# Reconstruction

#### >> Event reconstruction <<

The process of interpreting the electronic signals produced in a high-energy physics (HEP) experiment's detector to determine what original particles passed through the detector and their characteristics.

#### >> Event reconstruction <<

- Tracking and Vertexing
  - Hit Point
  - Track Finding
  - $\circ$  Track Fitting
  - Vertex Fitting
- Particle ID
  - Electron and Photon
  - $\circ$  Muon
- Jet Identification
  - $\,\circ\,$  Identification of b-jets

#### **Track Reconstruction**

(Slides are reused from https://indico.tlabs.ac.za/event/112/contributions/3196/attachments/1062/1453/MM\_Tracking\_TIPP\_2023.pdf)

## Tracking Systems in 'Old Days'

At the beginning of particle physics, the techniques for observing particles were developed together with the physical ideas about them. Most techniques were based on optically observing their paths and recording them by photographs.

A first tracking detector was the cloud chamber invented by Wilson in 1910: Particles traverse supersaturated water/alcohol vapor. The e<sup>-</sup>/ion pairs in the track act as condensation nuclei.





#### **Bubble Chambers**

The bubble chamber was invented by D. Glaser in 1952 (NP 1960). Particles traverse a superheated liquid and the deposited energy creates bubbles  $\rightarrow$  Photos are made.



Discovery of the  $\Omega^{-}$  in 1964



**Discovery of Neutral Currents** 

### General Requirements for a Tracking System

Some general statements can be made on general requirements of a tracking system:

- Detect charged particles with high efficiency
- Precise measurement of particle track (direction, origin, etc)
- Momentum measurement
- Determining the sign of the charge, possibly also the charge itself
- Particle identification for example by dE/dx
- Study impact parameter, that is the distance of the track to the expected point of collision
- Robust measurements in environments with many tracks
- Operation for a long time, in particular also able to stand a lot of radiation without aging
- Cheap

Experiment specific requirements will often surpass these.

## **Magnet Field Configurations**

In HEP experiments three field configurations are used:

 Dipole fields
 (for fixed target experiments)





2) Solenoidal fields (for collider experiments)





3) Toroidal fields(for muon system of collider experiment)



#### Track Parameters in B-fields (I)

In magnetic fields, the particle path can be derived starting from the Lorentz force:  $\vec{F}_{Lorentz} = m\dot{\vec{v}} = q\left(\vec{v} \times \vec{B}\right)$ 

Assuming a homogenous B field, which can be directed along the z axis allows to solve for v:

$$\vec{v}(t) = \begin{pmatrix} v_T \cos\left(\eta \omega_B t + \psi_0\right) \\ -v_T \sin\left(\eta \omega_B t + \psi_0\right) \\ v_z \end{pmatrix}$$

with  $\omega_{B} = |q|B/\gamma m$ ,  $\eta = q/|q|$ , and  $v_{T} = \sqrt{v_{x}^{2} + v_{y}^{2}}$ Integration gives

$$\vec{x}(t) = \begin{pmatrix} x_0 + \frac{v_T}{\eta\omega_B}\sin\left(\eta\omega_B t + \psi_0\right) \\ y_0 + \frac{v_T}{\eta\omega_B}\cos\left(\eta\omega_B t + \psi_0\right) \\ z_0 + v_z t \end{pmatrix}$$

=> Helix trajectory with 6 parameters  $x_{o'}$ ,  $y_{d'}$ ,  $v_{t'}$ ,  $\eta$ ,  $\omega_{B'}$ ,  $\psi_{o'}$ 



#### Solenoidal Setup



$$\frac{\sigma(p_T)}{p_T}\Big|^{det} = \frac{p_T}{0.3|z|} \frac{\sigma(x)}{BR^2} \sqrt{\frac{720}{N+4}}$$

1) Momentum resolution improves quadratically with radius

- 2) Momentum resolution improves linearly with the B-field
- 3) Detectors with better spatial resolution helps
- 4) Number of track points also improves the result
- 5)  $\sigma(p)/p$  increases with  $p \rightarrow$  more difficult to measure high energetic tracks

#### Example ATLAS TrackingPerformance

The estimate of  $\left. \frac{\sigma_{p_T}}{p_T} \right|^{det} = 0.0004 \cdot p_T$  fits well with the official detector

requirement of  $\sigma_{_{pT}}$  /p\_{\_{T}} = 0.05% p\_{\_{T}} (GeV/c) + 1%

The additional 1% is given because of the material budget of the inner detectors:



# KF for Track Finding

1) Find a seed track: This is often a combinatorial approach using the 2-3 outermost layers and an inner layers of measurement. The outside is chosen, because tracks are separated and possible combinations are reduced.



- 2) Make a track estimate: Based on the currently available track points and their errors, a prediction is made for hits in the next detector layer.
- 3) Looking for hit: If hit is found, add it to track and update the track prediction for the next layer.



#### Advantages of the KF

It is easy to take detector effects into account

- Energy loss
- Multiple Scattering
- Bremsstrahlung can be accommodated by recognizing the effect and correcting for it in the next step.



A filter can be built, that stores the intermediate results of the filter

 $\rightarrow$  outliers such as noise or hits from close tracks can be identified and removed afterward.

The best parameter estimate can be given at any point.

Because of the flexibility, the algorithm is widely used for tracking objects in real time:

Radar tracking, sonar ranging, satellite orbit computation, automated driving

# CMS Silicon Tracker

- All-silicon design:
  - Allows for high-precision charged particle tracking up to  $|\eta| < 3$ ;
  - Essential in particle identification, heavy-flavour tagging, trigger decisions, vertex reconstruction;
  - Largest Si tracker in the world: ~200 m<sup>2</sup> area, ~135M electronic channels
- Comprised of the Pixel (innermost parts)
  - 4 layers in the barrel (BPix) and 3 disk (FPix) in the forward regions:
    - 1,856 Pixel modules.
- and the Strips sub-detectors (outer parts)
  - 0 10 layers in the barrel (TIB, TOB) and 12 forward disks (TID, TEC):
    - 15,148 Strips modules.



# Track reconstruction in CMS

- Few, but precise measurements;
- Dead material inside the tracker volume
- Main tracking algorithm: Combinatorial Track Finder used in iterative steps:
  - limits the number of combinatorics in pattern recognition
  - tracking reach guaranteed, w/o degrading computing performance





# Track reconstruction in CMS

In each iteration, tracks are reconstructed in four steps:

#### 1. Seeding:

- provides track candidates, with an initial estimate of the trajectory parameters and their uncertainties (use combination of pixel, strip or mixed hits);
- 2. Pattern recognition:
  - hits compatible with the predicted track position are added (Kalman update) to the trajectory and track parameters are updated;

#### 3. Final fit:

- taking into account the B-field non uniformity and a detailed description of the material budget;
- provides the best estimate of the parameters of each smooth trajectory after combining all associated hits (outlier hits are rejected);

#### 4. Selection:

- sets quality flags based on a ML-based MVA with more than 20 inputs;
- o aims to reject fake tracks; tracks sharing too many hits are also cleaned as duplicates;



# The tracking challenge at LHC

- The tracking challenge at the LHC:
  - typically 30 charged particles within the tracking volume acceptance per proton-proton collision
  - and 50-60 collisions per event: O(1500) charged particles per event;
- These need to be reconstructed:
  - o with very high efficiency (>90% for ~GeV in pions)
  - o precise track parameters
  - o very low fake rate: O(~ few %)
  - o quickly (stringent CPU limits)
- Very strong requirements on track reconstruction algorithms
- Track reconstruction is not just about reconstructing charged particles:
  - o used in almost every element of reconstruction



# Summary for Tracking

- Tracking algorithms need to provide high-quality tracks efficiently and with an efficient usage of resources:
  - high tracking and vertexing performance is a must (despite challenging conditions at the LHC);
- To provide more precise and accurate track reconstruction sophisticated algorithms, techniques and calibrations have been developed.

#### **Vertex Reconstruction**

#### **Vertex Reconstruction**

Particles produced in the collision decay fast, but they can fly a certain distance before decaying:

 $I = \beta \gamma c \tau$ 

Particle	m (GeV/ $c^2$ )	au (10 <sup>-12</sup> s)	$I(p_{\rm T}=10{ m GeV})$
$\tau^+$	1.776	0.290	500 µm
$D^0$	1.865	0.410	700 µm
$D^+$	1.869	1.040	1700 µm
$\Lambda_c^+$	2.286	0.200	300 µm
$B_{\rm S}^0$	5.367	1.512	800 µm
$B^+$	5.279	1.641	900 µm
$\Lambda_b$	5.619	1.425	800 µm

# Vertexing

- Vertexing starts from a set of tracks.
- Then proceeds into two steps:
  - Clustering: group together close-by tracks in cluster candidates. The algorithm used is deterministic annealing;
  - Fitting: fit vertex properties of those clusters from those of the tracks. The algorithm used is Adaptive vertex fitting algorithm;
- Vertexing is based on optimizing an energy (assignment) function with a penalization entropy term:
  - Starting at very high temperature (T) all tracks are assigned to one single cluster;
  - As we lower T, splitting the cluster into several becomes beneficial;
  - Iteratively update assignment probabilities P while lowering T provides a final robust estimation of the clusters.



#### Impact Parameter



Impact parameter  $d_{\rho}$  quantifies the mismatch to the primary vertex (PV) The impact parameter significance  $S_{d0} = d_0 / \sigma_{d0}$ serves as selection criterion to distinguish tracks from primary or secondary vertices.

The track as measured by the tracking detectors has to be extrapolated to the vertices. This can be done with

• Linear extrapolation y = a + bx (no magnetic field)

• Quadratic extrapolation  $y = a + bx + cx^2$  (good approximation for helix in B)



Errors on the vertex position  $y_{y}$  is given for linear

approx. by  $\sigma_{d_0} = \sigma_y = \sqrt{\sigma_a^2 + x_v^2 \sigma_c^2}$ 

or for quadratic approx. by

$$\sigma_{d_0} = \sigma_y = \sqrt{\sigma_a^2 + x_v^2 \sigma_c^2 + \frac{1}{4} x_V^4 \sigma_c^2 + x_v^2 \sigma_{ac}}$$

### **Example of Decay Chain**

Identifying the primary vertex (PV), secondary vertex (SV) and tertiary vertex (TV) is important to understand the decay chain of the particle and to reconstruct its mass and life time completely.



#### **Muon Reconstruction**

(Slides are reused from https://indico.cern.ch/event/242419/contributions/520665/attachments/412163/572720/LHCFrance\_MuonReco\_NVranjes.pdf)

#### Muon detectors

#### DT (Drift Tubes)

long drift time (380ns) – low rate reg., wire pitch 4.2cm resolution (per chmber) rφ:100 μm, rθ:150 μm 8φ+4θ layers in station (only φ in MB4)

### RPC

#### (Resistive Plate Chambers)

Fast gaseous det. (~2ns), dedicated for L1 Efficiency >95% @ 1KHz Low noise (<5Hz/cm2), meas. Φ (strip Pitch 0.5-4cm)



#### CSC

(Cathode Strip Chambers) fast response, high rate close wire spacing (res. R75-150 μm) strips 6.7-16mm (res. Φ 150 μm)

#### Algorithms in Muon Detectors

**Local Reconstruction:** Find Track Segments which held information about position and direction of muon crossing one chamber. Track Segments are formed by straight line fit using multi-hit measurements in stations.

**DT:** hit position w.r.t. wire computed from drift time;  $r-\phi$  (8meas.) and  $r-\theta$  (4meas.); direction reconstructed independently and combined into segment

**CSC:** 2D points from wire and strips measurements in plane. Build segment using hits from up to 6 planes

**RPC:** secondary importance in track reconstruction (measure 3d hit only)

#### Stand-Alone Muon Reconstruction

Based on the Kalman Filter Technique Propagation with energy losses, in non-constant magnetic field. Seeding – definition of initial trajectory state.

Online: input (position, momentum) from L1 trigger Offline: global analysis of segments. Seed kinematics is estimated by simple parametrisation of bending in/between segments.

Forward Pattern Recognition (pre-filtering) goes from most inner to outer muon station. Segments compatible with trajectory ( $\chi^2$  based) are collected constraining trajectory state.

Backward Pattern Recognition: Trajectory Fitting: propagating outside-in update trajectory with individual hits from segments ( $\chi^2$  based). Optionally update fit with vertex constraint

### Algorithms in Tracker

#### **Global Muon:**

Define Region of Interest (ROI) which describes supposed track parameters at vertex (based on Stand-Alone Muon reconstruciton and assumed tolerances).

**Offline:** reuse tracks from standard tracker reconstruction Combinatorial Track Finder (CTF) - Kalman Filter based algorithm consisting of global hit based seeding, inside-out pattern recognition, final cleaning, fitting and smoothing (backward fitting).) Select tracks compatible with ROI.

**Online:** run regional tracker track reconstruction in ROI (find pixel hit pairs or triplets which are compatible with ROI). Standard tracker CTF, customized cleaning.

Match tracker tracks to Stand-Alone Muon (check trajectory compatibility on intermediate surface). Refit track using hits from Tracker Track and Stand-Alone Muon.

#### Tracker Muon

(offline only, alternative to start with Stand-Alone Muon)

Reuse tracks from standard tracker reconstruction For each track combine muon signatures (energy in calorimeters, segment crossed by extrapolation, discance from chamber edges)

Flag track as Tracker Muon if track has MIP signal in calorimeter or at least one matched muon segment

# Alignment

The structure of the CMS detector is not rigid:

- 1-3 cm deformation due to magnetic field
- 5-15 mm due to gravity (weight)
- 500 µm due to changes in temperature and humidity

Reconstruction requires a precise knowledge of the location of the detector components

(ex. In order not to degrade momentum measurements in muon system: 200  $\mu$ m in the r- $\phi$ ).

#### Alignment scenarios:

Ideal: assumes a perfectly placed detector
 Startup: our best estimate of

•Startup: our best estimate of alignment at day one

• Long-term: our expectation of improved knowledge with data

CMS strategy for alignment is based on:

- Optical system
- Tracking (from collisions, cosmics, halo)

#### **Electron & Photon Reconstruction**

# **Definition of Calorimeter**

- In particle physics a calorimeter is a detector measuring the energy carried by an incoming particle
  - Instrumented blocks of matter in which the particle interacts and deposits all its energy in the form of a cascade of particles
- The particle energy is measured in eV (MeV-GeV-TeV 10<sup>6</sup>, 10<sup>9</sup>, 10<sup>12</sup> eV)
  - 1 eV = energy acquired by one electron accelerated by 1 V
  - The temperature effect of a 100 GeV particle in 1 litre of water (at 20 °C) is ΔT = 3.8×10<sup>-12</sup> K



https://doi.org/10.1007/978-3-319-47999-6\_53-

### **General Features of Caloremeters**

- Calorimetry is a "destructive" method
  - The energy is measured by **total absorption** of the particle
- A calorimeter **converts** the **energy** of an incident particle to a **detectable signal**, proportional to the incoming energy
- Calorimeters can measure the energy of **electromagnetic radiation** (electrons, photons) or **hadronic particles** (charged pions, protons, neutrons)
- The **charged component** of the **particles' cascade** deposits energy in the active part of the calorimeter and it is **detected** in the form of **charge or light**
- This talk is mainly focused on **electromagnetic calorimeters**



https://doi.org/10.1007/978-3-319-47999-6\_53-

### **Particle-Matter Interactions**

- In matter electrons and photons loose energy interacting with nuclei and atomic electrons
- Main photon interactions with matter:
  - Photoelectric effect
  - Compton scattering
  - Pair production
- Main electron interactions with matter:
  - Ionization
  - Bremsstrahlung
  - Čerenkov radiation
  - Multiple scattering





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At colliders interesting electrons and photons have usually E > 1 GeV



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  - Čerenkov radiation
  - Multiple scattering

These **processes** are the **basis** of the **electromagnetic shower** 





Bremsstrahlung



# **Electromagnetic Shower**



- Electrons and photons create a **cascade** (shower) **of particles**
- Number of particles N
  - Is proportional to the energy of the incoming particle
  - Increases until the energy of the electron component falls below E<sub>c</sub> (critical energy ~ 5-10 MeV)
- With E < E<sub>c</sub> a slow decrease in number of particles occurs as electrons are stopped and photons absorbed
- Longitudinal extension of the shower is proportional to ln(E/ E<sub>c</sub>)

### **Electromagnetic Shower**



The evolution of an electromagnetic shower through a material is dictated by:

#### • Radiation length (X<sub>0</sub>) :

- Mean distance in which an electron will lose all but 1/e of its energy
- 0.78 of mean free path of a photon (photon showers will start later)

#### • Moliere radius (*M<sub>R</sub>*):

- 90% of shower's energy is contained within a cylinder of radius = 1 MR
- 2  $M_R$  contain 95% of its energy

#### Calorimeter's Design Characteristics

- Size of the detector: the longitudinal depth of the detector is dictated by X<sub>0</sub> and is driven by the required resolution
  - **Small X**<sub>0</sub> allows to reduce calorimeter size (compactness)
- **Cell size**: typically chosen such that 70-80% of energy of a centrally incoming particle is deposited in the cell, while having energy in the neighbouring cells large enough to measure the centre of gravity coordinates
  - Related to **M**<sub>R</sub>
- Granularity: size of detector elements in the transverse and longitudinal direction, which determines the ability to resolve two showers induced by nearby particles as distinct. It depends on the shower size, distance from the interaction point and transverse size of detector elements/cells



## LHC Requirements for Calorimeters

- **Fast response** (25 ns or faster) and **high granularity**, to reduce pile-up induced noise
- **Radiation-hard** detectors and electronics
- Hermetic and cover the full azimuthal angle and rapidity range, to tag very forward jets and well measure the missing energy
- Excellent electromagnetic energy resolution
  - To detect the two photon decay of an intermediate mass Higgs (golden channel together with H→ZZ →4I)



Courtesy of C. Mariotti

# **ECAL Energy Reconstruction**

- Energy in the ECAL observed as a pulse as the photons from the shower arrive over time
  - This pulse shape is converted to an energy (E ∝ A, signal channel amplitude)
- In case of out-of-time pile-up events, multiple pulses from different bunch crossings are generated
  - They lead to an **apparent increased** amplitude measurement
- The amplitudes of different pulses are resolved by fitting the multiple pulse shapes simultaneously





#### **Electron and Photon Reconstruction**



- First step is **to construct individual particles** from the reconstructed energy deposits (clustering)
- The clustering procedure looks for local maxima above a given threshold (1 GeV)
  - Energies between overlapping adjacent clusters are shared

# **Clustering of Crystals Energy**



- Found **5 clusters** in this region of the ECAL
- Each one represents the energy deposits of a particle (electron/photon)
- In practice **not** this **clean**: often clusters have a very large number of crystals with small energy fraction

### Superclusters



- An electron or photon when it arrives to ECAL, may be accompanied by multiple secondary particles created through interactions with matter on the way to ECAL
- **Superclustering** (clustering on clusters) aims to **combine** the individual electrons and photons **into a single object**, corresponding to the original electron/photon
- It starts by taking the highest energy cluster (in this case the light blue one) and looks for compatible clusters

# **Electron Track Reconstruction**

- Electrons leave a signal in both tracker and calorimeter
- Electron tracks have changing curvature because of radiative energy loss due to bremsstrahlung
- A **dedicated tracking algorithm** known as GSF tracking is used to take into account these changes in the curvature
- Used to associate additional bremsstrahlung radiation and photon conversion tracks to the supercluster





Courtesy of S. Harper

#### Courtesy of S. Harper

### **Refined Superclusters**



Recover of a very soft bremsstrahlung photon into the **refined supercluster** 

• **Refined superclusters** use the information from the **tracker**, to be able to link bremsstrahlung emissions to missed ECAL deposits and reject some clusters which are highly incompatible with its matched tracks

# **Energy Corrections**

- Energy deposited by electrons and photons in the ECAL and collected in superclusters is subject to losses
  - Energy lost in gaps
  - Large amount of material upstream of the calorimeter
  - Calorimeter measurements more sensitive to pileup than tracking.
- To calibrate the reconstructed energy back to generated energy a correction procedure is needed
  - Based on simulation
  - Uses machine learning techniques
  - Applied on data and MC



EGM-17-001

#### **Reconstruction Performance**

#### **Electron reconstruction**

efficiency is higher than 95% for E<sub>T</sub>> 20 GeV and is compatible between data and simulation within 2%



EGM-17-001

## **Electron and Photon Identification**

- Several variables are developed to separate electrons/photons from background (jets, photon conversions, particles from secondary vertices)
- They exploit that electrons/photons are **single objects** which are almost fully **contained** in the **ECAL**
- Many different types:
  - Shower-shape variables
  - Track matching variables
  - Conversion ID variables
  - Isolation variables



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- Many different types:
  - Shower-shape variables
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  - Isolation variables

Is there a large amount of other particles nearby the electron/photon? Are the energy deposits in
the calorimeters compatible with coming from a single electron/photon?

Does the ECAL deposit have a compatible track?

Are the tracks compatible with coming from the collision point? Or do they appear later on in the tracker?

# Shower Shape Variables: $\sigma_{i\eta i\eta}$

- $\sigma_{inin}$  is one of the **most important** electron/photon **ID variables** in CMS
- It measures the **spread** of an electromagnetic shower **along ieta** direction
- A **5x5 array of crystals** is the area where an electron/photon is almost **fully contained**



### Shower Shape Variables: H/E

- H/E is the ratio of the hadronic energy to the electromagnetic energy
- Excellent ID variable used in electron and photon identification
- Very well modelled in simulation



## Conversion ID Variables: R<sub>9</sub>

- **5x5 matrix** contains 96.5% (97.5%) of **unconverted photon energy** in EB (EE)
- R<sub>9</sub> is the energy sum of the 3×3 crystals centred on the most energetic crystal in the supercluster divided by the energy of the supercluster
- $R_9$  helps in **conversions identification** and to distinguish real photons from  $\pi_0$





#### Jet Reconstruction

#### **Event Reconstruction**



**1.** Build muon candidates (not shown), tracks, and calorimetry clusters

**2.** Link tracks and the calorimetry clusters based on spatial proximity

3. Identify 'charged hadron candidates' among the links by associating calorimetric energy to track momenta, when tracks are close
4. 'photon' and 'neutral hadron' candidates from excess energy

#### Particle Flow Event Reconstruction







- $\bullet$  Reconstruct charged/neutral hadrons,  $\gamma, e^\pm$  ,  $\mu^\pm$
- fully exploit tracking resolution and fine ECAL granularity
- optimal combination of track and calorimetry resolution



#### Particle Flow Event Reconstruction

	detector	Tracker	ECAL	HCAL	Muon	
	quantity	P <sub>T</sub> (Trk)	E <sub>ECAL</sub>	E <sub>HCAL</sub>	Ρ <sub>Τ</sub> (μ)	p <sub>T</sub> and E reconstructed by
	algorithm	fit	cluster	cluster	fit	
	object	reconstruction				
١.	muon	$\checkmark$	X	X ( except ∼IGeV MIP)	$\checkmark$	ʻglobal' fit of tracker- and muon-track
2.	electron	~	~	X	×	fit, dominated by p <sub>T</sub> (Trk) at low energy, ECAL at high energy
3.	charged hadron	$\checkmark$	~	$\checkmark$	×	track-p <sub>T</sub> and $E_{ECAL}$ , $E_{HCAL}$ linked to track
4.	photon	Х	1	X	×	E <sub>ECAL</sub> (not linked to track or HCAL)
5.	neutral hadron	X	~	$\checkmark$	×	E <sub>ECAL</sub> + E <sub>HCAL</sub> energy that was not linked to a track

 $\checkmark$  required  $\checkmark$  allowed  $\thickapprox$  not expected/ignored at this step  $\bigstar$  vetoed

### Jet Clustering

Event reconstruction provides list of particle candidates

- Need to correlate 'sprays' of particles from hadronization (jets) with the initial partons of the hard scatter event
- This is done by "sequential" jet clustering algorithms:
  - Identify seeds and devise a recursive procedure to associate other particles until the whole event is clustered
  - Controlled by an angular distance measure e.g. AR=0.4 ('slim' jets) or 0.8/1.0/1.2 ('fat' jets) that defines the angular size of the jets



### Jet Clustering

The parton shower is governed by QCD and contributes many soft and collinear particles

• Collinear splitting & soft ('infrared') particles shouldn't change jets

Jet 'catchment' area should be a disk of radius  $\Delta R$  in  $\Delta \eta$ ,  $\Delta \varphi$  coordinates, even in dense environment of many pile-up particles

Anti- $k_T$  algorithm satisfies all criteria!

- I. Select a cone size R (e.g. R=0.4)
- 2. For particle i, compute all distances d<sub>ij</sub> and d<sub>iB</sub>.

 $d_{iB} = \frac{1}{p_{Ti}^2}, \qquad d_{ij} = \min\left(\frac{1}{p_{T,i}^2}, \frac{1}{p_{T,j}^2}\right) \frac{\Delta R_{ij}^2}{R^2} \qquad \begin{array}{c} \mathsf{p_T}^{-2} \text{ prefers early merge} \\ \text{of close & energetic particles} \end{array}$ 

- If a pair (ij) has smallest distance in d<sub>ij</sub>, merge & add momenta. Repeat step 2.
- 4. Otherwise label jet, remove from list, start again with 2. until fully clustered.

Desired properties of jet clustering algorithms:



### Jet Algorithms



#### Jet Substructure



# **Tagged Jets**

• in many physical processes, b-quarks play a crucial role Displaced • e.g. t→bW with BR≈100% Tracks b-quarks hadronize into B-hadrons Secondary B-hadrons have a finite life time Vertex displaced particles are clustered in jet b (or c) Identify b-jets by the properties of the decay products d B-hadron with ~5 GeV mass Primary Vertex • large life-time  $c\tau \approx 450 \mu$ m, at E=70 GeV:  $\beta \gamma c\tau \approx 5$ mm displaced vertex identified by finding tracks that cross at • charged large impact parameter Lxv. do

Jet

neutral

particles

particles

• ~3 tracks at the displaced vertex

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•

- potentially a lepton at the displaced vertex
- potentially tertiary vertex (B-meson decay to charmed hadron  $c\tau \approx 120-310\mu$ m)
- all information is used in MVA classifier: typically find 60% at 1% mistag •

## Pile-Up Cleanup

- There are 10-40 pile-up (PU) collisions at each bunch crossing
  - Need to remove particles from PU collisions
- Vertices with charged particles are identified, and the most energetic one (leading vertex) is associated with a 'hard scatter'
- Remove all charged particles without association to the leading vertex
  - 'Charged hadron subtraction'
  - Neutral particles have no vertex association).
- Now proceed with jetclustering
  - neutral hadrons and photons from pile-up are a problem. How can it be tackled?



- charged hadron/e/ $\mu$  from hard scatter
- charged hadron/e/ $\mu$  from pile-up
- neutral hadron or photon
- particle in a jet
  - pile-up collision
  - k hard scatter

# Summary

Event reconstruction is a very rich topic. It combines particle interactions, detector knowledge, computing, algorithms, machine learning etc.

Event reconstruction is based on identification and reconstruction of individual objects such as tracks, vertices, electrons, photons, jets.

Data analysis is possible thanks to these objects.