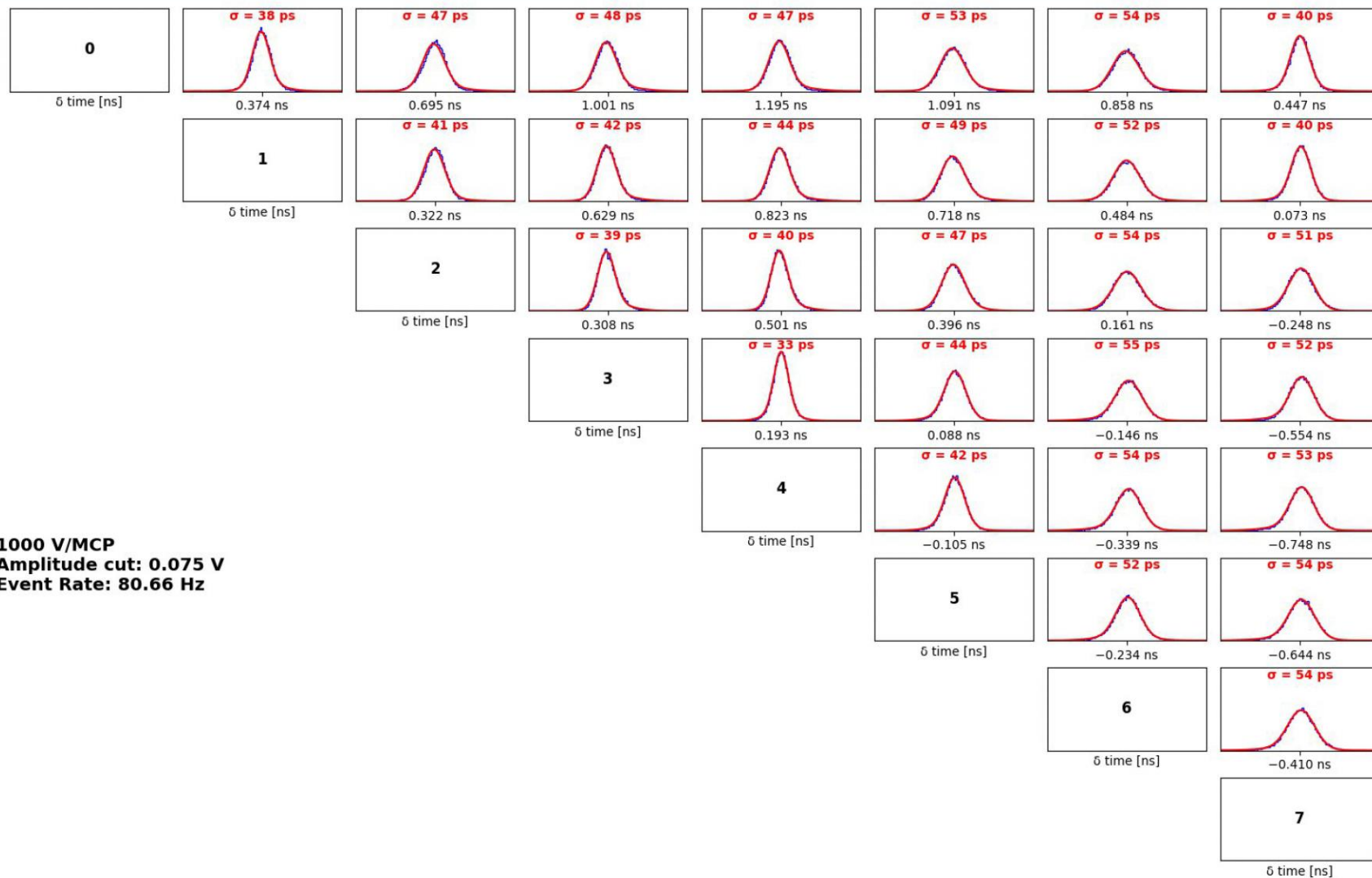


fitting function :

$$f = C + a \cdot (1 - v \cdot e^{-f(x-\mu)})^{-1/v}$$

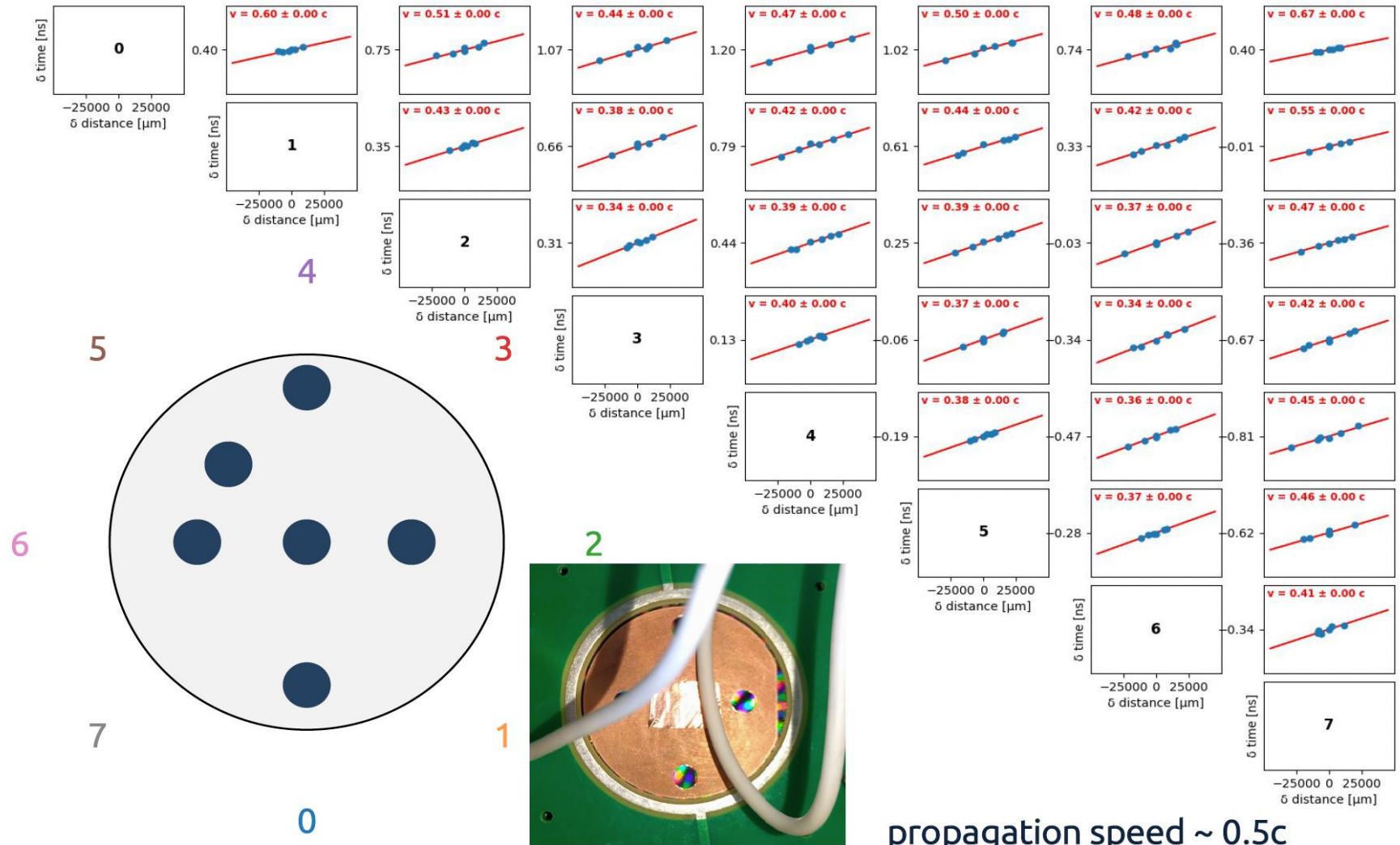


Timing detector – time resolution

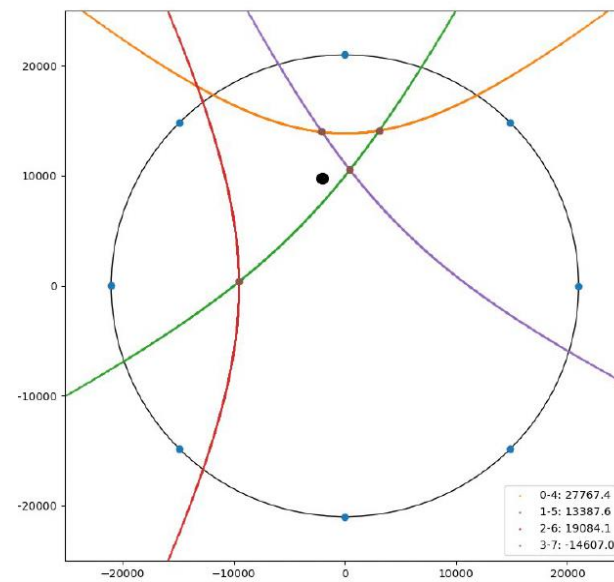
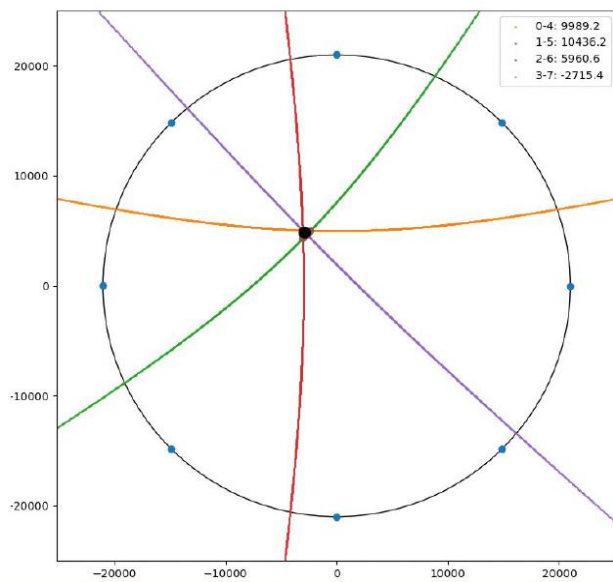
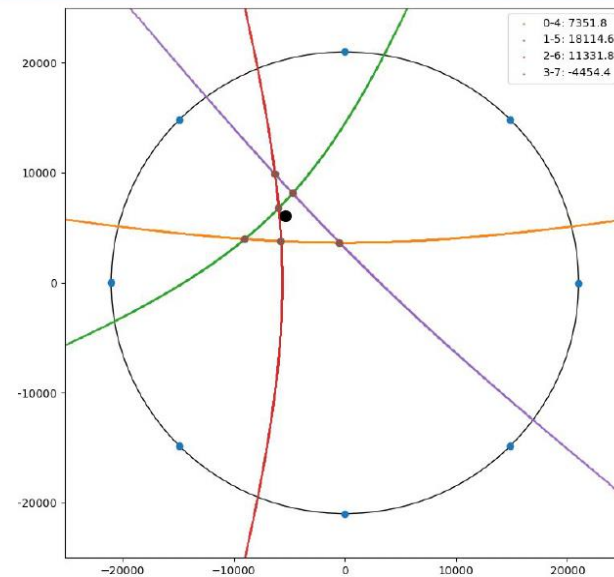
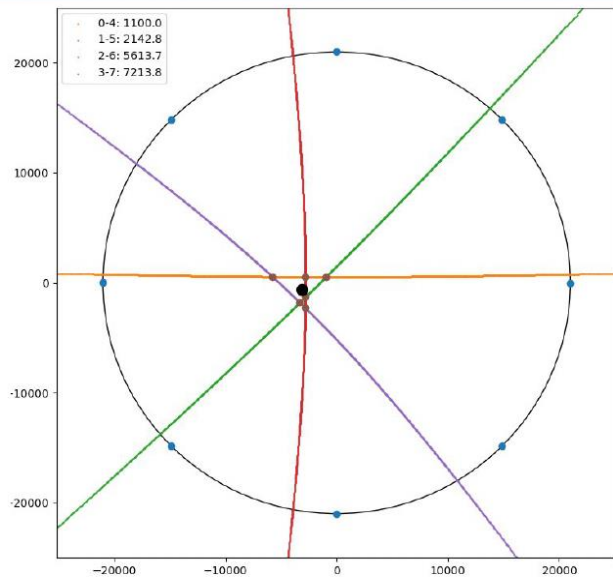


1000 V/MCP
Amplitude cut: 0.075 V
Event Rate: 80.66 Hz

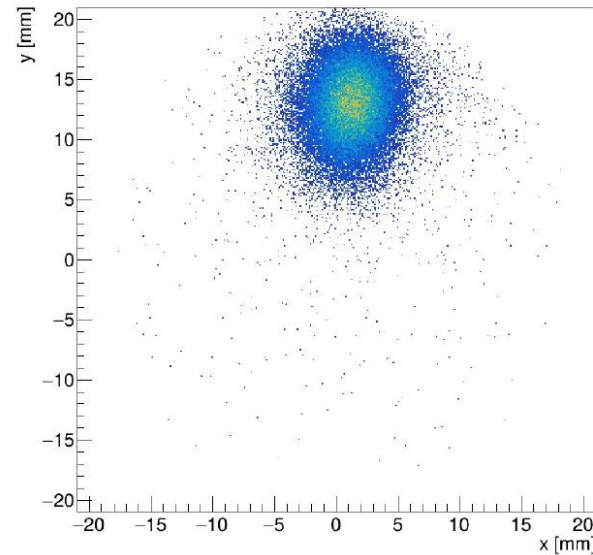
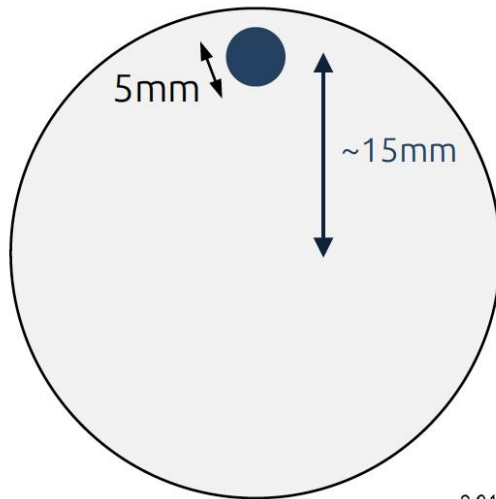
Timing detector – delta times vs delta distances



Timing detector – position reconstruction



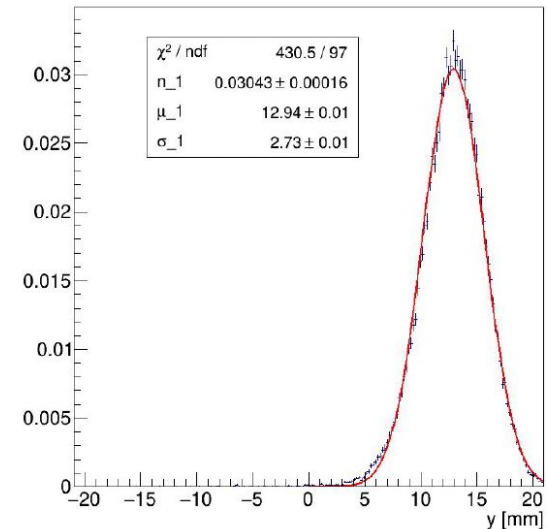
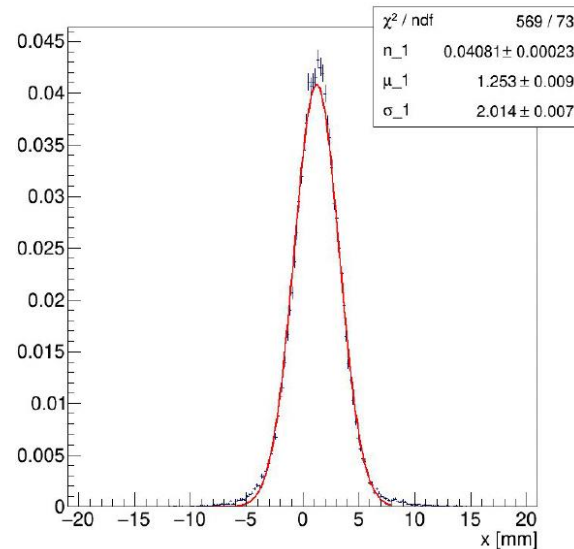
Timing detector – position resolution



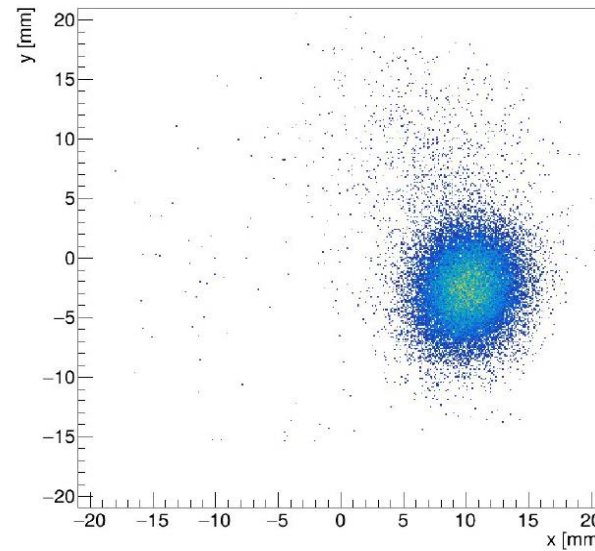
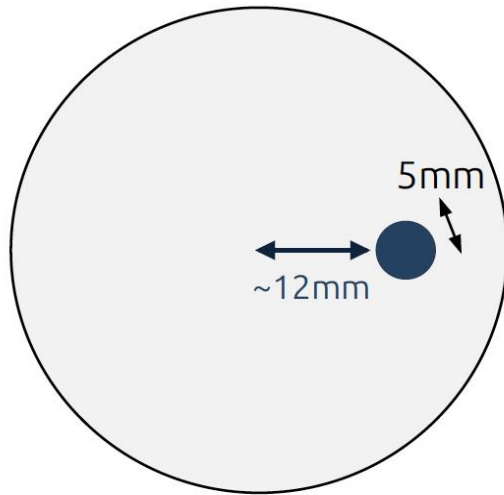
1000 V/MCP

$\sigma_{x_fit} = 2 \text{ mm}$
 $\sigma_{y_fit} = 2.7 \text{ mm}$

subtracting the hole width
 $\Rightarrow \sigma_x = 1.6 \text{ mm}$
 $\Rightarrow \sigma_y = 2.4 \text{ mm}$



Timing detector – position resolution



1000 V/MCP

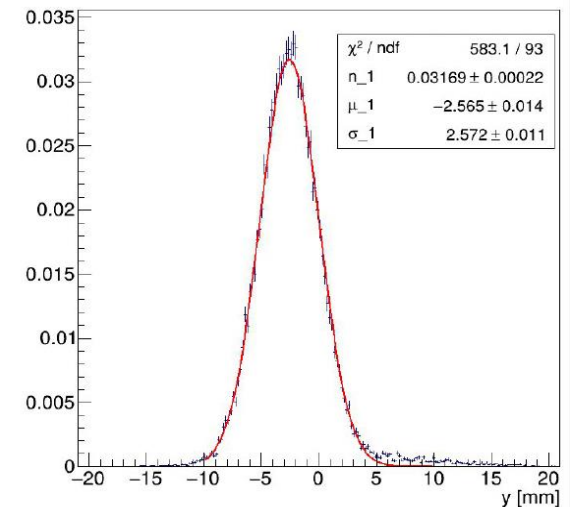
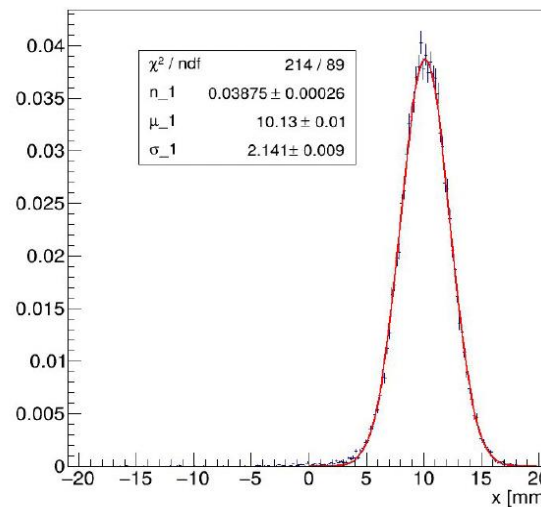
$\sigma_{x_fit} = 2.1 \text{ mm}$

$\sigma_{y_fit} = 2.6 \text{ mm}$

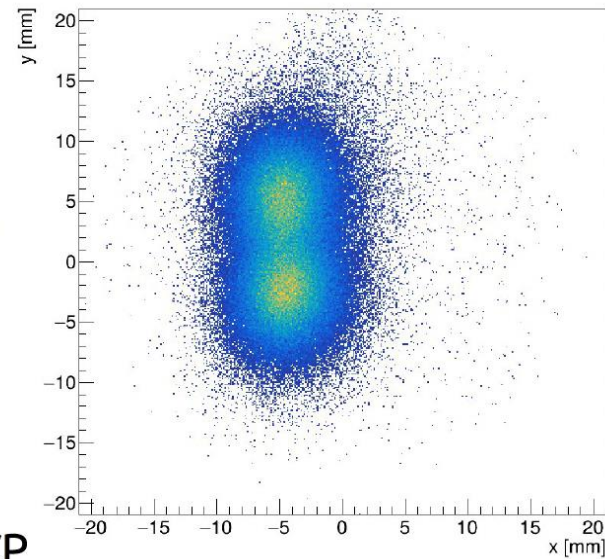
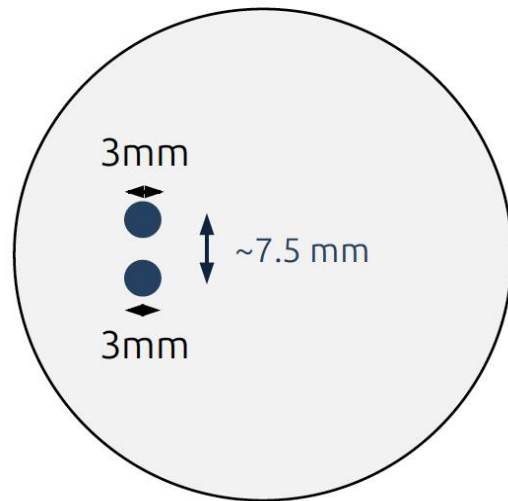
subtracting the hole width

$\Rightarrow \sigma_x = 1.7 \text{ mm}$

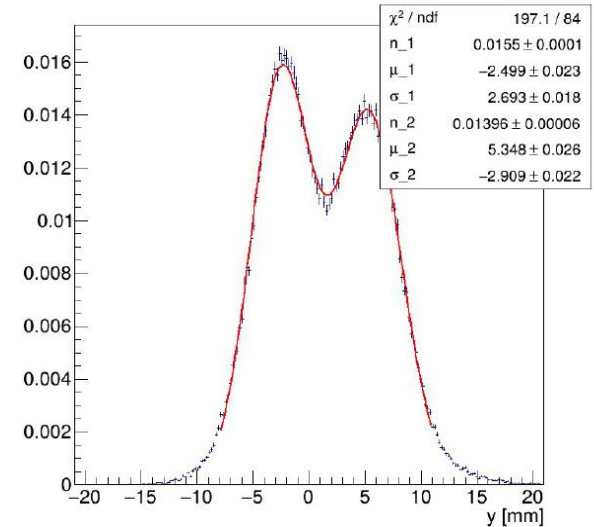
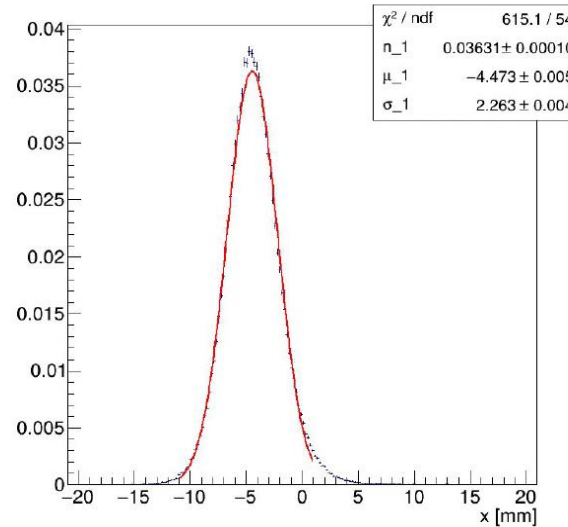
$\Rightarrow \sigma_y = 2.3 \text{ mm}$



Timing detector – position resolution



1000 V/MCP

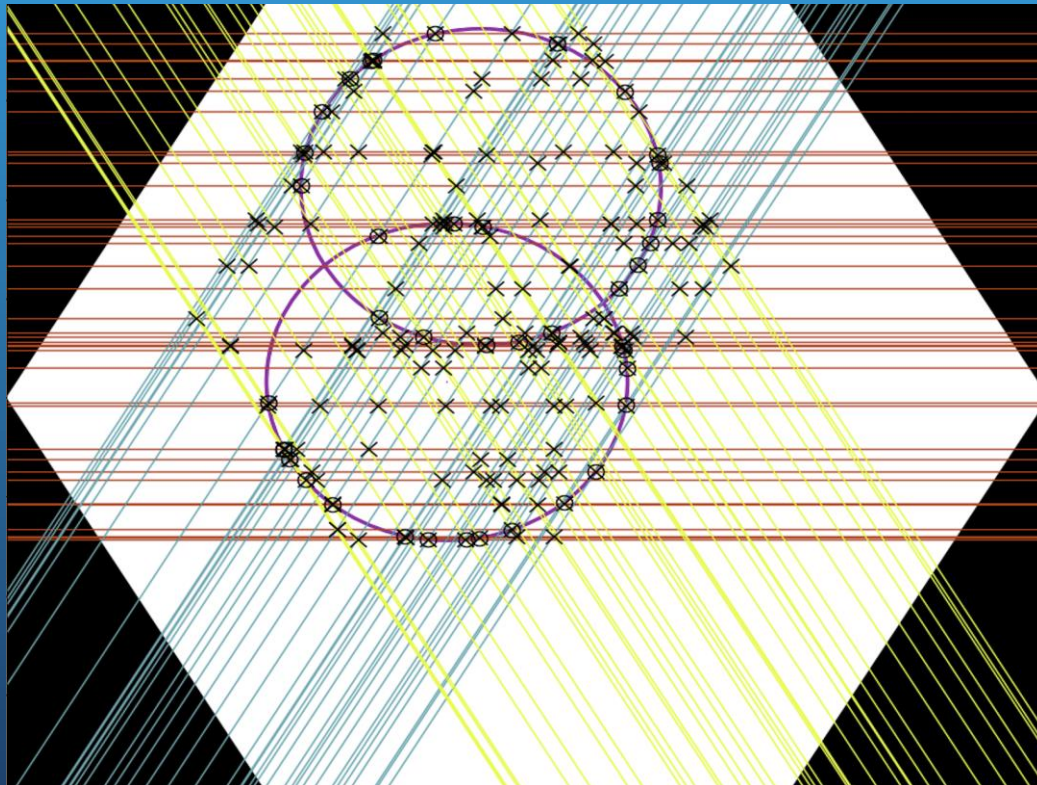


$\sigma_{x_fit} = 2.3 \text{ mm}$
 $\sigma_{y_fit} \sim 2.8 \text{ mm}$

subtracting the hole width
 $\Rightarrow \sigma_x = 2.2 \text{ mm}$
 $\Rightarrow \sigma_y = 2.7 \text{ mm}$

Can we use PICMIC for Cherenkov?

We are studying the performance of PICMIC to be used in a Cherenkov detector when associated to a photocathode and a radiator. Using Hough Transform we are able to determine the contour of a Cherenkov ring of a few mm.



P. Roger