

# MDSplus Redis Based Distributed Dispatcher for ITER Neutral Beam Test Facility

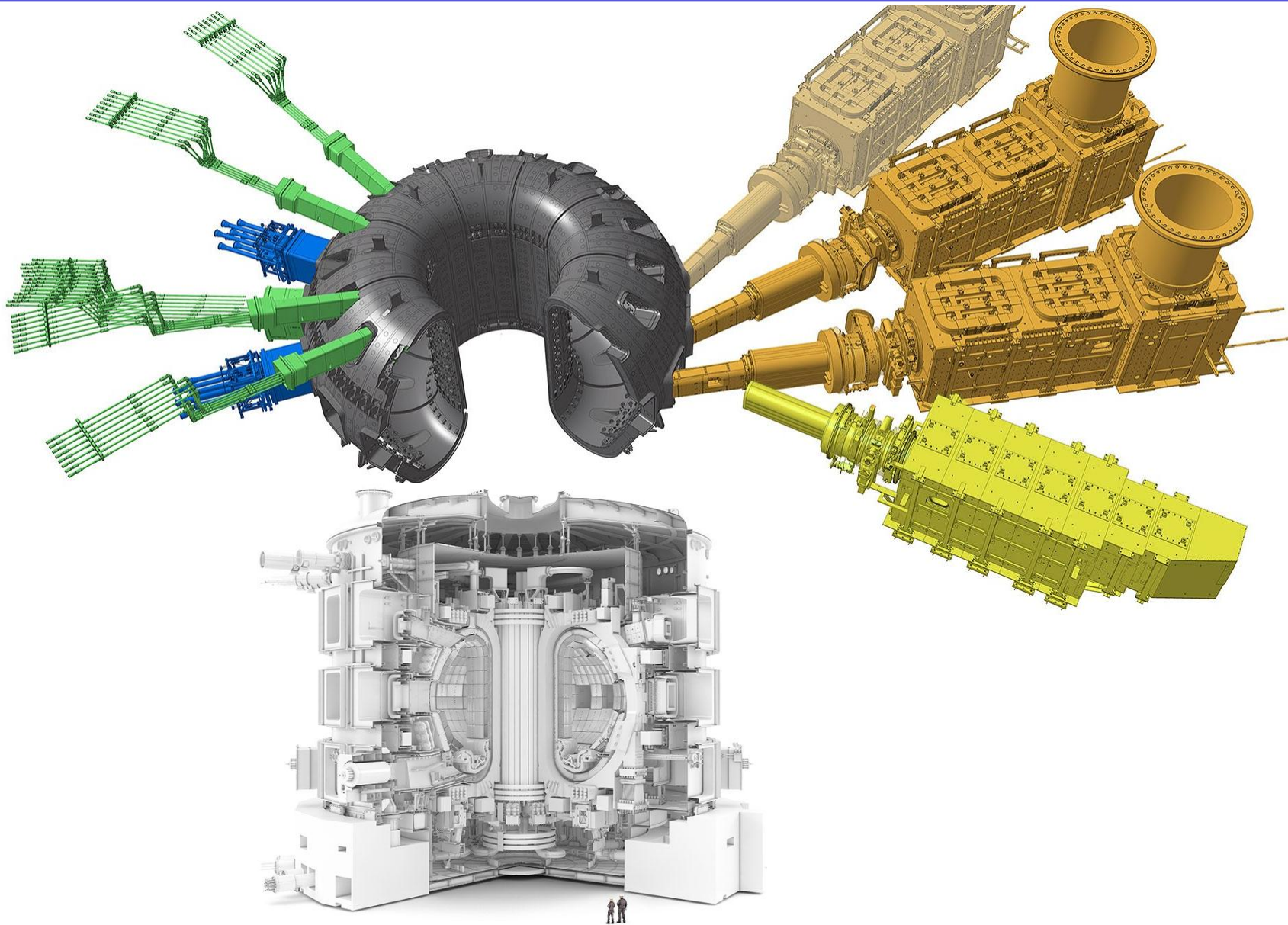
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25<sup>th</sup> IEEE NPSS Real Time Conference  
25–29 May 2026  
La Biodola - Isola d'Elba



## External Heating in ITER

- ITER will use several external heating methods at the same time:
  - **Electron cyclotron resonance heating system**
  - **Ion cyclotron resonance heating system**

## Neutral beam injection system

- ITER will use **two heating neutral beam injectors**:
  - Each provides **16.5 MW** of heating power.
  - Space is reserved for a possible third injector.
- A separate **Diagnostic Neutral Beam Injector**.

The ITER Neutral Beam Test Facility (NBTF) serves as a crucial testing ground for the development and validation of neutral beam injection systems essential for ITER's fusion power plant.



P. Sonato et al. *Fus. Eng. Des.*, 84 (2009), pp. 269-274  
V. Toigo et al. *New J. Phys.* 19 (2017) 085004

## SPIDER (Source for Production of Ion of Deuterium Extracted from Rf Plasma)

- Focuses on the development and optimization of the ion source.
- Responsible for producing and accelerating the deuterium ions.
- Serves as a prototype for the ion source planned for use in ITER.

## MITICA (Megavolt ITER Injector and Concept Advancement)

- Adds to the ion source technology by integrating high-energy beam acceleration.
- Aims to demonstrate the full-scale neutral beam injection system.
- Will be utilized in ITER for plasma heating, diagnostic, and control.

From a control-system perspective, these experiments are extremely demanding, involving several distributed servers, synchronized actions, real-time coordination, fault management, and continuous monitoring.

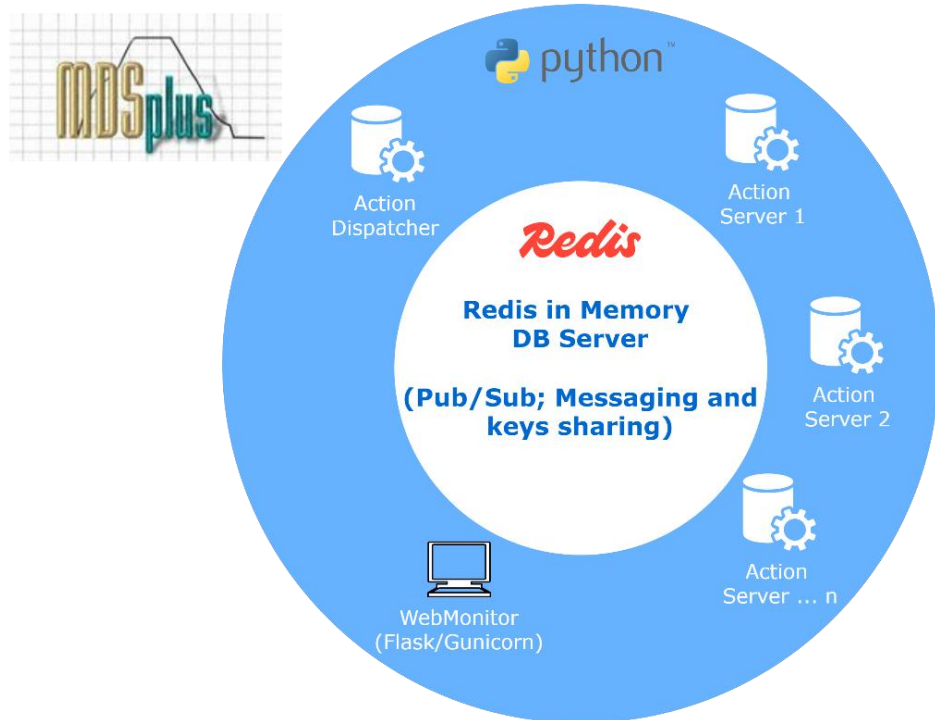
A dispatcher system is critical for managing a complex, distributed environment of an experiment. Its primary roles include:

- **Centralized Supervision and Coordination:** It supervises the execution of actions across various actors, ensuring that the entire system follows the experimental sequence.
- **Synchronization of Distributed Servers:** It ensures that multiple action server instances coordinate their work, specifically making sure all actions with a lower sequence number are completed before moving to the next number.
- **Effective Load Sharing:** It allows multiple instances of the same server class to share the workload by picking actions from a shared list, ensuring tasks are distributed rather than concentrated on one server.
- **Dependency Management:** It handles the logic for "triggered" or conditional actions, ensuring they only execute once their specific prerequisites (dependencies) are met.
- **System Safety and Oversight:** It provides vital mechanisms for monitoring **action timeouts** and processing **abort requests** if a task becomes jammed or an experiment needs to stop.
- **Operation Monitoring:** Provides operators with **real-time visibility** into the status of every action across the distributed network

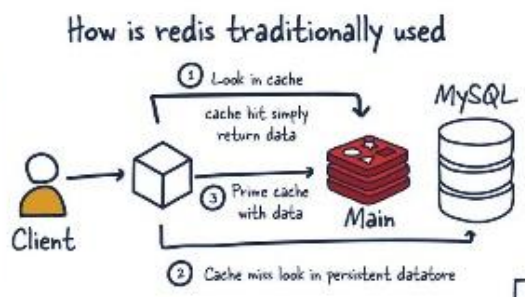
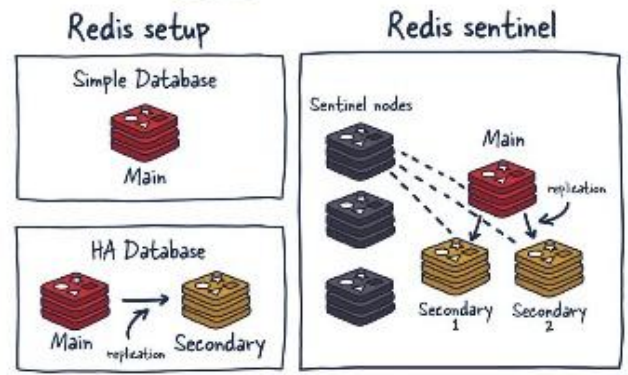
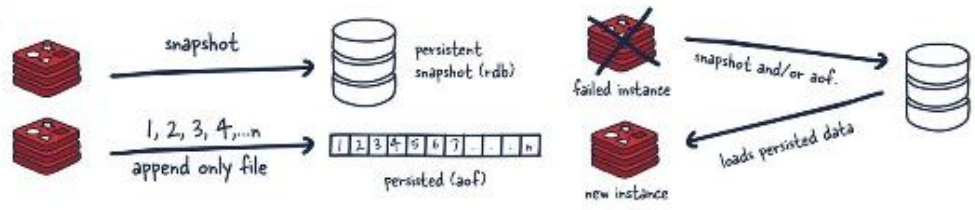
The new MDSplus Redis Dispatcher was developed to address several bottlenecks and functional gaps in MDSplus Dispatcher:

- **Blocking on Asynchronous Actions:** In the previous system, the dispatcher would wait for the termination of actions tagged as asynchronous, which caused unnecessary delays in the experimental workflow.
- **Centralized Dispatcher Dependency:** The old system relied on a central dispatcher entity to manage all tasks. The new architecture is "**dispatchless**", meaning action servers are now more autonomous.
- **Lack of Native Streaming Support:** The previous dispatcher supported **classic action execution**. Streamed actions—which allow for continuous method loops (init, step, finish)—were introduced with the new Redis-based version.
- **Synchronization and Race Conditions:** The new implementation specifically addresses potential **race conditions** using the REDIS mechanism to ensure that multiple servers do not attempt to execute the same action at the same time.
- **Improved Monitoring Technology:** Moved to a web-based Web Monitor improving real-time, browser-accessible, and highly reactive status updates.

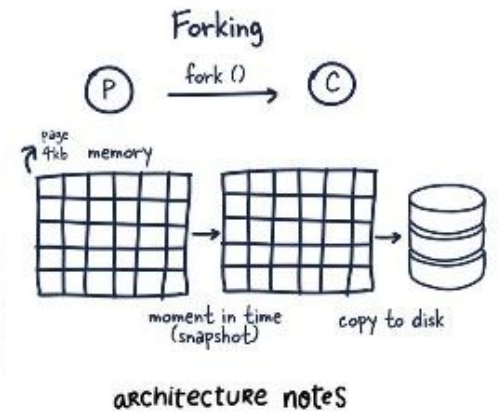
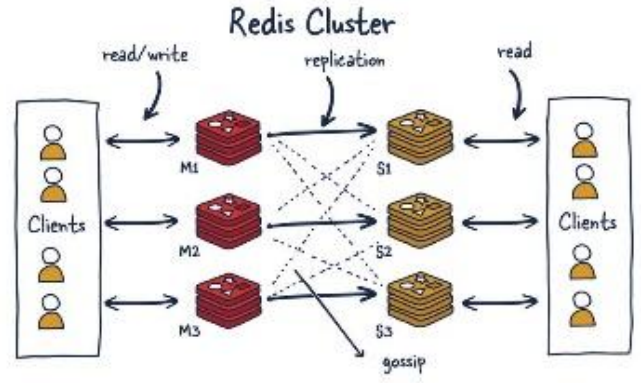
- **MDSplus acts as the data backbone**, storing experiment data, signals, and configuration information.
- **Action Dispatcher coordinates execution**, deciding which actions must run and in what order, **triggers tasks** to the available Action Servers and manages execution flow.



- **Redis is used as an in-memory coordination hub** for fast communication between components.
  - **Redis Pub/Sub handles event distribution**, so updates and triggers can be broadcast in real time.
  - **Redis shared keys provide lightweight state sharing**, allowing components to exchange status, flags, and control values.
- **Action Servers execute the workload**, with multiple workers available for parallel or distributed processing.
- **WebMonitor provides a live operational view** through a Flask/Gunicorn web interface.
- **Scalable architecture**, with additional Action Servers added as the workload grows.
- **Improved responsiveness, flexibility, and maintainability:**
  - **Design separates control, messaging, and execution,**
  - **All environment developed in Python**



**KEY**  
foo bar  
**VALUE**



- hello world String
- 011011010110111101101101 Bitmap
- {23334}[6634720][916] Bitfield
- {a: "hello", b: "world"} Hash
- [A>B<C] List
- {A<B<C} Set
- {A1, B:2, C:3} Sorted set
- {A: (50.1, 0.5)} Geospatial
- 01101101 01101111 01101101 Hyperlog
- [id]=binlogseq(l: "foo", a: "bar") Stream

Redis architecture fits the needs of real-time distributed control systems:

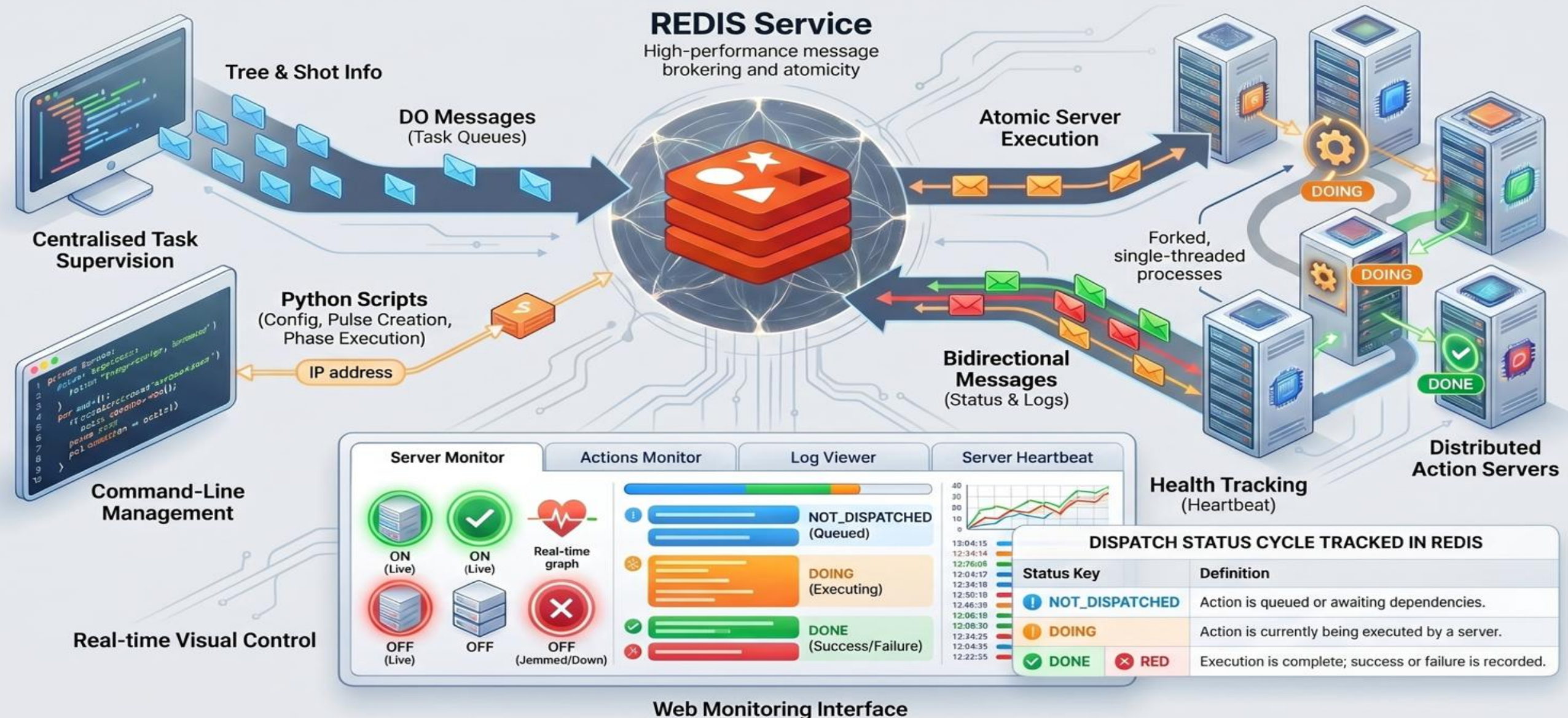
- In-memory operation provides low latency and high throughput
- Supports data structures (hashes, lists, sets, streams) for:
  - Task queues
  - System states
  - Priorities
  - Data synchronization

- Redis Pub/Sub - efficient event-driven communication
- Persistence and recovery mechanisms - robustness and fast failure recovery
- Lightweight design and strong Python integration simplified development

Redis acts not only as a message broker, but as the synchronization and coordination backbone of the dispatcher framework

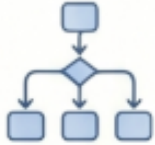
The Redis powerful capacity of handling data explained. Courtesy of Mahdi Yusuf (<https://architecturenotes.co/redis/>)

# MDSplus Redis Dispatcher Architecture



## Action Dispatcher

### Internal Table Building



Builds internal structures to identify all actions required for the specified tree, shot and phase.

### Command Initiation



**Processes DO\_PHASE**  
Triggers the Action Servers execution using Redis PUB/SUB channel

## Redis Server

### PUB/SUB

#### ACTION\_SERVER\_PUBSUB

Signals servers to check task lists  
Broadcasts DO message alert to all subscribed Action Servers



#### ACTION\_DISPATCHER\_PUBSUB

Signals servers completion feedback to the Dispatcher

### HASHES

#### ACTION\_INFO

Real-time updates to the current actions status



#### ACTION\_LOG

Stores the latest screen output STDOUT of executed actions for log monitoring

### LISTS

#### ACTION\_SERVER\_TODO



**Queue of actions for a server class**  
Ensures tasks are popped atomically after PUB/SUB notification to servers.

## Action Servers

### Action Server Execution



**Atomic Task Retrieval**  
After receiving DO signal repeatedly pops tasks from to do list until empty.

### Feedback and System Update



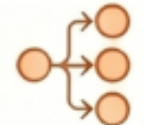
**Update State Hashes and Completion Info**  
Publishes message with tree shot, status and logs after child process completion.

### Forked Process Execution



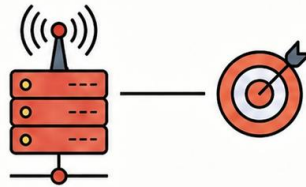
Actions are executed by forked, single threaded processes with SIGALARM managing timeouts

### Triggers Dependent Actions



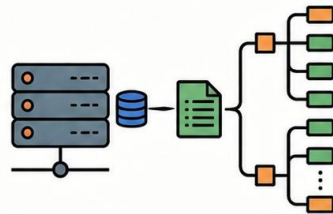
Automatically dispatches sequences for dependent actions when the completed action was a prerequisite.

## REDIS Sends BUILD\_TABLES Command



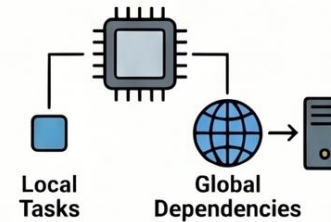
The command is broadcast via REDIS pubsub channels to the Action Dispatcher.

## Server Reads MDSplus Tree



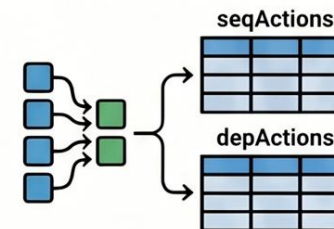
The server accesses the MDSplus Tree to collect all relevant action and timing information.

## Map Local and Global Triggers



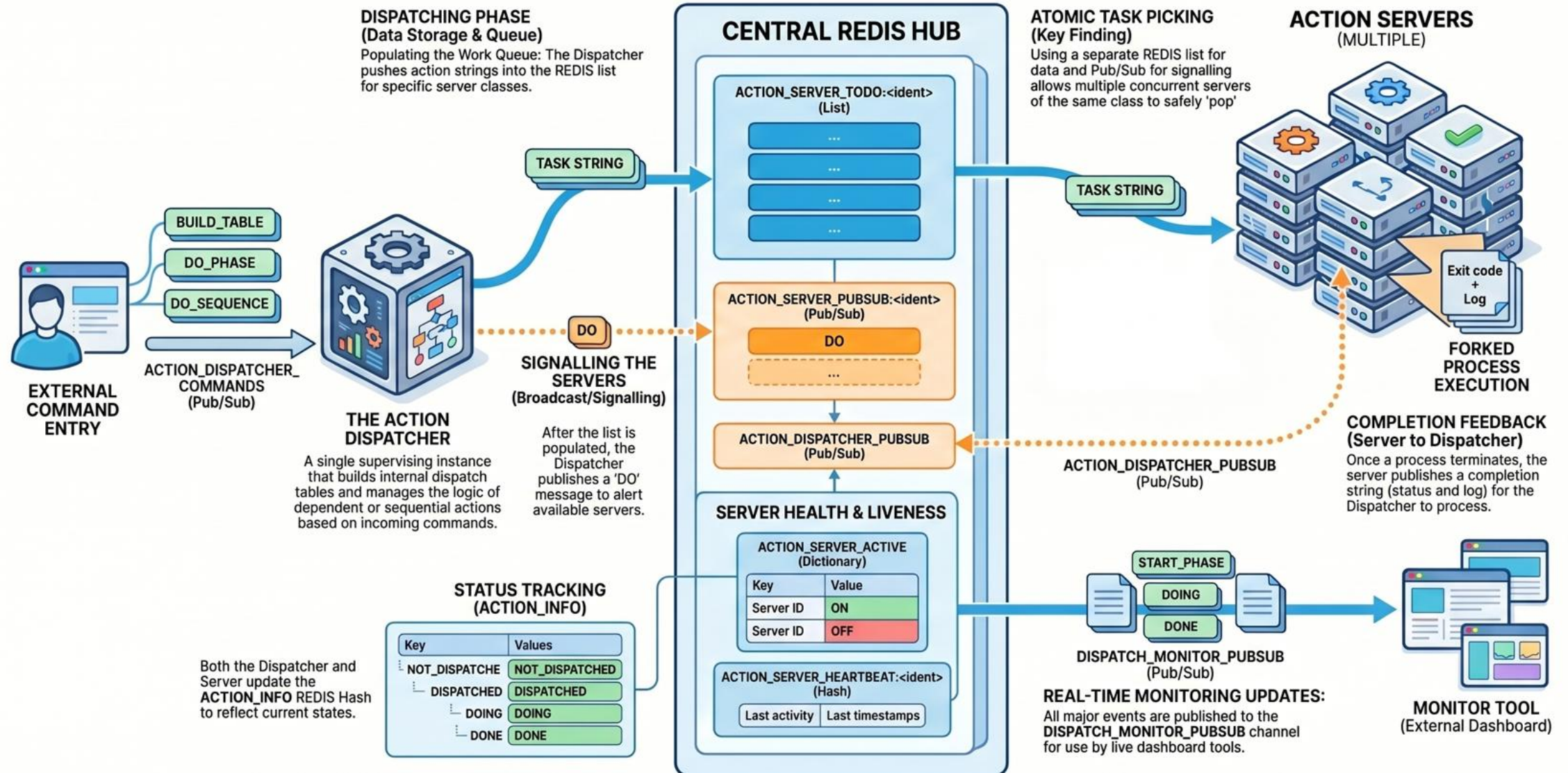
The system identifies **local tasks** and **dependencies** that will trigger other servers.

## Populate Internal Python Tables



Data is stored in structures like **seqActions** and **depActions** to manage future execution steps.

# MDSplus Redis Dispatcher Execution Flow



Server Monitor    Actions Monitor    Log Viewer    Server HeartBeat

### Redis Server Status Monitor (Live)

Server Key	Status	Controls
NEUTRON_SERVER	ON	<input type="button" value="Start Server"/> <input type="button" value="Quit Server"/> <input type="button" value="Restart Server"/> <input type="button" value="Kill Server"/>
SA_SERVER	ON	<input type="button" value="Start Server"/> <input type="button" value="Quit Server"/> <input type="button" value="Restart Server"/> <input type="button" value="Kill Server"/>
TIMING_SERVER	ON	<input type="button" value="Start Server"/> <input type="button" value="Quit Server"/> <input type="button" value="Restart Server"/> <input type="button" value="Kill Server"/>
AGPS_CAEN_SERVER	OFF	<input type="button" value="Start Server"/> <input type="button" value="Quit Server"/> <input type="button" value="Restart Server"/> <input type="button" value="Kill Server"/>
AGPS_NI_SERVER	OFF	<input type="button" value="Start Server"/> <input type="button" value="Quit Server"/> <input type="button" value="Restart Server"/> <input type="button" value="Kill Server"/>
BCM1_SERVER	OFF	<input type="button" value="Start Server"/> <input type="button" value="Quit Server"/> <input type="button" value="Restart Server"/> <input type="button" value="Kill Server"/>
BCM2_SERVER	OFF	<input type="button" value="Start Server"/> <input type="button" value="Quit Server"/> <input type="button" value="Restart Server"/> <input type="button" value="Kill Server"/>
BCM3_SERVER	OFF	<input type="button" value="Start Server"/> <input type="button" value="Quit Server"/> <input type="button" value="Restart Server"/> <input type="button" value="Kill Server"/>
BCM4_SERVER	OFF	<input type="button" value="Start Server"/> <input type="button" value="Quit Server"/> <input type="button" value="Restart Server"/> <input type="button" value="Kill Server"/>
BCM5_SERVER	OFF	<input type="button" value="Start Server"/> <input type="button" value="Quit Server"/> <input type="button" value="Restart Server"/> <input type="button" value="Kill Server"/>

## Server Monitor

- Real-time view of registered action servers
- Displays server ON/OFF state
- Automatic live status refresh
- Active servers prioritized at the top
- Start, restart, quit and kill controls from the interface

**Actions**

**Redis Action Status Monitor**

Active actions: 44
Dispatched: 13
Doing: 0
Done: 13
Success: 12
Failed: 1
Aborted: 0
Unknown: 0

**Redis Action Status Monitor - Current Phase**

Tree	Shot	Server	Node	State	Status	Phase	Controls
SPIDER	1234	TIMING_SERVER	\SPIDER::TOP.CODAS.TIMING:DIO4_2:INIT_ACTION	DONE	Failure	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	AGPS_NI_SERVER	\SPIDER::TOP.PLANTS.POWER.AGPS.ACQUISITION:NI6259_2:INIT_ACTION	SERVER_OFF	NotExecuted	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	AGPS_NI_SERVER	\SPIDER::TOP.PLANTS.POWER.AGPS.ACQUISITION:NI6368_1:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER	\SPIDER::TOP.PLANTS.POWER.ISEPS.TIMING:DIO4_1:INIT_ACTION	SERVER_OFF	NotExecuted	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER	\SPIDER::TOP.PLANTS.POWER.ISEPS.ACQUISITION:NI6368_1:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER	\SPIDER::TOP.CODAS.CONFIG:PLFE_1:INIT_ACTION	SERVER_OFF	NotExecuted	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER	\SPIDER::TOP.CODAS.ACQUISITION:NI6259_1:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER	\SPIDER::TOP.PLANTS.POWER.ISEPS.ACQUISITION:NI6259_1:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER_1	\SPIDER::TOP.PLANTS.POWER.ISEPS.ACQUISITION:NI6368_3:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER_1	\SPIDER::TOP.PLANTS.POWER.ISEPS.ACQUISITION:NI6368_4:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER_1	\SPIDER::TOP.PLANTS.POWER.ISEPS.ACQUISITION:NI6368_2:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	MARTE_SERVER	\SPIDER::TOP.PLANTS.POWER.ISEPS.CONTROL_NEW:MARTE2:INIT	SERVER_OFF	NotExecuted	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	MARTE_SERVER	\SPIDER::TOP.CODAS.TIMING:CODAS_DIO4:INIT_ACTION	SERVER_OFF	NotExecuted	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	NEUTRON_SERVER	\SPIDER::TOP.CODAS.TIMING:NE_CRDS_DIO4:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	SA_SERVER	\SPIDER::TOP.PLANTS.POWER.ISEPS.SETUP:STREAM_1:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	TIMING_SERVER	\SPIDER::TOP.CODAS.TIMING:DIO4_1:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	TIMING_SERVER	\SPIDER::TOP.CODAS.TIMING:DIO4_3:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	TIMING_SERVER	\SPIDER::TOP.CODAS.TIMING:EVENT_REC:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>

**Redis Action Status Monitor -All Phases**

Tree	Shot	Server	Node	State	Status	Phase	Controls
SPIDER	1234	ISEPS_NI_SERVER	\SPIDER::TOP.CODAS.ACQUISITION:NI6259_1:INIT_ACTION	DONE	Success	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER	\SPIDER::TOP.CODAS.ACQUISITION:NI6259_1:START_ACTION	NOT_DISPATCHED	none	READY	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER	\SPIDER::TOP.CODAS.ACQUISITION:NI6259_1:STOP_ACTION	NOT_DISPATCHED	none	POST_PULSE_CHECK	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER	\SPIDER::TOP.CODAS.ACQUISITION:NI6259_1:WAIT_ACTION	NOT_DISPATCHED	none	POST_PULSE_CHECK	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>
SPIDER	1234	ISEPS_NI_SERVER	\SPIDER::TOP.CODAS.CONFIG:PLFE_1:INIT_ACTION	SERVER_OFF	NotExecuted	INIT	<input type="button" value="Dispatch"/> <input type="button" value="Abort"/> <input type="button" value="Logs"/>

## Actions Monitor

- Monitors action execution in real time
- Groups actions by tree and shot

## Action Controls

- Dispatch and Abort individual actions
- Inspect execution logs stored in Redis
- Send global Commands, Dispatch and Build Tables

## Colour-Coded Status Indicators

## Live Summary Panel

- Failed actions
- Aborted actions
- Success
- Overall execution progress

Server Monitor   Actions Monitor   **Log Viewer**   Server HeartBeat

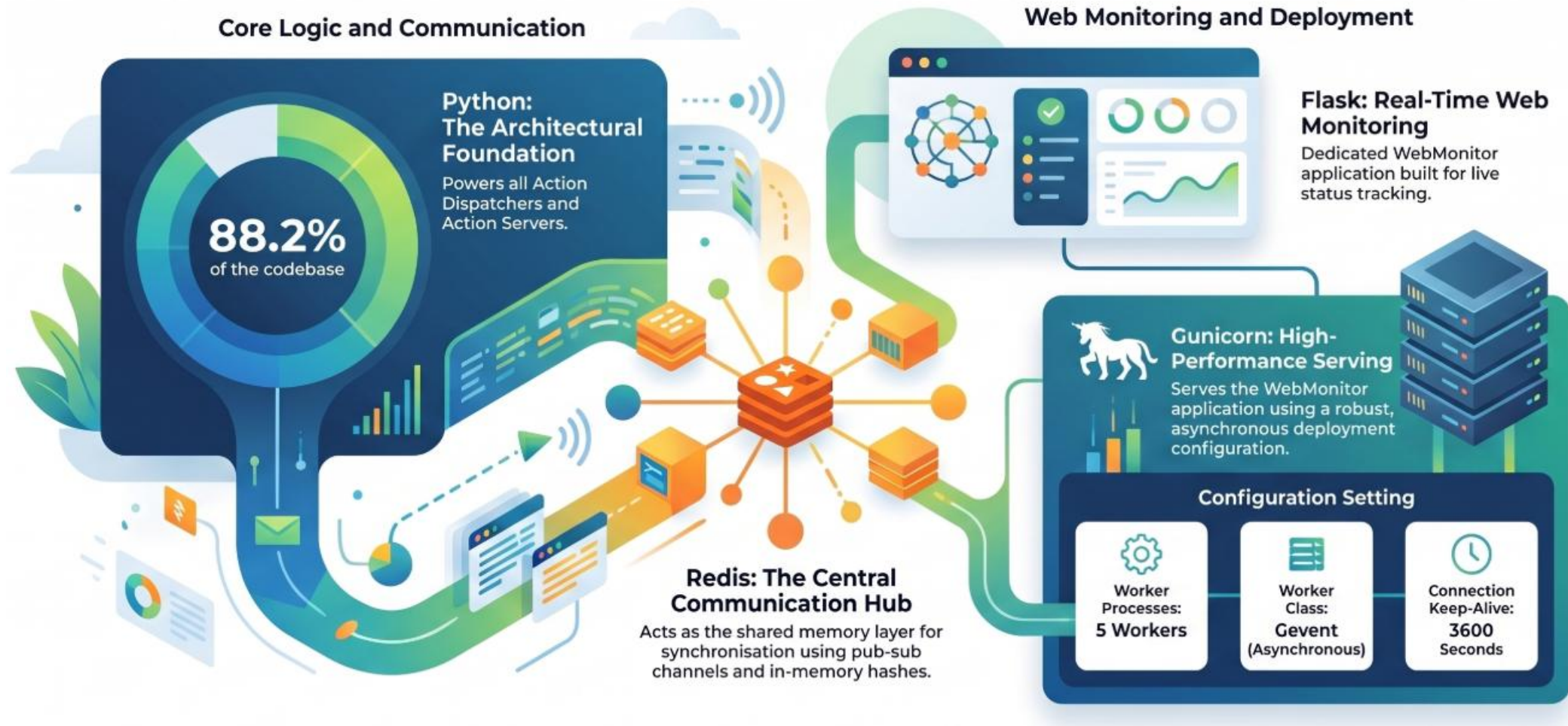
**Add to Log - Debugging**

**Live Log Viewer**

```
2025-10-20 17:34:36 - Running shell command: sh server_command.sh AGPS CAEN SERVER START &
2025-10-20 17:41:00 - Running shell command: sh server_command.sh AGPS CAEN SERVER START &
2025-10-20 17:41:12 - Running shell command: sh server_command.sh ISEPS NI SERVER 1 START &
2025-10-20 17:41:13 - Running shell command: sh server_command.sh ISEPS NI SERVER START &
2025-10-20 17:41:31 - Running shell command: sh server_command.sh ISEPS NI SERVER START &
2025-10-20 17:41:35 - Running shell command: sh server_command.sh ISEPS NI SERVER 1 START &
2025-10-20 17:43:04 - Running shell command: sh server_command.sh BCM1 SERVER START &
2025-10-20 17:43:30 - Running shell command: sh server_command.sh BES1 SERVER START &
2025-10-20 17:43:32 - Running shell command: sh server_command.sh CAMERA SERVER START &
2025-10-20 17:43:49 - Running shell command: sh server_command.sh PXI SERVER START &
2025-10-20 17:44:02 - Running shell command: python dispatcher_command.py soserver.nbtf.server_quit ISEPS_NI_SERVER_1_1 &
2025-10-20 17:44:35 - Running shell command: sh server_command.sh ISEPS NI SERVER 1 START &
2025-10-20 17:44:38 - Running shell command: sh server_command.sh ISEPS NI SERVER 1 START &
2025-10-20 17:48:36 - Running shell command: sh server_command.sh AGPS CAEN SERVER START &
2025-10-20 17:48:50 - Running shell command: sh server_command.sh BCM1 SERVER START &
2025-10-20 17:50:31 - Running shell command: sh server_command.sh BCM2 SERVER START &
2025-10-20 17:51:30 - Running shell command: sh server_command.sh BCM4 SERVER START &
2025-10-20 18:01:22 - Running shell command: sh server_command.sh AGPS CAEN SERVER START &
2025-10-20 18:01:43 - Running shell command: sh server_command.sh AGPS CAEN SERVER START &
```

## Log Viewer

- Real-time application log streaming
- Centralized view of runtime logs
- Submit test log messages for debugging
- Supports additional server-side log integration
- Useful for debugging and system verification



**Node.js and React were replaced by Flask for a unified Python technology stack that helps improving long-term maintainability and deployment simplicity.**

- **Shift to a “dispatchless” Architecture:** The system has transitioned from a fully centralized dispatcher to a more distributed model where autonomous **Action Servers** derive their own execution logic.
- **REDIS-Powered Synchronization:** The architecture leverages **REDIS in-memory hashes** for real-time status tracking and **Pub/Sub channels** for efficient command broadcasting across distributed actors.
- **Atomic Concurrency Control:** The implementation of the **REDIS “watch” mechanism** ensures thread safety and prevents race conditions, allowing multiple server instances to share the workload without duplicating tasks.
- **Support for Streamed Actions:** The new system introduces native support for **streamed actions** (utilizing init, step, and finish method loops), expanding capabilities beyond the classic execution modes.
- **Improved Experimental Efficiency:** By removing the requirement to wait for the termination of **asynchronous actions** before ending a phase, the new dispatcher reduces idle time during experiments.
- **Enhanced Real-Time Visibility:** The **WebMonitor** provides operators with a comprehensive, browser-based interface for monitoring action statuses, server heartbeats, and live execution logs.
- **Scalability and Robustness:** The decentralized design and load-sharing capabilities ensure the system is highly scalable and capable of handling the complex requirements of large-scale facilities like NBTF

- **Replacement of the legacy centralized dispatcher with a scalable Redis-based distributed architecture**  
The work successfully introduced a modular and fault-tolerant MDSplus Action Dispatcher using Redis as the coordination and messaging backbone, improving reliability, scalability, and recovery capabilities for complex fusion experiments such as SPIDER and MITICA.
- **Commissioning of the new fully integrated real-time monitoring and control environment**  
A Python-native WebMonitor was created to provide live supervision of servers, actions, logs, and heartbeat status, enabling operators to monitor and control distributed execution in real time through a unified interface.
- **Successful validation in operational fusion environments with broader adoption potential**  
The new dispatcher framework was tested during **full discharge cycles in SPIDER and MITICA** and has already attracted adoption interest from **external laboratories such as MIT Plasma Science and Fusion Center**, demonstrating its applicability beyond ITER NBTF.



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*Thank you for your attention*