

# Expansion by regions with pySecDec

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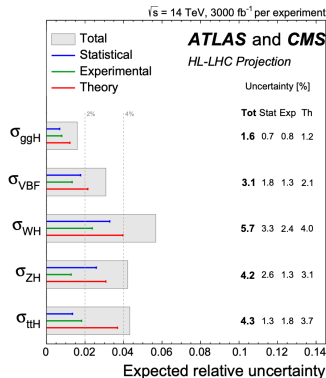
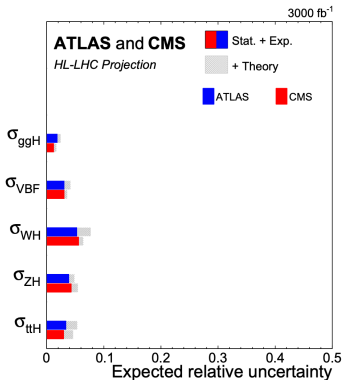
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# Introduction

# Introduction

Why caring about loop integrals?



Observables are dominated by theoretical uncertainties<sup>1</sup>

<sup>1</sup>image from *CERN HL-HE Yellow Report 2019*

There are **many techniques** to evaluate loop integrals:

- Mellin-Barnes representation
- Differential Equations
- Dimensional Recurrence
- Sector Decomposition
- Asymptotic expansions (e.g. Expansion by regions)

In the following → *Expansion by regions*

# Expansion by regions

# Expansion by regions<sup>2</sup>

First: **motivation**

$$G = \int \prod_{l=1}^L d^D \kappa_l \frac{1}{\prod_{j=1}^N P_j^{\nu_j}(\{k\}, \{p\}, m_j^2)}, \quad d^D \kappa \equiv \mu^{4-D} \frac{d^D k}{i\pi^{D/2}}$$

$G$  is a complicated function of **masses**  $m_j$  and **kinematics invariants**  $p_i \cdot p_j$

**Idea:** Exploit parameter hierarchies to expand **integrand** in small parameter, e.g.  $m^2/p^2 \rightarrow$  resulting integrals might be easier to evaluate

**Caveat:** one cannot just Taylor expand  $\rightarrow$  **magnitude of**  $k_l$

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<sup>2</sup>The method was pioneered in arXiv:hep-ph/9711391 by M. Beneke and V.A. Smirnov

# Expansion by regions

Example  $\rightarrow$  limit  $|p^2| \gg m^2$  of

$$G = \int d^D \kappa \frac{1}{(k+p)^2 (k^2 - m^2)^2} \equiv \int d^D \kappa \mathcal{I}$$

hard region:  $|k^2| \gg m^2$

soft region:  $|k^2|, |2k \cdot p| \ll p^2$

$$\mathcal{I}_{(h)} \sim \frac{1}{(k+p)^2 (k^2)^2} \left( 1 + 2 \frac{m^2}{k^2} \right)$$

$$\mathcal{I}_{(s)} \sim \frac{1}{p^2 (k^2 - m^2)^2} \left( 1 - \frac{k^2 + 2p \cdot k}{p^2} \right)$$

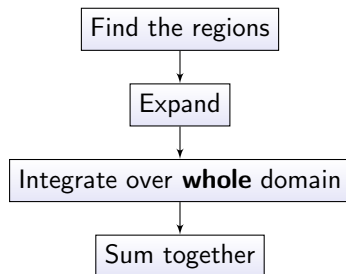
# Expansion by regions

Next  $\rightarrow$  *Integrate over whole domain*

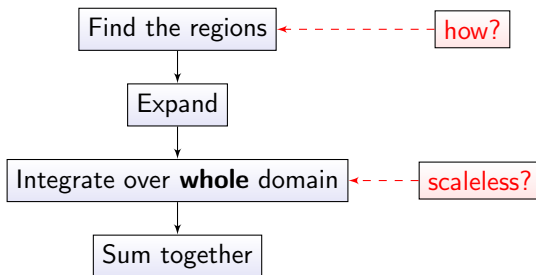
$$\begin{aligned} G &= \int d^D \kappa \mathcal{I}_{(h)} + \int d^D \kappa \mathcal{I}_{(s)} - \underbrace{\int d^D \kappa \mathcal{I}_{(hs)}}_{\text{scaleless} \rightarrow 0 \text{ in DR}} \\ &= \frac{1}{p^2} \left[ -\frac{1}{\epsilon} + \ln \left( \frac{-p^2}{\mu^2} \right) \right] + \frac{1}{p^2} \left[ \frac{1}{\epsilon} - \ln \left( \frac{m^2}{\mu^2} \right) \right] + o \left( \epsilon, \frac{m^2}{p^2} \right) \\ &= \frac{1}{p^2} \ln \left( \frac{-p^2}{m^2} \right) + o \left( \epsilon, \frac{m^2}{p^2} \right) \end{aligned}$$



## Workflow



## Workflow



# Expansion by regions

Let's move to Feynman parameters  $\rightarrow$  *Lee-Pomeransky parametrisation*<sup>3</sup>

$$G \propto \int_0^\infty \prod_j dx_j x_j^{\nu_j-1} P^{-D/2}$$

where  $P = F + U$  is a **polynomial**

$\rightarrow$  to find the regions we use the *Geometric Approach*<sup>4</sup>

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<sup>3</sup>arXiv:1308.6676 by R. Lee and A. Pomeransky

<sup>4</sup>arXiv:1011.4863 by A. Pak and A. Smirnov

# Expansion by regions

Consider

$$P(\mathbf{x}, t) = \sum_{i=0}^m c_i x_1^{p_{i,1}} \dots x_n^{p_{i,n}} t^{p_{i,n+1}}$$

with

- $c_i \rightarrow$  non-negative coefficients
- $x_i \rightarrow$  integration variables
- $\mathbf{p}_i = (p_{i,1}, \dots, p_{i,n+1}) \in \mathbb{N}^{n+1} \rightarrow$  exponent vectors
- $t \rightarrow$  small parameter

# Expansion by regions

We define  $\mathbf{u}$  such that  $x_i = t^{u_i}$  (note:  $t = t \rightarrow u_{n+1} = 1$ ) and write

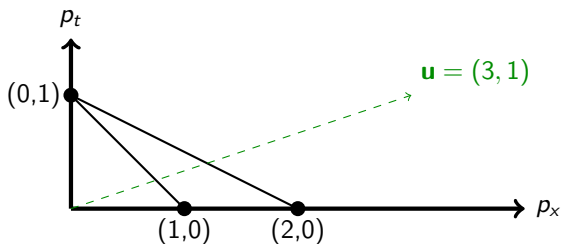
$$P(\mathbf{u}, t) = \sum_{i=0}^m c_i t^{\mathbf{p}_i \cdot \mathbf{u}}$$

The **largest term** of the polynomial is the one with the smallest value of  $\mathbf{p}_i \cdot \mathbf{u} \rightarrow$  let's visualise this with the **Newton polytope**  $\equiv \text{convHull}(\mathbf{p}_1, \mathbf{p}_2, \dots)$

$$\text{convHull}(\mathbf{p}_1, \mathbf{p}_2, \dots) = \left\{ a_1 \mathbf{p}_1 + \dots + a_n \mathbf{p}_n \mid a_i > 0 \quad \forall i, \sum_{i=1}^n a_i = 1 \right\}$$

# Expansion by regions

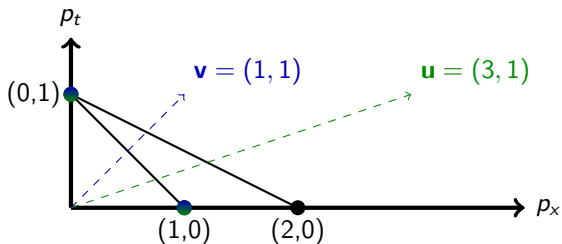
Newton polytope for  $P(x) = x + x^2 + t$ , along with an example vector  $\mathbf{u}$



$$\mathbf{p}_0 = (1, 0), \mathbf{p}_1 = (2, 0), \mathbf{p}_2 = (0, 1) \rightarrow P(t) = t^3 + t^6 + t$$

# Expansion by regions

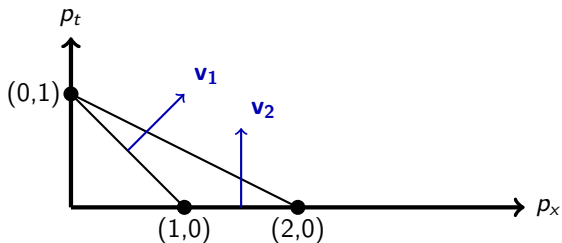
When expanding according to  $\mathbf{v}$  gives a convergent expansion at  $\mathbf{u}$ ?



**Answer:**  $\{\text{vertices closest along } \mathbf{v}\} \subseteq \{\text{vertices closest along } \mathbf{u}\}$

# Expansion by regions

We can find all the regions choosing the  $\mathbf{v}_i$

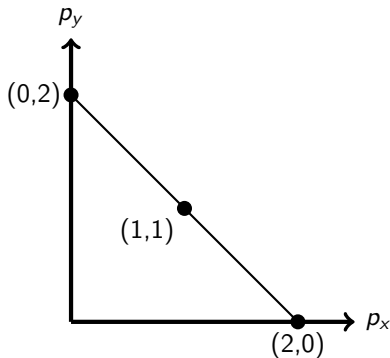


to be the **normal vectors** to the facets **pointing upwards**  $\rightarrow$  "how?" solved



# Expansion by regions

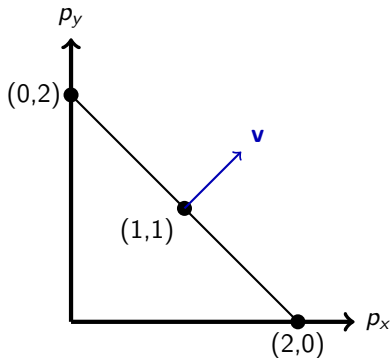
Consider now  $P(x,y) = x^2 + y^2 + xy$  and the corresponding polytope



the points lie on the line  $p_x + p_y = 2$  orthogonal to the  $\mathbf{v} = (1,1)$  direction.

# Expansion by regions

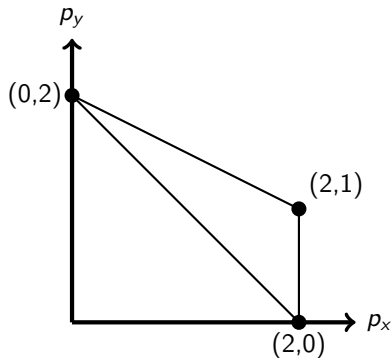
Rescaling with  $\mathbf{v} = (1, 1)$ , i.e.  $x \rightarrow \rho x$ ,  $y \rightarrow \rho y$  gives  $P(\rho x, \rho y) = \rho^2 P(x, y)$



Note that the **area** of the Newton polytope  $\mathcal{N}_P$  is **0**.

# Expansion by regions

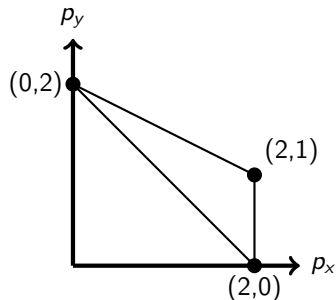
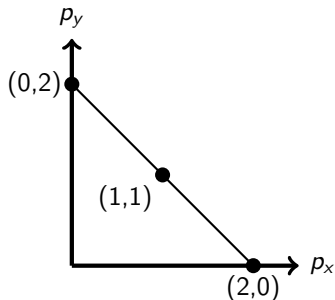
For non homogeneous polynomials  $\rightarrow Q(x,y) = x^2 + y^2 + x^2y$



The area of  $\mathcal{N}_Q$  is non-zero.

# Expansion by regions

Homogeneity<sup>5</sup>  $\equiv$  Scalelessness



Multiple expansions produce lower dimensional polytope  $\rightarrow$  "scaleless?" solved

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<sup>5</sup>homogeneity w.r.t. a subset of the Feynman parameters.

# Expansion by regions

*it's actually not that easy ...*

- with negative coefficients → **new regions** arise, hard to detect
- dimension as regulator not enough → **additional regulators** needed
- **overlap contributions**  $\neq 0$  → e.g. when not using analytic regulators

For more details → [arXiv:1111.2589](#) by *B. Jantzen*

**However:** Problematic cases can in general be **anticipated** and the validity of the method **assessed**

pySecDec: new release!

## What's new?

- 1 automated **Expansion by regions**

but also

- 2 automatic reduction of  $\lambda_j \rightarrow$  **no more sign check error!**
- 3  $\sum_k c_k I_k \rightarrow$  automatic adjustment  $\#$  evaluation points
- 4 FORM settings adjusted automatically<sup>6</sup>  $\rightarrow$  based on detected hardware

$\rightarrow$  towards *amplitudes* evaluation

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<sup>6</sup>Based on the work of T. Ueda

For **physical kinematics**, contour deformation might be needed:

$$z_i(\mathbf{x}) = x_i - i\lambda_i x_i(1 - x_i) \frac{\partial F}{\partial x_i}(\mathbf{x})$$

In order to preserve **Feynman prescription**  $-i\delta$ ,  $\lambda_i$  should be small enough.

Before: sign-check error and stop of the integration

Now: **automatic  $\lambda_i$  reduction**



## pySecDec: sum of integrals and coefficients

The # of **sampling points**  $N_s$  for each integral is set depending on its contribution to the **error estimate** of the sum and on the **time required** for each integrand evaluation. We set  $N_s$  minimising:

$$T = \sum_i t_i + \beta \left( \Delta_S^2 - \sum_i c_i^2 \Delta_i^2 \right)$$

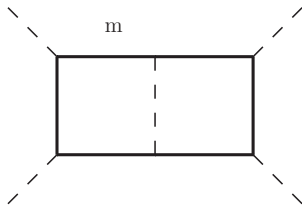
where:

- $t_i \rightarrow$  integration time of  $I_i$
- $\Delta_i \rightarrow$  absolute error of  $I_i$
- $\Delta_S \rightarrow$  absolute error of  $S$  (accuracy goal)
- $\beta \rightarrow$  Lagrange multiplier

$\rightarrow$  **global accuracy goal** for the sum reached more **efficiently**.

# Examples

# pySecDec: a hard example

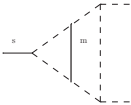
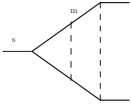
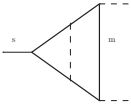


For  $s$ ,  $t$ ,  $m^2 = 5.3$ ,  $-1.86$ ,  $0.1$  and expanding at LO in  $m^2$ :

- regions: 13
- integrals: 5866
- time<sup>1</sup> (compile + integrate): 10 [h]
- accuracy: 1.4 %

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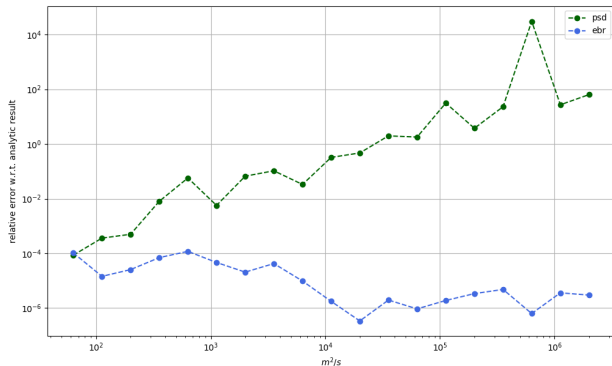
<sup>1</sup>Integration ran on a system with 4 GeForce 1080 Ti GPUs

Diagram	psd ( $r: 10^1$ ) [min]	psd ( $r: 10^3$ ) [min]	ebr ( $r: 10^3$ ) [min]
	5.23	101.94	1.61
	1.52	33.77	8.55
	0.12	0.13	0.09

$r \equiv$  invariants ratio, accuracy:  $10^{-2}$

# pySecDec: scan (ebr vs psd)

1<sup>st</sup> two loop triangle: scan over  $m^2/s$



**ebr** is numerically stable over many orders of magnitude as ratio of scales increases

# Conclusions

## Summary:

- Expansion by regions
- pySecDec new features:
  - 1 automatic  $\lambda_i$  reduction
  - 2 automatic adjustment # evaluation points
  - 3 FORM settings
- Examples

Thank you for listening!