

# RELATIVISTIC (A)CAUSALITY IN HYDRODYNAMICS AND ITS EFFECT ON BAYESIAN ANALYSES

Matthew Luzum

References:

T.S.Domingues, R.Krupczak, J.Noronha, T.N.da Silva, J-F.Paquet, ML; Phys.Rev.C 110 (2024) 6, 064904; arXiv:2409.17127  
Arthur Lopez, ML; work in progress

University of São Paulo

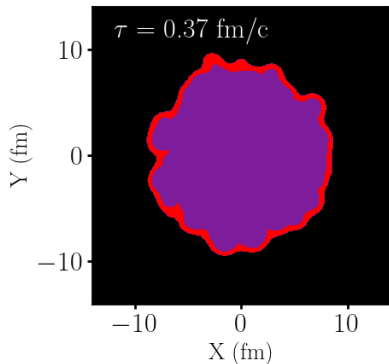
*Hot Jets: Advancing the Understanding of High Temperature QCD with Jets*  
January 9, 2025

## HYDRODYNAMIC VALIDITY

- Hydrodynamics central to simulations
- Validity of fluid description not always clear
- Typically derived as expansion around equilibrium
- Sometimes system is far from equilibrium (early times, near jets)
- Not definitive: hydro can be valid far from equilibrium
- Relativistic causality: definitive test
- How important is this issue? Quantify with Bayesian analysis

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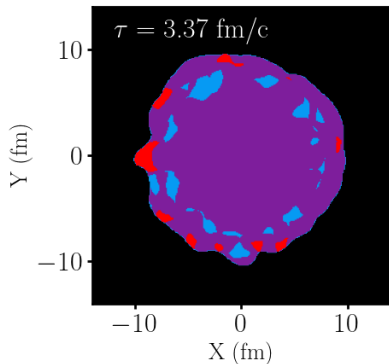


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Red: acausal  
Purple: unknown

*Phys.Rev.C 109 (2024) 3, 034908*

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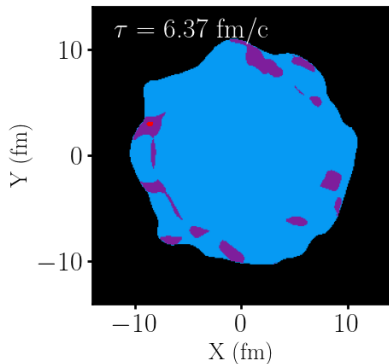
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# HYDRODYNAMICS AND CAUSALITY

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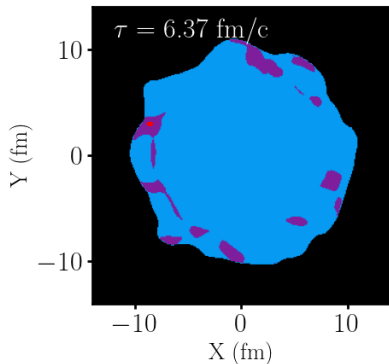


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- JETSCAPE performed large-scale analysis of soft sector  
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- How are these results affected if we don't allow hydro to be used in acausal regime?

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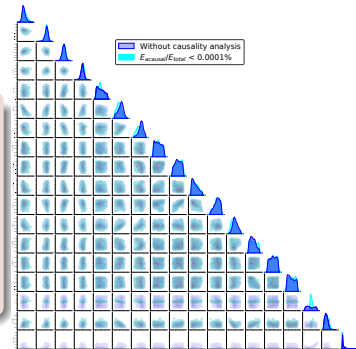
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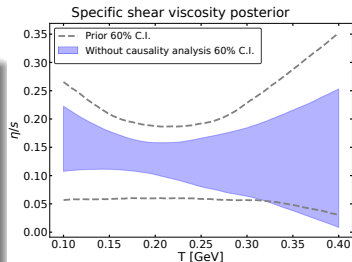
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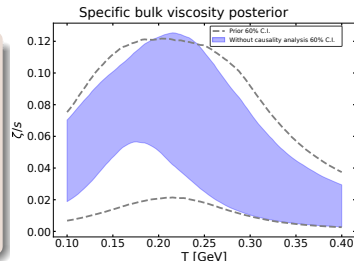
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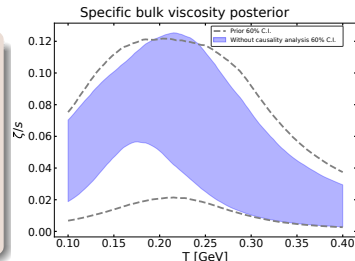
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- Modern hydrodynamic theory used in simulations:

$$\begin{aligned}
 T^{\mu\nu} &= \epsilon u^\mu u^\nu - (P + \Pi)\Delta^{\mu\nu} + \pi^{\mu\nu} \\
 \partial_\mu T^{\mu\nu} &= 0, \\
 \tau_\Pi \dot{\Pi} + \Pi &= -\zeta\theta - \delta_{\Pi\Pi}\Pi\theta + \lambda_{\Pi\pi}\pi^{\mu\nu}\sigma_{\mu\nu} \\
 \tau_\pi \dot{\pi}^{\langle\mu\nu\rangle} + \pi^{\mu\nu} &= 2\eta\sigma^{\mu\nu} - \delta_{\pi\pi}\pi^{\mu\nu}\theta + \varphi_7\pi_\alpha^{\langle\mu}\pi^{\nu\rangle\alpha} - \tau_{\pi\pi}\pi_\alpha^{\langle\mu}\sigma^{\nu\rangle\alpha} + \lambda_{\pi\Pi}\Pi\sigma^{\mu\nu}
 \end{aligned}$$

- Common parameterizations:

$$\begin{aligned}
 \tau_\Pi &= b_\Pi \frac{\zeta}{\left(\frac{1}{3} - c_s^2\right)^2 (\epsilon + p)} \\
 \tau_\pi &= b_\pi \frac{\eta}{sT}
 \end{aligned}$$

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 \frac{\delta_{\Pi\Pi}}{\tau_\Pi} &= \frac{2}{3} \\
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$$\begin{aligned}
 \frac{\lambda_{\Pi\pi}}{\tau_\pi} &= \frac{6}{5} \\
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# LINEAR CAUSALITY

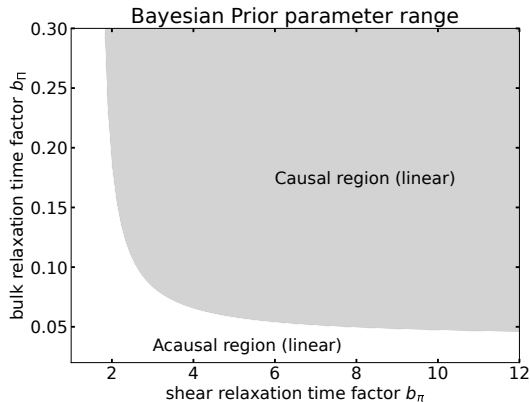
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- Linearize equations of motion. Demanding signal propagation  $v < c$  gives condition

$$n_{\text{static}} \equiv c_s^2 + \frac{4}{3} \frac{\eta}{\tau_\pi(\epsilon + P)} + \frac{\zeta}{\tau_\Pi(\epsilon + P)} \leq 1$$

$$\tau_\pi = b_\pi \frac{\eta}{sT}$$

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- Prior (and posterior) allows violation of linear causality!
- Small dependence of observables on  $\tau_\pi$  and  $\tau_\Pi$  gives flat posterior and no strong effect on conclusions about other parameters



Trajectory 1: *Phys. Rev. C* 103, 054909 (2021)

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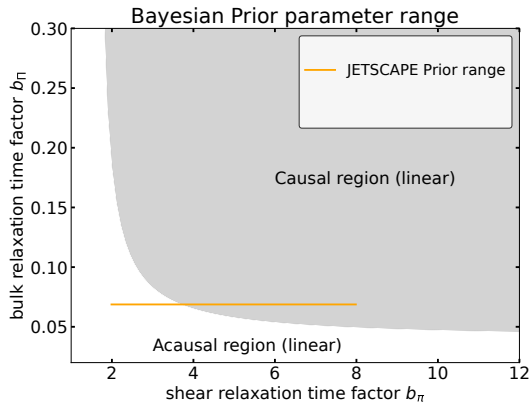
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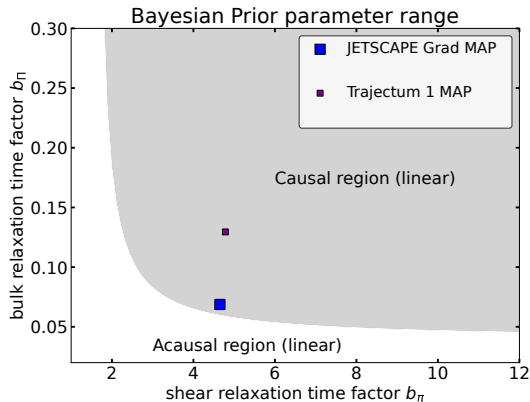
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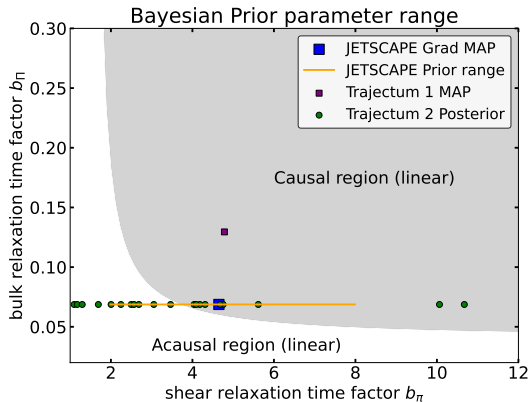
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Trajectory 2: *Phys. Rev. C* 106, 044903 (2022)

- Recently-derived (necessary) conditions for general, nonlinear case:

*Phys. Rev. Lett. 126, 222301 (2021)*

$$n_1 \equiv \frac{2}{b_\pi} + \frac{\lambda_{\pi\Pi}}{\tau_\pi} \frac{\Pi}{\varepsilon + P} - \frac{\tau_{\pi\pi}}{2\tau_\pi} \frac{|\Lambda_1|}{\varepsilon + P} \geq 0,$$

$$n_2 \equiv 1 - \frac{1}{b_\pi} + \left(1 - \frac{\lambda_{\pi\Pi}}{2\tau_\pi}\right) \frac{\Pi}{\varepsilon + P} - \frac{\tau_{\pi\pi}}{4\tau_\pi} \frac{\Lambda_3}{\varepsilon + P} \geq 0,$$

$$n_3 \equiv \frac{1}{b_\pi} + \frac{\lambda_{\pi\Pi}}{2\tau_\pi} \frac{\Pi}{\varepsilon + P} - \frac{\tau_{\pi\pi}}{4\tau_\pi} \frac{\Lambda_3}{\varepsilon + P} \geq 0,$$

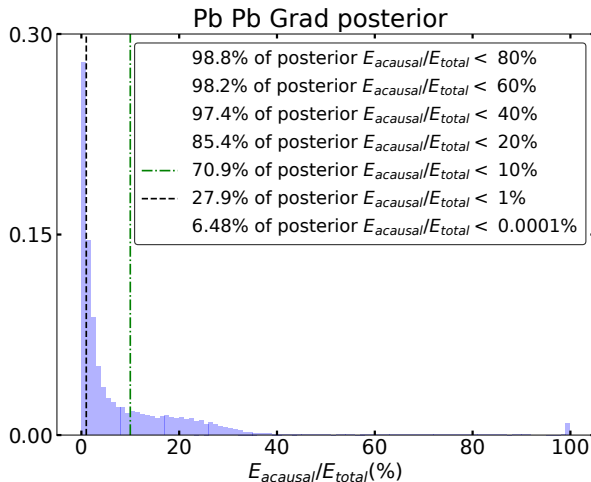
$$n_4 \equiv 1 - \frac{1}{b_\pi} + \left(1 - \frac{\lambda_{\pi\Pi}}{2\tau_\pi}\right) \frac{\Pi}{\varepsilon + P} + \left(1 - \frac{\tau_{\pi\pi}}{4\tau_\pi}\right) \frac{\Lambda_a}{\varepsilon + P} - \frac{\tau_{\pi\pi}}{4\tau_\pi} \frac{\Lambda_d}{\varepsilon + P} \geq 0,$$

$$n_5 \equiv c_s^2 + \frac{4}{3} \frac{1}{b_\pi} + b_\Pi \left(\frac{1}{3} - c_s^2\right)^2 + \left(\frac{2}{3} \frac{\lambda_{\pi\Pi}}{\tau_\pi} + \frac{\delta_{\Pi\Pi}}{\tau_\Pi} + c_s^2\right) \frac{\Pi}{\varepsilon + P} \left(\frac{3\delta_{\pi\pi} + \tau_{\pi\pi}}{3\tau_\pi} + \frac{\lambda_{\Pi\pi}}{\tau_\Pi} + c_s^2\right) \frac{\Lambda_1}{\varepsilon + P} \geq 0,$$

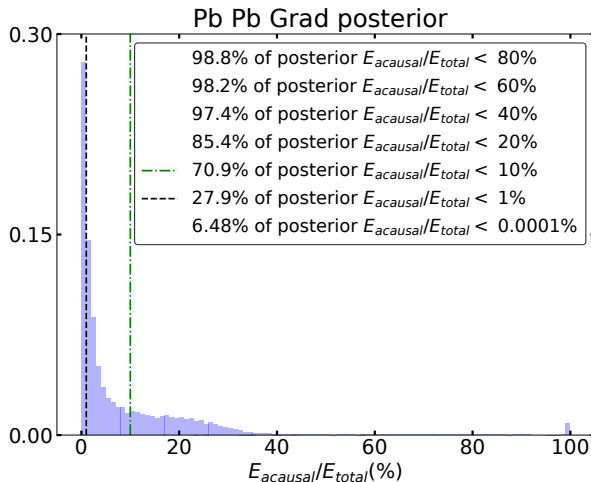
$$n_6 \equiv 1 - \left(c_s^2 + \frac{4}{3} \frac{1}{b_\pi} + b_\Pi \left(\frac{1}{3} - c_s^2\right)^2\right) + \left(1 - \frac{2}{3} \frac{\lambda_{\pi\Pi}}{\tau_\pi} - \frac{\delta_{\Pi\Pi}}{\tau_\Pi} - c_s^2\right) \frac{\Pi}{\varepsilon + P} + \left(1 - \frac{3\delta_{\pi\pi} + \tau_{\pi\pi}}{3\tau_\pi} - \frac{\lambda_{\Pi\pi}}{\tau_\Pi} - c_s^2\right) \frac{\Lambda_3}{\varepsilon + P} \geq 0.$$

- In practice,  $n_6$  is the most stringent condition

- JETSCAPE model: Trento  $\rightarrow$  Free Streaming  $\rightarrow$  Hydrodynamics  $\rightarrow$  Cooper-Frye
- We perform a  $b = 0$  simulation and quantify the fraction of system (defined by total energy) that is in an acausal regime at onset of hydrodynamics
- What happens if we make cuts on the posterior?

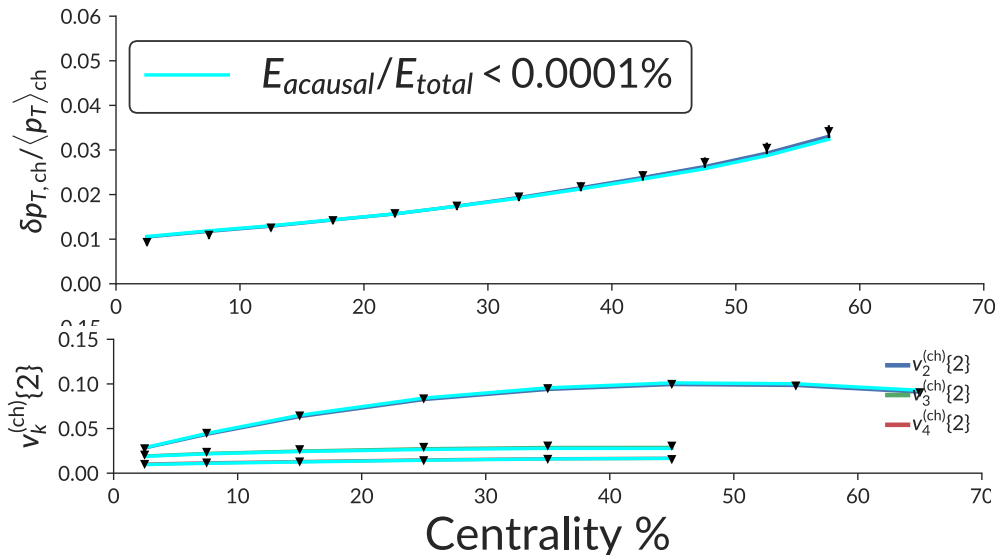


- JETSCAPE model: Trento  $\rightarrow$  Free Streaming  $\rightarrow$  Hydrodynamics  $\rightarrow$  Cooper-Frye
- We perform a  $b = 0$  simulation and quantify the fraction of system (defined by total energy) that is in an acausal regime at onset of hydrodynamics
- What happens if we make cuts on the posterior?

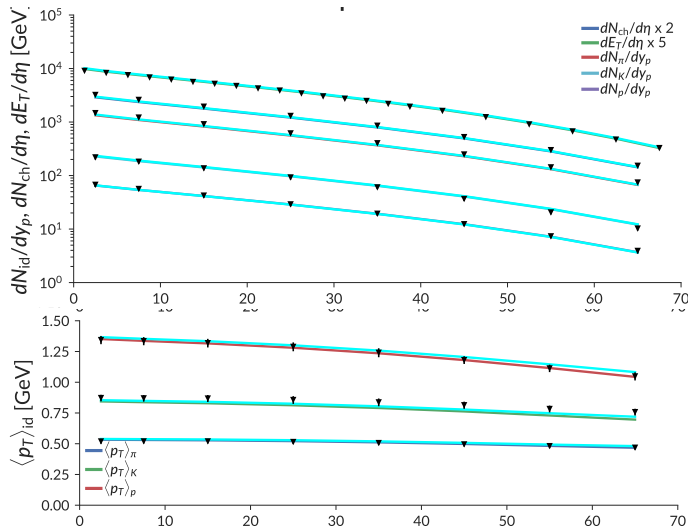




# OBSERVABLES (MAP WITH AND WITHOUT ACAUSALITY CUTS)



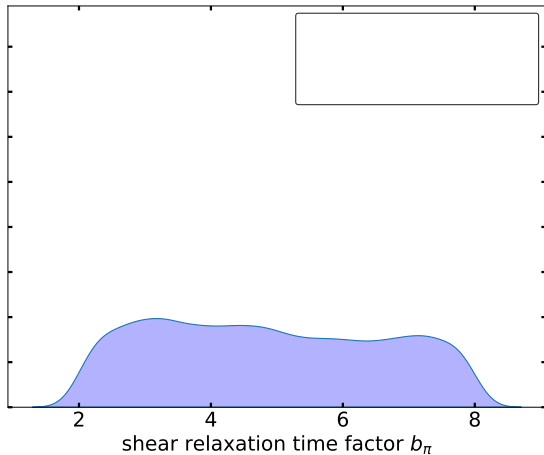
# OBSERVABLES (MAP WITH AND WITHOUT ACAUSALITY CUTS)



- Ability to fit data not destroyed by stringent causality demands
- Maximum probability (Maximum a Posteriori, MAP) of original posterior is  $\sim 3$  times as likely as best-fit after the strongest cut

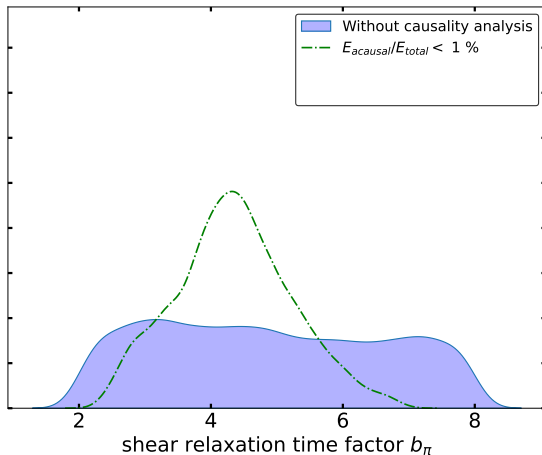
# 1D PARAMETER POSTERIORIORS

- 1D marginalized posterior distributions
- Demanding causality alters posteriors



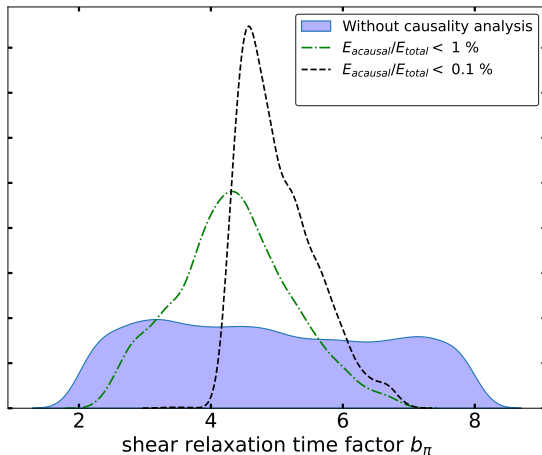
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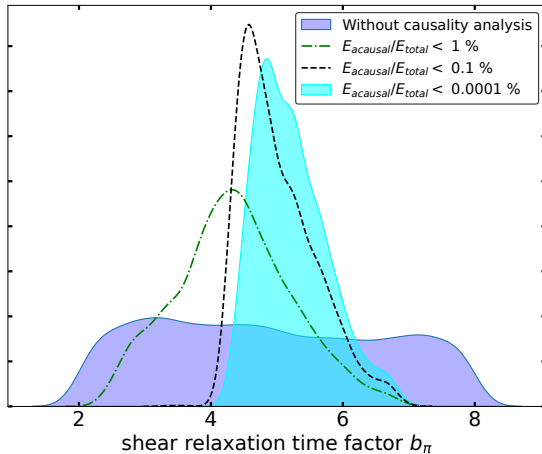
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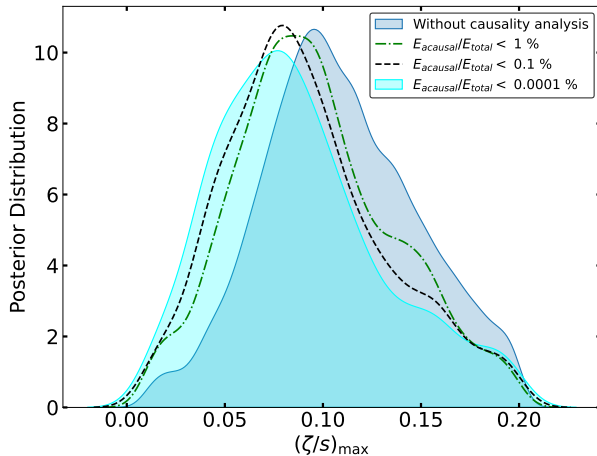
# 1D PARAMETER POSTERIOR DISTRIBUTIONS

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# 1D PARAMETER POSTERIOR

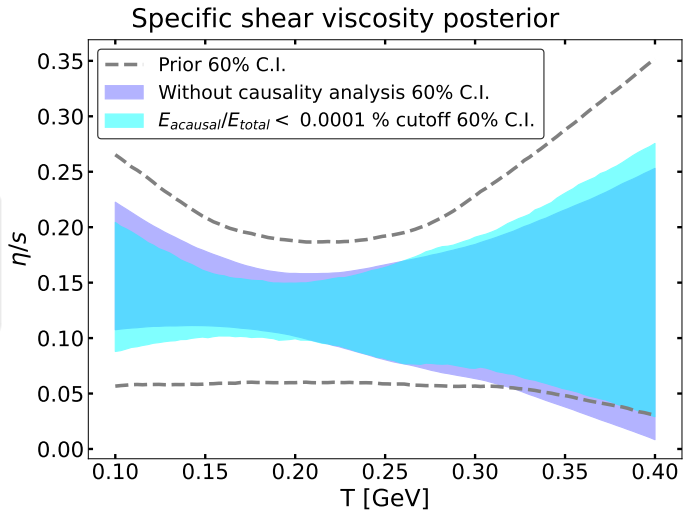
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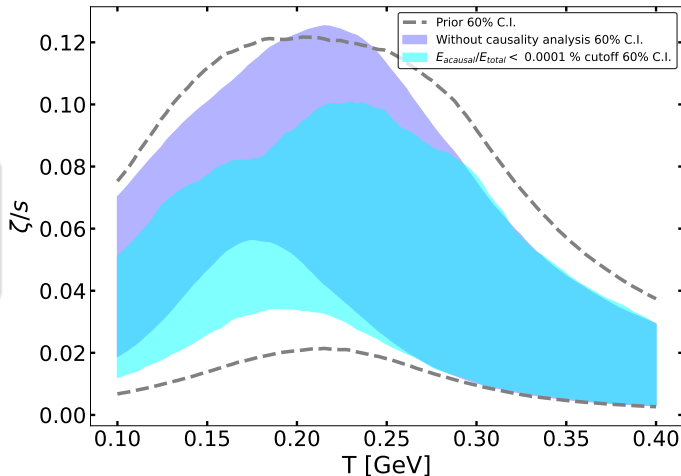
# VISCOSITY POSTERIOR

- Shear viscosity not significantly affected
- Large bulk viscosity disfavored by causality cuts



- Shear viscosity not significantly affected
- Large bulk viscosity disfavored by causality cuts

## Specific bulk viscosity posterior

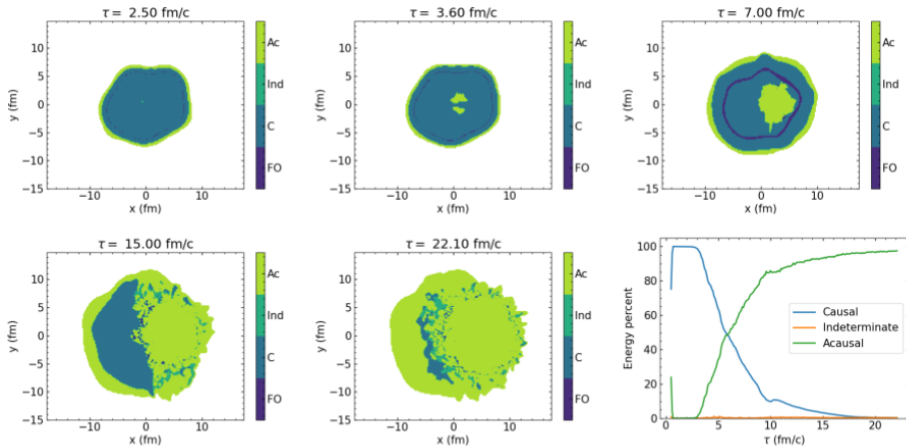


# CONCLUSIONS

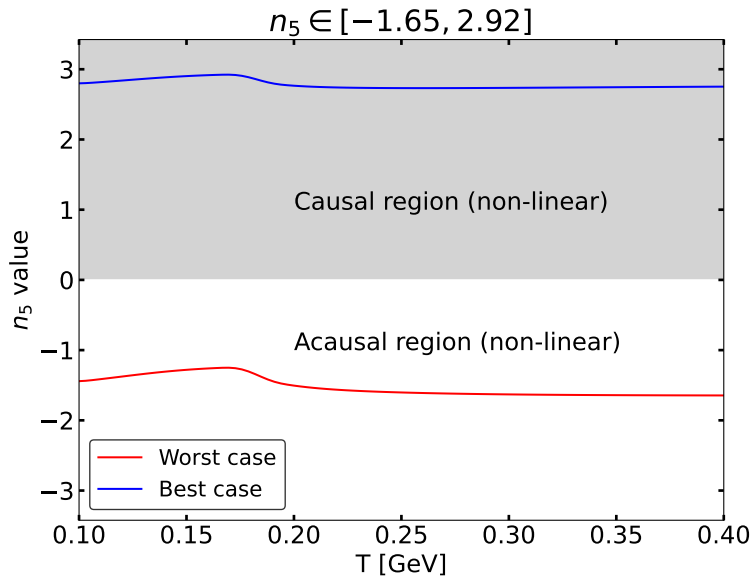
- Hydodynamic simulations typically enter acausal regimes, at least sometimes
- Demanding limits on acausality has nonnegligible effects on existing Bayesian analyses
- In the era of precision heavy-ion physics, it is an issue that should be addressed
  - Improve pre-hydrodynamic description
  - Further developments in hydrodynamic theory

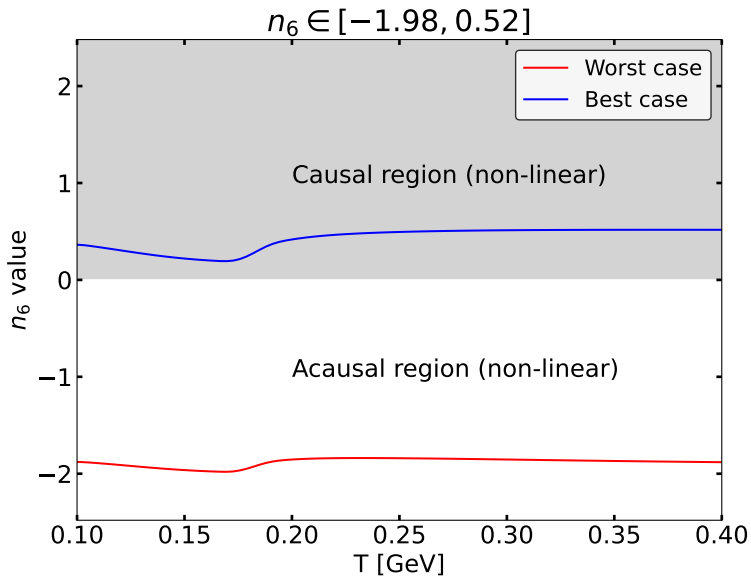
# BONUS: JET/MEDIUM INTERACTION

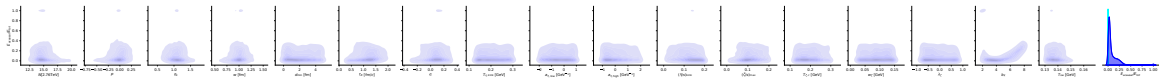
- Early times: system is far from equilibrium and must thermalize/hydrodynamize
- Same considerations near jets: energy lost by the jet must thermalize/hydrodynamize
- May have observable affects?



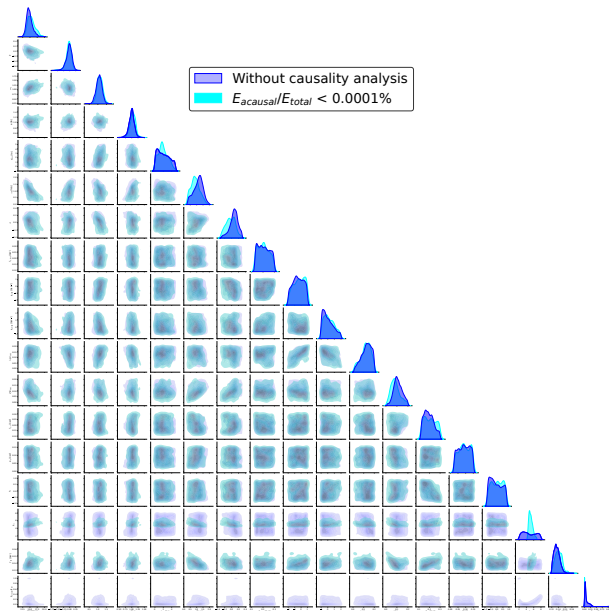
# EXTRA SLIDES





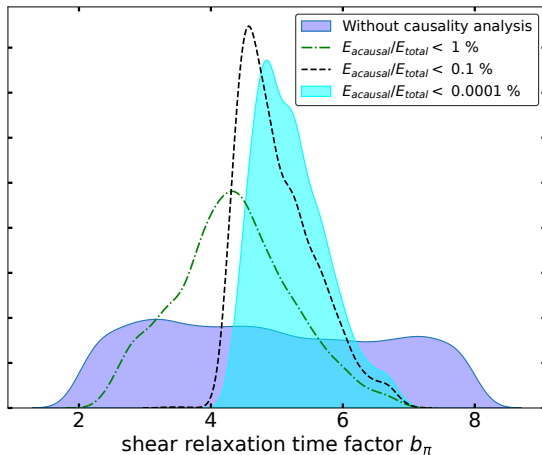






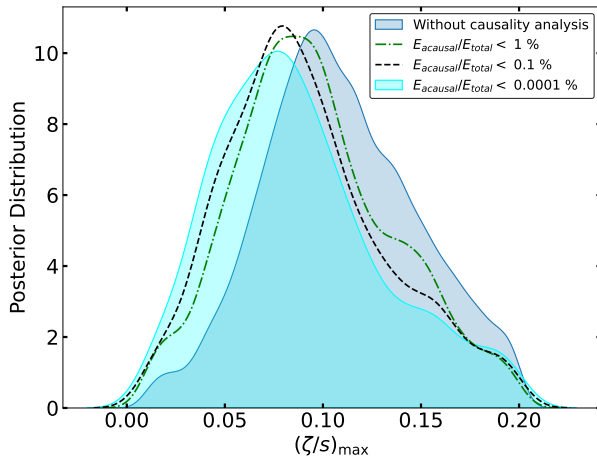
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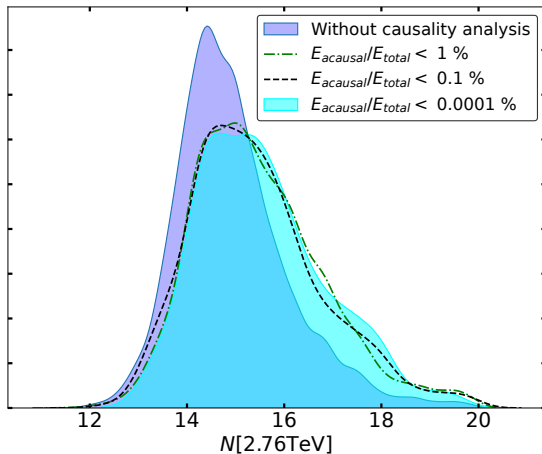
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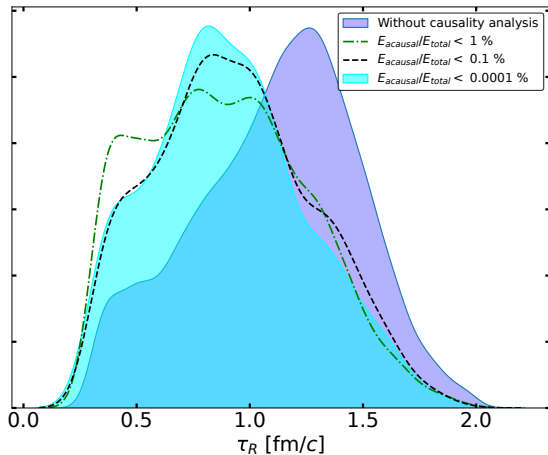
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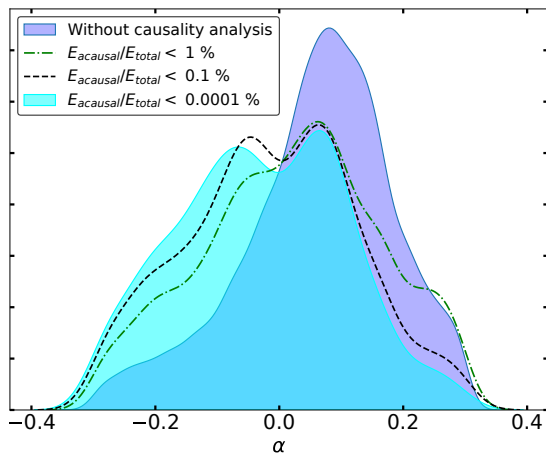
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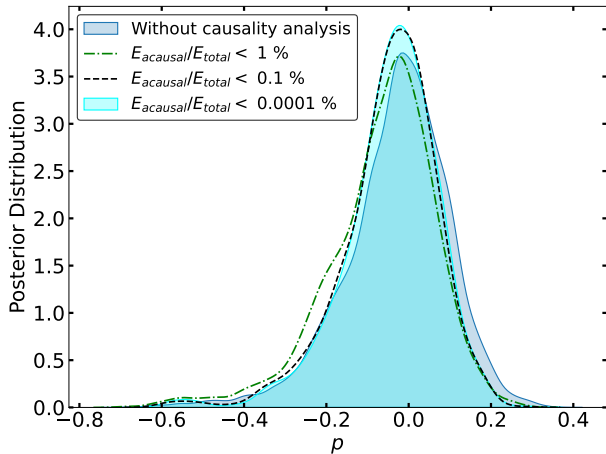
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