

Quantum mechanism angular momentum & graphical calculus

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Jinsong Yang (Guizhou university)

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References:

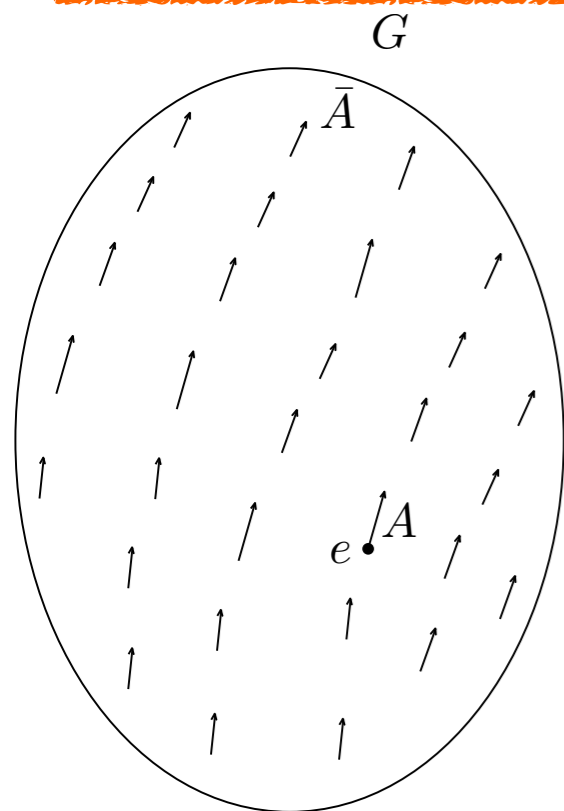
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1. Group theory

Def. (**Group**): a set G equipped with a mapping (group multiplication) $G \times G \rightarrow G$ satisfying the following conditions is called a group:

- (i) $(g_1 g_2) g_3 = g_1 (g_2 g_3), \quad \forall g_1, g_2, g_3 \in G$
- (ii) \exists identity element e such that $ge = eg = g, \quad \forall g \in G$
- (iii) $\forall g \in G \exists$ its inverse g^{-1} such that $gg^{-1} = g^{-1}g = e$

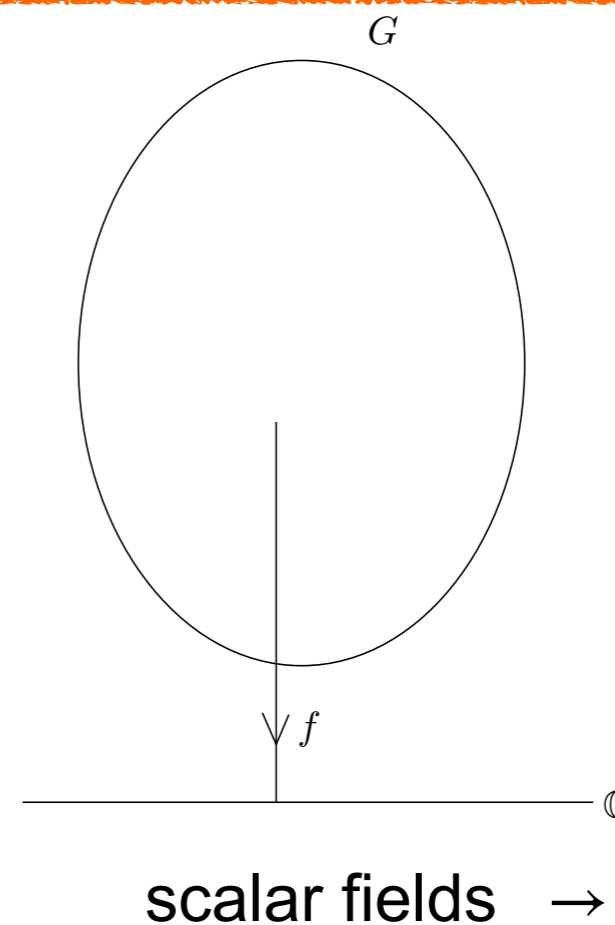
Def. (**Lie group**): if G both an n -dimensional manifold and a group, and the group multiplication mapping $G \times G \rightarrow G$ and the inverse mapping $G \rightarrow G$ are both C^∞ , then G is called an n -dimensional Lie group.



vector fields \rightarrow

angular momentum operator

left-invariant vector field



scalar fields \rightarrow

quantum state

Hilbert space

1. Group theory

Def. (**Group**): a set G equipped with a mapping (group multiplication) $G \times G \rightarrow G$ satisfying the following conditions is called a group:

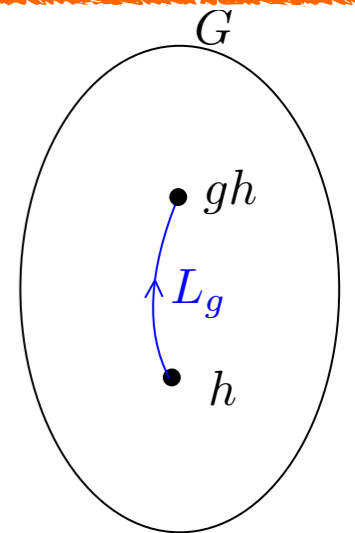
- (i) $(g_1 g_2) g_3 = g_1 (g_2 g_3), \quad \forall g_1, g_2, g_3 \in G.$
- (ii) \exists identity element e such that $ge = eg = g, \quad \forall g \in G.$
- (iii) $\forall g \in G \exists$ its inverse g^{-1} such that $gg^{-1} = g^{-1}g = e.$

Def. (**Lie group**): if G both an n -dimensional manifold and a group, and the group multiplication mapping $G \times G \rightarrow G$ and the inverse mapping $G \rightarrow G$ are both C^∞ , then G is called an n -dimensional Lie group.

Def. (**Left translation**): Let G be a Lie group, $\forall g \in G$, a map

$$L_g : h \mapsto gh \quad \forall h \in G$$

is called the left translation generated by g .



1. Group theory

Def. (**Left-invariant vector field**): A vector field \bar{A} on a Lie group G is called left-invariant if

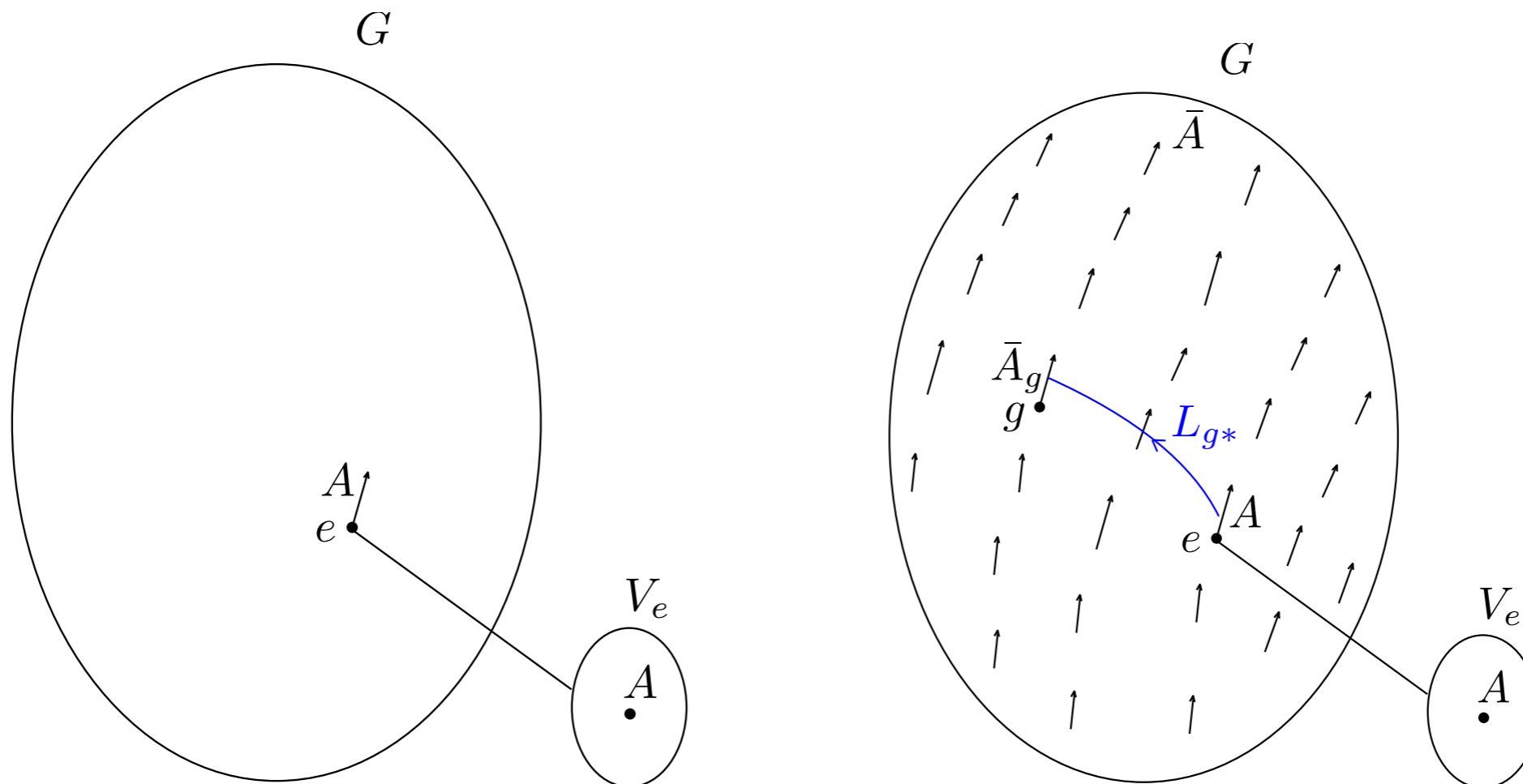
$$L_{g*}\bar{A} = \bar{A}, \quad \forall g \in G,$$

where L_{g*} is the pushforward mapping induced by the left translation $L_g : G \rightarrow G$.

Thm. Any vector $A \in V_e$ on a Lie group G determines a vector field by:

$$\bar{A}_g := L_{g*}A, \quad \forall g \in G,$$

which is left-invariant, and thus is called the left-invariant vector field generated by $A \in V_e$.



1. Group theory

Def. (**One-parameter subgroup**): A C^∞ curve $\gamma : \mathbb{R} \rightarrow G$ is called a one-parameter subgroup of a Lie group G if

$$\gamma(s + t) = \gamma(s)\gamma(t), \quad \forall s, t \in \mathbb{R}$$

where $\gamma(s)\gamma(t)$ denotes the group product of the group elements $\gamma(s)$ and $\gamma(t)$.

Thm. Any vector $A \in V_e$ on a Lie group G determines a one-parameter subgroup by exponential map as:

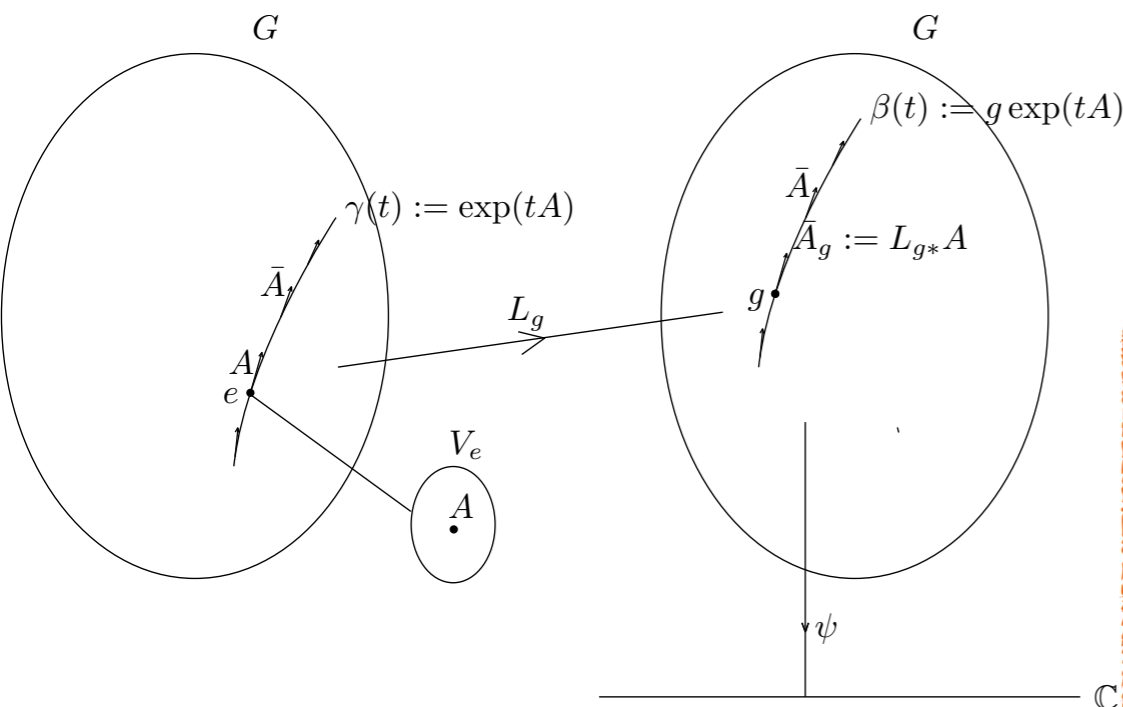
$$\gamma(t) := \exp(tA), \quad \forall t \in \mathbb{R}, A \in V_e,$$

which is an integral curve of the left-invariant vector field \bar{A} generated by $A \in V_e$.

Let

$$\beta(t) \equiv g\gamma(t), \quad \forall g \in G,$$

then $\beta : \mathbb{R} \rightarrow G$ is also an integral curve of \bar{A} passing through g .



$$\begin{aligned} \bar{A}_g \psi(g) &= \left. \frac{d}{dt} \right|_{t=0} \psi \circ \beta = \left. \frac{d}{dt} \right|_{t=0} \psi(\beta(t)) \\ &= \left. \frac{d}{dt} \right|_{t=0} \psi(g \exp(tA)) \end{aligned}$$

Hence

$$\bar{A}_g \psi(g) := \left. \frac{d}{dt} \right|_{t=0} \psi(g \exp(tA))$$

is often used to give the definition of the left-invariant vector field \bar{A} generated by $A \in V_e$.

1. Group theory

Quantum mechanics on $SU(2)$

$G = SU(2)$: a Lie group

$$\dim(SU(2)) = \dim(\mathfrak{su}(2)) = 2^2 - 1 = 3$$

$\forall g \in SU(2)$ can be uniquely written as

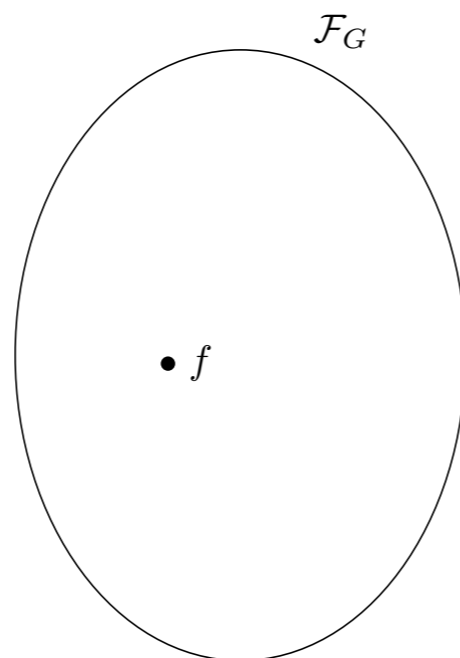
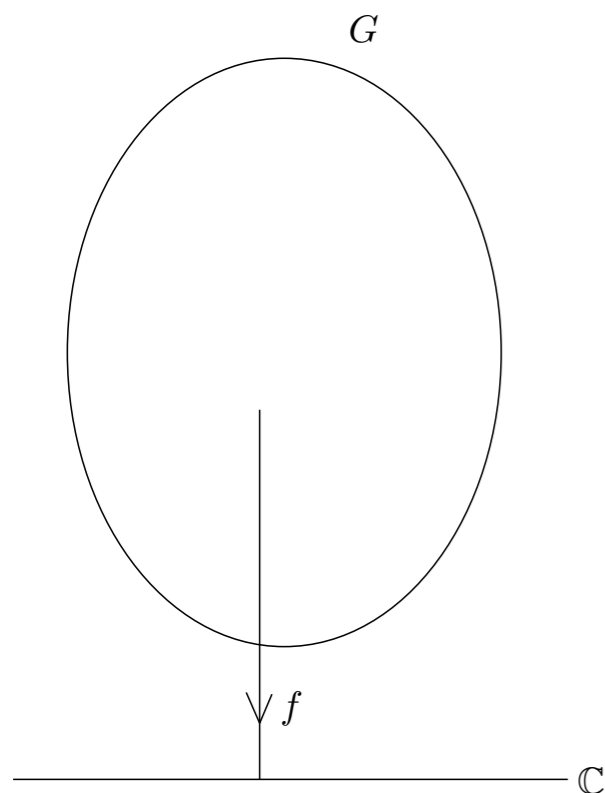
$$g = \begin{pmatrix} a & -\bar{b} \\ b & \bar{a} \end{pmatrix} \quad \text{with } a, b \in \mathbb{C}, \quad a\bar{a} + b\bar{b} = 1$$

Thm. There exists a unique Haar measure μ_H over $SU(2)$ which satisfies

(i) Invariant: $\mu_H(h) = \mu_H(hg) = \mu_H(gh) = \mu_H(h^{-1})$

(ii) Normalized: $\mu_H(SU(2)) = 1$

The Hilbert space $\mathcal{H}_{SU(2)}$ composed of complex-valued functions f over $SU(2)$



$$(f_1, f_2) := \int_{SU(2)} \overline{f_1(g)} f_2(g) d\mu_H(g)$$

$$\mathcal{H}_{SU(2)} := \overline{(\mathcal{F}_{SU(2)}, (\cdot, \cdot))} = L^2(SU(2), d\mu_H)$$

Completion of $\mathcal{F}_{SU(2)}$ w.r.t. the inner product

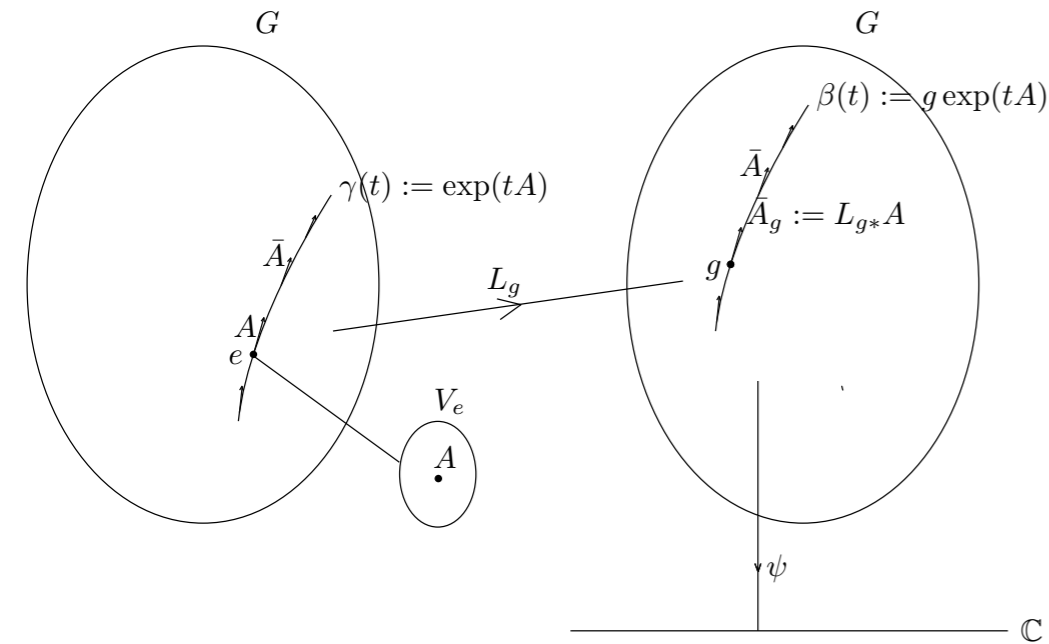
1. Group theory

$G = SU(2)$: a Lie group

$$\dim(SU(2)) = \dim(su(2)) = 2^2 - 1 = 3$$

$\forall g \in SU(2)$ can be uniquely written as

$$g = \begin{pmatrix} a & -\bar{b} \\ b & \bar{a} \end{pmatrix} \quad \text{with } a, b \in \mathbb{C}, \quad a\bar{a} + b\bar{b} = 1$$



Hence

$$\bar{A}_g \psi(g) := \left. \frac{d}{dt} \right|_{t=0} \psi(g \exp(tA))$$

is often used to give the definition of the left-invariant vector field \bar{A} generated by $A \in V_e$.

The **left-invariant vector field** $L^{(\tau_i)}$ and the **right-invariant vector field** $R^{(\tau_i)}$ on $SU(2)$, determined by the generator, $\tau_i = -\frac{1}{2}\sigma_i \in V_e$ with σ_i being the Pauli matrices, are defined by

$$L^{(\tau_i)} \psi(g) := \left. \frac{d}{dt} \right|_{t=0} \psi(g e^{t\tau_i})$$

$$L^{(\tau_i)} g^A_B = (g\tau_i)^A_B \quad \Leftrightarrow \quad L^{(\tau_i)} g = g\tau_i$$

$$R^{(\tau_i)} \psi(g) := \left. \frac{d}{dt} \right|_{t=0} \psi(e^{-t\tau_i} g)$$

$$R^{(\tau_i)} g^A_B = -(\tau_i g)^A_B \quad \Leftrightarrow \quad R^{(\tau_i)} g = -\tau_i g$$

Then one can define the so-called **angular momentum operators** on $\mathcal{H}_{SU(2)}$ by

$$\hat{J}_i^{(L)} := iL^{(\tau_i)} \quad \text{and} \quad \hat{J}_i^{(R)} := iR^{(\tau_i)},$$

satisfying $[\hat{J}_i^{(L)}, \hat{J}_j^{(L)}] = i\epsilon_{ij}^k \hat{J}_k^{(L)}$, $[\hat{J}_i^{(R)}, \hat{J}_j^{(R)}] = i\epsilon_{ij}^k \hat{J}_k^{(R)}$, $[\hat{J}_i^{(L)}, \hat{J}_j^{(R)}] = 0$.

The Casimir operator on $\mathcal{H}_{SU(2)}$ can be expressed as $\hat{J}^2 := \delta^{ij} \hat{J}_i^{(L)} \hat{J}_j^{(L)} = \delta^{ij} \hat{J}_i^{(R)} \hat{J}_j^{(R)}$.

2. Representation theory of a group

Def. (A representation of a group). A representation of a group G is a map

$$\begin{aligned}\pi : G &\rightarrow \mathcal{B}(V) \\ g &\mapsto \pi(g)\end{aligned}$$

where $\mathcal{B}(V)$ denotes the bounded linear operators on some Hilbert space V , called the representation space, satisfying

$$\pi(g_1 g_2) = \pi(g_1) \pi(g_2), \quad \forall g_1, g_2 \in G$$

Def. (Faithful and trivial representation). A representation π is called faithful if it is injective, equivalently,

$$\pi(g) = \mathbb{I}_V \quad \Rightarrow \quad g = e$$

and it called trival if

$$\pi(g) = \mathbb{I}_V, \quad \forall g \in G$$

Def. (Dual representation). Let V^* be the space dual to V , that is, the space of continuous linear functionals on V (since V is a Hilbert space, $V^* = V$ by the Riesz lemma). Then the representation π^* dual (or contragredient) to π is defined by

$$[\pi^*(g)f](v) := f(\pi(g^{-1})v)$$

In a Hilbert space V we have $f(\cdot) = \langle f, \cdot \rangle$ so that $\pi^*(g) = [\pi(g^{-1})]^\dagger$ where \dagger denotes the adjoint with respect to $\langle \cdot, \cdot \rangle$.

Def. (Unitary representation). A representation $\pi : G \rightarrow \mathcal{B}(V)$ is called unitary if $\pi(g)$ is a unitary operator on V for all $g \in G$, that is, $[\pi(g)]^\dagger = [\pi(g)]^{-1}$.

Def. (Tensor product representation). Let $\pi_i : G \rightarrow \mathcal{B}(V_i)$, $i = 1, 2$, be representations. The tensor product $\pi_1 \otimes \pi_2 : G \rightarrow \mathcal{B}(V_1 \otimes V_2)$ is defined by

$$[\pi_1 \otimes \pi_2](g) \cdot v_1 \otimes v_2 := (\pi_1(g)v_1) \otimes (\pi_2(g)v_2)$$

2. Representation theory of a group

Def. (**Invariant subspace & irreducible/reducible representation**). A closed subspace $V_1 \subset V$ is called invariant for a representation $\pi : G \rightarrow \mathcal{B}(V)$ iff

$$\pi(g)V_1 \subset V_1, \quad \forall g \in G.$$

A representation is called irreducible if it has no invariant subspace except for the trivial invariant subspaces V and $\{0\}$, otherwise reducible.

Def. (**Completely reducible representation**). A representation $\pi : G \rightarrow \mathcal{B}(V)$ is said to be completely reducible if it decomposes into a direct sum of irreducible representations π_i on the spaces V_i , that is,

$$\pi = \bigoplus_i \pi_i$$

where $V = \bigoplus_i V_i$ and the set of indices i is countable.

Thm. Every finite-dimensional unitary representation is completely reducible.

2. Representation theory of a group

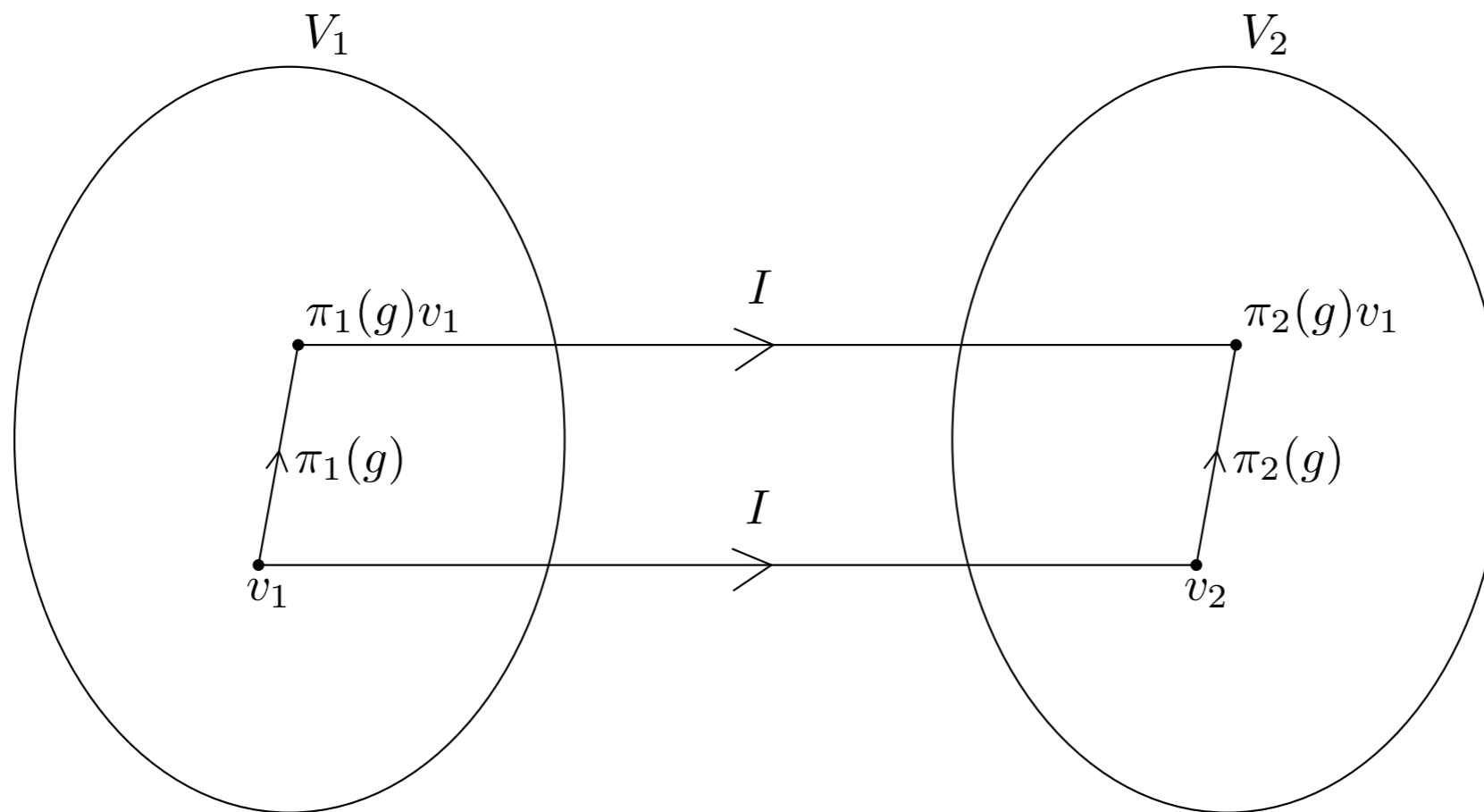
Def. (Equivalent representations & intertwiner). Two representations $\pi_i : G \rightarrow \mathcal{B}(V_i)$, $i = 1, 2$, are called equivalent iff there exists an invertible (unitary) linear map

$$I : V_1 \rightarrow V_2$$

satisfying [it “commutes” with the corresponding operators of the representations]

$$I \pi_1(g) = \pi_2(g) I \quad \Leftrightarrow \quad \pi_1(g) = I^{-1} \pi_2(g) I \quad \Leftrightarrow \quad \pi_2(g)^{-1} I \pi_1(g) = I, \quad \forall g \in G$$

Such a map I is called an intertwiner (intertwining operator, invariant tensor) for these two representations.



2. Representation theory of a group

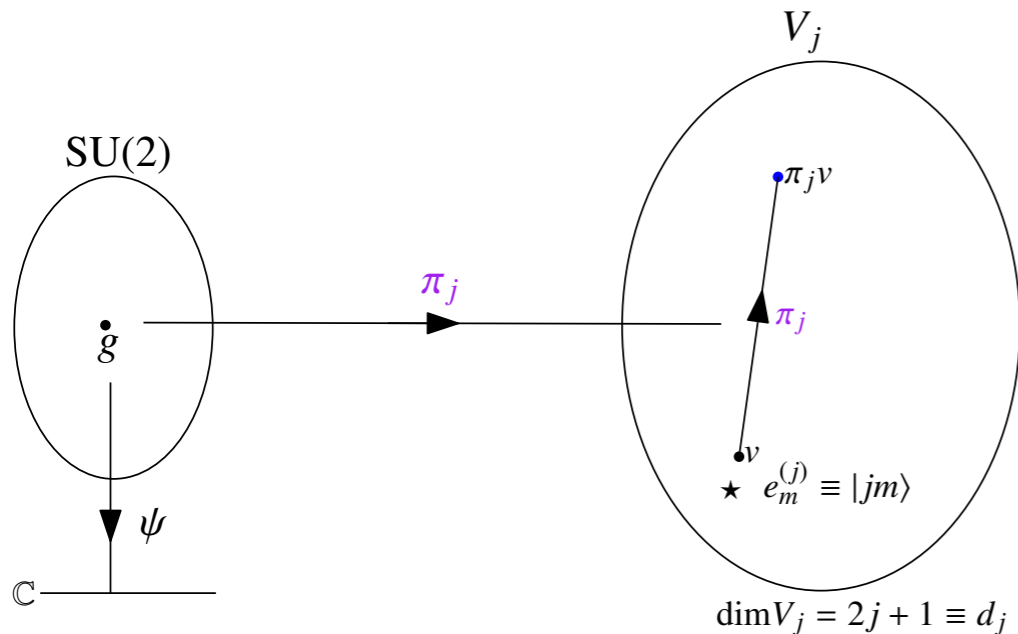
$G = \text{SU}(2)$: a Lie group

$$\dim(\text{SU}(2)) = \dim(\mathfrak{su}(2)) = 2^2 - 1 = 3$$

$\forall g \in \text{SU}(2)$ can be uniquely written as

$$g = \begin{pmatrix} a & -\bar{b} \\ b & \bar{a} \end{pmatrix} \quad \text{with } a, b \in \mathbb{C}, a\bar{a} + b\bar{b} = 1$$

The irreducible unitary representation of $\text{SU}(2)$ group (characterized by spin quantum number $j = 0, \frac{1}{2}, 1, \frac{3}{2}, 2, \dots$)



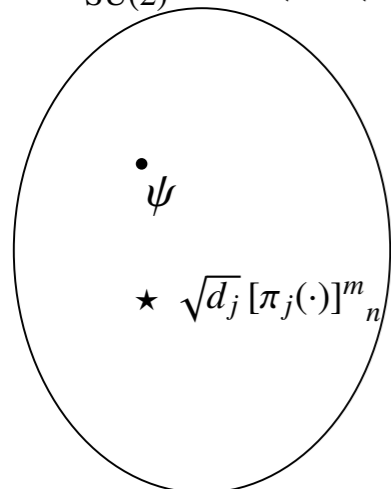
$$[\pi_j(g)]^m_n \equiv \langle jm | \pi_j(g) | jn \rangle$$

$$= \sum_{\ell} \frac{\sqrt{(j+m)!(j-m)!(j+n)!(j-n)!}}{(j-m-\ell)!(j+n-\ell)!(m-n+\ell)!\ell!} a^{j+n-\ell} (\bar{a})^{j-m-\ell} b^{\ell} (-\bar{b})^{m-n+\ell}$$

Thm (Peter and Weyl). Let G be a compact Lie group (such as $\text{SU}(2)$). The system of (spin network) functions on G , consisting of matrix elements $\sqrt{d_j} [\pi_j(\cdot)]^m_n$ in finite dimensional irreducible representations π_j labeled by half-integers j with dimension d_j , is a complete orthonormal basis for $\mathcal{H}_G \equiv L^2(G, d\mu_H)$,

$$\int_G d_j \overline{[\pi_{j'}(g)]^{m'}_{n'}} [\pi_j(g)]^m_n d\mu_H(g) = \delta_{j'j} \delta^{m'm} \delta_{n'n}$$

$$\mathcal{H}_{\text{SU}(2)} = L^2(\text{SU}(2), d\mu_H)$$



$$\psi(g) = \sum_{j,m,n} \psi_m^{jn} \sqrt{d_j} [\pi_j(g)]^m_n, \quad \forall \psi \in \mathcal{H}_{\text{SU}(2)}$$

2. Representation theory of a group

$G = SU(2)$: a Lie group

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Angular momentum operators on $\mathcal{H}_{SU(2)}$

$$\hat{J}_i^{(L)} := iL^{(\tau_i)} \quad \text{and} \quad \hat{J}_i^{(R)} := iR^{(\tau_i)},$$

$$L^{(\tau_i)}\psi(g) = \left. \frac{d}{dt} \right|_{t=0} \psi(ge^{t\tau_i})$$

$$R^{(\tau_i)}\psi(g) = \left. \frac{d}{dt} \right|_{t=0} \psi(e^{-t\tau_i}g)$$

$\forall g \in SU(2)$ can be uniquely written as

$$g = \begin{pmatrix} a & -\bar{b} \\ b & \bar{a} \end{pmatrix} \quad \text{with } a, b \in \mathbb{C}, \quad a\bar{a} + b\bar{b} = 1$$

$$\pi_j(\tau_k)]^m_n := \left. \frac{d}{dt} \right|_{t=0} [\pi_j(e^{t\tau_k})]^m_n, \quad e^{t\tau_i} = \cos(t)\mathbb{I}_2 + 2\sin(t)\tau_i \quad \longrightarrow$$

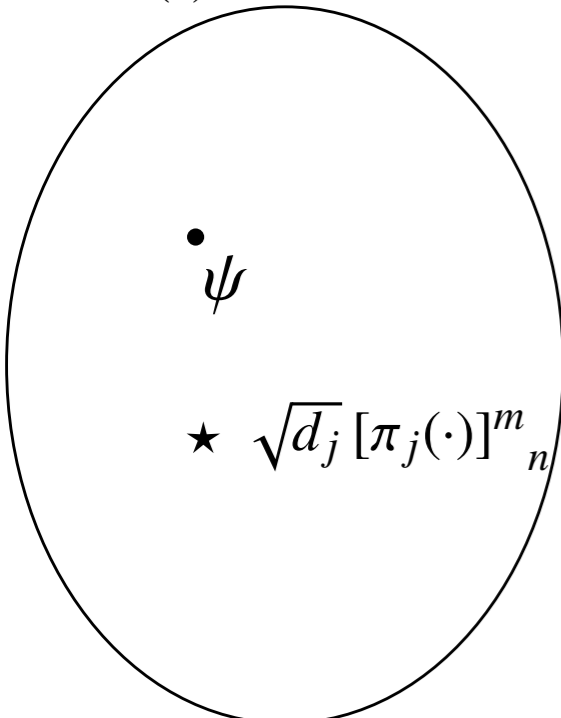
$$[\pi_j(\tau_1)]^m_n = -\frac{i}{2} \sqrt{j(j+1) - m(m-1)} \delta_{m-n,1} - \frac{i}{2} \sqrt{j(j+1) - m(m+1)} \delta_{m-n,-1}$$

$$[\pi_j(\tau_2)]^m_n = -\frac{1}{2} \sqrt{j(j+1) - m(m-1)} \delta_{m-n,1} + \frac{1}{2} \sqrt{j(j+1) - m(m+1)} \delta_{m-n,-1}$$

$$[\pi_j(\tau_3)]^m_n = -im \delta_{m-n,0}$$

The irreducible unitary representation of $SU(2)$ group

$$\mathcal{H}_{SU(2)} = L^2(SU(2), d\mu_H)$$

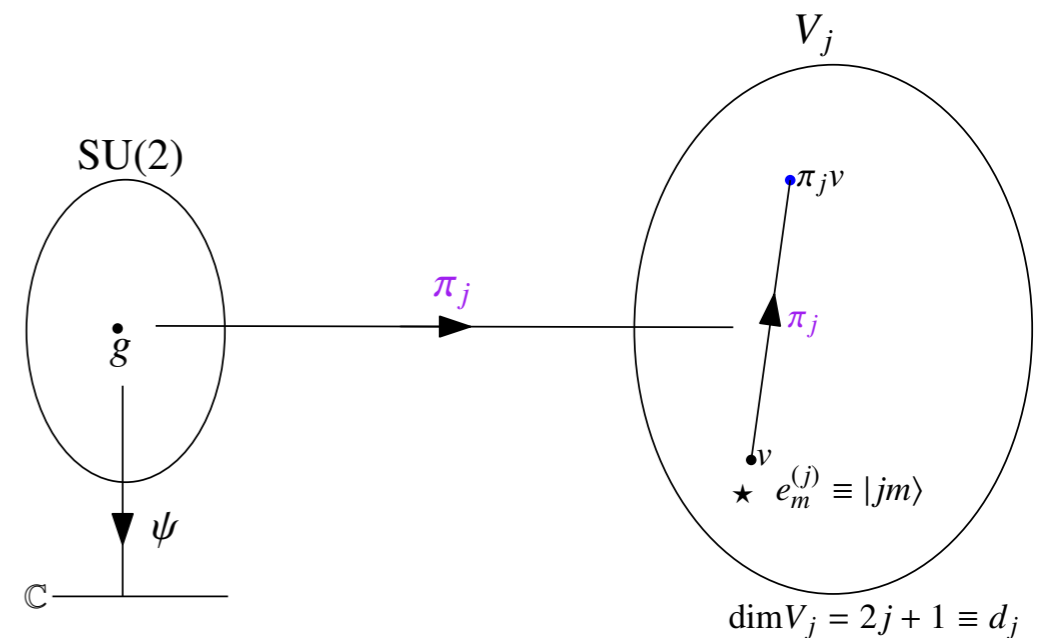


$$\hat{J}^2 [\pi_j(g)]^m_n = j(j+1) [\pi_j(g)]^m_n$$

$$\hat{J}_3^{(R)} [\pi_j(g)]^m_n = -m [\pi_j(g)]^m_n$$

$$\hat{J}_3^{(L)} [\pi_j(g)]^m_n = n [\pi_j(g)]^m_n$$

$$[\pi_j(g)]^m_n = \langle jm | \pi_j(g) | jn \rangle$$



$$\hat{J}_3^{(R)} \langle jm | = -m \langle jm |,$$

$$\hat{J}_3^{(L)} |jn\rangle = n |jn\rangle$$

$$\dim V_j = 2j + 1 \equiv d_j$$

2. Representation theory of a group

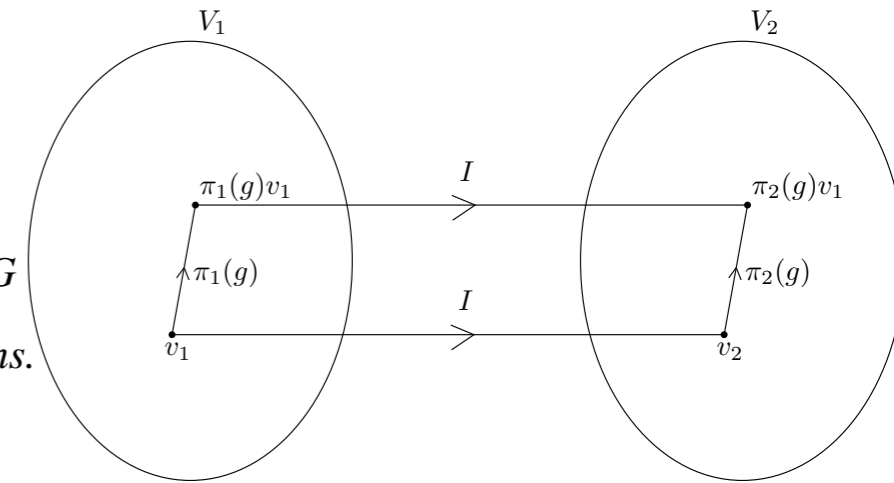
Def. (Equivalent representations & intertwiner). Two representations $\pi_i : G \rightarrow \mathcal{B}(V_i)$, $i = 1, 2$, are called equivalent iff there exists an invertible (unitary) linear map

$$I : V_1 \rightarrow V_2$$

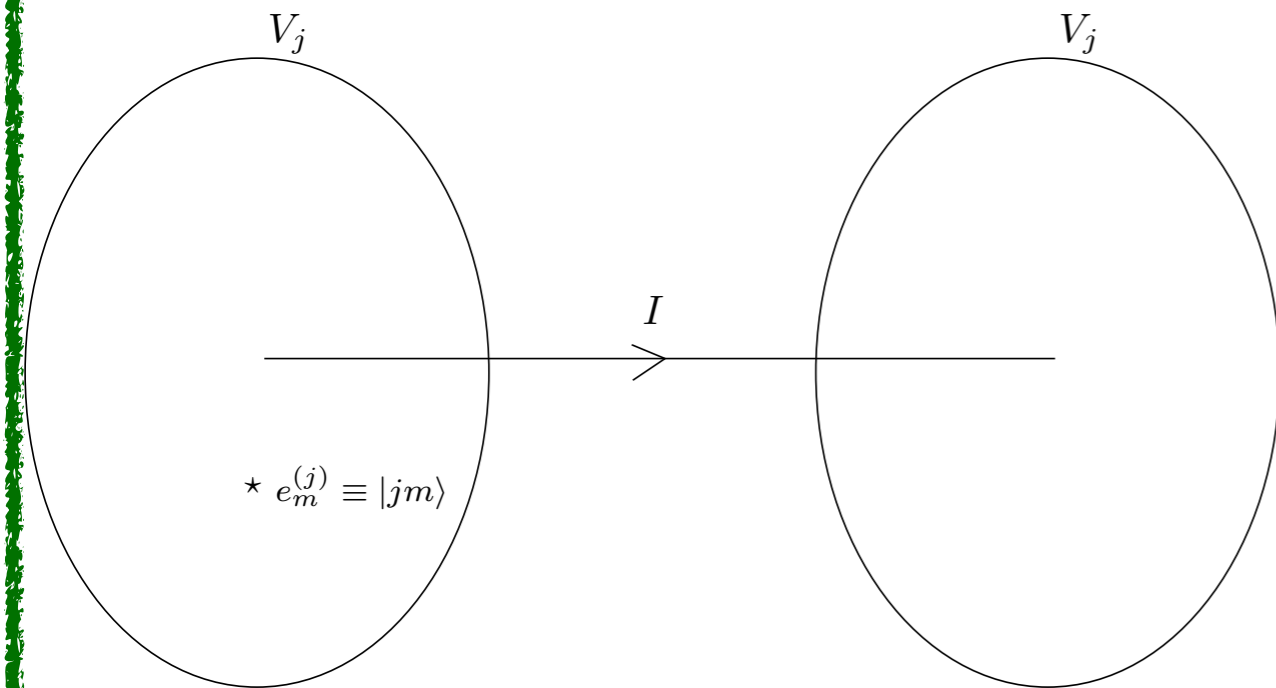
satisfying [it “commutes” with the corresponding operators of the representations]

$$I \pi_1(g) = \pi_2(g) I \Leftrightarrow \pi_1(g) = I^{-1} \pi_2(g) I \Leftrightarrow \pi_2(g)^{-1} I \pi_1(g) = I, \quad \forall g \in G$$

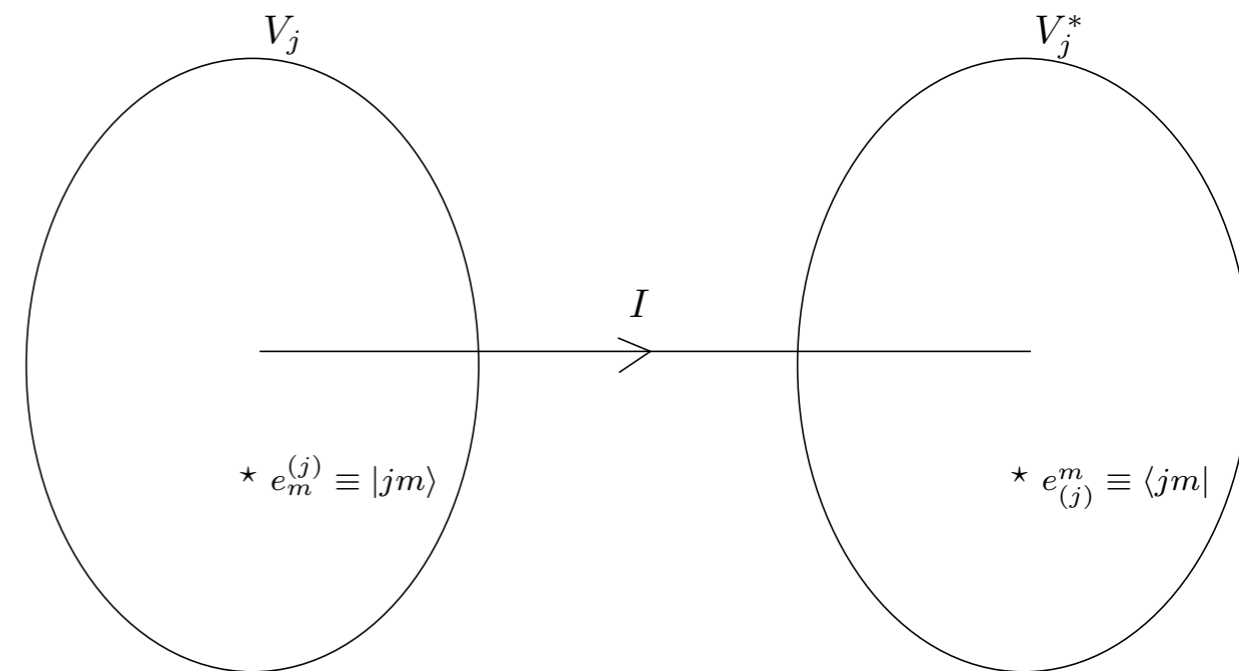
Such a map I is called an intertwiner (intertwining operator, invariant tensor) for these two representations.



Two frequently used intertwiners in irrep. of SU(2)



$$I_{m' m}^m = \delta_{m' m}^m$$



Notation in Wigner's book

$$I_{m' m}^m \equiv C_{m' m}^{(j)} := (-1)^{j-m} \delta_{m, -m'}$$

$$I^{m m'} \equiv C_{(j)}^{m m'} := (-1)^{j-m} \delta_{m, -m'}$$

2. Representation theory of a group

Let $\pi_{j_i} : G \rightarrow \mathcal{B}(V_{j_i})$, $i = 1, 2$, be two irreducible unitary representations of $SU(2)$. Consider the direct product representation:

$$\pi_1 \otimes \pi_2 : G \rightarrow \mathcal{B}(V_1 \otimes V_2)$$

Thm.. *Every finite-dimensional unitary representation is completely reducible.*

Means: The direct product rep. can be written as a direct sum of irreps.

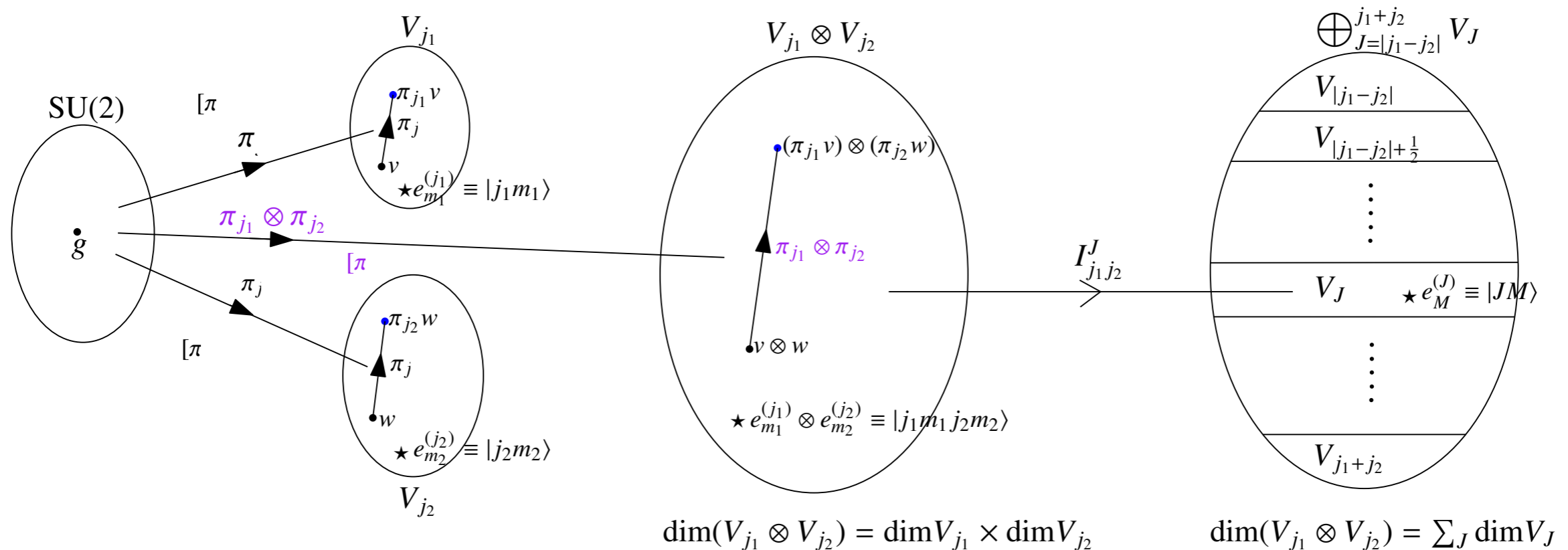
i.e. there exists a bijective intertwiner that maps the tensor product to a direct sum of irreps.

Physics: angular momentum coupling

Mathematics: recoupling theory

$$V_{j_1} \otimes V_{j_2} \cong \bigoplus_J V_J$$

equivlance of reps.



2. Representation theory of a group

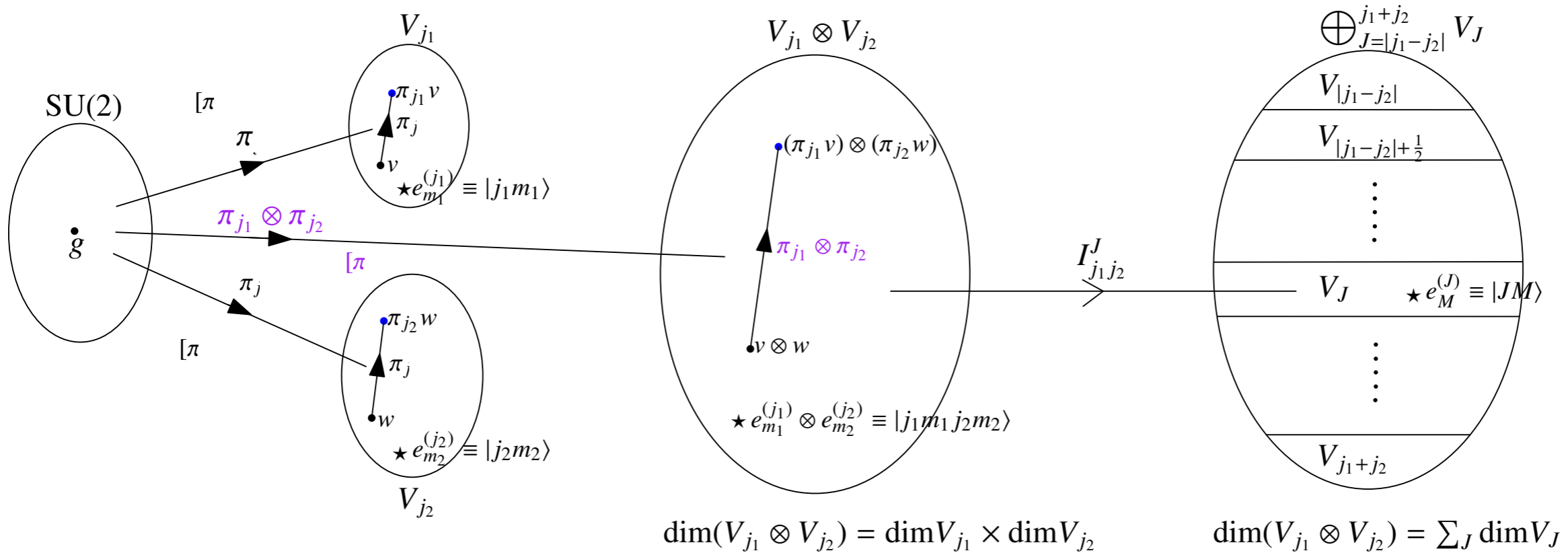
Physics: angular momentum coupling

Mathematics: recoupling theory

Let $\pi_{j_i} : G \rightarrow \mathcal{B}(V_{j_i})$, $i = 1, 2$, be two irreducible unitary representations of $SU(2)$

$$V_{j_1} \otimes V_{j_2} \cong \bigoplus_J V_J$$

equivlance of reps.



The intertwiner:

$$I_{j_1 j_2}^J : V_{j_1} \otimes V_{j_2} \rightarrow \bigoplus_J V_J$$

$$\begin{aligned} e_{m_1}^{(j_1)} \otimes e_{m_2}^{(j_2)} &\mapsto I_{j_1 j_2}^J (e_{m_1}^{(j_1)} \otimes e_{m_2}^{(j_2)}) = \sum_M \langle JM | I_{j_1 j_2}^J | j_1 m_1 j_2 m_2 \rangle e_M^{(J)} \\ &= \sum_M \langle JM | j_1 m_1 j_2 m_2 \rangle e_M^{(J)} \end{aligned}$$

The Clebsch-Gordan coefficients (CGCs) are chosen as real numbers in the Condon-Shortley gauge

$$\langle j_1 m_1 j_2 m_2 | JM \rangle = \langle JM | j_1 m_1 j_2 m_2 \rangle$$

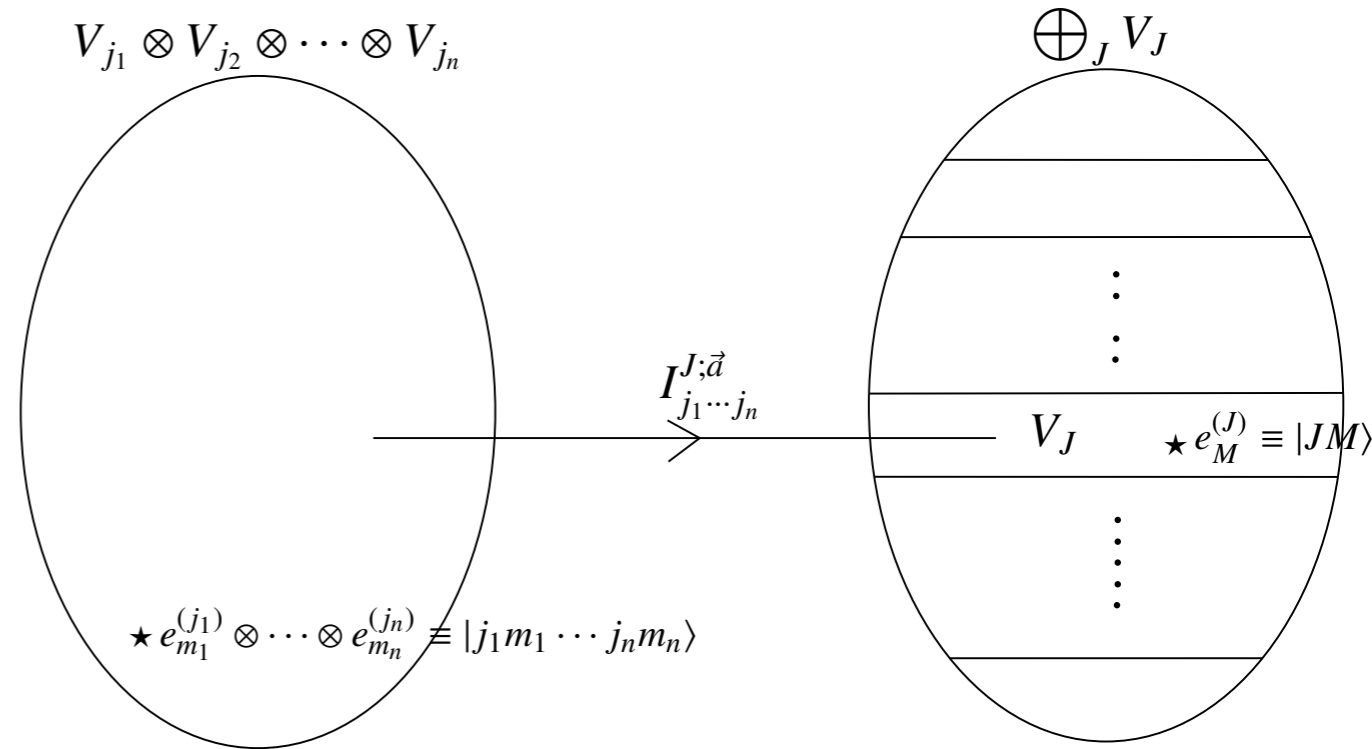
2. Representation theory of a group

Physics: angular momentum coupling

Mathematics: recoupling theory

Let $\pi_{j_i} : G \rightarrow \mathcal{B}(V_{j_i})$, $i = 1, 2, \dots, n$, be n irreducible unitary representations of $SU(2)$

$$V_{j_1} \otimes V_{j_2} \otimes V_{j_3} \otimes \dots \otimes V_{j_{n-1}} \otimes V_{j_n} \cong \bigoplus_J V_J$$



The intertwiner:

$$\left(I_{j_1 \dots j_n}^{J; \vec{a}} \right)_{m_1 \dots m_n}^M = \sum_{k_2, \dots, k_{n-1}} \left(I_{j_1 j_2}^{a_2} \right)_{m_1 m_2}^{k_2} \dots \left(I_{a_i j_{i+1}}^{a_{i+1}} \right)_{k_i m_{i+1}}^{k_{i+1}} \dots \left(I_{a_{n-1} j_n}^J \right)_{m_n}^M$$

$$\langle JM; \vec{a} | j_1 m_1 j_2 m_2 \dots j_n m_n \rangle = \sum_{k_2, \dots, k_{n-1}} \langle a_2 k_2 | j_1 m_1 j_2 m_2 \rangle \langle a_3 k_3 | a_2 k_2 j_3 m_3 \rangle \dots \langle JM | a_{n-1} k_{n-1} j_n m_n \rangle$$

where $\vec{a} \equiv \{a_2, \dots, a_{n-1}\}$ denotes the set of the angular momenta appeared in the intermediate coupling.

The Clebsch-Gordan series: $\pi_{j_1}(g) \otimes \pi_{j_2}(g) \otimes \dots \otimes \pi_{j_n}(g) = (I_{j_1 j_2}^J)^{-1} \pi_J(g) I_{j_1 j_2}^J$

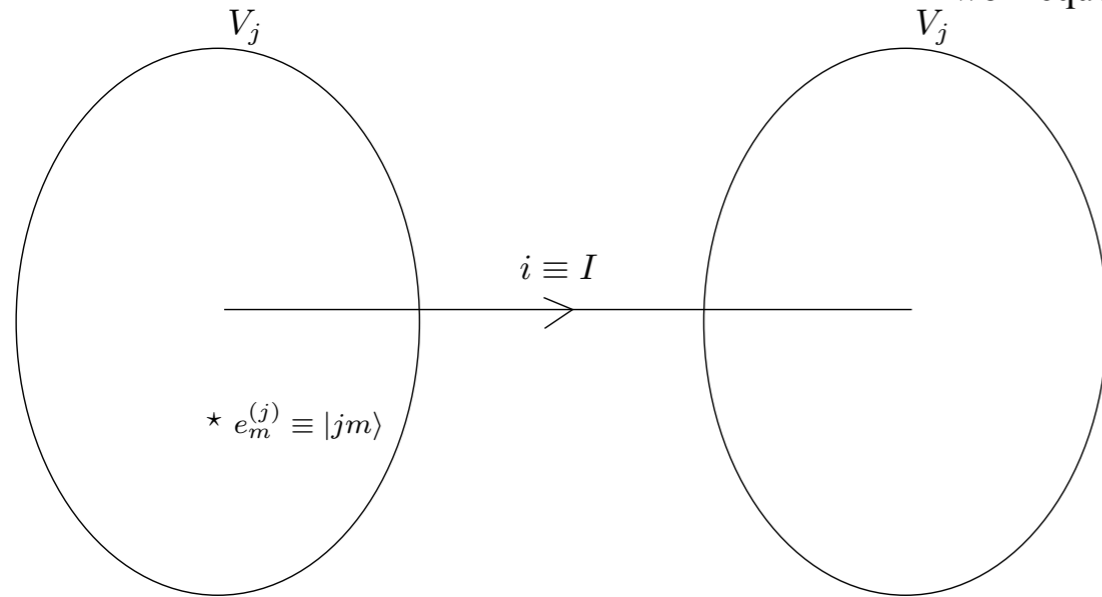
$$[\pi_{j_1}(g)]_{n_1}^{m_1} \dots [\pi_{j_n}(g)]_{n_n}^{m_n} = \sum_{J, M, N} \left((I_{j_1 \dots j_n}^{J; \vec{a}})^{-1} \right)_M^{m_1 \dots m_n} [\pi_J(g)]_N^M \left(I_{j_1 \dots j_n}^{J; \vec{a}} \right)_{n_1 \dots n_n}^N$$

$$\left((I_{j_1 \dots j_n}^{J; \vec{a}})^{-1} \right)_M^{m_1 \dots m_n} = \left((I_{j_1 \dots j_n}^{J; \vec{a}})^\dagger \right)_M^{m_1 \dots m_n} = \left(I_{j_1 \dots j_n}^{J; \vec{a}} \right)_{m_1 \dots m_n}^M$$

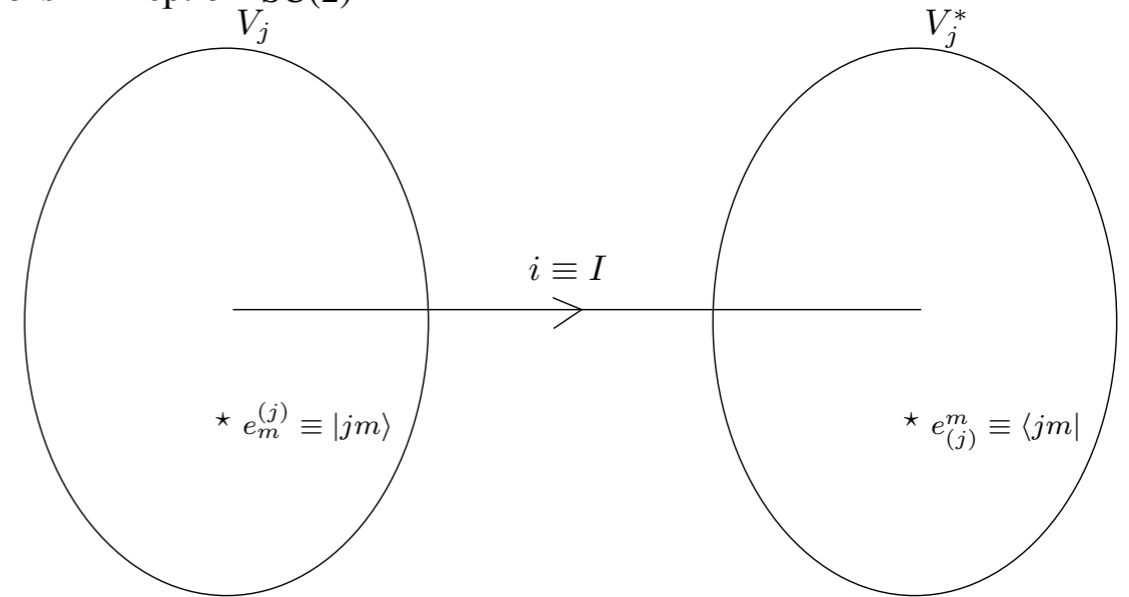
2. Representation theory of a group

To be convenient to be suitable for graphical formula, we induce i to represent intertwiner, instead of I .

Two frequently used intertwiners in irrep. of SU(2)

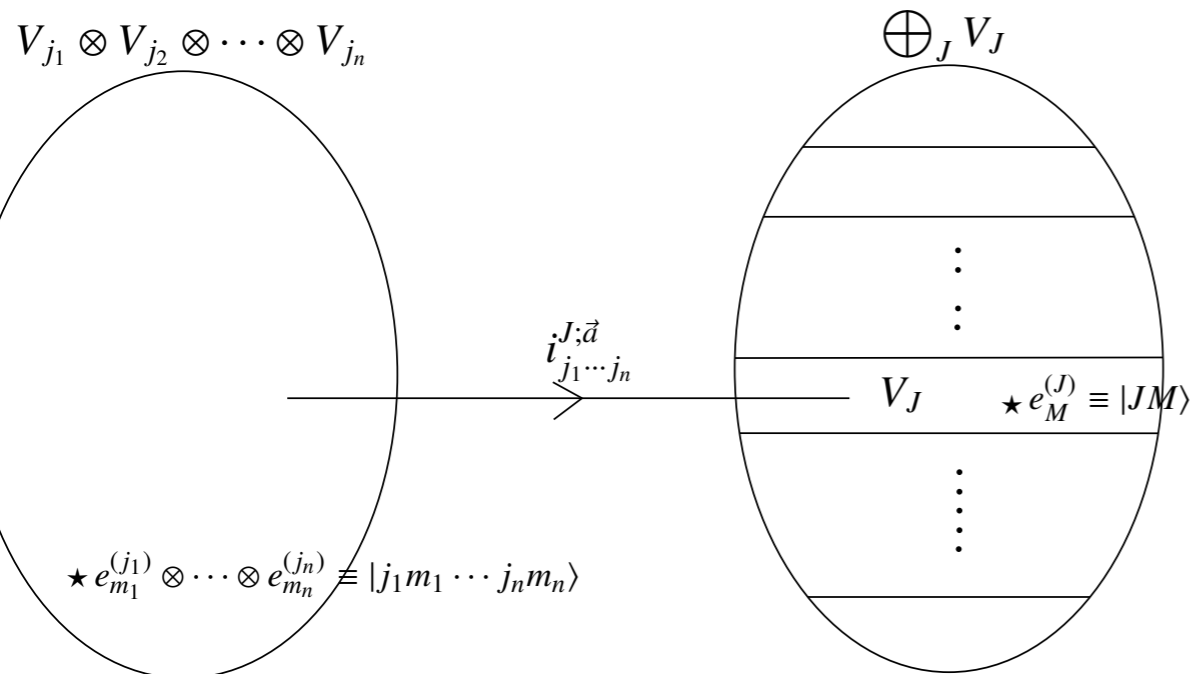


$$i^m_n := I^m_n = \delta^m_n$$



$$i_{m'm} := I_{m'm} \equiv C_{m'm}^{(j)} := (-1)^{j-m} \delta_{m,-m'}$$

$$i^{mm'} := I^{mm'} \equiv C_{(j)}^{mm'} := (-1)^{j-m} \delta_{m,-m'}$$



The intertwiner:

$$\left(i_{j_1 \dots j_n}^{J; \vec{a}} \right)_{m_1 \dots m_n}^M := (-1)^{j_1 - \sum_{i=2}^n j_i - J} \left(I_{j_1 \dots j_n}^{J; \vec{a}} \right)_{m_1 \dots m_n}^M$$

$$= (-1)^{j_1 - \sum_{i=2}^n j_i - J} \langle JM; \vec{a} | j_1 m_1 j_2 m_2 \dots j_n m_n \rangle$$

The Clebsch-Gordan series:

$$[\pi_{j_1}(g)]_{n_1}^{m_1} \dots [\pi_{j_n}(g)]_{n_n}^{m_n} = \sum_{J, M, N} \left(\left(i_{j_1 \dots j_n}^{J; \vec{a}} \right)^{-1} \right)_M^{m_1 \dots m_n} [\pi_J(g)]_N^M \left(i_{j_1 \dots j_n}^{J; \vec{a}} \right)_{n_1 \dots n_n}^N$$

Thanks for your attention!