



A common framework for real-time structured data communication in fusion devices

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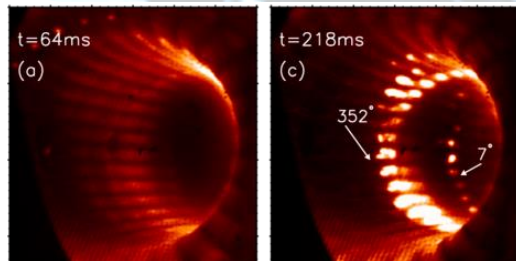


Fig. 1: RFX-mod, an RFP confinement device

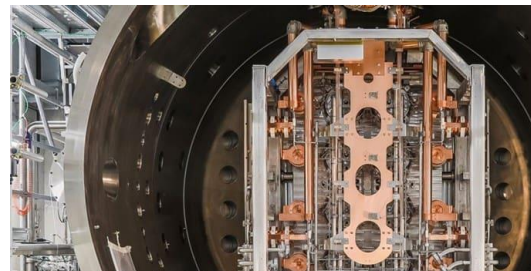


Fig. 2: SPIDER, the linear accelerator for ITER

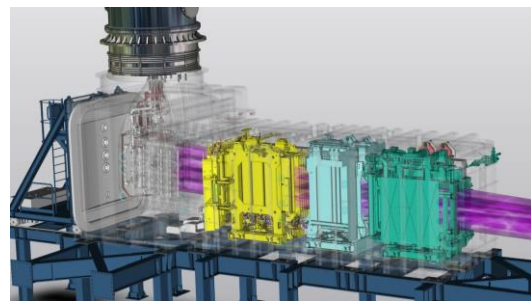


Fig. 3: MITICA, the 1:1 NBI prototype for ITER

1. At Consorzio RFX we host **three main experiments**:

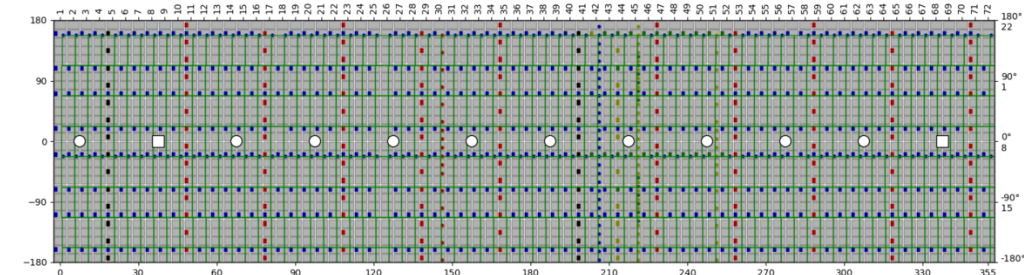
1. RFX-mod2
2. SPIDER
3. MITICA

2. To drive these experiments we use **MARTe2 + MDSplus + MATLAB/Simulink®**

- a. MARTe2: C++ real-time framework
- b. MDSplus: fast data storage and management
- c. MATLAB/Simulink: algorithm design and simulation

3. This mix is/will be/was also used JET, TCV, COMPASS, SPARC, DTT [and ITER]

4. They were exchanging **only unstructured/plain** signals and parameters:



```
+IOGAM_MDSReader2 = {
  Class = MDSWriter
  InputSignals = {
    // ===== triaxial pickups (poloidal) set 2 =====
    BP_1102 = { Type = float64 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1102_Qual = { Type = uint8 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1106 = { Type = float64 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1106_Qual = { Type = uint8 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1110 = { Type = float64 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1110_Qual = { Type = uint8 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1114 = { Type = float64 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1114_Qual = { Type = uint8 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1118 = { Type = float64 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1118_Qual = { Type = uint8 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1122 = { Type = float64 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1122_Qual = { Type = uint8 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1126 = { Type = float64 NumberOfElements = 1 DataSource = MDSReader2 }
    BP_1126_Qual = { Type = uint8 NumberOfElements = 1 DataSource = MDSReader2 }
    // ... to be continued (this configuration files is 2600 lines long)
  }
}
```

1. We develop a modular and flexible set of tools to provide **structured data communication** in a popular PCS configuration in fusion devices
2. With structures, the experimental data:
 - a. remains tidy, easy to maintain and fast to consult
 - b. is less error-prone
 - c. implicitly carries additional information about each dataset
3. Structured data allows the workflow in fig. 4
 1. ML/S to MDSplus: custom APIs
 2. MDSplus to MARTe2: MARTe2 component
 3. Direct communication between ML/S and MARTe2 is also possible
4. **Conclusions:** this work
 1. bridges the architectural gaps between software
 2. establishes a unified framework from design to discharge
 3. enhances data integrity and metadata retention without sacrificing real-time performance
 4. provides a robust, scalable foundation essential for handling the increasing data complexity of next-generation fusion devices

```
+Types = {  
  Class = ReferenceContainer  
  +Triaxi_Signals_t = {  
    Class = IntrospectionStructure  
    BP_Signal = { NumberOfElements = {1} Type = float64 }  
    BP_Qual   = { NumberOfElements = {1} Type = uint8   }  
  }  
}  
+IOGAM_MDSReader2 = {  
  Class = IOGAM  
  InputSignals = {  
    // ===== triaxial pickups (poloidal) set 2 =====  
    BP_Signals_Struct = { Type = Triax_Signals_t NumberOfElements = 72 DataSource = MDSReader2 }  
  }  
}
```

Fig. 4: the same configuration now takes 1 line!

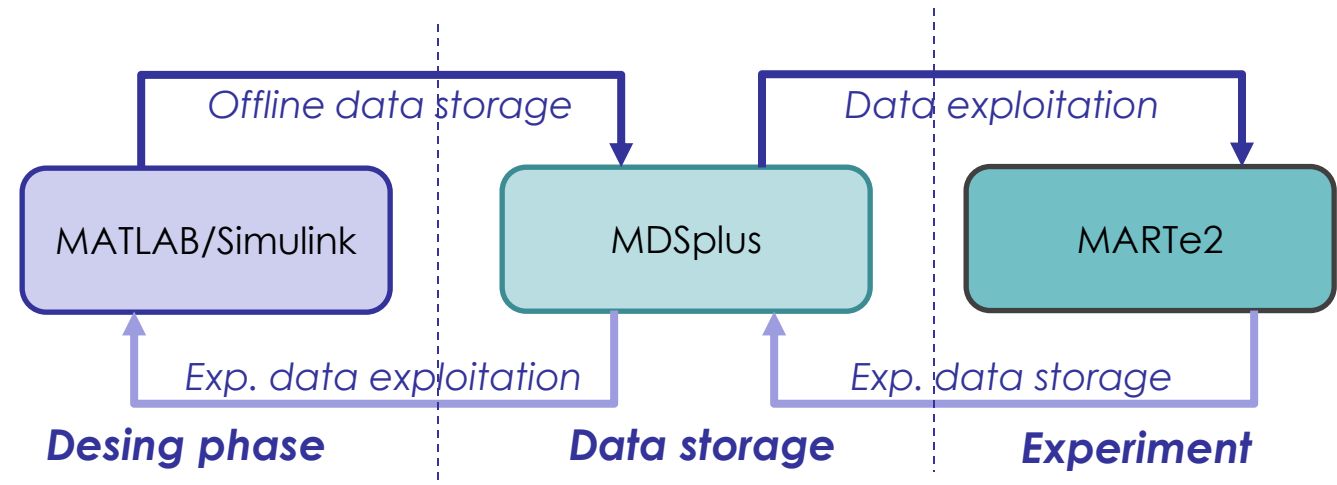


Fig. 5: Workflow allowed by structured data