



University of Colorado **Boulder**

Renormalization Group inspired inverse blocking with conditional normalizing flows

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Outline

Introduction

Perfect blocking implementation

Invertibility: The picture in momentum space

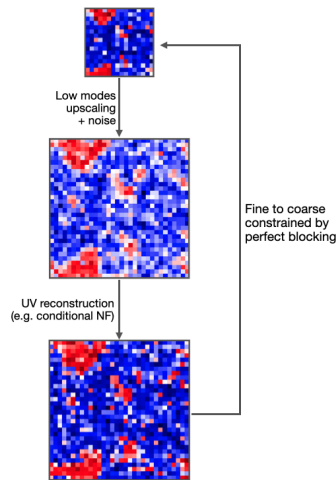
Upscaling flow (preliminary)

Conclusions

Introduction

Motivations

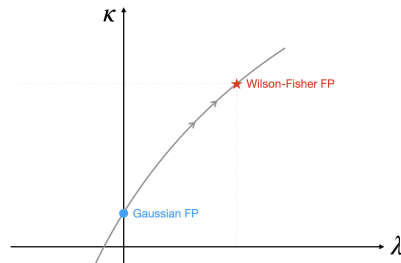
- Critical slowing down of MCMC near continuous phase transitions.
 - Alternative ML-based sampling
 - Normalizing Flows ([arXiv:1904.12072](#))
 - Multiscale / hierarchical generative models ([arXiv:2604.10209](#))
 - Inverse RG upscaling ([arXiv:2107.00466](#))
 - Diffusion and transport methods ([arXiv:2311.03578](#); [2605.06134](#))
 - ...
-
- Many existing generative models learn both infrared and ultraviolet degrees of freedom simultaneously.
 - Investigate **perfect blocking** as a tool to reduce the learning task to the missing UV degrees of freedom.
 1. Upscale coarse MC-generated ensemble,
 2. Reconstruct the missing UV modes,
 3. Fine/coarse consistency enforced by perfect blocking.



The model: 2d ϕ^4

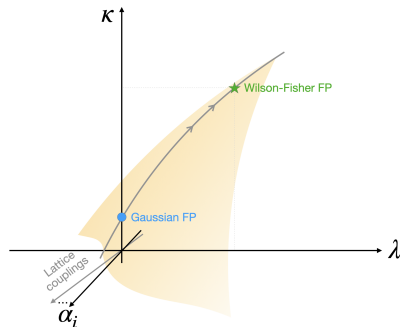
$$S[\phi] = -2\kappa \sum_{x,\mu} \phi_x \phi_{x+\hat{\mu}} + \sum_x \left[\phi_x^2 + \lambda(\phi_x^2 - 1)^2 \right]$$

- Gaussian fixed point (no interactions).
- Wilson–Fisher fixed point (interacting critical point).
- $\lambda = 1$, $\kappa_c(\lambda) = 0.34$
- RG flow toward the Wilson–Fisher point.



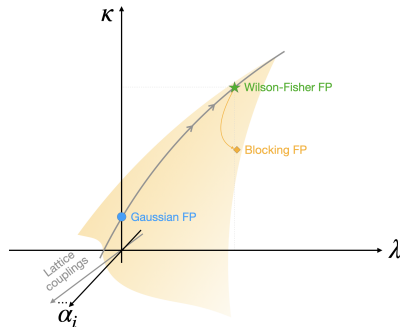
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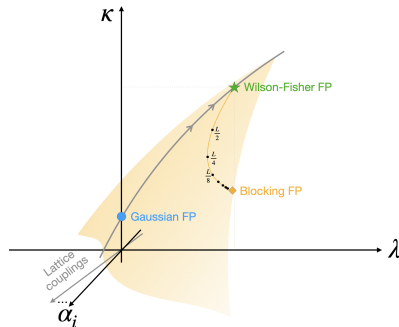
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Perfect blocking

$$\langle \mathcal{O}_i(\Phi_L) \rangle = 2^{-(p + \frac{n\eta}{2})} \langle \mathcal{O}_i(\phi_{L/2}) \rangle \quad \forall \mathcal{O}_i \quad \begin{cases} n = \# \text{ of fields, } p = \# \text{ of derivatives in } \mathcal{O}_i \\ \eta = 0.25 \end{cases}$$

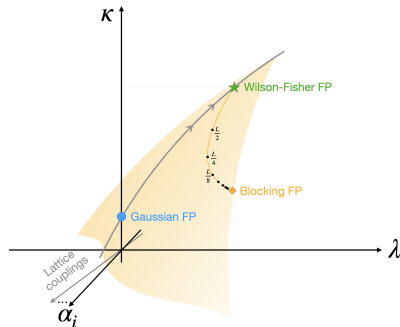
- RG blocking changes the effective action:
new couplings appear.
- Traditional route: **perfect action** for a fixed
blocking transformation.
([arXiv:2311.17816](#); [2502.03315](#); [2504.15870](#))
- Complementary route: **perfect blocking** for a
fixed target action.
 - At this blocking FP, action is $\approx$ target one.
 - Upscaling flow $\approx$ in same parameter region



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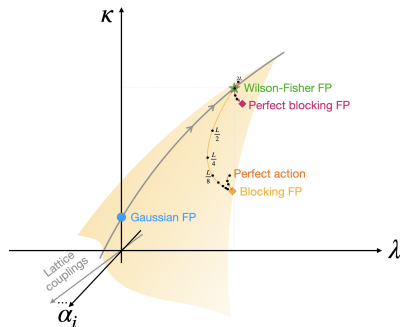
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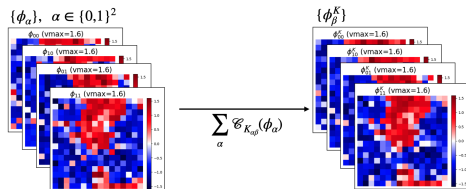
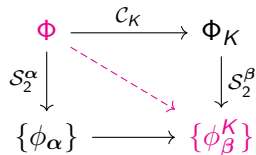
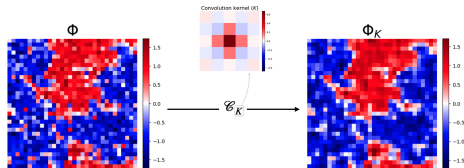
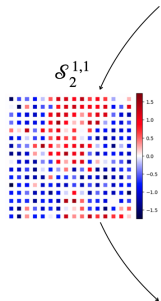


Perfect blocking implementation

Perfect blocking: Illustration

- Φ : $2L \times 2L$ configuration
- ϕ_α^K : $L \times L$ configurations with $\alpha \in \{00, 10, 01, 11\}$
- C_K : local stride-1 convolution
- S_2 : stride-2 decimation
- $S_2 \circ C_K$: "perfect" blocking (after proper training of K)
- (!) Convolution might not be invertible, depending on K

$$\Phi \stackrel{?}{\leftarrow} \Phi^K$$



Perfect blocking: Training details

Kernel parametrization:

- D_4 -symmetric local kernel K
- $\Rightarrow$ real in momentum space
- Normalized to $\sum_{\vec{r}} K(\vec{r}) = 2^{\eta/2}$
- η trained or fixed

Choice of observables:

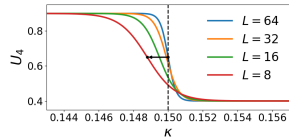
- Vol-averaged set of local operators^a

$$\mathcal{O}_i(\phi) = \phi \prod_{m=1}^{M_{\max}-1} (\partial_1^{n_1(m)} \partial_2^{n_2(m)} \phi)$$

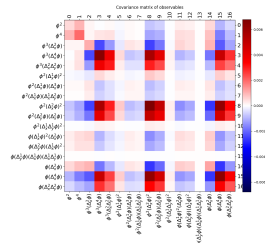
- $M_{\max}$ derivatives and $N_{\max}$ fields

^aSymmetric derivatives, iterations of 1d discrete derivatives
 $\nabla^{(1)}\phi \equiv \frac{1}{2}(\phi_{x+1} - \phi_{x-1})$ and $\nabla^{(2)}\phi \equiv (\phi_{x+1} + \phi_{x-1} - 2\phi_x)$

Training ensembles: Blocked_(L×L) vs MC-gen_(L×L)

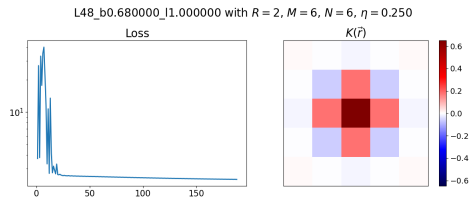
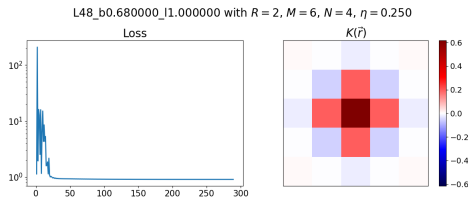
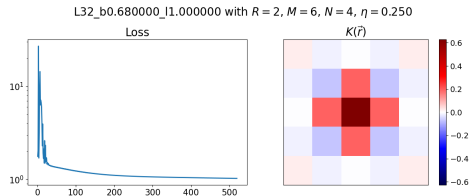
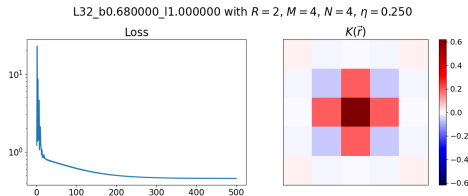


$$\text{Loss} = \delta^T C^{-1} \delta, \text{ w/ } \delta = (\langle \mathcal{O}(\phi_{00}^K) \rangle - \langle \mathcal{O}(\Phi) \rangle)$$



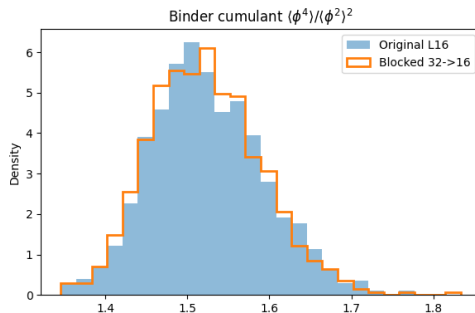
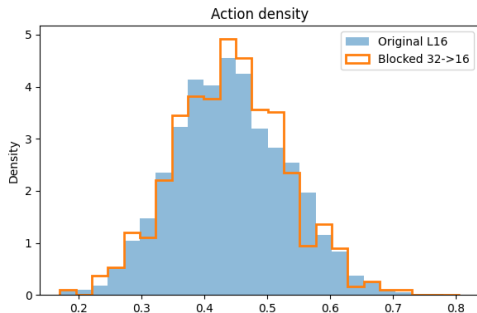
Perfect blocking: Training results at fixed $\eta = 0.25$

- Kernel parametrization in position space.
- Same R , increasing $M_{\max}$, $N_{\max}$ and lattice size L .

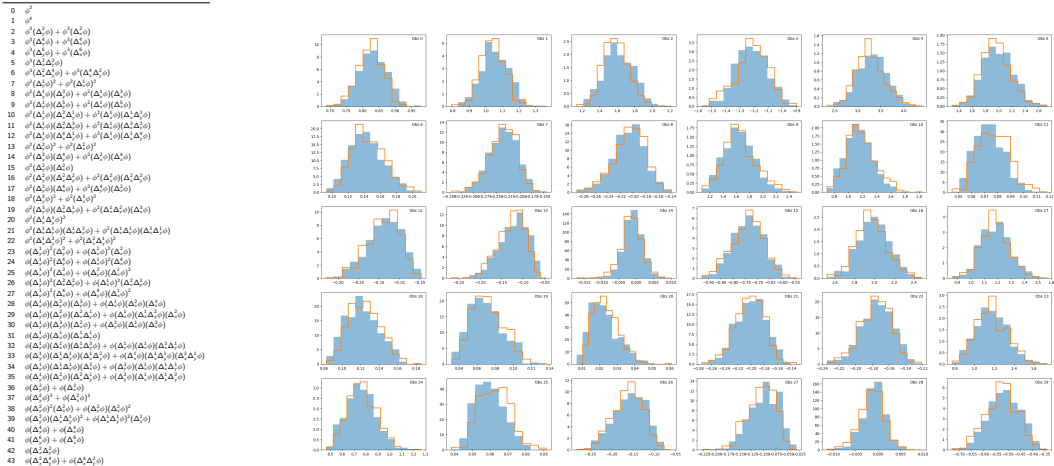


Action density and Binder cumulant

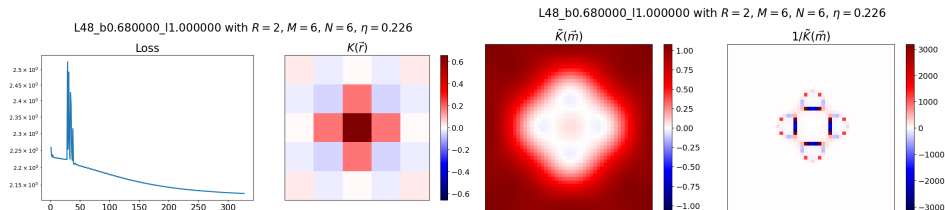
- $N_{\max} = 4$, $M_{\max} = 6$, $R = 2$, $\eta = 0.25$
- Blue: MC-gen $L = 16$ ensemble, orange line: blocked $L = 32 \rightarrow L = 16$
- Observables not in the loss.



Other $\langle \mathcal{O}_i \rangle$ histograms



Blocking kernel in momentum space



■ D_4 -symmetric parametrization

$$\tilde{K}(\vec{n} + \vec{s}L) = \sum_{\vec{r}} b(\vec{r}) \cos\left(\frac{\pi}{L} \vec{r} \cdot \vec{n}\right) (-1)^{\vec{r} \cdot \vec{s}}, \quad b(g\vec{r}) = b(\vec{r}) \quad \forall g \in D_4$$

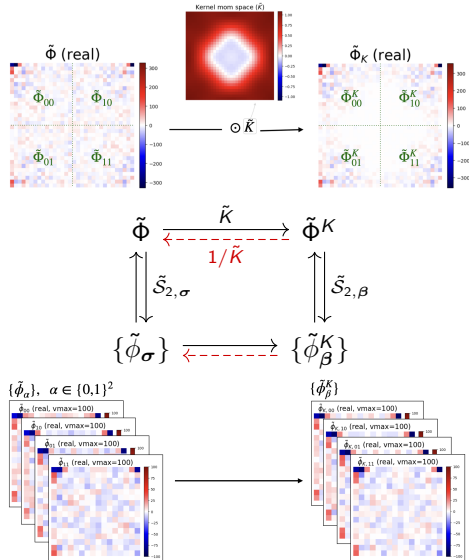
$n_i = 0, \dots, L - 1$ momenta on coarse lattice. Fine lattice: $\vec{n} + \vec{s}L$ with $\vec{s} \in \{0, 1\}^2$

- Enforcing positivity worsens the cost function and η (when trained).
- Can we get away with a non-invertible kernel? Or do we need to sacrifice some freedom to impose invertibility?

Invertibility: The picture in momentum space

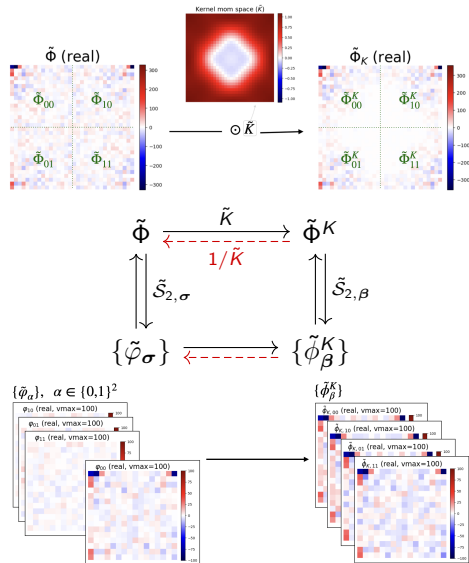
Blocking in momentum space

- Coarse lattice: $\vec{k} = \frac{2\pi}{L} \vec{n}$, $n_i = 0, \dots, L-1$.
- Fine lattice: $\vec{m} = \vec{n} + \vec{s}L$, $\vec{s} \in \{0, 1\}^2$
- $\Rightarrow \tilde{\Phi}(\vec{m}) \equiv \tilde{\Phi}_{\vec{s}}(\vec{n})$.
- Convolution: $\tilde{\Phi}_K(\vec{m}) = \tilde{K}(\vec{m}) \tilde{\Phi}(\vec{m})$.
- Define: $M_{\sigma}(\vec{n} + \vec{s}L) = (-1)^{\sigma \cdot \vec{s}} e^{i\pi \vec{n} \cdot \sigma / L}$.
- (Note: $M_{\sigma}(\vec{n} + \vec{s}L) = 1 \forall \vec{n}$.)
- Stride-2: $\tilde{\phi}_{\sigma}^K(\vec{n}) = \frac{1}{4} \sum_{\vec{s}} M_{\sigma\vec{s}}(\vec{n}) \tilde{\Phi}^K(\vec{n} + \vec{s}L)$.
- L.h.s.: Any choice of basis P_{σ} s.t. $\det P_{\sigma} \neq 0$ and $P_{\sigma}^{\dagger}(\vec{m}) = P_{\sigma}(-\vec{m})$.
- E.g., low/high-mode basis $P_{\alpha} = \frac{1}{4} H_{\alpha\sigma} M_{\sigma}$.



Blocking in momentum space

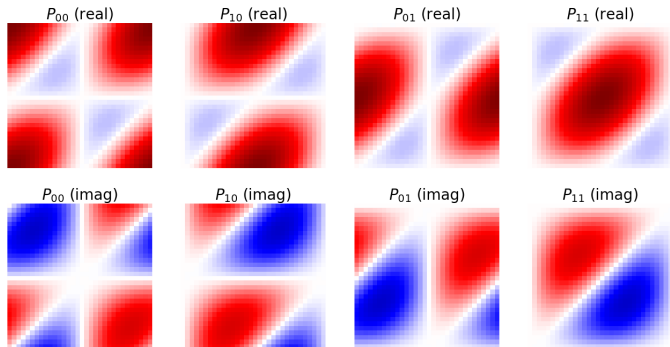
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- E.g., low/high-mode basis $P_{\alpha} = \frac{1}{4} H_{\alpha\sigma} M_{\sigma}$.



Low/high modes separation

- Choose $P_\sigma(\vec{n}) = \frac{1}{4} H_{\sigma\alpha} M_\alpha(\vec{n})$ with H the Hadamard matrix.
- $\tilde{\varphi}_\alpha(\vec{n}) = \frac{1}{4} \sum_s \Phi(\vec{n} + \mathbf{s}L) P_\alpha(\vec{n} + \mathbf{s}L)$
- $\Phi(\vec{n} + \mathbf{s}L) = P_\alpha^\dagger(\vec{n} + \mathbf{s}L) \tilde{\varphi}_\alpha(\vec{n})$

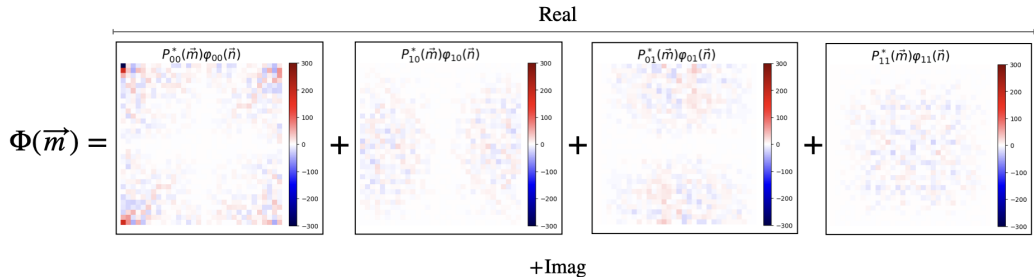
$$\begin{array}{ccc}
 \tilde{\Phi} & \xleftrightarrow[\text{---}]{\tilde{K}} & \tilde{\Phi}^K \\
 \updownarrow \tilde{S}_{2,\sigma} & \text{---} \times \text{---} & \updownarrow \tilde{S}_{2,\beta} \\
 \{\tilde{\varphi}_\sigma\} & \xleftrightarrow[\text{---}]{\quad} & \{\tilde{\varphi}_\beta^K\}
 \end{array}$$



Low/high modes separation

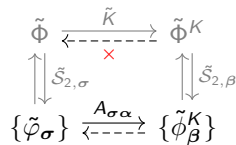
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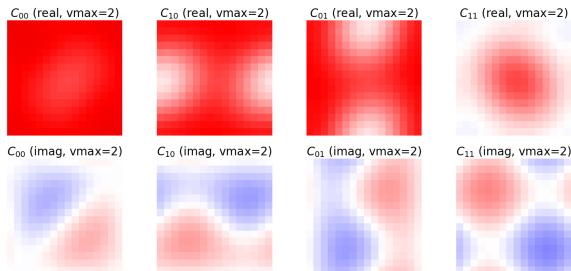


Maps between small volumes

- $\tilde{\phi}_\alpha^K(\vec{n}) = \sum_\beta A_{\alpha\beta}(\vec{n}) \tilde{\varphi}_\beta(\vec{n}),$
- Focus on $C_\beta \equiv A_{00,\beta}$; $C_\beta(\vec{n}) = \frac{1}{4} \sum_s \tilde{K}(\vec{n} + sL) P_\beta(\vec{n} + sL)$
- $\Rightarrow \tilde{\phi}_{00}^K = \sum_\beta C_\beta \tilde{\varphi}_\beta$
- $\Rightarrow \tilde{\varphi}_{00}^K = C_{00}^{-1} \left(\tilde{\phi}_{00}^K - \sum_{\beta \neq 00} C_\beta \tilde{\varphi}_\beta \right)$



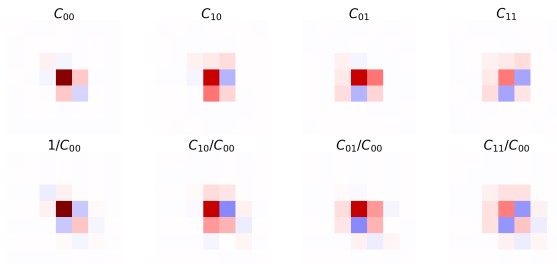
Only $C_{00}(\vec{n})$ needs to be invertible!



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- $\Rightarrow \tilde{\varphi}_{00}^K = C_{00}^{-1} \left(\tilde{\phi}_{00}^K - \sum_{\beta \neq 00} C_\beta \tilde{\varphi}_\beta \right)$
- $\varphi_\beta(\vec{n}) C_\beta(\vec{n})$ in position space correspond to local convolutions

$$\begin{array}{ccc}
 \tilde{\Phi} & \xleftrightarrow[\text{red } \times]{\tilde{K}} & \tilde{\Phi}^K \\
 \updownarrow \tilde{S}_{2,\sigma} & & \updownarrow \tilde{S}_{2,\beta} \\
 \{\tilde{\varphi}_\sigma\} & \xleftrightarrow[A_{\sigma\alpha}]{\quad} & \{\tilde{\phi}_\beta^K\}
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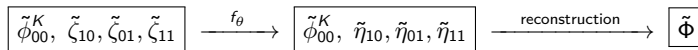
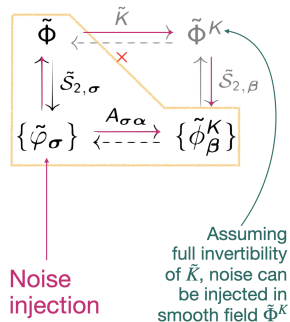


Reconstruction strategy

- On *l.h.s.*, pick masks P_α , which sets $\tilde{\Phi} \xrightarrow{P_\alpha} \{\tilde{\varphi}_\sigma\}$.
- The choice of P_α determines the shape of $C_\beta(\vec{n})$ masks: if P_α separates low/high modes, then $C_{00}(\vec{n})$ becomes easily invertible.
- Training/reconstruction can be performed through the map

$$\tilde{\Phi} \longleftrightarrow \{\tilde{\varphi}_\sigma\} \longleftrightarrow \{\tilde{\phi}_\beta^K\}.$$

-
- Given an **input** coarse configuration $\tilde{\phi}_{00}^K$, only the three missing UV components $\tilde{\varphi}_{10}$, $\tilde{\varphi}_{01}$, $\tilde{\varphi}_{11}$ remain undetermined.
 - $\tilde{\varphi}_{\beta \neq 00}$ natural latent space in which to inject trainable noise.



Upscaling flow (preliminary)

Conditional Normalizing Flow

Triangular conditional flow

$$\begin{aligned}\eta_{10} &= f_{10}(\phi_{00}^K, \zeta_{10}), \\ \eta_{01} &= f_{01}(\phi_{00}^K, \eta_{10}, \zeta_{01}), \\ \eta_{11} &= f_{11}(\phi_{00}^K, \eta_{10}, \eta_{01}, \zeta_{11}).\end{aligned}$$

Tested

- affine couplings,
- spline couplings,
- many orderings...

Affine flow

$$\eta_i = e^{s_i} \zeta_i + t_i$$

$$\log |\det J| = \sum_i s_i - \log C_{00}$$

Fixed reconstruction

$$\Phi \rightarrow \begin{pmatrix} \varphi_{00} \\ \varphi_{10} \\ \varphi_{01} \\ \varphi_{11} \end{pmatrix} = \begin{pmatrix} C_{00}^{-1} & -C_{10} & -C_{01} & -C_{11} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \phi_{00}^K \\ \eta_{10} \\ \eta_{01} \\ \eta_{11} \end{pmatrix}$$

C_{00}^{-1} and C_β are the position-space convolutions corresponding to the momentum-space kernels C_{00}^{-1} and $C_{00}^{-1} C_\beta$.

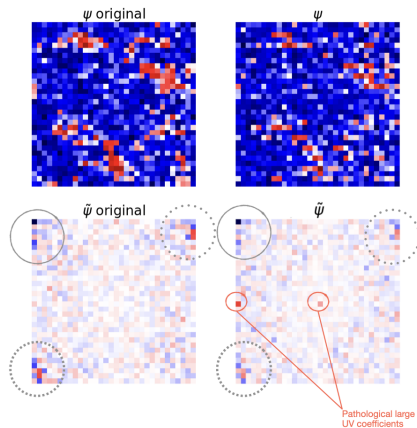
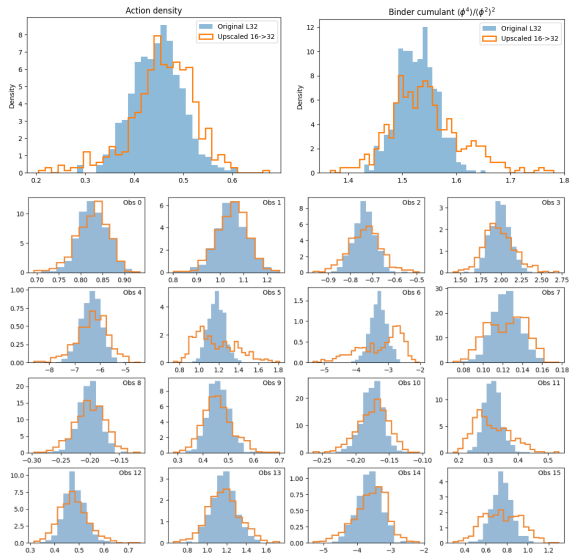
Metropolis-Hastings correction All info known to compute A/R

$$P_{\text{acc}}(\Phi \rightarrow \Phi') = \min \left(1, \frac{\pi(\Phi') q(\Phi | \phi_{00}^K)}{\pi(\Phi) q(\Phi' | \phi_{00}^K)} \right),$$

$$q(\Phi | \phi_{00}^K) = \frac{p(\zeta)}{|\det J_{\zeta \rightarrow \eta}| |C_{00}|^{-1}},$$

$$p(\zeta) = \mathcal{N}(0, \mathbf{I}), \quad \pi(\Phi) \propto e^{-S_{\phi^4}[\Phi]}.$$

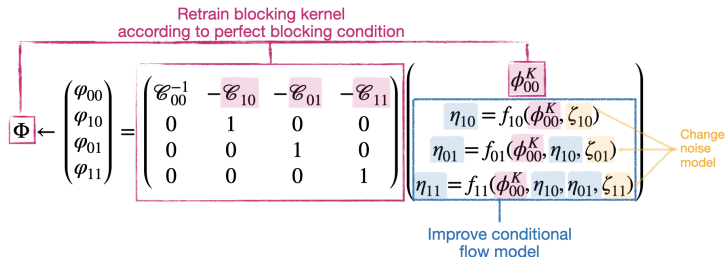
Results (preliminary...)



Why doesn't it work yet?

- An upscaling flow is possible! (A. Hasenfratz poster at this conference).
- Work presented in the poster assumes **full invertibility** of blocking kernel,
- $\Rightarrow$ noise can be injected directly in smoothed Φ^K .

Possibility 1: reconstruction tested until now not good enough:



Possibility 2: Partial invertibility is indeed a limitation.

Conclusions

Conclusions and Outlook

- Perfect blocking: physically motivated framework for upscaling ensembles near criticality.
- The optimized blocking kernels appear to be
 - consistent across observables and training volumes,
 - effectively localized within a $\sim 5 \times 5$ stencil,
 - when trained, $\eta \approx 0.25 \pm 0.05$.
- The reconstruction explored here suggests full kernel invertibility may not be necessary $\rightarrow$ greater freedom for perfect blocking kernels.
- Under the assumption that the blocking kernel is fully invertible, successful upscaling ([A. Hasenfratz poster at this conference](#)).
- Future work:
 - clarify the minimal invertibility requirements,
 - extend the construction to other theories with infrared fixed points.

