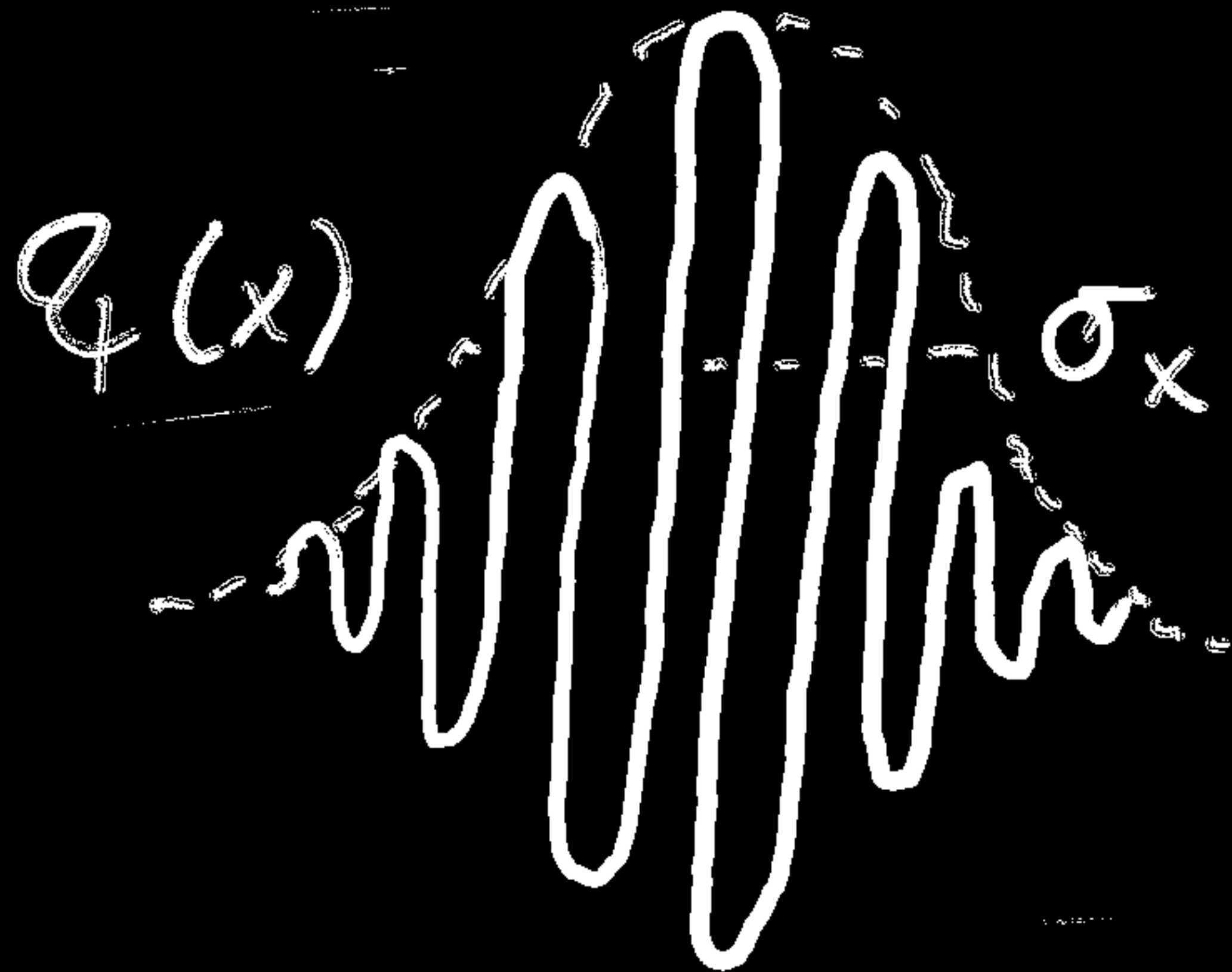


# Asymptotic Extended Generalized Uncertainty Principle

Fabian Wagner  
([fabian.wagner@usz.edu.pl](mailto:fabian.wagner@usz.edu.pl))

based on: Mariusz P. Dąbrowski & FW, Eur. Phys. J. C (2019) 79: 716  
Mariusz P. Dąbrowski & FW, Eur. Phys. J. C (2020) 80: 676

26/09/2020



$$\sigma_x \sigma_p \geq \hbar/2$$

How does space-time curvature affect the uncertainty principle?

What can we learn from  
this result?

# Overview

1. What the adjectival hell?

a. Generalized

b. Extended

c. Asymptotic

2. Method of derivation

3. Result

4. Conclusion

What the adjectival  
hell?

# Generalised (GUP)

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$$\sigma_x \sigma_p \geq \frac{\hbar}{2}$$

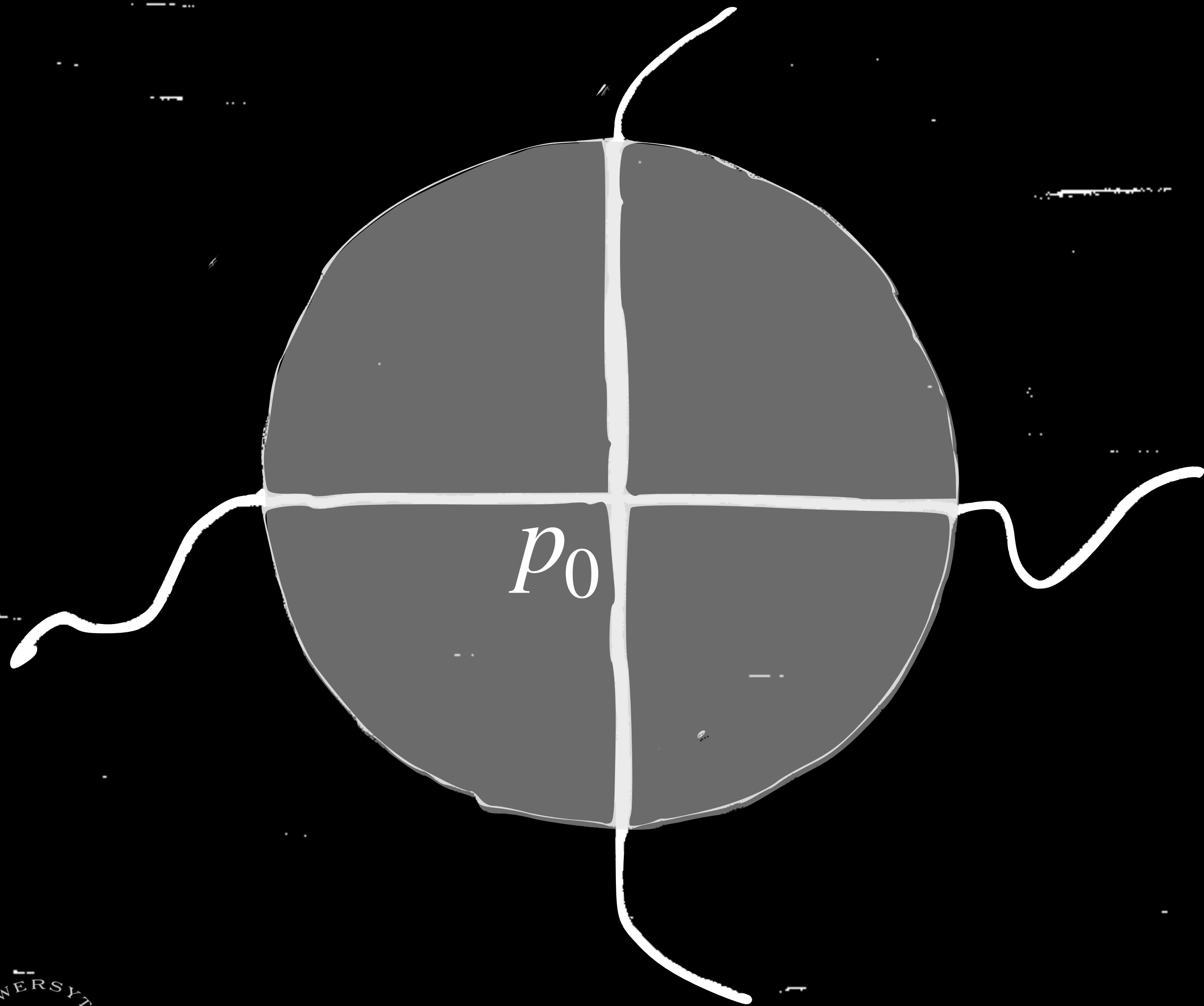
# Generalised (GUP)

$$\sigma_x \sigma_p \gtrsim \frac{\hbar}{2} \left( 1 + \alpha \frac{l_P^2 \sigma_p^2}{\hbar^2} \right)$$

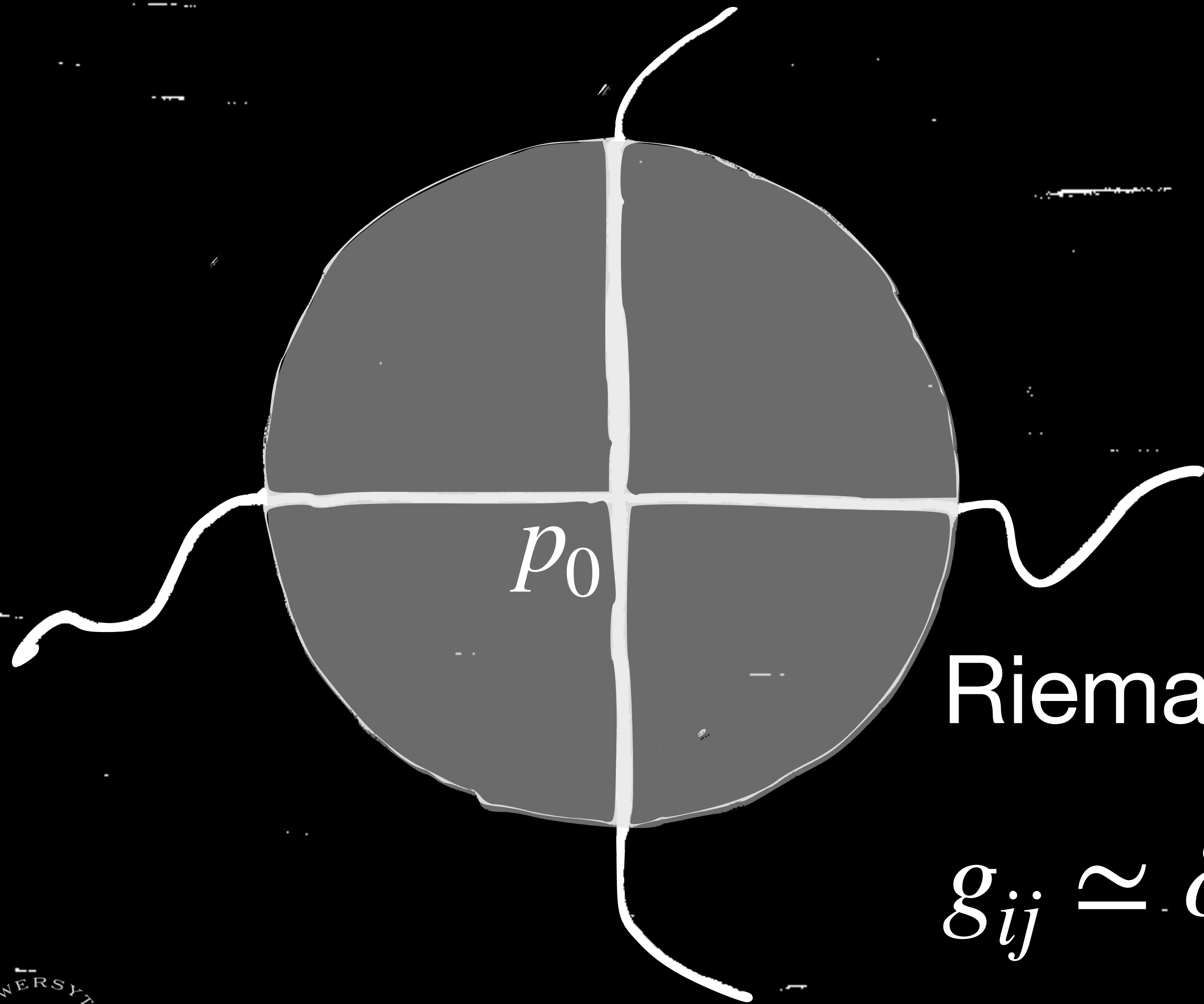
# Extended (EUP)

$$\sigma_x \sigma_p \gtrsim \frac{\hbar}{2} \left( 1 + \beta \frac{\sigma_x^2}{l_C^2} \right)$$

# Asymptotic



# Asymptotic

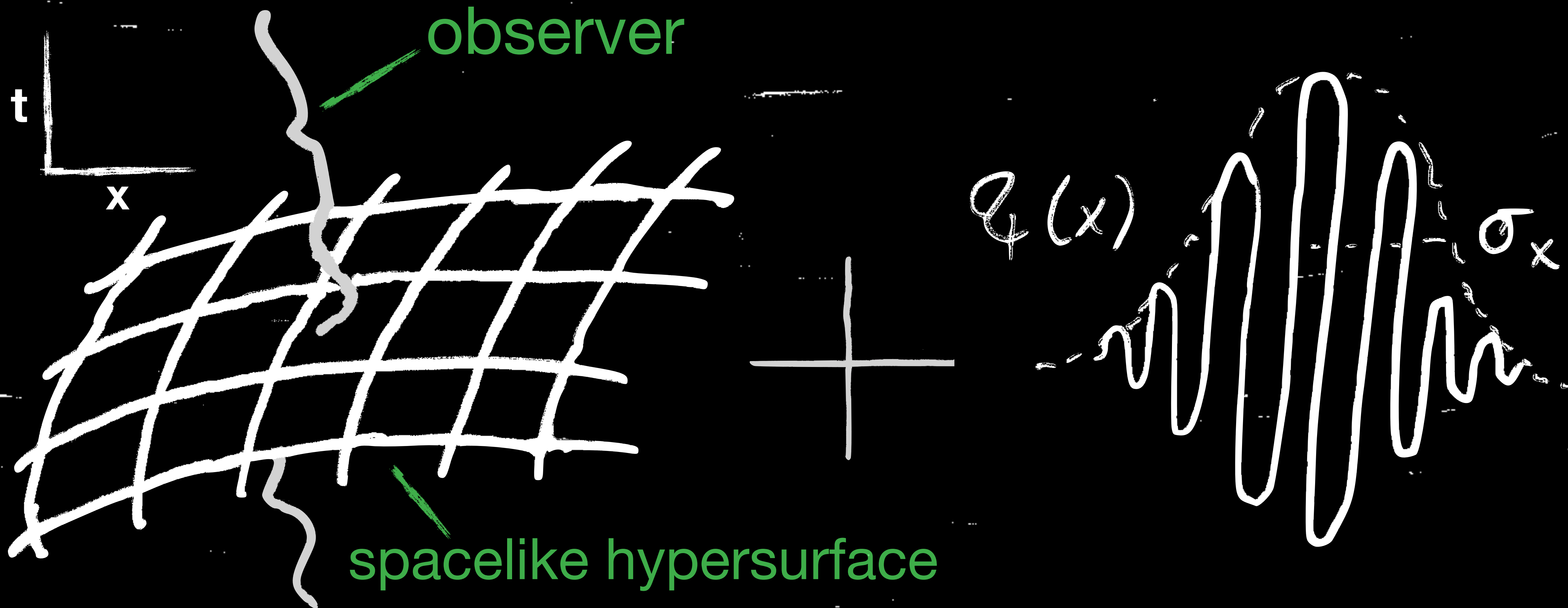


Riemann Normal Coordinates  $x^i$

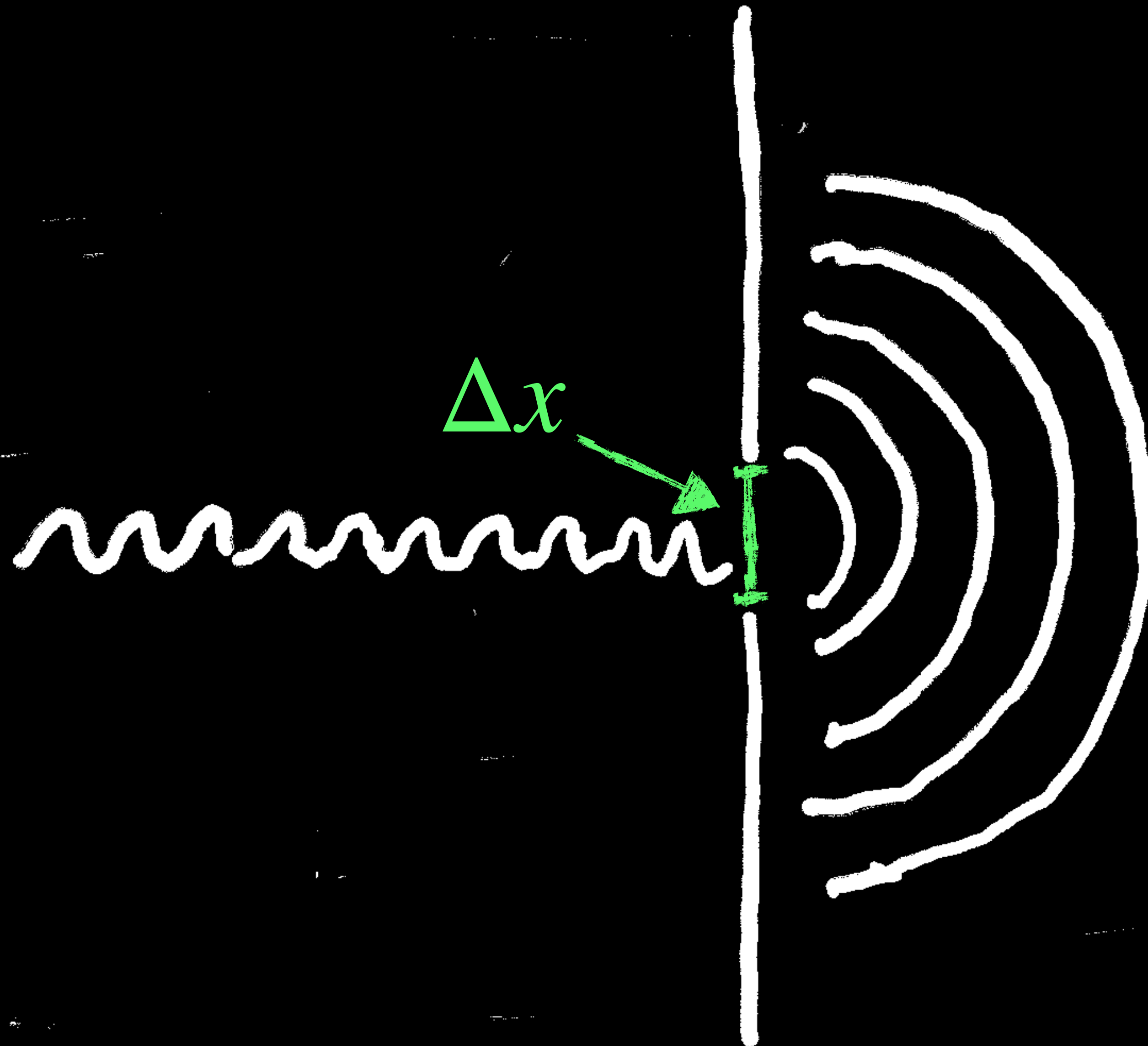
$$g_{ij} \simeq \delta_{ij} - \frac{1}{3} R_{ikjl} |_{p_0} x^k x^l$$

# Method of derivation

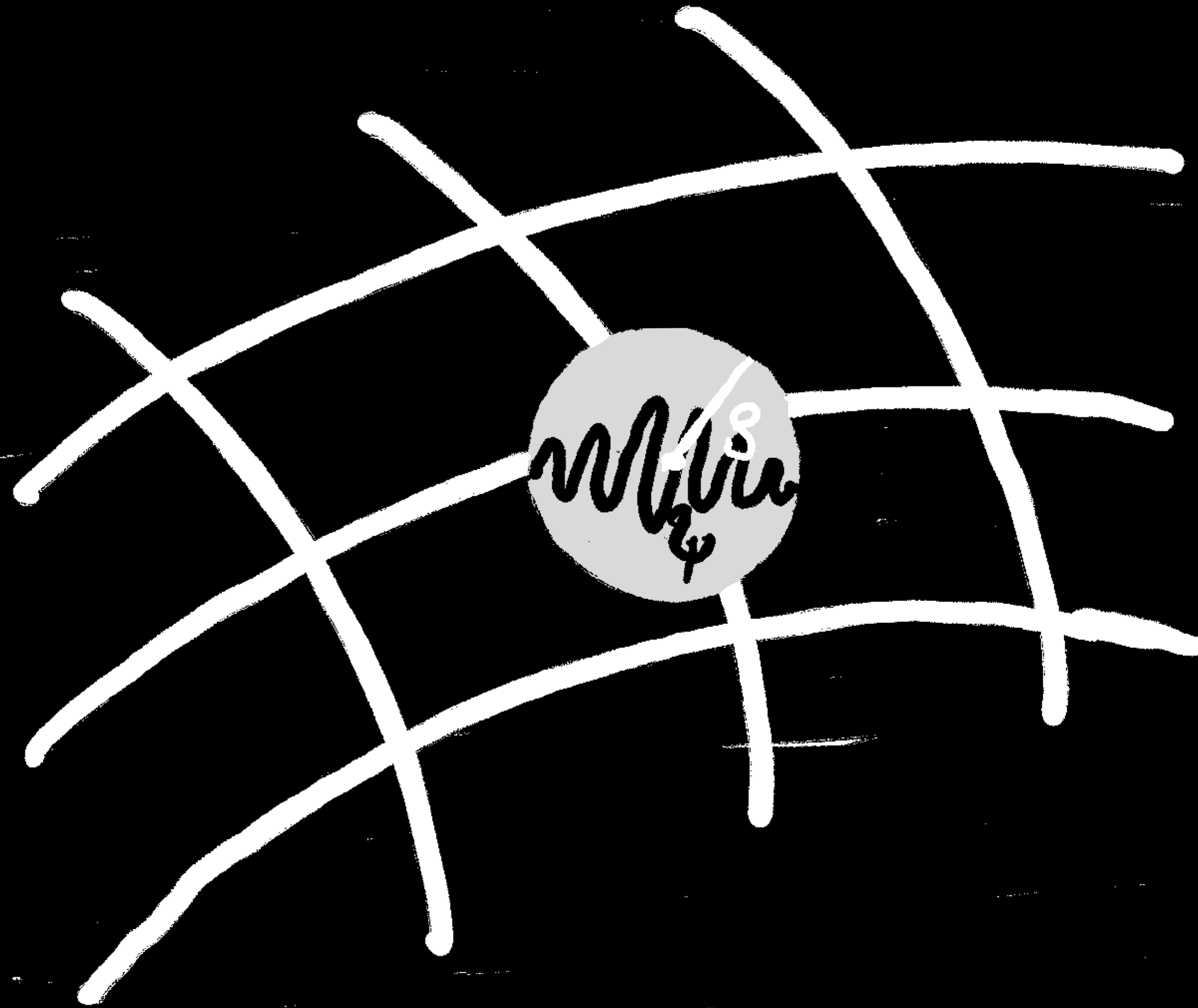
# QM on curved 3D manifolds



# Heisenberg's position uncertainty



# Generalisation to curved 3D



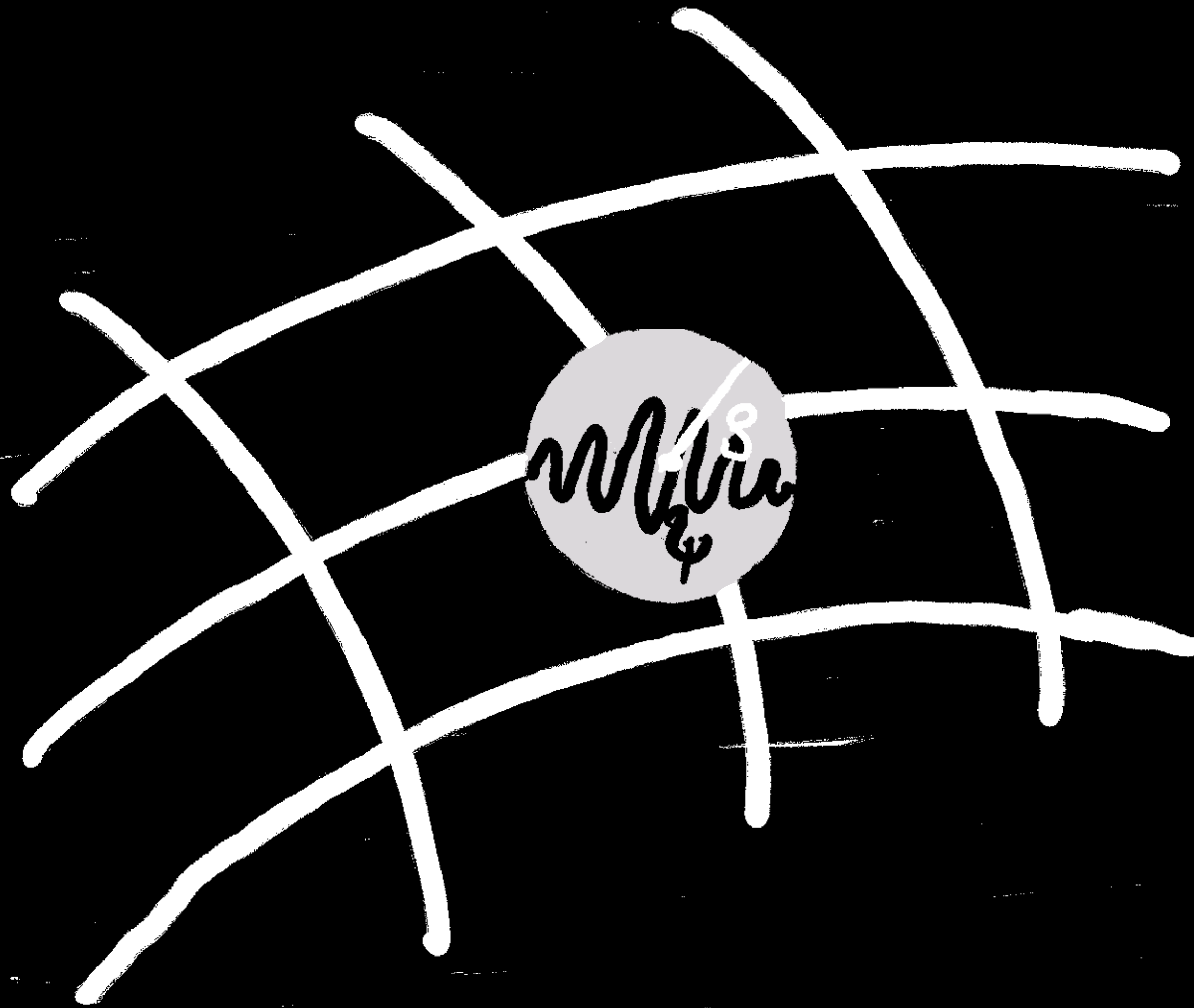
# Generalisation to curved 3D



Geodesic distance

$$\sigma(P, Q) = \int_P^Q ds$$

# Generalisation to curved 3D



Geodesic distance

$$\sigma(P, Q) = \int_P^Q ds$$

Geodesic ball  $B_\rho$

$$\sigma(p_0, x) \leq \rho$$

# Momentum standard deviation

$$\sigma_p \rho \gtrsim \pi \hbar (1 + \dots)$$

# Result

# Asymptotic EGUP

$$\sigma_{p\rho} \gtrsim \pi\hbar \left( 1 + \alpha \frac{l_p^2 \sigma_p^2}{\hbar^2} - \frac{1}{12\pi^2} {}^{(3)}R|_{p_0} \rho^2 \right)$$

# Asymptotic EGUP

GUP

$$\sigma_{p\rho} \gtrsim \pi\hbar \left( 1 + \alpha \frac{l_p^2 \sigma_p^2}{\hbar^2} - \frac{1}{12\pi^2} {}^{(3)}R|_{p_0} \rho^2 \right)$$

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EUP

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# Asymptotic EGUP

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$\beta$

# Conclusion

How does the  
curvature of space-  
time affect the  
uncertainty principle?

# What can we learn from this result?

- Every kind of curved space leads to an EUP
  - even in Minkowski space-time (with appropriate slicing)
- Positive curvature decreases uncertainty ("quantumness")
  - Can vanish if manifold is closed
- Momentum space curvature = GUP
  - Point  $p_0$  corresponds to  $\vec{p} = 0$  (low energy)
- Approach well-suited for quantum mechanics in curved position or momentum space

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Can we generalize to  
curvature in both  
spaces  
simultaneously?



THE MORE  
UNCERTAINTY  
YOU CAN  
TOLERATE  
= THE  
MORE  
CREATIVE  
YOU CAN  
BECOME.

the  
blue  
limb

# Appendix

# GEUP/ EGUP

$$\sigma_x \sigma_p \gtrsim \frac{\hbar}{2} \left( 1 + \alpha \frac{l_P^2 \sigma_p^2}{\hbar^2} + \beta l_C^{-2} \sigma_x^2 \right)$$

# Momentum standard deviation

$$\text{Dirichlet: } \psi|_{\partial B_\rho} = 0 \longrightarrow \langle \hat{p} \rangle = 0$$

$$\begin{aligned} \sigma_p &= \sqrt{\langle \hat{p}^2 \rangle} \\ &\geq \sqrt{\lambda_1(\rho)} \end{aligned}$$

# Schürmann's result

Constant curvature  $K$

$$\sigma_{p\rho} \geq \pi\hbar \left( 1 - \frac{K\rho^2}{2\pi^2} \right)$$

# Eigenvalue problem

$$(\hbar^2 \Delta + \lambda) \psi|_{B_\rho} = 0$$

$$\psi|_{\partial B_\rho} = 0$$

# Perturbation theory

$$g_{ij} = g_{ij}^{(0)} + g_{ij}^{(2)} + \dots$$
$$\Delta = \Delta^{(0)} + \Delta^{(2)} + \dots$$

$$\psi = \psi^{(0)} + \psi^{(2)} + \dots$$
$$\lambda = \lambda^{(0)} + \lambda^{(2)} + \dots$$

# Perturbation theory

Complication:

$$\begin{aligned}\langle \psi | \phi \rangle &= \int \sqrt{g} d^3x (\psi^* \phi) \\ &= \langle \psi | \phi \rangle^{(0)} + \langle \psi | \phi \rangle^{(2)} + \dots\end{aligned}$$

# Deformed commutator (GUP)

$$\text{In 1D: } [\hat{x}, \hat{P}] = i\hbar \left( 1 + \frac{\alpha l_P^2}{\hbar^2} \hat{P}^2 \right)$$

$$\hat{P} \simeq \hat{p} \left( 1 + \frac{\alpha l_P^2}{\hbar^2} \hat{p}^2 \right)$$

$$\text{In 3D: } \hat{P}_i \simeq \hat{p}_i \left( 1 + \frac{\alpha l_P^2}{\hbar^2} \hat{p}^2 \right)$$

# Asymptotic EGUP

$$\sigma_p \rho \gtrsim \pi \hbar \left[ 1 + \alpha \frac{l_p^2 \sigma_p^2}{\hbar^2} + \frac{\rho^2}{\pi^2} \left( \lambda_1^{(2)} + \dots \right) \right]$$

$$\sigma_x \sigma_p \gtrsim \frac{\hbar}{2} \left( 1 + \alpha \frac{l_p^2 \sigma_p^2}{\hbar^2} + \beta l_C^2 \sigma_x^2 \right)$$